

## Lecture 16: Graphs

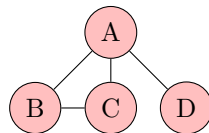
*Lecturer: Dr. Andrew Hines**Scribes: Philip McGrath, Daniel Raftery*

**Note:** *LaTeX template courtesy of UC Berkeley EECS dept.*

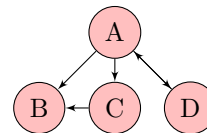
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## 16.1 Outline

A graph is a non-linear abstract data type (ADT) which consists of a finite set of vertices (nodes) joined via edges, similar to a tree. However, unlike in a tree, cycles and non-connected components are permitted in a graph. Graphs do not have a definite beginning or end, and can be either directed or undirected.



undirected graph



directed graph

An example of a graph structure is a list of websites produced by a search engine. After the search is executed, a tree starting from a root parents website leading to children sites is produced. These children sites may possibly link back to their parent size, thus producing a graph structure.

## 16.2 Terminology

- Each element within a graph is called a **node**.
- Each node is connected to another node bide an **edge**.
- A **neighbour** to a node is another node such that there exists an edge between them.
- A **cycle** may consist of different components and occurs when
  1. A node is connected to itself.
  2. A node is connected to itself via edges between other nodes.

## 16.3 Graph ADT

A graph  $G$  with vertices  $x, y$  has ADT operations defined by

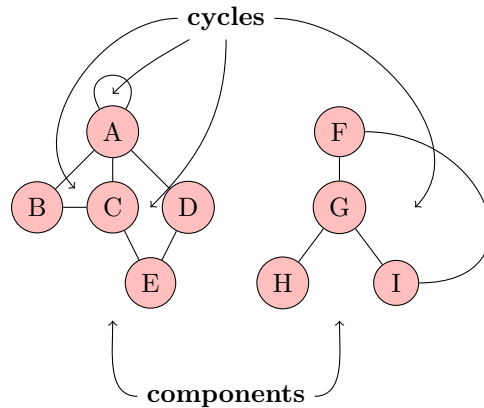
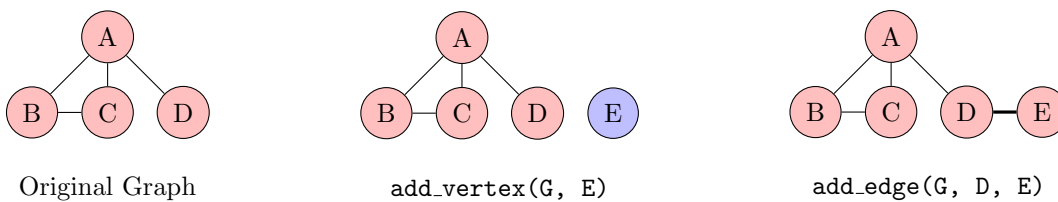
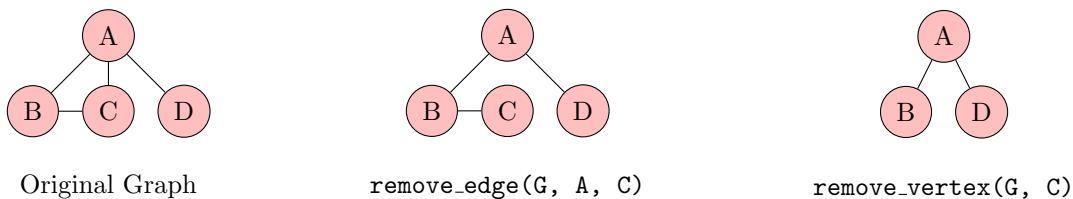


Figure 16.1: Illustration of a graph with cycles and components labelled

- `adjacent(G, x, y)`  
Tests if there exists an edge from vertex `x` to vertex `y`.
- `neighbours(G, x)`  
Lists all vertices `y` such that there exists an edge from vertex `x` to vertex `y`.
- `add_vertex(G, x)`  
Adds the vertex `x` to `G` if it does not already exist.
- `remove_vertex(G, x)`  
Removes the vertex `x` from `G` if it exists.
- `add_edge(G, x, y)`  
Adds an edge from vertex `x` to vertex `y` if one does not already exist.
- `remove_edge(G, x, y)`  
Removes the edge from vertex `x` to vertex `y` if it exists.

Figure 16.2: Demonstration of `add_vertex()` and `add_edge()`Figure 16.3: Demonstration of `remove_edge()` and `remove_vertex()`

## 16.4 Graph Representation

A graph  $G$  can be computationally represented as a function of the vertices  $V$  and edges  $E$ , as  $G(V, E)$ . There are two distinct methods to represent the graph depending on the data, using an *adjacency-list* or an *adjacency-matrix*.

### 16.4.1 Adjacency-list

An adjacency-list is more suitable for data that produces a sparse graph, where  $|E| \ll |V|^2$ . As an example, consider the following graph.

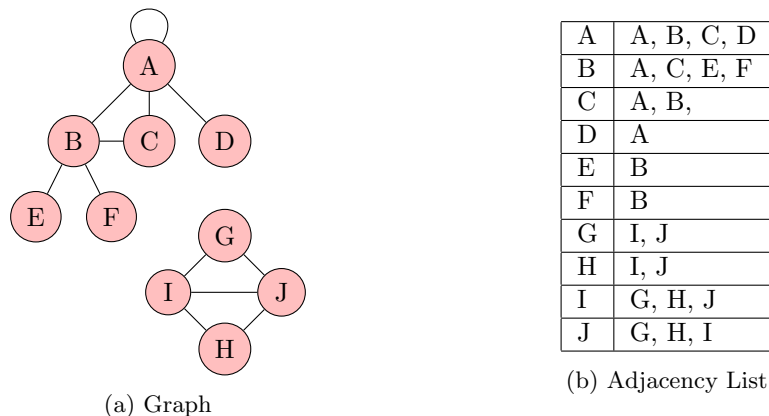


Figure 16.4: Example of a graph and the corresponding adjacency-list

An adjacency-list can be described as an array of lists. In this array, an entry `array[i]` is a list of all vertices adjacent to the vertex `i`. The beneficial aspect of using a list is that addition of vertices is easy and adjacency-lists tend to consume less space [GG].

### 16.4.2 Adjacency-matrix

In cases where the data would instead produce a dense graph, an adjacency-matrix is a better alternative to an adjacency-list. This is when  $|E| \approx |V|^2$ , when the number of edges is approximately equal to the number of vertices squared. An adjacency-matrix is a 2-dimensional array, and if the graph is undirected is it square symmetric, having equal number of rows as columns. In this representation, an edge exists between vertices `i` and `j` if in the adjacency-matrix (denoted `adm`), `adm[i][j] = 1` [GG]. The benefit of using an adjacency-matrix is that removing edges and performing queries to determine the existence of an edge between two vertices is much easier to implement than with an adjacency-list. However, an adjacency-list is faster when adding vertices and also consumes less space than an adjacency-matrix. [GG]

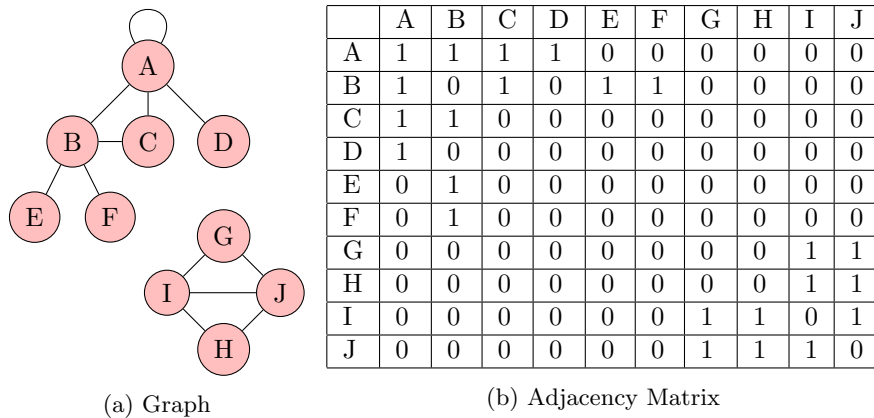


Figure 16.5: Example of a graph and the corresponding adjacency-matrix

## 16.5 Traversing a Graph/Searching

### 16.5.1 Depth First Search

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#### Algorithm 1: DFS (non-recursive)

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```

1 DFS ( $g, n$ );
   Input : A Graph  $g$  and node  $n$ 
   Output: The procedure explores every node station from  $n$ 
2 to_visit  $\leftarrow$  empty stack
3 add  $n$  to to_visit
4 while to_visit is not empty do
5     current  $\leftarrow$  pop to_visit
6     push all neighbours of current (not in visited) to to_visit
7     do something
8 endfor

```

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**Algorithm 2:** DFS (recursive)

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```

1 DFS ( $g, n$ );
   Input : a Graph  $g$  and node  $n$ 
   Output: the function explores every node from  $n$ 
2 flag  $n$  as visited
3 for each neighbour  $n_c$  of  $n$  which is not visited do
4     dfs( $n_c$ )
5 endfor

```

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### 16.5.2 Breadth First Search

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**Algorithm 3:** BFS (recursive)

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```

1 BFS( $g, q$ );
   Input : a Graph  $g$  and a queue  $q$  (originally having a starting node)
   Output: the functions explores every node from  $n$ 
2 if queue is empty then # base case
3     do something
4 else
5     current  $\leftarrow$  dequeue  $q$ 
6     flag current as visited
7     for each neighbour  $n_c$  of current not visited do
8         enqueue  $n_c$ 
9     endfor
10    do something
11    bfs( $q$ )
12 endif

```

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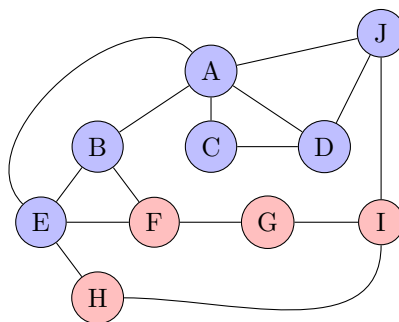
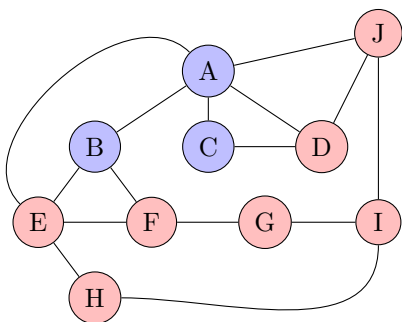
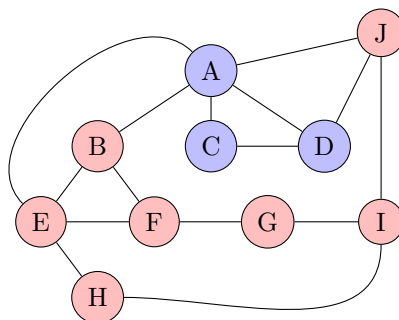
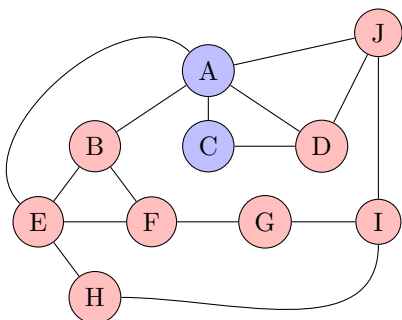
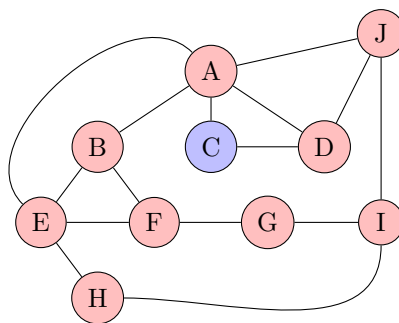
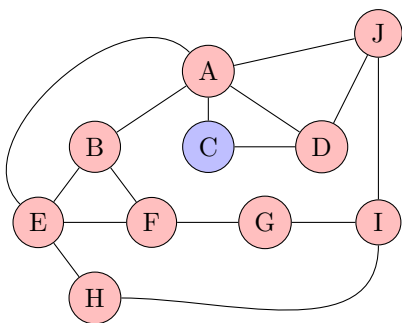
1 BFS( $g, n$ );
   Input : a Graph  $g$  and a node  $n$ 
   Output: this procedure explores every node of  $g$  from  $n$ 
2 to_visit is a queue
3 enqueue  $n$ 
4 visited is a sequence

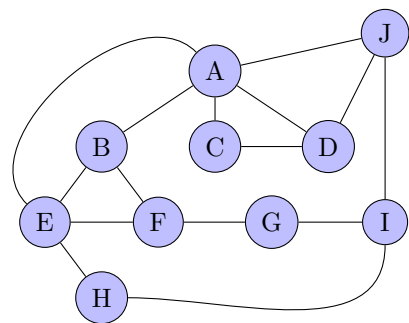
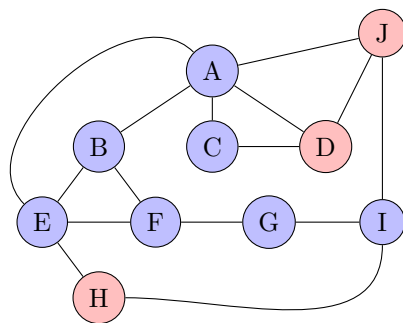
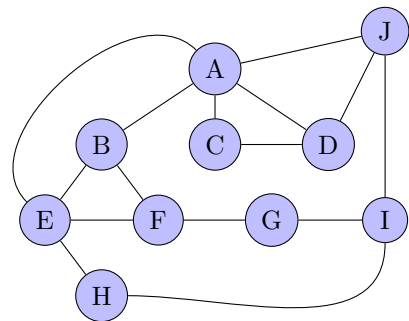
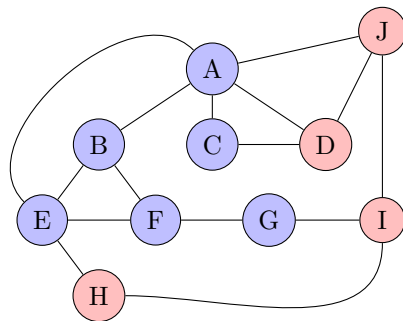
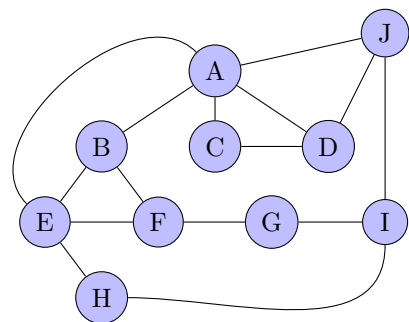
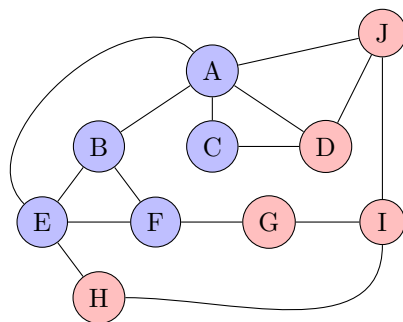
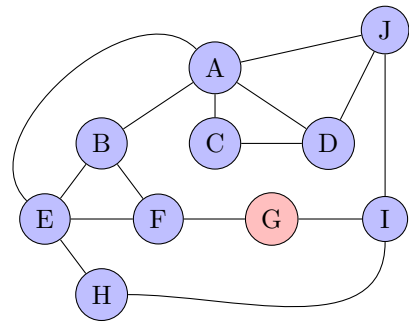
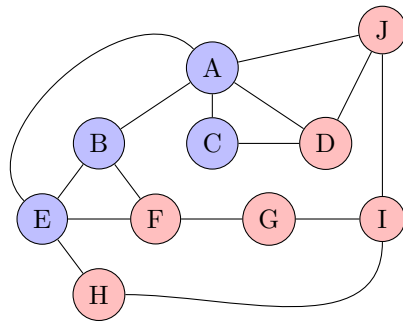
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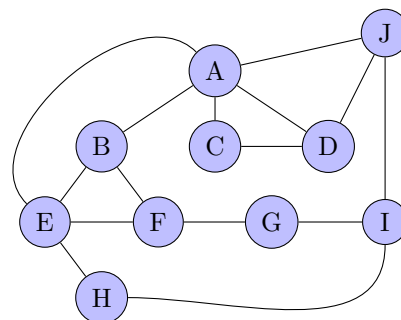
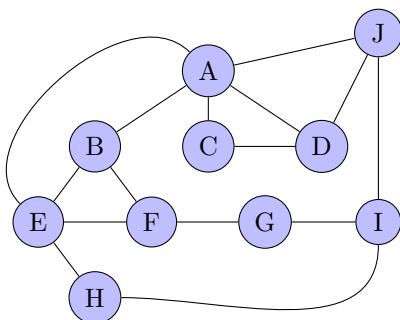
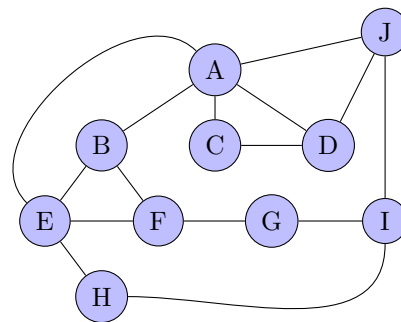
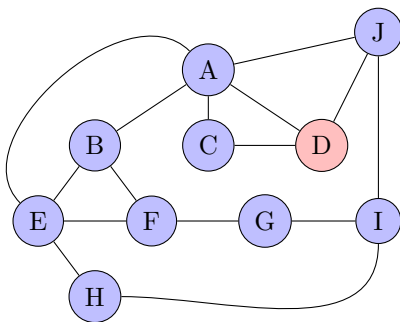
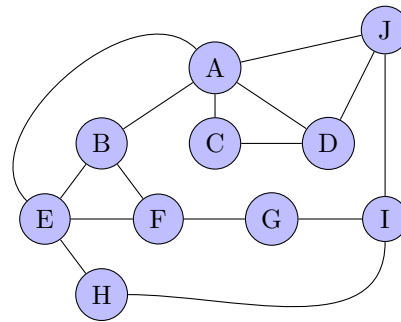
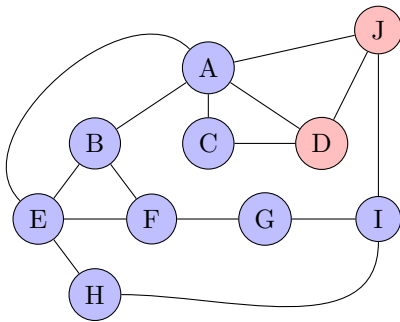
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### 16.5.3 Illustrated Comparison

For the purposes of this illustration DFS will be contained within the column on the left-hand side, whereas BFS will be contained within the column on the right-hand side (all the way down).







## References

- [1] Graph and its representations. Accessed 15/04/19.  
<https://www.geeksforgeeks.org/graph-and-its-representations/>