

Complete Solution to Exercises 3.3

1. (a) We are given the matrices $\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and $\mathbf{B} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and the matrix \mathbf{A} is **not** a multiple of matrix \mathbf{B} therefore the matrices are linearly independent.

(b) What do you notice about given matrices $\mathbf{A} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ and $\mathbf{B} = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}$?

Matrix \mathbf{B} is twice matrix \mathbf{A} , that is $\mathbf{B} = 2\mathbf{A}$ or $\mathbf{B} - 2\mathbf{A} = \mathbf{O}$ which means that the matrices are linearly dependent.

(c) Matrices $\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ and $\mathbf{B} = \begin{pmatrix} 2 & 2 \\ 2 & 2 \end{pmatrix}$ are **not** multiples of each other therefore they are linearly independent.

(d) Can you spot a relationship between $\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ and $\mathbf{B} = \begin{pmatrix} 2/5 & 4/5 \\ 6/5 & 8/5 \end{pmatrix}$?

$\mathbf{B} = \frac{2}{5}\mathbf{A}$ or $\mathbf{B} - \frac{2}{5}\mathbf{A} = \mathbf{O}$. Since we can produce the zero vector with non-zero scalars, 1 and $-\frac{2}{5}$, therefore the given vectors are linearly dependent.

2. (a) We are given the functions $\mathbf{f} = (x+1)^2$ and $\mathbf{g} = x^2 + 2x + 1$. What do you notice about these functions?

$$(x+1)^2 = x^2 + 2x + 1$$

This means that we have

$$(x+1)^2 - (x^2 + 2x + 1) = 0$$

$$\mathbf{f} - \mathbf{g} = \mathbf{O} \quad \left[\text{Because } \mathbf{f} = (x+1)^2 \text{ and } \mathbf{g} = x^2 + 2x + 1 \right]$$

Hence \mathbf{f} and \mathbf{g} are linearly dependent.

(b) Using scalars k and c we have

$$k\mathbf{f} + c\mathbf{g} = k(2) + cx^2 = 0 \quad (\$)$$

Substituting $x = 0$ into (\$) gives $2k + c(0)^2 = 2k = 0 \Rightarrow k = 0$. Substituting $x = 1$ into

(§) gives $2k + c(1)^2 = 2k + c = 0$ because $k = 0$ therefore $c = 0$.

Hence $k = 0$ and $c = 0$ that is **all** (both) scalars are zero therefore we conclude that the given functions $\mathbf{f} = 2$ and $\mathbf{g} = x^2$ are linearly independent.

(c) Using scalars k and c we have

$$k\mathbf{f} + c\mathbf{g} = k(1) + ce^x = 0$$

Substituting $x = 0$ and $x = 1$ gives the simultaneous equations

$$k + c = 0$$

$$k + ce = 0$$

Solving these simultaneous equations gives $k = 0$ and $c = 0$.

All (both) scalars are zero therefore we conclude that the given functions

$\mathbf{f} = 1$ and $\mathbf{g} = e^x$ are linearly independent.

(d) Using scalars k and c we have

$$k\mathbf{f} + c\mathbf{g} = k \cos(x) + c \sin(x) = 0 \quad (*)$$

Substituting $x = 0$ into (*)

$$k \underbrace{\cos(0)}_{=1} + c \underbrace{\sin(0)}_{=0} = 0 \quad \text{gives} \quad k = 0$$

Substituting $x = \frac{f}{2}$ into (*)

$$k \underbrace{\cos\left(\frac{f}{2}\right)}_{=0} + c \underbrace{\sin\left(\frac{f}{2}\right)}_{=1} = 0 \quad \text{gives} \quad c = 0$$

Hence $k = 0$ and $c = 0$. Both scalars are zero therefore the given functions

$$\mathbf{f} = \cos(x) \quad \text{and} \quad \mathbf{g} = \sin(x)$$

are linearly independent.

[Showing $\cos(x)$ and $\sin(x)$ are linearly independent is important in the theory of differential equations].

(e) We need to test $\mathbf{f} = \sin(x)$ and $\mathbf{g} = \sin(2x)$ for linear independence. Since $\sin(2x)$ is not a scalar multiple of $\sin(x)$ so they are linear independent.

3. (a) We have the fundamental trigonometric identity

$$\cos^2(x) + \sin^2(x) = 1$$

Multiplying each side by 5 gives

$$5\cos^2(x) + 5\sin^2(x) = 5$$

$$5\cos^2(x) + 5\sin^2(x) - 5 = 0 \quad (*)$$

Consider the linear combination

$$k_1\mathbf{f} + k_2\mathbf{g} + k_3\mathbf{h} = k_1\cos^2(x) + k_2\sin^2(x) + k_3(5) = 0$$

Comparing this with (*) we have $k_1 = 5$, $k_2 = 5$ and $k_3 = -1$ gives 0. All scalars are **not** zero therefore vectors \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly dependent.

(b) We are given the functions $\mathbf{f} = \cos(2x)$, $\mathbf{g} = \sin^2(x)$ and $\mathbf{h} = \cos^2(x)$. *Can you remember any trigonometric identity relating these functions?*

$$\cos(2x) = \cos^2(x) - \sin^2(x)$$

Rearranging this gives

$$\cos(2x) + \sin^2(x) - \cos^2(x) = 0 \quad (\dagger)$$

The linear combination

$$k_1\mathbf{f} + k_2\mathbf{g} + k_3\mathbf{h} = k_1\cos(2x) + k_2\sin^2(x) + k_3\cos^2(x) = 0$$

Comparing with (\dagger) we have $k_1 = 1$, $k_2 = 1$ and $k_3 = -1$. Hence \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly dependent.

(c) We are given the functions $\mathbf{f} = 1$, $\mathbf{g} = x$ and $\mathbf{h} = x^2$. Writing these as a linear combination:

$$k_1\mathbf{f} + k_2\mathbf{g} + k_3\mathbf{h} = k_1(1) + k_2x + k_3x^2 = 0$$

Equating coefficients gives $k_1 = k_2 = k_3 = 0$. The functions \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly independent.

(d) We are given the functions $\mathbf{f} = \sin(2x)$, $\mathbf{g} = \sin(x)\cos(x)$ and $\mathbf{h} = \cos(x)$. *Do you remember any trigonometric identity which relates these 3 functions?*

$$\sin(2x) = 2\sin(x)\cos(x)$$

We can write this as

$$\sin(2x) - 2\sin(x)\cos(x) = 0 \quad (\$)$$

Consider the linear combination

$$k_1 \mathbf{f} + k_2 \mathbf{g} + k_3 \mathbf{h} = k_1 \sin(2x) + k_2 \sin(x)\cos(x) + k_3 \cos(x) = 0$$

Comparing this with (\$) gives $k_1 = 1$, $k_2 = -2$ and $k_3 = 0$. Since we have non-zero scalars (k 's) therefore \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly dependent.

(e) We need to decide whether the following functions

$$\mathbf{f} = e^x \sin(2x), \quad \mathbf{g} = e^x \sin(x)\cos(x) \quad \text{and} \quad \mathbf{h} = e^x \cos(x)$$

are linearly dependent or independent. Since these are the same functions as part (d) apart from the multiple e^x therefore we have

$$\begin{aligned} k_1 \mathbf{f} + k_2 \mathbf{g} + k_3 \mathbf{h} &= k_1 e^x \sin(2x) + k_2 e^x \sin(x)\cos(x) + k_3 e^x \cos(x) \\ &= e^x [k_1 \sin(2x) + k_2 \sin(x)\cos(x) + k_3 \cos(x)] = 0 \end{aligned}$$

The square bracket term is 0 for the k values given in part (d) above:

$$e^x [\sin(2x) - 2\sin(x)\cos(x) + 0\cos(x)] = 0$$

We have $k_1 = 1$, $k_2 = -2$ and $k_3 = 0$. We have non-zero scalars (k 's) therefore \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly dependent.

Later on in question 8 we will prove:

A set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is linearly independent then

$$\{k\mathbf{v}_1, k\mathbf{v}_2, k\mathbf{v}_3, \dots, k\mathbf{v}_n\}$$

where k is a non-zero scalar, is also linearly independent.

We can use this result in our case with $k = e^x \neq 0$.

(f) Writing the given functions $\mathbf{f} = 1$, $\mathbf{g} = e^x$ and $\mathbf{h} = e^{-x}$ in a linear combination

$$k_1 \mathbf{f} + k_2 \mathbf{g} + k_3 \mathbf{h} = k_1 (1) + k_2 e^x + k_3 e^{-x} = 0$$

By substituting various values of x we get the only possible solution

$k_1 = 0$, $k_2 = 0$ and $k_3 = 0$. Hence the functions \mathbf{f} , \mathbf{g} and \mathbf{h} are linearly independent.

(g) We need to test $\mathbf{f} = e^x$, $\mathbf{g} = e^{2x}$ and $\mathbf{h} = e^{3x}$ for linear independence. Since we cannot write e^{3x} in terms of e^x and e^{2x} :

$$c_1 e^x + c_2 e^{2x} \neq e^{3x}$$

Similarly

$$k_1 e^x + k_2 e^{3x} \neq e^{2x}$$

By (3.14):

The vectors in the set $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ are linearly dependent \Leftrightarrow one of these vectors, say \mathbf{v}_k , is a linear combination of the preceding vectors, that is

$$\mathbf{v}_k = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + c_3 \mathbf{v}_3 + \dots + c_{k-1} \mathbf{v}_{k-1}$$

Applying this result to the above we conclude that $\mathbf{f} = e^x$, $\mathbf{g} = e^{2x}$ and $\mathbf{h} = e^{3x}$ linearly independent.

4. Required to show that $\mathbf{f} = \sin(x)$, $\mathbf{g} = \sin(3x)$ and $\mathbf{h} = \sin(5x)$ are linearly independent. From our knowledge of trigonometry we know that $\sin(5x)$ cannot be written in terms of $\sin(x)$ and $\sin(3x)$, that is

$$k \sin(x) + c \sin(3x) \neq \sin(5x)$$

Hence by Proposition (3.14) we conclude that the given vectors

$$\mathbf{f} = \sin(x), \mathbf{g} = \sin(3x) \text{ and } \mathbf{h} = \sin(5x)$$

are linearly independent.

5. Need to show that the following matrices form a basis for M_{22} :

$$\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \mathbf{B} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \mathbf{C} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \text{ and } \mathbf{D} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

For a basis we need to prove that \mathbf{A} , \mathbf{B} , \mathbf{C} and \mathbf{D} span M_{22} and also these matrices are linearly independent.

Span: Let $\mathbf{X} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ be an arbitrary matrix and

$$k_1 \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + k_2 \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + k_3 \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + k_4 \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} k_1 & k_2 \\ k_3 & k_4 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

Equating the entries, we have $k_1 = a$, $k_2 = b$, $k_3 = c$ and $k_4 = d$. Since the matrix \mathbf{X} was arbitrary therefore we can produce any 2 by 2 matrix by a linear combination of matrices \mathbf{A} , \mathbf{B} , \mathbf{C} and \mathbf{D} . Hence these matrices span M_{22} .

Linearly Independent: Using the above to produce the zero matrix, $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, we have

$k_1 = a$, $k_2 = b$, $k_3 = c$ and $k_4 = d$ and because each entry is 0 therefore **all** the k 's are zero, that is $k_1 = 0$, $k_2 = 0$, $k_3 = 0$ and $k_4 = 0$. Hence matrices \mathbf{A} , \mathbf{B} , \mathbf{C} and \mathbf{D} are linearly independent.

We have both, span and linear independence, therefore the given matrices form a basis for M_{22} .

6. We need to show that $\{1, t-1, (t-1)^2\}$ span P_2 and is linearly independent.

Span: Let $at^2 + bt + c$ be an arbitrary member of P_2 . We have

$$\begin{aligned} k_1(1) + k_2(t-1) + k_3(t-1)^2 &= k_1 + k_2t - k_2 + k_3(t^2 - 2t + 1) && \text{[Expanding]} \\ &= k_1 + k_2t - k_2 + k_3t^2 - 2k_3t + k_3 \\ &= k_3t^2 + (k_2 - 2k_3)t + (k_1 - k_2 + k_3) && \left[\begin{array}{l} \text{Collecting Like} \\ \text{Terms} \end{array} \right] \\ &= at^2 + bt + c \end{aligned}$$

Equating coefficients gives

$$k_3 = a, \quad k_2 - 2k_3 = b \text{ and } k_1 - k_2 + k_3 = c$$

Substituting the first equation $k_3 = a$ into the middle equation $k_2 - 2k_3 = b$ gives

$$k_2 - 2a = b \Rightarrow k_2 = 2a + b$$

Substituting $k_2 = 2a + b$ and $k_3 = a$ into the last equation $k_1 - k_2 + k_3 = c$:

$$k_1 - (2a + b) + a = c \quad \text{gives} \quad k_1 = c + (2a + b) - a = c + a + b$$

Hence we have found scalars, $k_1 = c + a + b$, $k_2 = 2a + b$ and $k_3 = a$, which produce the arbitrary polynomial $at^2 + bt + c$ therefore we conclude that the given set of vectors

$$\{1, t-1, (t-1)^2\} \text{ span } P_2.$$

Linearly Independent: Using the above to produce the zero polynomial, with $a = 0$, $b = 0$ and $c = 0$:

$$k_1 = 0 + 0 + 0 = 0, \quad k_2 = 2(0) + 0 = 0 \quad \text{and} \quad k_3 = 0$$

Since **all** the scalars are zero therefore $\{1, t-1, (t-1)^2\}$ is linearly independent.

The set $\{1, t-1, (t-1)^2\}$ span P_2 and is linearly independent therefore we can say it forms a basis for P_2 .

By the spanning set from above we have

$$at^2 + bt + c = (c + a + b)(1) + (2a + b)(t-1) + a(t-1)^2$$

For our polynomial $\mathbf{p} = t^2 + 1$ we have $a = 1$, $b = 0$ and $c = 1$. Putting these values into the above gives

$$\begin{aligned} t^2 + 1 &= (1 + 1 + 0)(1) + (2(1) + 0)(t-1) + 1(t-1)^2 \\ &= 2 + 2(t-1) + (t-1)^2 \end{aligned}$$

7. We need to show the following vectors of P_2 do **not** form a basis:

$$\{1, t^2 - 2t, 5(t-1)^2\}$$

Easier to show that this set is linearly dependent.

$$\begin{aligned} k_1(1) + k_2(t^2 - 2t) + 5k_3(t-1)^2 &= k_1 + k_2t^2 - 2tk_2 + 5k_3(t^2 - 2t + 1) \quad [\text{Expanding}] \\ &= k_1 + k_2t^2 - 2tk_2 + 5k_3t^2 - 10k_3t + 5k_3 \\ &\stackrel{\text{Collecting Like Terms}}{=} (k_2 + 5k_3)t^2 + (-2k_2 - 10k_3)t + (k_1 + 5k_3) = 0 \end{aligned}$$

Equating coefficients we have

$$t^2: \quad k_2 + 5k_3 = 0$$

$$t: \quad -2k_2 - 10k_3 = 0$$

$$\text{const:} \quad k_1 + 5k_3 = 0$$

From the bottom equation we have $k_1 = -5k_3$. Let $k_3 = 1$ then $k_1 = -5(1) = -5$.

Substituting $k_3 = 1$ into the top equation $k_2 + 5k_3 = 0$ gives

$$k_2 + 5(1) = 0 \quad \text{gives} \quad k_2 = -5$$

We have non-zero scalars, $k_1 = -5$, $k_2 = -5$ and $k_3 = 1$, therefore the given set of vectors

$$\{1, t^2 - 2t, 5(t-1)^2\} \text{ is linearly dependent.}$$

This means that $\{1, t^2 - 2t, 5(t-1)^2\}$ **cannot** form a basis for P_2 .

8. We need to prove that if a set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is linearly independent then $\{k\mathbf{v}_1, k\mathbf{v}_2, k\mathbf{v}_3, \dots, k\mathbf{v}_n\}$, where k is a non-zero scalar, is also linear independent.

Proof.

Consider the linear combination

$$c_1(k\mathbf{v}_1) + c_2(k\mathbf{v}_2) + c_3(k\mathbf{v}_3) + \dots + c_n(k\mathbf{v}_n) = \mathbf{0} \quad (*)$$

where the c 's are scalars.

What do we need to prove?

Required to prove that the only scalars which satisfy (*) is when they are **all** zero, that is $c_1 = c_2 = c_3 = \dots = c_n = 0$. We have

$$c_1(k\mathbf{v}_1) + c_2(k\mathbf{v}_2) + c_3(k\mathbf{v}_3) + \dots + c_n(k\mathbf{v}_n) = \mathbf{0}$$

$$kc_1\mathbf{v}_1 + kc_2\mathbf{v}_2 + kc_3\mathbf{v}_3 + \dots + kc_n\mathbf{v}_n = \mathbf{0}$$

$$k(c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 + \dots + c_n\mathbf{v}_n) = \mathbf{0} \quad [\text{Taking Out a Factor of } k]$$

$k \neq 0$ [Not Zero] because the proposition states this.

We are also given that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ are linearly independent therefore they satisfy

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 + \dots + c_n\mathbf{v}_n = \mathbf{0} \Rightarrow c_1 = c_2 = c_3 = \dots = c_n = 0$$

Hence $\{k\mathbf{v}_1, k\mathbf{v}_2, k\mathbf{v}_3, \dots, k\mathbf{v}_n\}$ are linearly independent.

9. We need to prove a non-zero vector \mathbf{v} is linearly independent.

Proof.

Let \mathbf{v} be a non-zero vector in a vector space V . Consider the linear combination

$$k\mathbf{v} = \mathbf{0} \Rightarrow k = 0 \text{ or } \mathbf{v} = \mathbf{0} \quad [\text{By (3.1) part (d)}]$$

The only way this scalar multiplication $k\mathbf{v}$ is zero is if $k = 0$ because \mathbf{v} is non-zero.

Hence the vector \mathbf{v} is linearly independent.

10. We are required to prove the zero, $\mathbf{0}$, vector is dependent.

Proof.

$k\mathbf{0} = \mathbf{0}$ for any non-zero scalar k therefore $\mathbf{0}$ is linearly dependent.

11. Need to prove that if any two vectors are equal, $\mathbf{v}_j = \mathbf{v}_m$ where $j \neq m$, then the set is linearly dependent.

Proof.

Without Loss of Generality we can assume $j < m$. Consider the linear combination

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3 + \dots + k_j\mathbf{v}_j + \dots + k_m\mathbf{v}_m + \dots + k_n\mathbf{v}_n = \mathbf{0} \quad (*)$$

Take all the k 's to equal zero apart from k_j and k_m . Let $k_j = 1$ and $k_m = -1$ then (*) becomes

$$0\mathbf{v}_1 + 0\mathbf{v}_2 + 0\mathbf{v}_3 + \dots + \mathbf{v}_j + \dots + (-1)\mathbf{v}_m + \dots + 0\mathbf{v}_n = \mathbf{v}_j - \mathbf{v}_m$$

Since we are given $\mathbf{v}_j = \mathbf{v}_m$ therefore $\mathbf{v}_j - \mathbf{v}_m = \mathbf{0}$. We have non-zero scalars,

$k_j = 1$ and $k_m = -1$, which produce the zero vector therefore the given set is linearly dependent.

12. We need to prove that any non-empty subset of a linearly independent set of $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is also independent.

Proof.

Any non-empty subset of S will contain vectors from this list $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n$. Let these vectors be $\mathbf{v}_j, \mathbf{v}_{j+1}, \dots, \mathbf{v}_{m-1}, \mathbf{v}_m$ where $1 \leq j \leq m$ and $m \leq n$.

Suppose these are linearly dependent. Consider the linear combination

$$k_j \mathbf{v}_j + k_{j+1} \mathbf{v}_{j+1} + \dots + k_{m-1} \mathbf{v}_{m-1} + k_m \mathbf{v}_m = \mathbf{O} \quad (\dagger)$$

Then all the scalars k 's are not zero.

Take $k_1 = k_2 = k_{j-1} = k_{m+1} = \dots = k_n = 0$. The linear combination

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n = \mathbf{O} \quad (\dagger\dagger)$$

By (\dagger) all the scalars are not zero in $(\dagger\dagger)$ which means the vectors in

$$S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$$

are linearly dependent. This cannot be the case because we are given that these vectors are independent. Hence our supposition – the vectors $\mathbf{v}_j, \mathbf{v}_{j+1}, \dots, \mathbf{v}_{m-1}, \mathbf{v}_m$ are dependent must be wrong so they are linearly independent.

13. We need to prove that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n, \mathbf{w}\}$ spans V but is linearly dependent provided that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ spans V .

Proof.

Vectors $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ span V therefore we can write the vector $\mathbf{w} \in V$ as a linear combination of the vectors in $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$.

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n = \mathbf{w}$$

Rearranging this gives

$$k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n - \mathbf{w} = \mathbf{O}$$

We can produce the zero vector with **non-zero** scalars (the scalar associated with \mathbf{w} is -1) therefore $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n, \mathbf{w}\}$ is linearly dependent.

Let \mathbf{u} be an arbitrary vector in V . Since we are given that $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ spans V therefore

$$\begin{aligned} \mathbf{u} &= k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n \\ &= k_1 \mathbf{v}_1 + k_2 \mathbf{v}_2 + k_3 \mathbf{v}_3 + \dots + k_n \mathbf{v}_n + (0) \mathbf{w} \end{aligned}$$

Hence $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n, \mathbf{w}\}$ also spans V .

14. We are required to prove that if $B = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ is a basis for V and $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_m\}$ is a set of linearly independent vectors in V then $m \leq n$.

Proof.

Suppose $m > n$ then by the result of question 13 the set $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_m\}$ is linearly dependent which contradicts that S is linearly independent. Hence $m \leq n$.

15. We need to prove that if $B_1 = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ and $B_2 = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \dots, \mathbf{u}_m\}$ are bases for a vector space V then $n = m$.

Proof.

By the result (proposition) of question 13 we have $n \leq m$ and $m \leq n$ which means that $n = m$.

16. We need to prove that if the largest number of linearly independent vectors in a vector space V is n then any n linearly independent vectors forms a basis for V .

Proof.

Let $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ be a set of n linearly independent vectors in V .

Let \mathbf{w} be an arbitrary vector in V . Since n is the largest number of independent vectors in V therefore $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n, \mathbf{w}\}$ is a set of linearly dependent vectors which

means that the vector \mathbf{w} is a linear combination of $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$. Hence the set

$\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ span V . Since we know these \mathbf{v} 's are linearly independent

therefore $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ are a basis for V .

17. We need to prove that if S and V have the same basis then $S = V$.

Proof.

Let $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$ be the basis vectors of S and V . Let a vector \mathbf{u} be in S . This vector must also be a member of V . *Why?*

Because $\mathbf{u} = k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + k_3\mathbf{v}_3 + \dots + k_n\mathbf{v}_n$ and V is a vector space. Similarly a vector in V must be in S . Since every vector in S is in V and every vector in V is in S so they must be equal, $S = V$.