EX6 Mobile Robotics

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A, 0.0

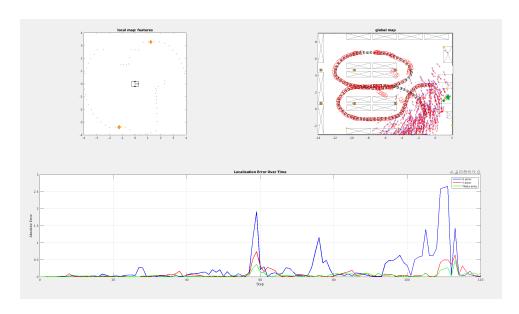


Figure 1: NEFFTHESHOLD = 0.0 , NParticles = 500, Systematic resampling

A 0.1

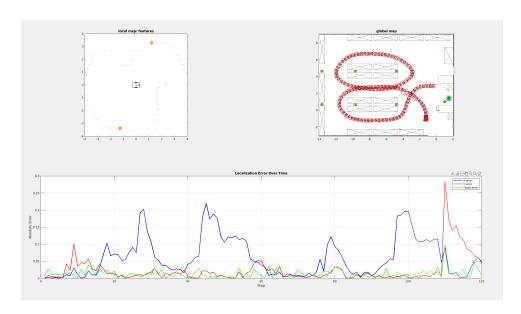


Figure 2: NEFFTHESHOLD = 0.1 , NParticles = 500, Systematic resampling

A 0.5

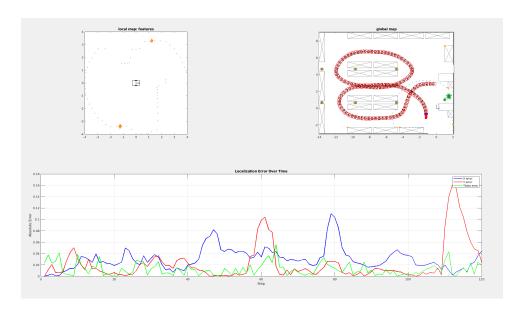


Figure 3: NEFFTHESHOLD = 0.5 , NParticles = 500, Systematic resampling

A 1

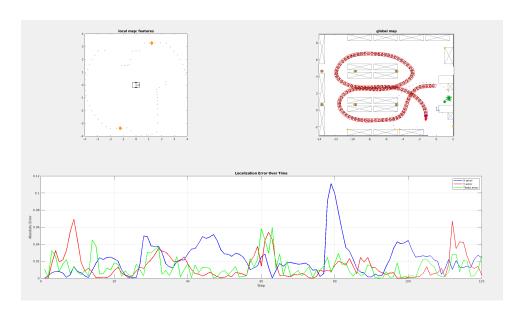


Figure 4: NEFFTHESHOLD = 1 , NParticles = 500, Systematic resampling

b

B, 50

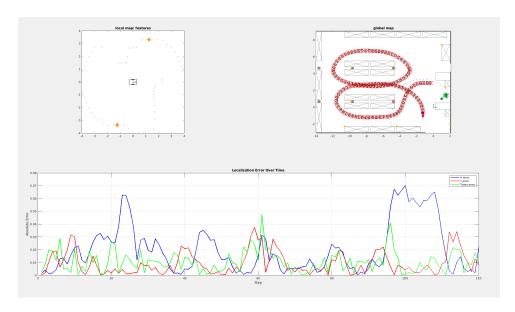


Figure 5: NEFFTHESHOLD = 0.66, NParticles = 50, Systematic resampling

1 B 500

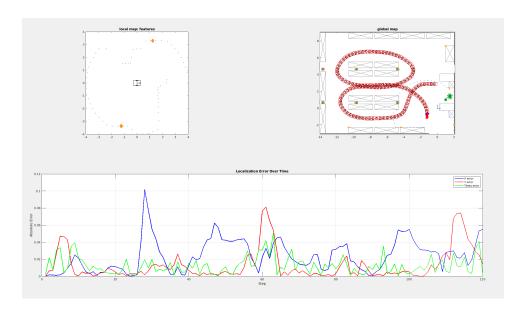


Figure 6: NEFFTHESHOLD = 0.66 , NPar ticles = 500, Systematic resampling

B 2000

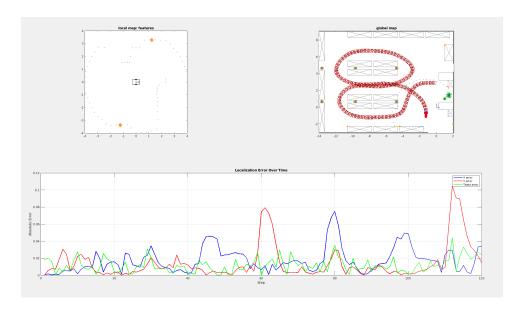


Figure 7: NEFFTHESHOLD = 0.66 , NParticles = 2000, Systematic resampling