

National University of Computer & Emerging Sciences

CS 3001 - COMPUTER NETWORKS

Lecture 19 Chapter 5

26th October, 2023

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Office Hours: 02:30 pm till 06:00 pm (Every Tuesday & Thursday)

Chapter 5

Network Layer: Control Plane

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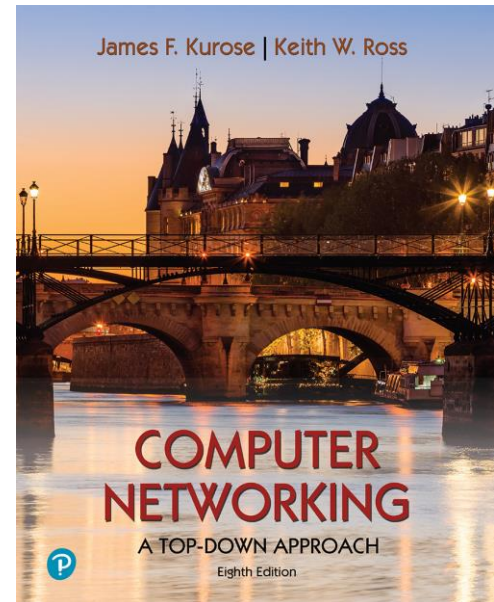
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Computer Networking: A Top-Down Approach

8th edition

Jim Kurose, Keith Ross
Pearson, 2020

Network layer control plane: our goals

- understand principles behind network control plane:
 - traditional routing algorithms
 - SDN controllers
 - network management, configuration
- instantiation, implementation in the Internet:
 - OSPF, BGP
 - OpenFlow, ODL and ONOS controllers
 - Internet Control Message Protocol: ICMP
 - SNMP, YANG/NETCONF

Network layer: “control plane” roadmap

- introduction
- routing protocols
 - link state
 - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- SDN control plane
- Internet Control Message Protocol



- network management, configuration
 - SNMP
 - NETCONF/YANG

Network-layer functions

- **forwarding:** move packets from router's input to appropriate router output
- **routing:** determine route taken by packets from source to destination

data plane

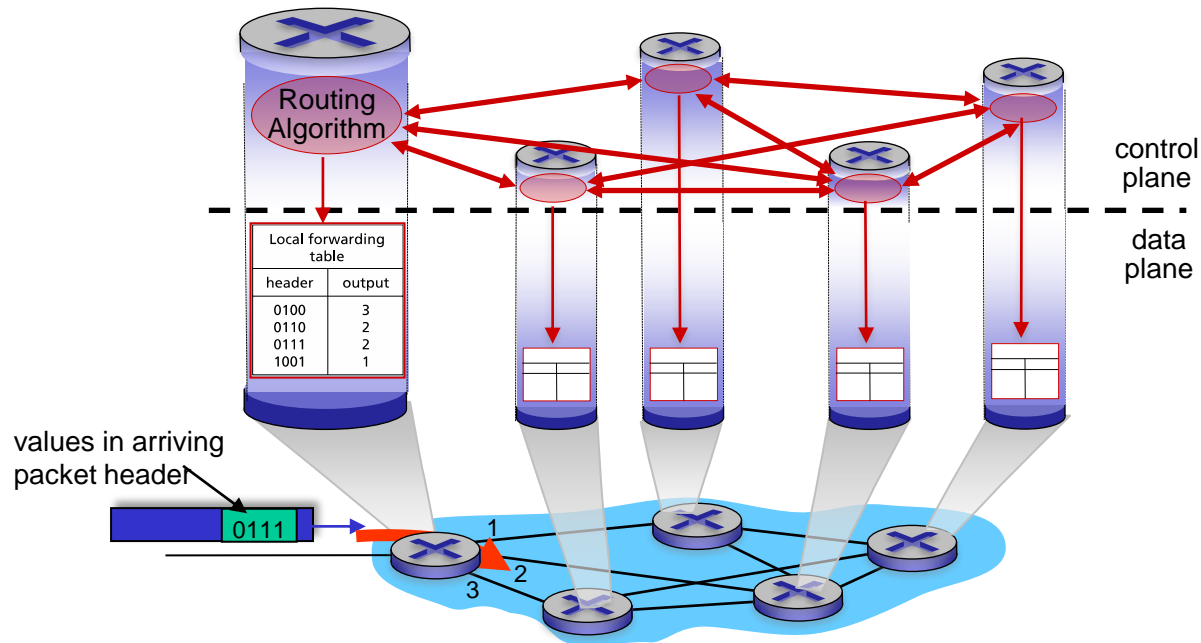
control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

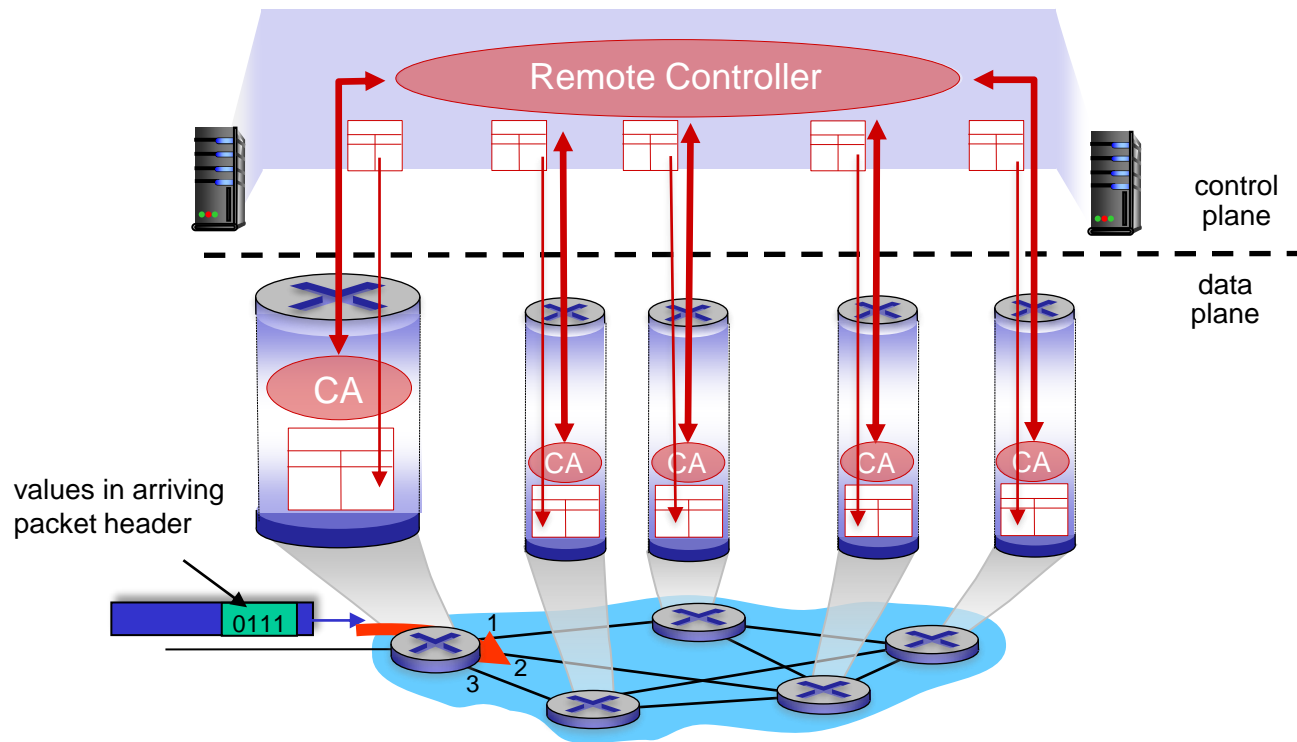
Per-router control plane

Individual routing algorithm components *in each and every router* interact in the control plane

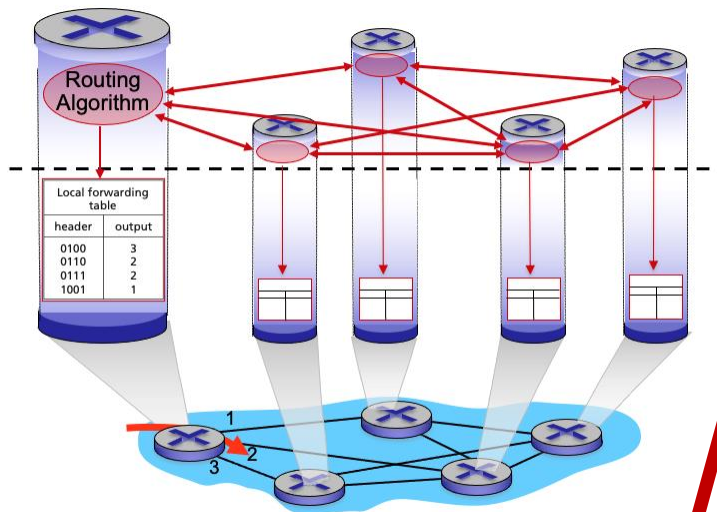


Software-Defined Networking (SDN) control plane

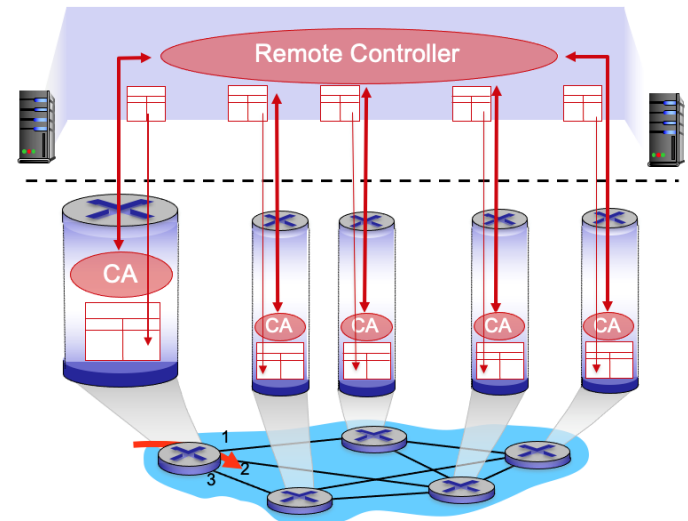
Remote controller computes, installs forwarding tables in routers



Per-router control plane



SDN control plane



Network layer: “control plane” roadmap

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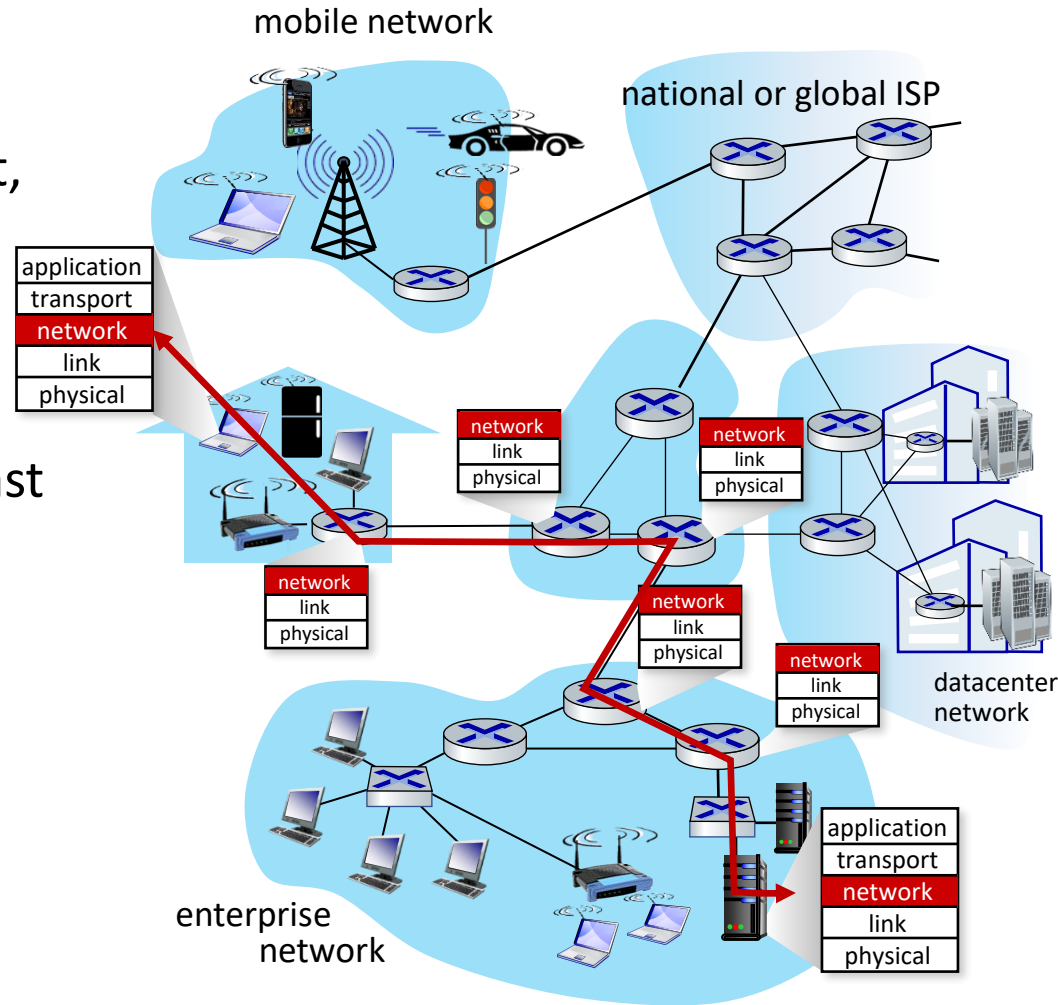


- network management, configuration
 - SNMP
 - NETCONF/YANG

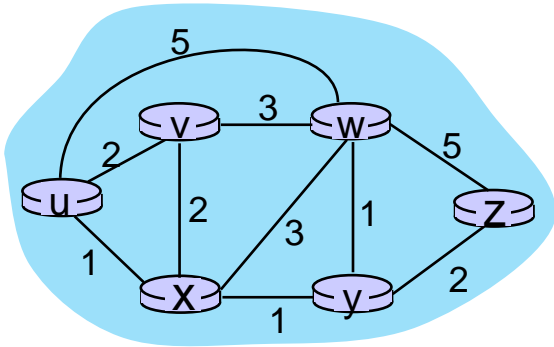
Routing protocols

Routing protocol goal: determine “good” paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- **path:** sequence of routers packets traverse from given initial source host to final destination host
- **“good”:** least “cost”, “fastest”, “least congested”
- routing: a “top-10” networking challenge!



Graph abstraction: link costs



$c_{a,b}$: cost of *direct* link connecting a and b

e.g., $c_{w,z} = 5$, $c_{u,z} = \infty$

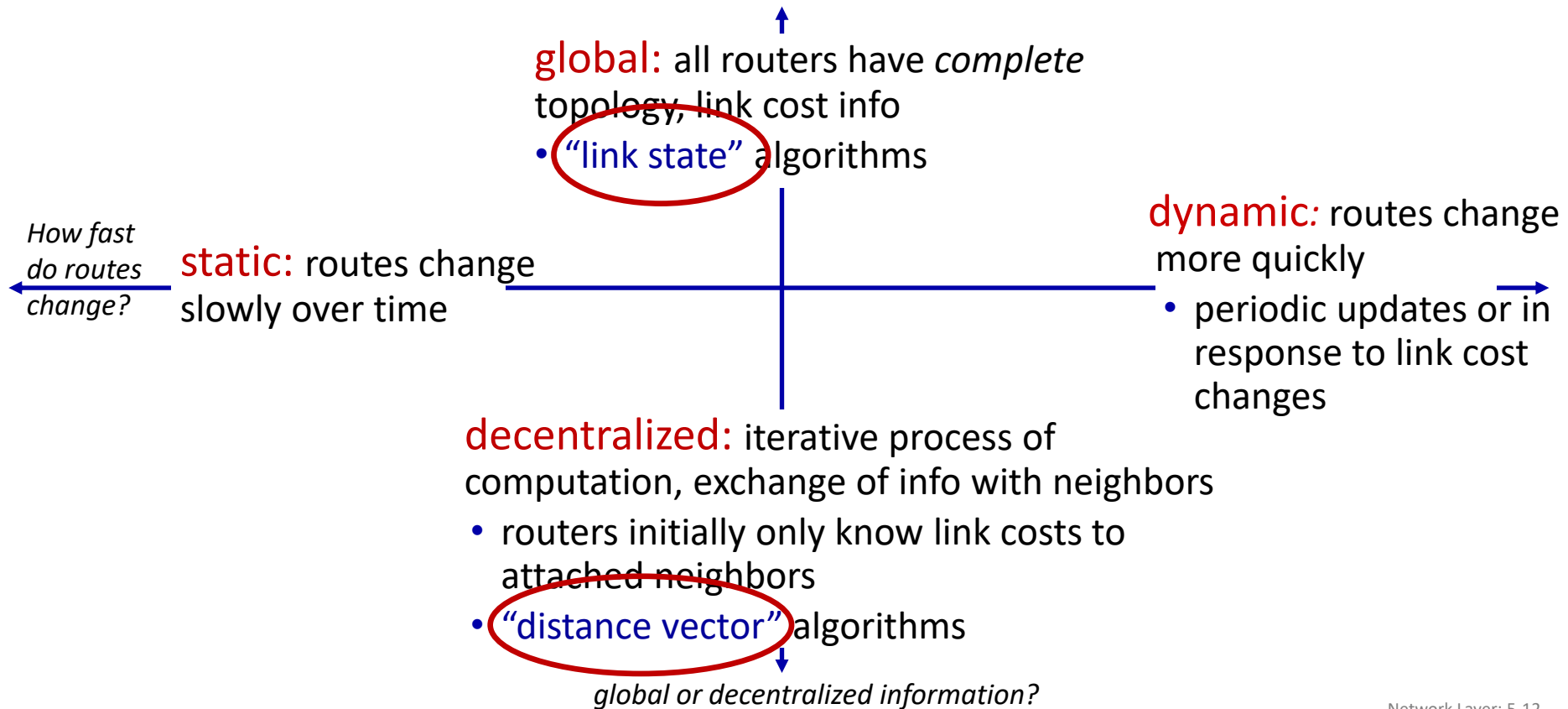
cost defined by network operator:
could always be 1, or inversely related
to bandwidth, or inversely related to
congestion

graph: $G = (N, E)$

N : set of routers = $\{ u, v, w, x, y, z \}$

E : set of links = $\{ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) \}$

Routing algorithm classification



Network layer: “control plane” roadmap

- introduction
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- network management, configuration
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 - NETCONF/YANG

Dijkstra's link-state routing algorithm

- **centralized**: network topology, link costs known to *all* nodes
 - accomplished via “link state broadcast”
 - all nodes have same info
- computes least cost paths from one node (“source”) to all other nodes
 - gives *forwarding table* for that node
- **iterative**: after k iterations, know least cost path to k destinations

notation


- $c_{x,y}$: direct link cost from node x to y ; $= \infty$ if not direct neighbors
- $D(v)$: *current* estimate of cost of least-cost-path from source to destination v
- $p(v)$: predecessor node along path from source to v
- N' : set of nodes whose least-cost-path *definitively* known

Dijkstra's link-state routing algorithm

1 *Initialization:*

```
2   $N' = \{u\}$                                 /* compute least cost path from u to all other nodes */
3  for all nodes  $v$ 
4    if  $v$  adjacent to  $u$                         /*  $u$  initially knows direct-path-cost only to direct neighbors */
5      then  $D(v) = c_{u,v}$                       /* but may not be minimum cost! */
6    else  $D(v) = \infty$ 
7
```

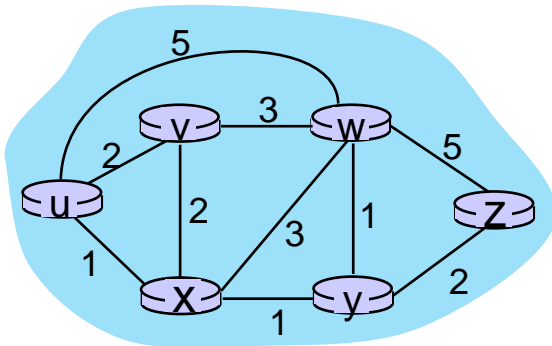
8 *Loop*



```
9  find  $w$  not in  $N'$  such that  $D(w)$  is a minimum
10 add  $w$  to  $N'$ 
11 update  $D(v)$  for all  $v$  adjacent to  $w$  and not in  $N'$  :
12    $D(v) = \min ( D(v), D(w) + c_{w,v} )$ 
13 /* new least-path-cost to  $v$  is either old least-cost-path to  $v$  or known
14    least-cost-path to  $w$  plus direct-cost from  $w$  to  $v$  */
15 until all nodes in  $N'$ 
```

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1						
2						
3						
4						
5						

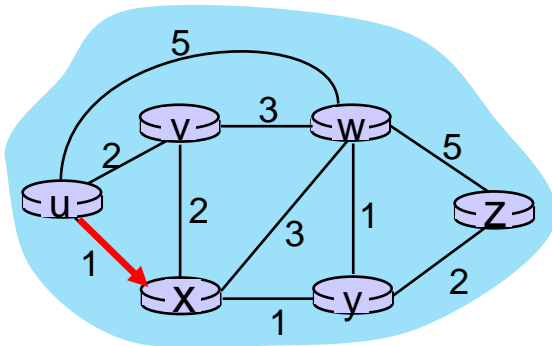


Initialization (step 0):

For all a : if a adjacent to u then $D(a) = c_{u,a}$

Dijkstra's algorithm: an example

Step	N'	^v $D(v), p(v)$	^w $D(w), p(w)$	^x $D(x), p(x)$	^y $D(y), p(y)$	^z $D(z), p(z)$
0	u	2, u	5, u	1, u	∞	∞
1	u, x					
2						
3						
4						
5						

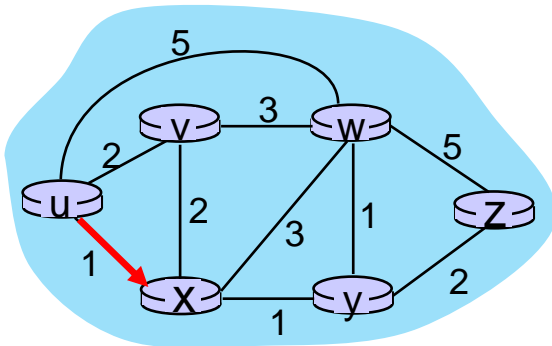


8 Loop

- 9 find a not in N' such that $D(a)$ is a minimum
- 10 add a to N'

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2						
3						
4						
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(v) = \min (D(v), D(x) + c_{x,v}) = \min(2, 1+2) = 2$$

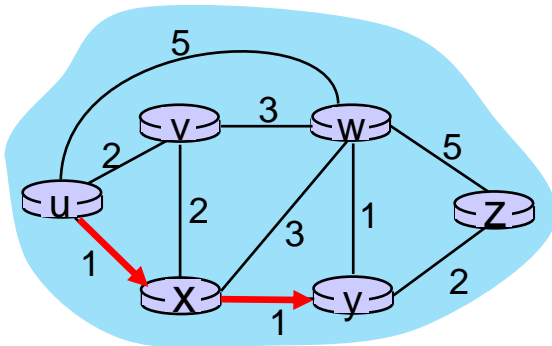
$$D(w) = \min (D(w), D(x) + c_{x,w}) = \min(5, 1+3) = 4$$

$$D(y) = \min (D(y), D(x) + c_{x,y}) = \min(\infty, 1+1) = 2$$



Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy					
3						
4						
5						

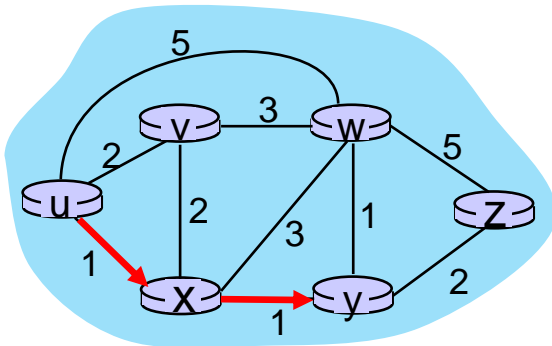


8 Loop

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- 10 add a to N'

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3						
4						
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

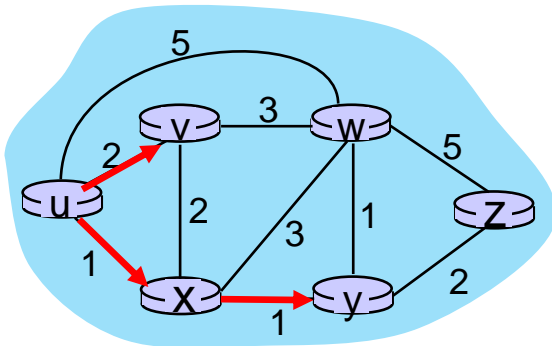
$$D(w) = \min (D(w), D(y) + c_{y,w}) = \min (4, 2+1) = 3$$

$$D(z) = \min (D(z), D(y) + c_{y,z}) = \min (\infty, 2+2) = 4$$



Dijkstra's algorithm: an example

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxy					
4						
5						

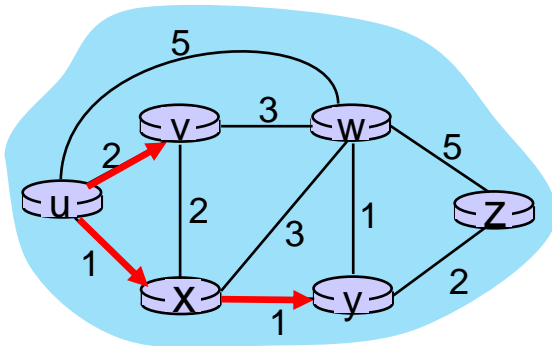


8 Loop

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Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4						
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum

10 add a to N'

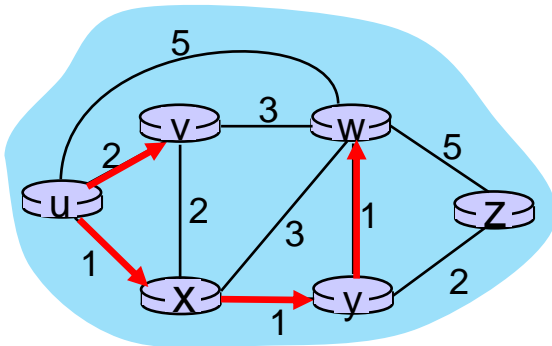
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$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(w) = \min (D(w), D(v) + c_{v,w}) = \min (3, 2+3) = 3$$

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					
5						

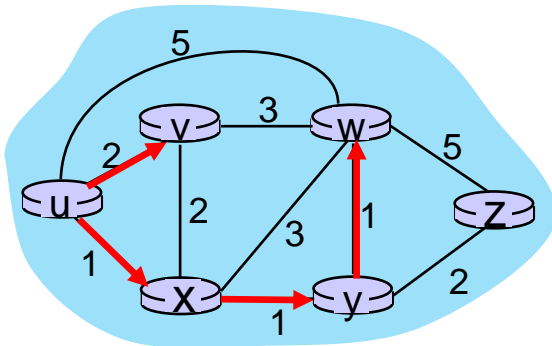


8 Loop

- 9 find a not in N' such that $D(a)$ is a minimum
- 10 add a to N'

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5						



8 Loop

9 find a not in N' such that $D(a)$ is a minimum
10 add a to N'

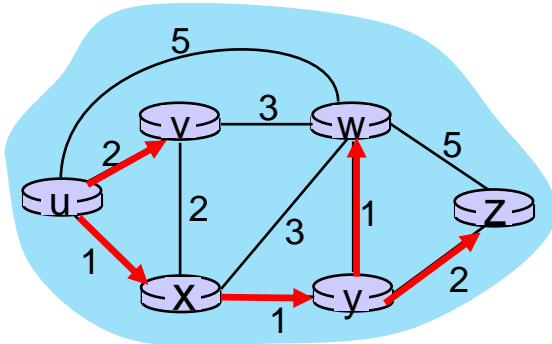
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$$D(b) = \min (D(b), D(a) + c_{a,b})$$

$$D(z) = \min (D(z), D(w) + c_{w,z}) = \min (4, 3+5) = 4$$

Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

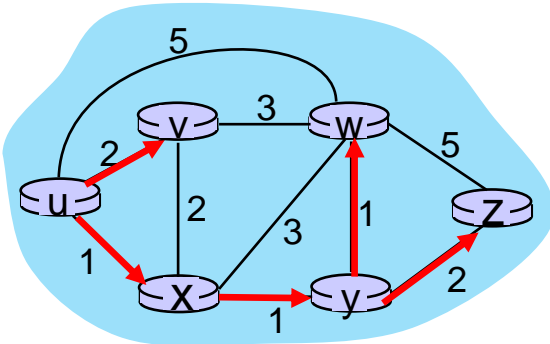


8 Loop

- 9 find a not in N' such that $D(a)$ is a minimum
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Dijkstra's algorithm: an example

Step	N'	^v D(v),p(v)	^w D(w),p(w)	^x D(x),p(x)	^y D(y),p(y)	^z D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					

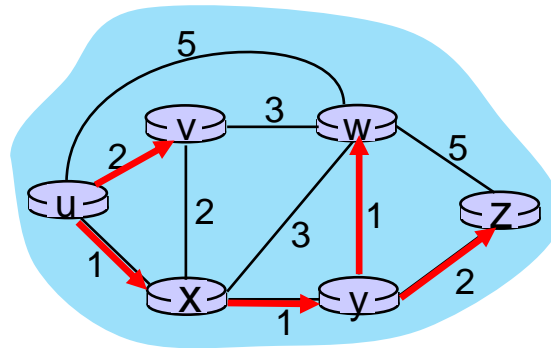


8 Loop

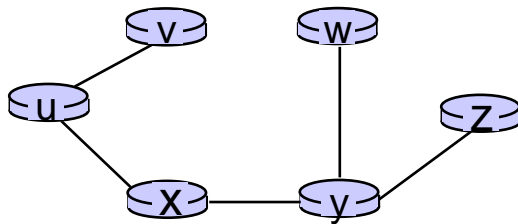
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- 10 add a to N'
- 11 update $D(b)$ for all b adjacent to a and not in N' :

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

Dijkstra's algorithm: an example



resulting least-cost-path tree from u:



resulting forwarding table in u:

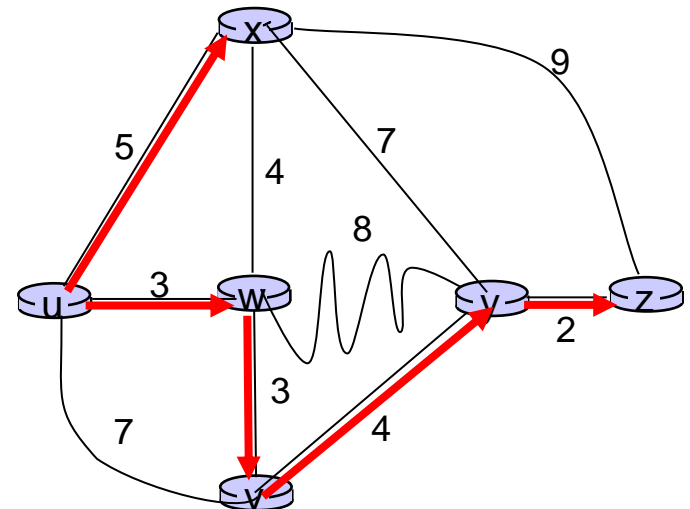
destination	outgoing link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

route from u to v directly

route from u to all other destinations via x

Dijkstra's algorithm: another example

Step	N'	$D(v), p(v)$	$D(w), p(w)$	$D(x), p(x)$	$D(y), p(y)$	$D(z), p(z)$
0	u	7,u	3,u	5,u	∞	∞
1	uw	6,w		5,u	11,w	∞
2	uwvx	6,w			11,w	14,x
3	uwxv				10,v	14,x
4	uwxvy					12,y
5	uwxvyz					



notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: n nodes

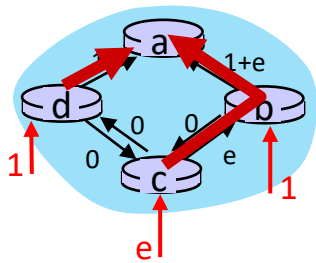
- each of n iteration: need to check all nodes, w , not in N
- $n(n+1)/2$ comparisons: $O(n^2)$ complexity
- more efficient implementations possible: $O(n \log n)$

message complexity:

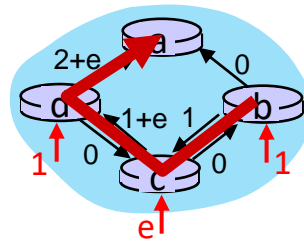
- each router must *broadcast* its link state information to other n routers
- efficient (and interesting!) broadcast algorithms: $O(n)$ link crossings to disseminate a broadcast message from one source
- each router's message crosses $O(n)$ links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

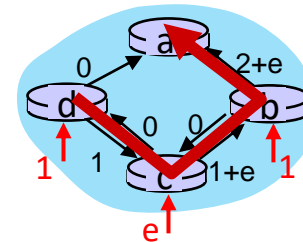
- when link costs depend on traffic volume, **route oscillations** possible
- sample scenario:
 - routing to destination a, traffic entering at d, c, e with rates 1, e (<1), 1
 - link costs are directional, and volume-dependent



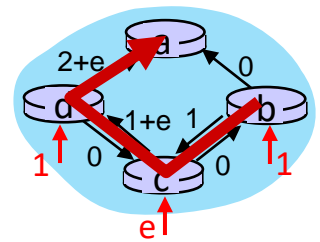
initially



given these costs,
find new routing....
resulting in new costs



given these costs,
find new routing....
resulting in new costs



given these costs,
find new routing....
resulting in new costs

Assignment # 4 (Chapter - 4)

- *4th Assignment will be uploaded on Google Classroom on Thursday, 26th October, 2023, in the Stream - Announcement Section*
- *Due Date: Thursday, 2nd November, 2023 (Handwritten solutions to be submitted during the lecture)*
- *Please read **all the instructions** carefully in the uploaded Assignment document, follow & submit accordingly*

Quiz # 4 (Chapter - 4)

- *On: Thursday, 2nd November, 2023 (During the lecture)*
- *Quiz to be taken during own section class only*