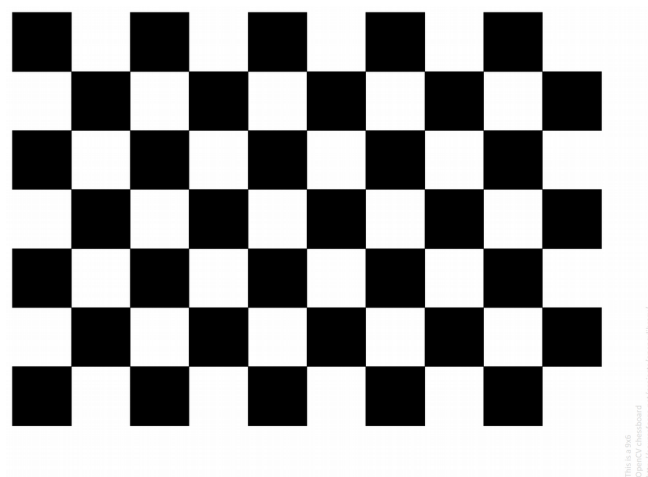


# Stereo Vision with OpenCV 3.2 in Python3

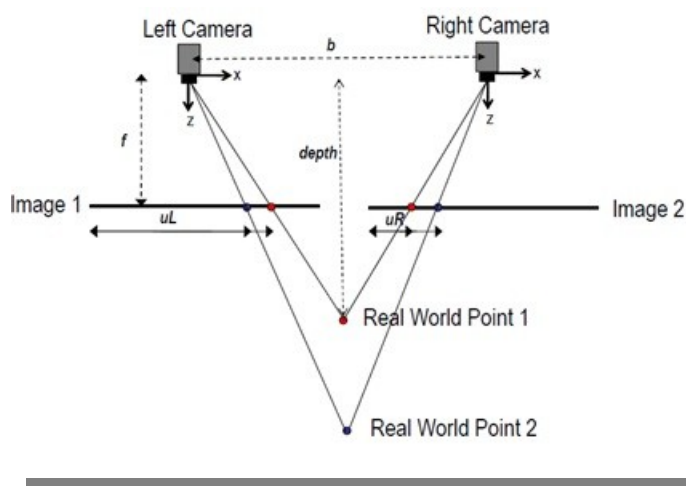
Calibration



Save matrix  
and files



Run - Stereo



R

L