COMP20230: Data Structures & Algorithms Lecture 17: Graphs (2)

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Outline

Today

- Graph Traversal: DFS and BFS Complexity
- Weighted Graphs
- Shortest Path Dijkstra's Algorithm

Take home message

Graphs can be weighted along edges to better represent and model some scenarios.

Dijkstra's algorithm is a shortest path algorithm.

Recap: Graphs

A collection of vertices (nodes), joined together by edges. No definite beginning or end.

Representations of graphs

Two common methods: adjacency lists and adjacency matrices

Searching

Many algorithms begin by searching (e.g. DFS, BFS) their input graph to obtain this structural information.

BFS Complexity

Worst case is you need to traverse and explore **every** vertex and **every** edge.

Time Complexity for |V| vertices and |E| edges

 $\mathcal{O}(|V| + |E|)$

where, depending on sparsity, $\mathcal{O}(|E|)$ is between $\mathcal{O}(1)$ and $\mathcal{O}(|V|^2)$

Breadth-first search is **complete**, but depth-first search is not, i.e. the input to breadth-first search is assumed to be a finite graph, represented explicitly (e.g. by an adjacency list).

Weighted Graphs

Sometimes graphs have a weights on edges.

Examples

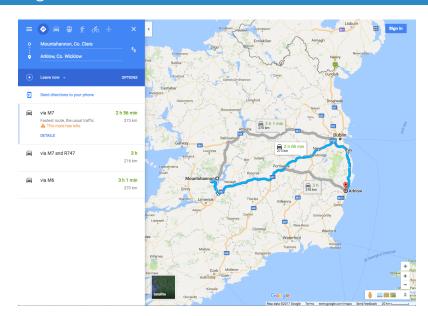
A road network with the distance between two cities

A computer network – hops between routers for a streaming video packet with time between nodes (e.g. think ping and traceroute).



(2018-19)

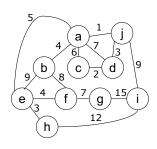
Routing



Distance Matrix (Jacob Stockdale, 1805)

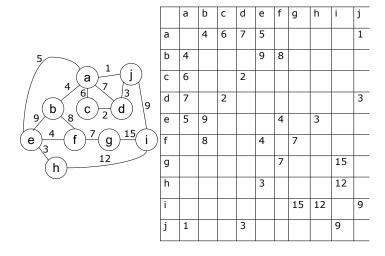


Weighted Graph Adjacency List



а	b(4), c(6), d(7), e(5), j(1)
b	a(4), e(9), f(8)
С	a(6), d(2)
d	a(7), c(2), j(3)
е	a(5), b(9), f(4), h(3)
f	b(8), e(4), g(7)
g	f(7), i(15)
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Weighted Graph Adjacency Matrix



Unweighted Graph Shortest Path

Shortest Path - Simple Case

How would we calculate the shortest path if there were no weights?

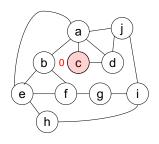
Unweighted Graph Shortest Path

Shortest Path – Simple Case

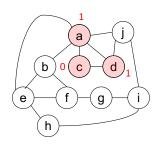
How would we calculate the shortest path if there were no weights?

Ignore weights on edges

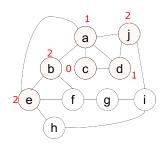
Breadth First Search will give us shortest path



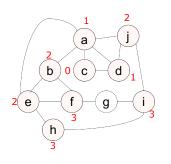
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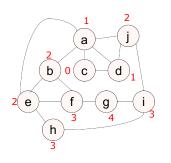
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Searching a weighted graph

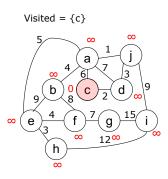
Dijkstra's algorithm

Find the shortest paths between nodes in a graph.

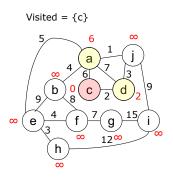
Dijkstra Variations

Original is to finds the shortest path between two given nodes Variant fixes a vertex as the origin and finds shortest paths to all other nodes in the graph (a shortest-path tree)

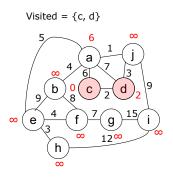
- Pick start and end vertices (from c to g)
- ullet Mark start vertex as 0 distance and all other vertices at ∞
- Repeat until we reach end vertex:
 - Calculates total distance to each unvisited neighbour for the current vertex
 - Update neighbour's distance if smaller
 - Pick the vertex with the lowest marked distance and set as current
 - Mark current as visited



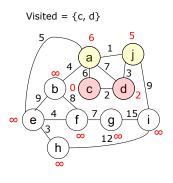
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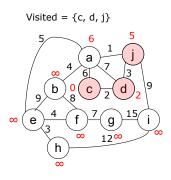
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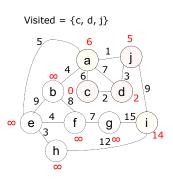
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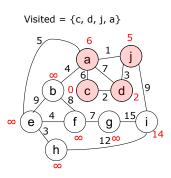
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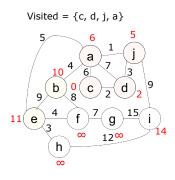
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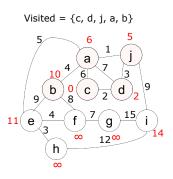
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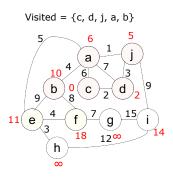
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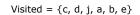
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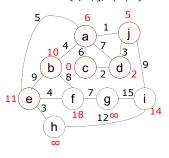


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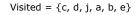


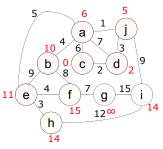
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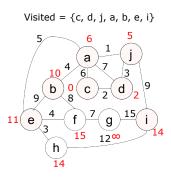


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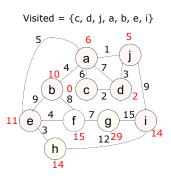




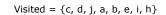
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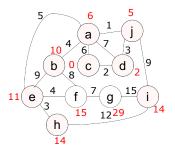


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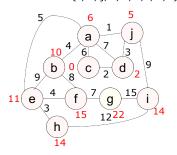
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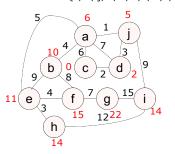
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Visited = $\{c, d, j, a, b, e, i, h, f\}$



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```
function dijkstra:
Input: a graph G, a node n
Output: each node of G gets the shortest distance from n
for each node c of G not n do
    distance[c] \leftarrow infinitv
endfor
distance[n] \leftarrow 0
current ← n
visited \leftarrow \{n\}
while visited does not contain all nodes of G do
    for each node c neighbour of current and not visited do
        # is new route to neighbour better? min(|n|+|n-c|) and |c|
        distance[c] \( \times \text{min(distance[n] + weight(current, c),} \)
distance[c])
    endfor
    # set next node to search from - lowest of all non-visited
    current \leftarrow non visited node with smallest value
    add current to visited
endwhile
```

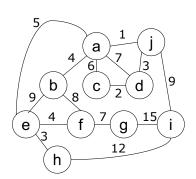
Dijkstra Steps

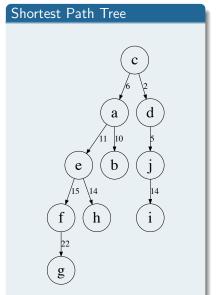
Shortest Path Tree

- Visited nodes are in the rows
- Distance from node c in columns for visited nodes
- Best distance from c to a column's node is highlighted in bold

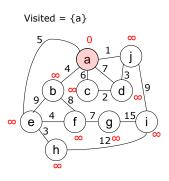
	а	ь	С	d	е	f	g	h	i	j
O	6(c-a)	∞		2(c-d)	∞	∞	∞	∞	∞	∞
d	6(c-a)	∞			∞	∞	∞	∞	∞	5(c-d-j)
j	6(c-a)	∞			∞	∞	∞	∞	14(c-d-j-i)	
a		10(c-a-b)			11(c-a-e)	∞	∞	∞	14(c-d-j-i)	
Ь					11(c-a-e)	18(c-a-b-f)	∞	∞	14(c-d-j-i)	
e						15(c-a-e-f)	∞	14(c-a-e-h)	14(c-d-j-i)	
i						15(c-a-e-f)	29(c-d-j-i)	14(c-a-e-h)	, -,	
h						15(c-a-e-f)	29(c-d-j-i)	` '		
f						` ′	22(c-a-e-f-g)			

Dijkstra: Shortest Path Tree





Exercise: From A to G?



b(4), c(6), d(7), e(5), j(1)
a(4), e(9), f(8)
a(6), d(2)
a(7), c(2), j(3)
a(5), b(9), f(4), h(3)
b(8), e(4), g(7)
f(7), i(15)
e(3), i(12)
g(15), h(12), j(9)
a(1), d(3), i(9)

Summary

Complexity

Basic Dijkstra is $\mathcal{O}(|V|^2)$ Can be optimised to $\mathcal{O}(|E| + |V| \log |V|)$

Graphs can have weighted edges to better represent and model some scenarios.

Dijkstra's algorithm is a shortest path algorithm to traverse weighted edges.