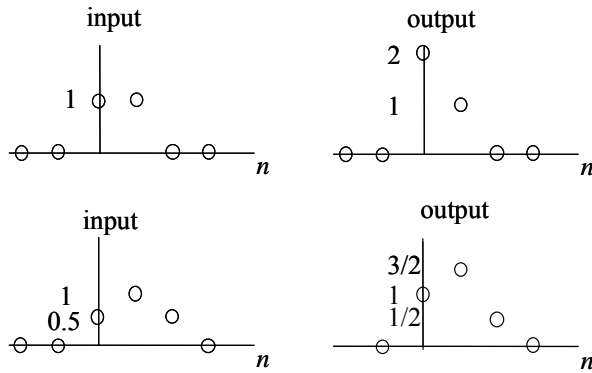


ECE-314 Fall 2012
Midterm I (75 minutes); Closed Book/Notes

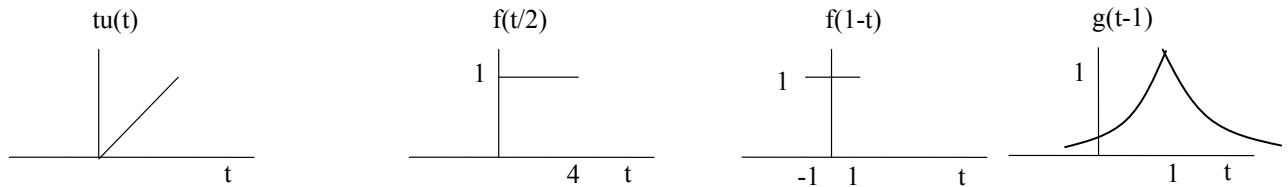
1. A linear time-invariant system has the input-output characteristics shown in the first row of the diagram below. Determine the output for the input shown on the second row of the diagram. Justify your answer carefully.



Solution: Note that $x_2[n] = 0.5x_1[n-1] + 0.5x_1[n]$. As a consequence of the system being LTI, we must have $y_2[n] = 0.5y_1[n-1] + 0.5y_1[n]$. Sketch it below.

2. Consider the signals $f(t) = u(t) - u(t-2)$ and $g(t) = \exp(-2|t|)$.

(a) Sketch the signals: $tu(t)$, $f(t/2)$, $f(1-t)$ and $g(t-1)$.



(b) Is g a power or an energy signal? Calculate the appropriate quantity.

Energy signal; $E = 2 \int_0^{\infty} \exp(-4t) dt = 1/2$. Power = 0.

3. Evaluate the following quantities:

a. $\int_{-\infty}^{\infty} \sqrt{s} \delta(s-4) ds$ 2

b. $\int_{-\infty}^{t-1} \delta(s) ds$ $u(t-1)$

c. $\sum_{k=-\infty}^{\infty} \delta(n-k) \sin(k+2n)$ $\sin(3n)$

d. $\sum_{k=-\infty}^n \delta(n-k)$ 1

4. Consider a system described by the following input-output relation:

$$y(t) = 2x(e^t).$$

(a) Is the system linear? Justify. It is linear because it satisfied superposition and homogeneity.

Superposition: $O(x_1 + x_2)(t) = 2(x_1 + x_2)(e^t) = 2x_1(e^t) + 2x_2(e^t) = O(x_1)(t) + O(x_2)(t)$

Homogeneity: $O(ax)(t) = 2(ax)(e^t) = 2a x(e^t) = a O(x)(t)$

(b) Is it time invariant? Justify. No.

$$O(x_{t_0})(t) = 2(x_{t_0})(e^t) = 2x(e^t - t_0), \text{ but } O(x)(t - t_0) = 2x(e^{t-t_0})$$

(c) Is it memoryless? Justify.

No. $O(x)(0) = 2x(e^0) = 2x(1)$ depends on $x(1)$.

(d) Is it causal? Justify.

No. $O(x)(0) = 2x(e^0) = 2x(1)$ depends on future value of input, namely $x(1)$.

5. Determine whether the following systems are BIBO stable, you must show proper justification (i.e., provide a proof in the case of stable and a counter example otherwise).

(a) $y(t) = 1 + \int_{-\infty}^t x(s)ds$.

Pick a bounded input, $x(t)=u(t)$, for example. Now note that for this input, $y(t) = 1 + t$, which is unbounded. Hence, we found a bounded input whose output is unbounded. Hence the system is not BIBO stable.

(b) $y(t) = x(t) + \int_{t-4}^t x(s)ds$

Let an input signal x be bounded by M , namely, $|x| < M$. Then,

$$|y(t)| \leq M + \left| \int_{t-4}^t x(s)ds \right| \leq M + \int_{t-4}^t |x(s)| ds \leq M + \int_{t-4}^t M ds = M + M(4) = 5M$$

Hence, the output remains bounded for any input as long as the input is bounded.
Hence, the system is BIBO stable.

(c) $y(n) = 0.5\{x(n-1) - x(n)\}$

Let an input signal x be bounded by M , namely, $|x| < M$. Then,

$$|y(n)| = |0.5(x(n-1) + x(n))| \leq 0.5|x(n-1)| + 0.5|x(n)| \leq 0.5(M + M) = M.$$

Hence, the output is bounded as long as the input is bounded.
Hence, the system is BIBO stable.

6. Show that the system described by $y(n)=x(3n)$ is not time invariant.

$$O(x_{n0})(n) = x_{n0}(3n) = x_{n0}(3n - n_0); \text{ but } O(x)(n-n_0) = x(3(n-n_0)) = x(3n-3n_0).$$

7. A moving-window system is defined by the following input-output relation:

$$y(n) = M^{-1} \sum_{k=n-M}^n x(k).$$

(a) Show that it is LTI and find its impulse response $h(n)$.

$$\text{Superposition: } O(x_1 + x_2)(n) = M^{-1} \sum_{k=n-M}^n (x_1(k) + x_2(k)) =$$

$$M^{-1} \sum_{k=n-M}^n x_1(k) + M^{-1} \sum_{k=n-M}^n x_2(k) = O(x_1)(n) + O(x_2)(n)$$

$$\text{Homogeneity: } O(ax)(n) = M^{-1} \sum_{k=n-M}^n ax(k) = M^{-1} a \sum_{k=n-M}^n x(k) = a O(x)(n)$$

Impulse response: set $x=\delta$ to obtain

$$h(n) = M^{-1} \sum_{k=n-M}^n \delta(k) = M^{-1} \left(\sum_{k=-\infty}^n \delta(k) - \sum_{k=-\infty}^{n-M-1} \delta(k) \right) = M^{-1} (u(n) - u(n-M-1)).$$

(b) Show that this system is stable.

Let an input signal x be bounded by K , namely, $|x| < K$. Then,

$$|y(n)| = |M^{-1} (x(n-M) + \dots + x(n))| \leq M^{-1} (|x(n-M)| + \dots + |x(n)|) \leq M^{-1} (K + \dots + K) = M^{-1} (M+1)K.$$

Hence, the output remains bounded for any input as long as the input is bounded.

Hence, the system is BIBO stable.

8. Show that for an LTI system an identically-zero input signal will result in an identically-zero output signal.

Let O be any LTI system, let $\underline{0}(t)$ denote the all-zero signal, and let x be an arbitrary signal. Note that $\underline{0}(t)$ can be written as $0x(t)$.

Now $O(\underline{0})(t) = O(0x)(t) = 0O(x)(t) = 0$, where the second equality follows from homogeneity.

9. Consider a system given by $y(t) = 1 + x'(t)$. Prove that this system is not BIBO stable.

Consider the input $x(t) = \sqrt{1-t^2}(u(t) - u(t-1))$, which is bounded by 1. However, note that $x'(t)$ is unbounded because $x'(t)$ diverges to $-\infty$ as t approaches 1. Hence, we found a bounded input whose output is unbounded. Hence, the system is not BIBO stable.

10. Find the impulse response of the system described in 5(b)

Replace x with δ in $y(t) = x(t) + \int_{t-4}^t x(s)ds$ to obtain

$$h(t) = \delta(t) + \int_{t-4}^t \delta(s)ds = \delta(t) + \int_{-\infty}^t \delta(s)ds - \int_{-\infty}^{t-4} \delta(s)ds = \delta(t) + u(t) - u(t-4).$$