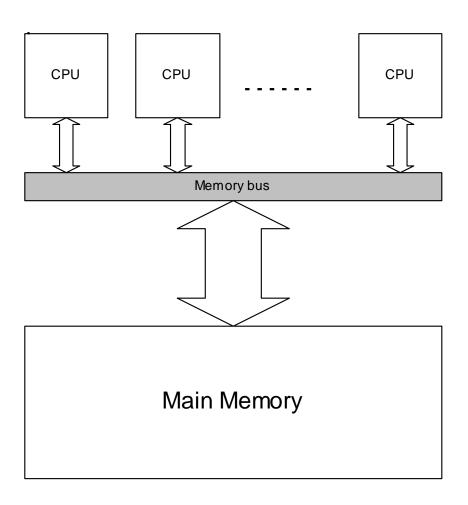
Shared Memory Multiprocessors

Shared Memory Multiprocessor



High-Performance Computing

Programming Model

- Primary programming model
 - Parallel threads of control
 - each running on a separate processor of the SMP computer
 - sharing memory with other threads in the framework of the same process
- A *multi-threaded* (MT) program
 - All threads share the same process-level structures and data (file descriptors, user ID, etc.)
 - => Threads have access to all the same functions, data, open files, etc.

Programming Model (ctd)

- MT program
 - Starts up with one initial main thread
 - Each thread may create new threads
 - by calling the create routine, passing a routine for that new thread to run
 - the new thread now runs the routine and provides another stream of instructions operating on data in the same address space
 - Threads coordinate the usage of shared data via synchronization variables such as a *mut*ual *exclusion* lock (a *mutex*)
 - Another way for threads to synchronize their work is to direct signals internally to individual threads

Programming Model (ctd)

- Secondary programming model
 - Parallel processes
 - each running on a separate processor
 - not sharing main memory with other processes
 - using message passing to communicate with the others in order to coordinate their work
 - Is a primary one for the distributed-memory multiprocessor architecture

Shared Memory Multiprocessor (ctd)

- SMP architecture
 - Provides more parallelism than VPs and SPs
 - Adds parallel streams of instructions to the instructionlevel parallelism
- How significant is the performance potential of the SMP architecture?
 - One might expect a *n*-processor SMP computer to provide *n*-fold speedup compared to its 1-processor configuration
 - The real picture is different

Shared Memory Multiprocessor (ctd)

- What do you see in reality
 - Let you start from a 1-processor configuration and add processors one by one
 - Each next processor is adding only a fraction of the performance that you got from the first
 - The fraction is becoming smaller and smaller
 - Eventually, adding one more processor will just decrease performance
- This cannot be explained by the Amdahl law
 - "Normal" programs see other limitations far before they ever hit this one

Shared Memory Multiprocessor (ctd)

- The real bottleneck is the memory bus
- Heavy matrix multiplication programs come up against the limited memory bandwidth very quickly
 - Let 30 possible processors average one main memory reference every 90 bus cycles (which is quite possible for such programs)
 - Then there will be a reference every third cycle
 - If a request/reply occupies the bus for ~6 cycles, then that will be already twice what the bus can handle

Optimising Compilers

Optimising Compilers

- The main specific optimisation is *loop parallelization*
 - Different iterations are simultaneously executed by different parallel threads
- The most difficult problem is the recognition of parallelizable loops
 - Based on the analysis of data dependencies in loops
 - Optimising C and Fortran 77 compilers for SMPs use the same methods and algorithms as optimising C and Fortran 77 compilers for VP and SPs
- Advantages and disadvantages of the use of optimising C and Fortran 77 compilers for parallel programming are generic

Optimising Compilers (ctd)

- Can optimising C and Fortran 77 compiler be used to port legacy serial code to SMP computers?
- A good efficient serial algorithm
 - Tries to minimize redundant computations
 - Tries to maximize re-use of information, computed at each loop iteration, by all following iterations to minimize redundant computations
 - This leads to strong inter-iteration data dependences
 - Optimising compilers cannot parallelize the most principal and time-consuming loops
- Serial legacy code must be re-designed for SMPs

Thread Libraries

Thread Libraries

- Thread libraries directly implement the thread parallel programming model
 - The basic paradigm of multithreading is the same in different thread libraries (POSIX, NT, Solaris, OS/2, etc.)
 - The libraries just differ in details of implementation
- We outline the POSIX thread library, aka Pthreads
 - In 1995 Pthreads became a part of the IEEE POSIX standard => considered standard for Unix systems
 - Most hardware vendors offer Pthreads in addition to their proprietary thread libraries.

Pthreads

- Pthreads are defined as a C language library
 - A standard Fortran interface is not yet complete
- Pthreads introduce 3 classes of objects (and operations on the objects)
 - Threads
 - Mutexes
 - Condition variables

- Thread
 - Represented by its ID
 - ID is a reference to an opaque data object holding full information about the thread
 - This information is used and modified by operations on threads
- Operations on threads
 - Create threads, terminate threads, join threads, etc.
 - Set and query thread attributes

- Mutex
 - The primary means of thread synchronization
 - normally used when several threads update the same global data
 - Acts as a lock protecting access to the shared data resource
 - Only one thread can lock a mutex at any given time
 - If several threads simultaneously try to lock a mutex, only one will succeed and start owning that mutex
 - Other threads cannot lock that mutex until the owning thread unlocks it
 - Mutexes serialize access to the shared resource

- Operations on mutexes
 - Creating
 - Destroying
 - Locking
 - Unlocking
 - Setting and modifying attributes associated with mutexes

- Condition variable
 - Another way for threads to synchronize their work
 - Is a global variable shared by several threads
 - Used by threads to signal each other that some condition is satisfied
- A thread, willing to wait for some condition to be satisfied
 - Blocks itself on a condition variable, and
 - Does nothing until some other thread unblocks it
 - by performing a corresponding operation on the same condition variable as soon as the condition is satisfied

- Condition variables
 - Allow the programmer to use the "cold" waiting
 - Otherwise, the thread would be constantly polling to check the condition out making the processor busy
- Operations on condition variables
 - Creating condition variables
 - Waiting and signalling on condition variables
 - Destroying condition variables
 - Set and query condition variable attributes

Operations on Threads

- An MT program starts up with one initial thread running the function main
 - All other threads must be explicitly created

Creation of a new thread

- The newly created thread
 - Runs concurrently with the calling thread
 - Executes the function start routine
 - Only one argument may be passed to this function via arg
 - If multiple arguments must be passed, a structure may be created, which contains all of the arguments
 - attr specifies attributes to be applied to the new thread
 - can be NULL (default attributes are used)
 - ID of the thread is returned in thread
 - May create other threads (once created, threads are peers)
- On error, a non-zero error code is returned

• Learning its own ID

```
pthread_t pthread_self(void)
```

• Comparing thread IDs

```
int pthread_equal(pthread_t t1, pthread_t t2)
```

- A thread can *terminate*
 - Explicitly
 - By calling function void pthread_exit(void *status)
 - Implicitly
 - by returning from the start_routine function
 - equivalent to calling pthread_exit with the result returned by start_routine as exit code

- The exit status specified by status
 - Is made available to any join with the terminating thread
 - If the thread is not detached

Joining

 A synchronization operation on threads implemented by function

```
int pthread join(pthread t t, void **status)
```

- Blocks the calling thread until the thread t terminates
- Returns successfully when thread t terminates
- The value passed to pthread_exit by thread t will be placed in the location referenced by status

- There are two types of threads -joinable and detached
 - It is impossible to join a detached thread
 - A detached or joinable state of the thread is set by using the attrargument in the pthread create function
 - attr points to a variable of the pthread_attr_t type (an attribute variable)
- The attribute variable is an opaque data object holding all attributes of the thread

• The attribute variable is first initialised with function

```
int pthread_attr_init(pthread_attr_t *attr)
```

that sets the default value for all attributes

• Then the *detached status* attribute is set with function

```
int pthread_attr_setdetachstate(
          pthread attr t *attr, int detstat)
```

• detstat can be either PTHREAD_CREATE_DETACHED or PTHREAD CREATE JOINABLE (default value)

Function

```
int pthread_attr_getdetachstate(
   const pthread_attr_t *attr, int *pdetstat)
retrieves the detached status attribute
```

- Function int pthread_detach(pthread_t *t)
 explicitly detaches thread t
- Using detached threads reduces the overhead
- A single attribute object can be used in multiple simultaneous calls to function pthread create

- Other attributes specify
 - the address and size for a thread's stack (allocated by system by default)
 - priority of the thread (0 by default)
 - etc
- Function

```
int pthread_attr_destroy(pthread_attr_t *attr)
```

releases resources used by the attribute object attr

Operations on Mutexes

- A typical sequence of operations on a mutex includes
 - Creation of a mutex
 - Initialisation of the mutex
 - Locking the mutex by one of several competing threads
 - The winner starts owning the mutex
 - The losers act depending on the type of lock operation used
 - The blocking lock operation blocks the calling thread
 - The non-blocking lock operation terminates even if the mutex has been already locked by another thread. On completion, the operation informs the calling thread whether or not it has managed to lock the mutex

- A typical sequence of operations on a mutex (ctd)
 - Unlocking the mutex by its current owner
 - The mutex becomes available for locking by other competing threads
 - The mutex is destroyed
- Creation of a mutex <=> declaration of a variable of the pthread_mutex_t type
 - The variable is an opaque data object that contains all information about the mutex

- *Initialisation* of the mutex
 - Dynamic
 - Static
- Dynamic initialisation
 - With function

- mutexattr is typically NULL (accept default attributes)
- Upon successful initialisation, the state of the mutex becomes *initialised* and *unlocked*

- Static initialisation
 - With the macro PTHREAD_MUTEX_INITIALIZER when the mutex variable is declared
 - Example.

```
pthread mutex t mut = PTHREAD MUTEX INITIALIZER;
```

- Equivalent to dynamic initialization with mutexattr specified as NULL
- Function

```
int pthread_mutex_destroy(pthread_mutex_t *mutex)
```

destroys the mutex object

Function

```
int pthread_mutex_lock(pthread_mutex_t *mutex)
```

locks the mutex object referenced by mutex

- The calling thread blocks if the mutex is already locked
- Returns with the mutex in the locked state with the calling thread as its owner

Function

```
int pthread_mutex_trylock(pthread_mutex_t *mutex)
```

- Implements non-blocking lock
 - Returns immediately anyway
- Returns 0 if it succeeds to lock the mutex
- Returns a non-zero if the mutex is currently locked
- Function

```
int pthread_mutex_unlock(pthread_mutex_t *mutex)
```

releases the mutex object

High-Performance Computing

Example

- Example. The dot product of two real *m*-length vectors *x* and *y* on a *n*-processor SMP computer.
- The MT application divides x and y into n sub-vectors
 - the first *n*-1 sub-vectors are of the same length *m/n*
 - the last *n*-th subvector may be shorter if *m* is not a multiply of *n*
- This application uses *n* parallel threads
 - *i*-th thread computes its fraction of the total dot product by multiplying sub-vectors x_i and y_i

Example (ctd)

- The *n* parallel threads
 - Share a data object accumulating the dot product
 - Synchronize their access to the data object with a mutex
- The main thread
 - Creates the *n* threads
 - Waits for them to complete their computations
 - via joining with each of the threads
 - Outputs the result
- <For the source code see handout>

Parallel Languages

High-Performance Computing

Parallel Languages

- Thread libraries support efficiently portable parallel programming the SMP architecture
- But some people find their power redundant for the goals of parallel programming
 - The multi-threaded programming model underlying the libraries is universal
 - It supports both parallel and diverse distributed computing technologies

Parallel Languages (ctd)

- Most of these design approaches are mainly used in distributed programming
 - In particular, when implementing servers in server/client applications
- The *producer/consumer* design
 - Some threads create work and put it on a queue
 - Other threads take work items off the queue and execute them

Parallel Languages (ctd)

- The *pipeline* design
 - Each thread performs some part of an entire work and passes the partially completed work to the next thread
- The *personal servant* design
 - A thread is dedicated to each client, serving only that client
- The *master/slave* design
 - One thread does the main work of the program, occasionally creating other threads to help in some portion of the work

Parallel Languages (ctd)

- In mutli-threaded *parallel* programming, the master/slave design is predominantly used
 - If you want to use the MT libraries only for parallel programming, their programming model is seen too powerful and complicated (and, hence, *error-prone*)
- Parallel extensions of Fortran 77 and C
 - Provide a simplified multi-threaded programming model based on the master/slave strategy
 - Aimed specifically at parallel computing on SMPs
- We outline Fortran 95 and OpenMP

Fortran 95

- Fortran 95 is the Fortran standard released by ISO in December 1997
 - A minor enhancement of Fortran 90
 - Consists of a small number of new features
- The FORALL statement and construct
 - The major new feature added to support parallel programming SMP computers

The FORALL statement

- The FORALL statement
 - An alternative to the DO-loop
 - Its content can be executed in any order
 - It therefore can be implemented with parallel threads

• Example 1. The FORALL statement defining a Hilbert matrix of order N

```
FORALL (I = 1:N, J = 1:N) H(I,J) = 1./REAL(I+J-1)
```

The FORALL statement

• Example 2. The FORALL statement inverts the elements of a matrix, avoiding division with zero

```
FORALL (I=1:N, J=1:N, Y(I, J).NE.O.) X(I, J) = 1/Y(I, J)
```

The general form of the FORALL statement is

FORALL
$$(v_1 = l_1 : u_1 : s_1, ..., v_n = l_n : u_n : s_n, mask)$$

 $a(e_1, ..., e_m) = expr$

- First the triplets are evaluated in any order
 - All possible pairings of indices form the set of combinations

The FORALL statement (ctd)

Example. The set of combinations of I and J for

```
FORALL (I=1:3, J=4:5) A(I,J) = A(J,I)
is { (1,4), (1,5), (2,4), (2,5), (3,4), (3,5) }
```

- Secondly, *mask* is evaluated, in any order, producing a set of *active combinations*
- Example. If mask (I+J.NE.6) is applied to the above set, the set of active combinations is:

```
\{(1,4),(2,5),(3,4),(3,5)\}
```

The FORALL statement (ctd)

• Then, expressions $e_1, ..., e_m$, and expr are evaluated in any order for all active combinations of indices

• Finally, the computed values of *expr* are assigned to the corresponding elements of *a* in any order for all active combinations of indices

The FORALL construct

- The FORALL construct is a multi-line extension of the single line FORALL statement
- Example.

```
REAL, DIMENSION(N, N) :: A, B
...

FORALL (I = 2:N-1, J = 2:N-1)
    A(I,J) = 0.25*(A(I,J-1)+A(I,J+1)+A(I-1,J)+A(I+1,J))
    B(I,J) = A(I,J)

END FORALL
```

High-Performance Computing

PURE and ELEMENTAL functions

- FORALL statements and constructs by design require that all referenced functions be free of side effects
 - A procedure can be specified as side effect free, or PURE
- A restricted form of a PURE procedure is called ELEMENTAL
 - A procedure that operates elementally
 - A single procedure to operate on scalars and on arrays of different ranks
 - In Fortran 90, you must provide a separate version for scalars and for each rank from one to seven

OpenMP

- OpenMP is an API for writing multi-threaded applications based on the master/slave design strategy
- Supports parallel programming in C, C++ and Fortran on all SMP architectures
 - Including Unix platforms and Windows NT platforms
- Intel, HP, SGI, IBM, SUN, Compaq, KAI, PGI, NAG, and many others took part
- First specifications appeared in late 1998

- OpenMP is a set of language extensions
 - Compiler directives
 - Library procedures
 - Environmental variables
- OpenMP is semantically the same between Fortran and C/C++
- We use the C/C++ API to present OpenMP

• An OpenMP compiler directive is a C/C++ preprocessing pragma directive of the form:

#pragma omp directive-name list-of-clauses

- C/C++ compilers that do not support OpenMP can compile an OpenMP program
- OpenMP also specifies stubs for the run-time library
 - Enables portability to platforms not supporting OpenMP
 - OpenMP programs must be linked with the stub library
 - The stub functions emulate serial semantics assuming that the directives in the OpenMP program are ignored

- As a rule, an OpenMP directive applies to a structured block
 - A statement (single or compound) that has a single entry and a single exit
- The directive and the structured block, which the directive applies to, make up an OpenMP *construct*
 - Some directives are not part of a construct

- A typical sequence of OpenMP's constructs and single directives do the following:
 - Define a structured block, which is to be executed by multiple threads in parallel, and create the parallel threads
 - that structured block is called a parallel region
 - Distribute the execution of the parallel region among the parallel threads

- A typical sequence of OpenMP's constructs and single directives do the following (ctd):
 - Synchronize the work of the parallel threads during the execution of the parallel region
 - Control the data environment during the execution of the parallel region
 - via specification of shared data, private data, accumulating variables, etc.

Parallel Regions

 A parallel construct starts parallel execution of a parallel region

```
#pragma omp parallel list-of-clauses structured-block
```

- When a thread encounters a parallel construct
 - A team of threads is created
 - This thread becomes the master thread of the team, with a thread number of 0
 - All threads, including the master thread, execute the region in parallel

Parallel Regions (ctd)

- By default, the number of threads that are requested is implementation-defined
- To explicitly determine the number of threads
 - Use the num_threads clause in the parallel directive
 - Call the omp_set_num_threads function before activization of the parallel region

Parallel Regions (ctd)

Example. Parallel initialisation of an array:

```
int a[5][5];
omp_set_num_threads(5);
#pragma omp parallel
{
   int thrd_num = omp_get_thread_num();
   zero_init(a[thrd_num], 5);
}
```

- omp_get_thread_num returns the thread number (within its team)
- The thread number lies between 0 and 4 (the master is thread 0)
- Array a is shared between all the threads
- Variable thrd_num is private to each thread

Parallel Regions (ctd)

- There is a barrier at the end of a parallel region
 - Each thread waits until all threads in the team arrive at this point
- Only the master thread of the team continues execution at the end of the parallel region
- A thread encountering another **parallel** construct
 - Creates a new team, and it becomes its master
 - By default, nested parallel regions are serialized
 - a nested parallel region is executed by a team of one thread

Work-Sharing Constructs

- A work-sharing construct
 - Does distribute the execution of the associated statement among the members of the team that encounter it
 - Does not launch new threads
 - There is no implicit barrier on entry to a work-sharing construct.
- Every thread in a team must encounter the same sequence of work-sharing constructs and **barrier** directives

• A **for** construct:

```
#pragma omp for list-of-clauses for-loop
```

- The iterations of the loop will be executed in parallel
- The **for** loop must be of the *canonical* form that allows the number of loop iterations to be computed upon entry to the loop

```
for(var = lb; var logical-op rb; incr-expr)
```

• The **schedule** clause of the for construct

```
schedule(kind [, chunk-size])
```

- Specifies how iterations are divided among threads
- kind may be static, dynamic, guided, or runtime
- If *kind* is **static**, iterations are divided into chunks of a size specified by *chunk-size*
 - The chunks are statically assigned to threads in a round-robin fashion in the order of the thread number
 - When *chunk-size* is omitted, the iteration space is divided into approximately equal chunks (one chunk assigned to each thread)

Example. Parallel initialisation of an array:

```
int a[10][10], k;
omp_set_num_threads(5);
#pragma omp parallel
#pragma omp for schedule(static)
for(k=0; k<10; k++)
  zero_init(a[k], 10);</pre>
```

- Each of 5 threads will execute two successive iterations of the loop
- Variable k will be private to each of the threads

- The **schedule** clause of the **for** construct (ctd)
 - If *kind* is **dynamic**, the iterations are divided into a series of chunks, each containing *chunk-size* iterations
 - Each chunk is assigned to a thread that is waiting for an assignment
 - The thread executes the chunk of iterations and then waits for its next assignment, until no chunks remain to be assigned
 - When no *chunk-size* is specified, it defaults to 1

Example. Parallel initialisation of an array:

```
int a[10][10], k;
omp_set_num_threads(5);
#pragma omp parallel
#pragma omp for schedule(dynamic,2)
for(k=0; k<10; k++)
zero_init(a[k], 10);</pre>
```

- Each two successive iterations of the loop will be executed by one of the 5 threads
- Which thread will execute which pair of iterations is decided at run time

- The **schedule** clause of the **for** construct (ctd)
 - If *kind* is **guided**, the iterations are assigned to threads in chunks with decreasing sizes
 - When a thread finishes its assigned chunk of iterations, it is dynamically assigned another chunk, until none remains
 - If *chunk-size* = 1, the size of each chunk is approximately the number of unassigned iterations divided by the number of threads. These sizes decrease approximately exponentially to 1
 - If *chunk-size* > 1, the sizes decrease approximately exponentially to *chunk-size* (the last chunk may be fewer than *chunk-size* iterations)
 - When no chunk-size is specified, it defaults to 1

- The schedule clause of the for construct (ctd)
 - If *kind* is **runtime**, the decision regarding scheduling is deferred until runtime
 - The schedule kind and size of the chunks can be chosen at run time by setting the environment variable OMP_SCHEDULE
 - If **OMP_SCHEDULE** is not set, the resulting schedule is implementation–defined
 - No chunk-size must be specified

- If no **schedule** clause is explicitly defined, the default **schedule** is implementation-defined
- There is an implicit barrier at the end of a **for** construct unless a **nowait** clause is specified

• A sections construct:

```
#pragma omp sections list-of-clauses
{
    [#pragma omp section]
    structured-block
    [#pragma omp section
    structured-block]
    ...
}
```

- Specifies a set of sections to be divided among threads
 - Each section is executed once by a thread in the team
 - Each section must be preceded by a **section** directive (except for the first one)
 - An implicit barrier at the end of the **sections** construct

The sections Construct

Example. Parallel initialisation of an array

```
int a[4][10];
omp_set num threads(2);
#pragma omp parallel
#pragma omp sections
    zero init(a[0], 10);
    zero init(a[1], 10);
  #pragma omp section
    zero init(a[2], 10);
    zero init(a[3], 10);
```

• A single construct:

```
#pragma omp single list-of-clauses structured-block
```

- Specifies that the associated structured block is executed by only one thread in the team
 - Not necessarily the master thread
- There is an implicit barrier after the **single** construct
 - Unless a nowait clause is specified

A task construct:

```
#pragma omp single
{
    #pragma omp task
    f1();
    #pragma omp task
    f2();
}
```

• A master construct:

```
#pragma omp master structured-block
```

- Specifies that the associated structured block is executed by the master thread in the team
 - Other threads of the team do not execute this statement
- There is no implicit barrier on entry to or exit from the **master** section

• OpenMP provides shortcuts for specifying a parallel region that contains only one work-sharing construct:

```
#pragma omp parallel for list-of-clauses
for-loop
and

#pragma omp parallel sections list-of-clauses
{
    [#pragma omp section]
    structured-block
    [#pragma omp section
    structured-block]
    ...
}
```

Synchronization Directives and Constructs

- Implicit barriers are implied on some OpenMP constructs
- OpenMP provides a number of directives and constructs for explicit synchronization of threads
 - The **barrier** directive
 - The **ordered** construct
 - The **critical** construct
 - The atomic construct
 - The **flush** directive

Synchronization Directives and Constructs (ctd)

• The **barrier** directive

#pragma omp barrier

- When encountered, each thread of the team waits until all of the others have reached this point
- An ordered construct

```
#pragma omp ordered list-of-clauses structured-block
```

 Specifies that the structured block is executed in the order in which iterations would be executed in a sequential loop

The critical Construct

• The critical construct

```
#pragma omp critical [(name)]
structured-block
```

- Synchronizes access to shared data
 - Restricts execution of the structured block to a single thread at a time
- A thread waits at the beginning of a critical region until no other thread is executing a critical region (anywhere in the program) with the same name *name*
- All unnamed critical regions have the same unspecified name

The critical Construct (ctd)

• Example.

```
int a[100], ind[100], b[100], k;
...
omp_set_num_threads(5);
#pragma omp parallel for
for(k=0; k<100; k++)

{
    #pragma omp critical
    a[ind[k]] += f(k);

    b[k] += g(k);
}</pre>
```

Different iterations may update the same element of a =>
 the serialization is needed to avoid race conditions

The atomic Construct

• The atomic construct

```
#pragma omp atomic
expression-statement
```

- May be seen as a special case of a critical section
- Does not prevent simultaneous execution by multiple threads of the associated statement
- Ensures that a specific memory location is updated atomically
 - prevents simultaneous access to the memory location by multiple threads

The atomic Construct (ctd)

- The atomic construct (ctd)
 - expression-statement is $x \circ p = expr, x++, ++x, x--, \text{ or } --x$
 - x is an lvalue of scalar type
 - expr is an expression of scalar type not referencing the object designated by x
 - op is one of the binary operators +, *, -, /, &, $^{\land}$, |, <<, or >>
 - Only the load and store of *x* are atomic
 - The evaluation of *expr* is not atomic
 - To avoid race conditions, all updates of the location in parallel should be protected with the atomic directive

The atomic Construct (ctd)

• Example.

```
int a[100], ind[100], b[100], k;
...
omp_set_num_threads(5);
#pragma omp parallel for
for(k=0; k<100; k++) {
    #pragma omp atomic
    a[ind[k]] += f(k);
    b[k] += g(k);
}</pre>
```

- Allows updates of two different elements of a to occur in parallel
 - the **critical** directive leads to serial updates
- More efficient than the critical directive if supported by hardware

The **flush** Directive

• The **flush** directive

```
#pragma omp flush [(variable-list)]
```

- Specifies a sequence point at which all threads in a team must have a consistent view of memory
 - all memory operations (both reads and writes) specified before the sequence point must complete
 - all memory operations specified after the point must have not yet begun
- An explicit mechanism to ensure consistency of shared data not depending on cache management in SMP computers

The **flush** Directive (ctd)

- The **flush** directive (ctd)
 - Without a *variable-list* synchronizes all shared objects
 - With a *variable-list* synchronizes only the objects in the *variable-list*
 - It is implied
 - for the **barrier** directive
 - at entry to and exit from critical and ordered constructs
 - at exit from parallel, for, sections, and single constructs
 - not implied if a nowait clause is present

Data Environment

- Two kinds of variable in an OpenMP program
 - Shared
 - Private
- A *shared* variable
 - Designates a single region of storage
 - All threads in a team that access this variable will access this single region of storage

- By default,
 - A variable defined outside a **parallel** construct and visible when the **parallel** construct is encountered, is shared within the **parallel** construct
 - Static variables declared within a parallel region are shared
 - Heap allocated memory is shared
- A *private* variable
 - Designates a region of storage that is unique to the thread making the reference

- Automatic variables declared within a parallel construct are private
- Other ways to specify that a variable is private
 - A threadprivate directive
 - A private, firstprivate, lastprivate, or reduction clause
 - Use of the variable as a **for** loop control variable immediately following a **for** or **parallel for** directive

The threadprivate directive

```
#pragma omp threadprivate [(variable-list)]
```

- Makes each variable in variable-list private to a thread
 - The variable must be global or static block-scope
 - Each copy of the variable is initialised once, before the first reference to that copy, and in the usual manner

- The **parallel** directive and most of work-sharing directives accept clauses explicitly specifying whether a variable is private or shared, how the variable is initialised, etc.
- A copyin clause

```
copyin(variable-list)
```

- A mechanism to assign the same value to **threadprivate** variables for each thread in the team executing the parallel region
- For each variable in *variable-list*, the value of the variable in the master thread of the team is copied, as if by assignment, to the thread-private copies at the beginning of the parallel region

A private clause

```
private(variable-list)
```

- Declares the variables in variable-list to be private to each thread in a team
- Creates private automatic variables (with a construct scope) overriding the original (possibly, global or local static) variable
- A firstprivate clause

```
firstprivate(variable-list)
```

- A special case the **private** clause
- Additionally initialises each new private object by the value of the original object that exists immediately before the parallel or work-sharing construct for the thread that encounters it

• A lastprivate clause

lastprivate(variable-list)

- A special case of the **private** clause
- Additionally determines the original object upon exit from the work-sharing construct
 - If a **lastprivate** variable is assigned a value by the sequentially last iteration of the associated loop, or the lexically last section, the value is assigned to the variable's original object
 - Other lastprivate variables have indeterminate values after the construct

A shared clause

shared(variable-list)

- Shares variables in *variable-list* among all the threads in a team
 - All threads within a team access the same region of storage for **shared** variables

A copyprivate clause

copyprivate(*variable-list*)

- May only appear on the single directive
- The thread that executed the associated structured block broadcasts the value of each copyrivate variable to other threads
 - Logically, it happens after the execution of the structured block and before any of the threads in the team have left the barrier at the end of this single construct

A reduction clause

```
reduction (op: variable-list)
```

- Specifies how to perform a reduction operation with operator *op* on a scalar variable in *variable-list*
 - It is supposed that the corresponding parallel or work-sharing construct must implement the reduction operation

- A reduction clause (ctd)
 - Inside this construct a private copy of each reduction variable is created, one for each thread (as if the **private** clause had been used), and initialised depending on the *op*
 - 0 for +, -, |, ^, and | |
 - 1 for * and & &
 - ~0 for &
 - Then each thread updates its private copy of the variable
 - Then, the original object is updated by combining its original value with the final value of each of the private copies using the operator op

• Example. Efficient computing the sum of elements of an array by parallel threads:

A default clause

default (none)

- May be used in the parallel directive
- Repeals all defaults for implicit specification of shared variables
 - requires explicit specification of their shared status

Run-Time Library Functions

- Two classes of the run-time library functions
 - To control and query the parallel execution environment
 - Implementing a mutex-like explicit synchronization mechanism
- The control-and-query functions
 - void omp_set_num_threads(int num_threads)
 - sets the default number of threads in a team
 - int omp_get_num_threads(void)
 - returns the number of threads currently in the team executing the parallel region from which it is called

Run-Time Library Functions (ctd)

- The control-and-query functions (ctd)
 - int omp get max threads (void)
 - returns the maximum value that can be returned by calls to omp_get_num_threads
 - int omp_get_thread_num(void)
 - returns the thread number, within its team, of the calling thread
 - int omp_get_num_procs(void)
 - returns the maximum number of processors that could be assigned to the program

Run-Time Library Functions (ctd)

- A part of the OpenMP run-time library provides a mutex-like synchronization mechanism
 - Declares two types of *lock* variables (an analog of mutex variables of Pthreads)
 - Declares functions for
 - Initialising a lock variable
 - Destroying the lock variable
 - Setting the lock variable (an analog of locking a mutex in Pthreads)
 - Unsetting the lock variable (an analog of unlocking a Pthreads mutex)
 - Testing the lock variable (an analog of the Pthreads's trylock)

OpenMP (ctd)

- Example. Consider an OpenMP application that computes the dot product of two real vectors *x* and *y* implementing the same parallel algorithm as the Pthreads application presented earlier.
 - <For the source code see handout>
 - One can see that this OpenMP code is significantly simpler and more compact than the Pthreads code

SMP Architecture: Summary

- SMPs provide higher level of parallelism than VPs and SPs via multiple parallel streams of instructions
 - Still not a scalable parallel architecture
 - The speedup is limited by the bandwidth of the memory bus
- Multithreading is the primary programming model
- C / Fortran 77 + optimizing compilers may be used to write efficient programs for SMPs
 - Only a quite limited and simple class of MT algorithms can be implemented this way

SMP Architecture: Summary (ctd)

- Thread libraries directly implement the MT paradigm
 - Explicit MT programming
 - Use of ordinary compilers
 - Pthreads are standard for Unix platforms
 - Too powerful, complicated and error-prone if used for parallel programming only
- OpenMP is a high-level parallel extension of Fortran and C/C++
 - Supports a simplified master/slave design strategy of MT programming
 - Aimed specifically at parallel programming SMPs