

Abduragim Shtanchaev



✉ name.surname@gmail.com



EDUCATION

- **Skoltech** Moscow, RU
M.Sc. in Information Systems and Technology, GPA: 3.92/4.00
May 2020
- **University of Turkish Aeronautical Association UTAA** Ankara, Turkey
B.Sc. in Mechatronics Engineering, GPA: 3.35/4.00
July 2018

WORK & RESEARCH EXPERIENCE

- **NeurodataLab LLC** Moscow, RU
Data Scientist
April 2020 - Present
 - **Ad Power:** Built predictive models for ad recall predictions based on the emotional state of respondents, media coverage of ads, and information about ads. Currently, working on converting the models for production.
 - **Data collection and preprocessing pipeline:** Created data preprocessing pipeline for ad recall prediction models from a scratch
 - **Paper:** Contributed to a [paper](#) on ad recall prediction
- **German Orbital Systems** Berlin, GE
Research Intern
Summer 2019
 - **ADCS:** Developed testbed for Attitude Determination and Control System for small cubesats satellites. The control system enables small satellites to control attitude and tilt using only magnetorquer. For [more details](#)
- **Skoltech** Moscow, RU
A list of valuable projects accomplished as a student
2018 - 2020
 - **Optimizing GANs using non-classical optimizers:** GANs are known as "difficult to train" for various stability reasons. We used non-classical optimizers in deep learning to remedy the problem. Implemented and tested on GANs using Pytorch following optimizers: Gradient Sliding, Ellipsoid, and Quick prop. [Code](#) and [presentation](#)
 - **Camera Trajectory Estimation:** Implemented a model for estimating the trajectory of a framing camera using RGB-D images and classical computer vision techniques. Wrote a [blog on medium](#) about the project. Source [code](#)
 - **Recybot:** A project in collaboration with the Department of Mechanical Engineering at MIT under Prof. Kamal Youcef-Toumi and Skoltech Robotics lab. Built screw detection model for automated e-waste disassembly - recybot. More about project [here](#)

OTHER PROJECTS

- **Automated Forest Inventory Using Satellite Images**
M.Sc. Thesis advised by Prof. Anton Ivanov
 - **Python:** Developed a semi-supervised approach for tree crown classification in boreal forest using World-View2 satellite imagery with a low spatial resolution - 0.5m/pix. Accepted abstract at IAF conference. The full [thesis](#) and [code](#)
- **Pipeline Inspection Robot - PIG**
B.Sc. Thesis advised by Prof. Habib Ghanbarpourasl
 - **C++:** Odometry calculation in wheel slippage cases. Developed and tested an algorithm for a robot odometry using camera assistance in the cases when wheel slippage is present.

ACHIEVEMENTS

2020	Competed SMILES , selected 10% applicants. Certificate	Moscow, RU
	Graduated with High Honors from Skoltech	
2018	Prestigious Full Scholarship at Skoltech for M.Sc, selected from 3k+ (<1 %)	
	Graduated with Honors from UTAA	Ankara, TU
2013	Full Scholarship for B.Sc. at UTAA	
	Graduated with High Honors from Liceum	Makhachkala, RU
2011	Ranked 4 th in Russian Regional History Olympiad	

SKILLS & INTEREST

>**5000 lines** **Python** ◦ Pytorch
>**1000 lines** Java ◦ **C++** ◦ bash ◦ git
familiar Tensorflow ◦ **Keras** ◦ mxnet ◦ HTML ◦ C ◦ Jekyll ◦ SQL ◦ Docker ◦ Flask