

Assignment 6

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1. *Balls and bins revisited.* There are 10 bins numbered $1, 2, \dots, 10$. n balls are thrown into the 10 bins. For each ball, the probability that it falls into bin i is $\frac{1}{10}$ for $i = 1, 2, \dots, 10$. Different balls are thrown independently of each other. Let Y be the number of balls in bin 1. Let Z be the total number of balls in bins 6, 7, 8, 9, 10.
 - (a) Find $P(Y = y | Z = z)$. Please specify the range of y, z .
 - (b) Given $Z = z$, find the estimator $\hat{y}(z)$ that minimizes conditional MSE $E[(\hat{y}(z) - Y)^2 | Z = z]$.
 - (c) Find the conditional MSE $E[(\hat{y}(z) - Y)^2 | Z = z]$ for the estimator in part (b).
 - (d) Find the linear LMS estimator of Y given $Z = z$.
 - (e) Find $E[Z]$ and $\text{Var}[Z]$.
 - (f) Find $E[Y]$ and $\text{Var}[Y]$.
 - (g) Find $\text{Cov}(Y, Z)$.

Hint: Use the law of total expectation. Try to first determine the conditional pmf.

 - (h) Find the linear LMS estimator of Z given Y .
 - (i) Find the corresponding (overall) MSE for the estimator in part (h).

From Assignment 4:

$$\begin{aligned}
 Y &\sim \text{Binom}(n, 1/10) \\
 Z &\sim \text{Binom}(n, 1/2) \\
 Y | Z = z &\sim \text{Binom}(n - z, 1/2) \\
 Z | Y = y &\sim \text{Binom}(n - y, 5/9)
 \end{aligned}$$

$a) P(Y = y | Z = z) = \binom{n-z}{y} \left(\frac{1}{2}\right)^y \left(\frac{1}{2}\right)^{n-z-y}$
 for $z = 0, 1, \dots, n$ & $y = 0, 1, \dots, n - z$

$$b) \hat{y}(z)_{LMS} = E[Y | Z = z] = \sum_y y P_{YZ}(y | z) = \frac{n-z}{2}$$

$$\begin{aligned}
 c) MSE_{LMS}(z) &= \text{Var}(Y | z) = E[Y^2 | z] - E[Y | z]^2 \\
 &= \sum_y y^2 P_{YZ}(y | z) - \left(\frac{n-z}{2}\right)^2 = \frac{(n-z)^2}{6} - \left(\frac{n-z}{2}\right)^2
 \end{aligned}$$

$$d) \hat{y}_{LMS} = \underset{y=0,1,\dots}{\text{argmin}} (E[(Y - y)^2]) = \frac{n}{10} - \frac{n-z}{5}$$

$$\begin{aligned}
 e) E[Z] &= \sum_z z \left(\frac{1}{2}\right) = \frac{n(n+1)}{4} \\
 \text{Var}(Z) &= \sum_z \frac{(z - E[Z])^2}{n}
 \end{aligned}$$

$$\begin{aligned}
 f) E[Y] &= \sum_y y \left(\frac{1}{10}\right) = \frac{n(n+1)}{20} \\
 \text{Var}(Y) &= \sum_y \frac{(y - E[Y])^2}{n}
 \end{aligned}$$

$$\begin{aligned}
 g) \text{Cov}(Y, Z) &= E[YZ] - E[Y]E[Z] = -\frac{n}{20} \\
 &\hookrightarrow E[YZ] = E[E[YZ | Y]] = E[Y E[Z | Y]]
 \end{aligned}$$

$$\begin{aligned}
 h) LMS &= \frac{\text{Cov}(Y, Z)}{\text{Var}(Y)} (Y - E[Y]) + E[Z] \\
 &= \frac{n}{2} - \frac{5}{9} \left(Y - \frac{n}{10}\right)
 \end{aligned}$$

$$i) MSE = \text{Var}(Z) - \frac{\text{Cov}(Z, Y)^2}{\text{Var}(Y)} = \frac{2n}{9}$$

2. *Estimation vs. detection.* Let the signal

$$X = \begin{cases} +1, & \text{with probability } \frac{1}{2} \\ -1, & \text{with probability } \frac{1}{2}, \end{cases}$$

and the noise $Z \sim \text{Unif}[-2, 2]$ be independent random variables. Their sum $Y = X + Z$ is observed.

- Find the LMS estimate of X given Y
- Find the (overall) MSE for the estimator you find in part (a).
- Now suppose we use a decoder to decide whether $X = +1$ or $X = -1$ so that the probability of error is minimized. Find the MAP decoder and its probability of error. Compare the MAP decoder's MSE to the least MSE.

$$X = \begin{cases} 1 \\ -1 \end{cases}, \quad \text{w.p. } \frac{1}{2} \quad Z \sim \text{Unif}[-2, 2] \rightarrow Y = X + Z$$

$$P(X=1) = P(X=-1) = \frac{1}{2}$$

$$f(y|x) = f_Z(y-x) = \frac{1}{4}$$

$$f(x|y) = \frac{f(y|x)P_X(x)}{f_Y(y)} = \frac{\frac{1}{4} \cdot \frac{1}{2}}{\frac{1}{4} \cdot \frac{1}{2} + \frac{1}{4} \cdot \frac{1}{2}} = \frac{1}{2}$$

$$a) \hat{X}_{\text{LMS}}(y) = E[X|Y] = \sum_{x=-1}^1 x \left(\frac{1}{2}\right) = 0$$

$$b) \text{MSE}_{\text{LMS}}(y) = E[X^2|Y] - E[X|Y]^2 = \sum_{x=-1}^1 x^2 \left(\frac{1}{2}\right) - \left[\sum_{x=-1}^1 x \left(\frac{1}{2}\right)\right]^2 = 1 - 0^2 = 1$$

$$c) \hat{X}_{\text{MAP}}(y) = \underset{x}{\text{argmax}} f(x|y) = \frac{f(y|x)P_X(x)}{f_Y(y)}$$

$$\hookrightarrow f_Z(y-x) = \begin{cases} \frac{1}{4}, & -2 \leq y-x \leq 2 \\ 0, & \text{otherwise} \end{cases}$$

$$\hookrightarrow \underset{x}{\text{argmax}} f_Z(y-x) = \begin{cases} -1, & y < 0 \\ +1, & y \geq 0 \end{cases}$$

$$P_Y = P(Y > 0 | X = -1)P(X = -1) + P(Y < 0 | X = 1)P(X = 1)$$

$$= P(-1 + Z > 0) + P(1 + Z < 0) = P(Z > 1) + P(Z < -1) = \frac{1}{4} + \frac{1}{4} = \frac{1}{2}$$

$$\begin{aligned} \text{MSE}_{\text{MAP}}(y) &= E[(X - \hat{X}_{\text{MAP}})^2|Y] = E[X^2|Y] - 2\hat{X}_{\text{MAP}}(y)E[X|Y] + \hat{X}_{\text{MAP}}(y)^2 \\ &= 1 - 2(-1)(0) + (-1)^2 = 2 \rightarrow y < 0 \\ &= 1 - 2(1)(0) + (1)^2 = 2 \rightarrow y \geq 0 \end{aligned} \quad \text{MSE}_{\text{MAP}} = 2$$

$\therefore \text{MSE}_{\text{MAP}}$ is twice MSE_{LMS}

3. *Stick breaking.* Given a stick of length 1, break it into two pieces at a location chosen uniform at random. Denote the breaking location by X , then $X \sim \text{Unif}[0, 1]$. Keep the piece corresponding to the interval $[X, 1]$. Break it again into two pieces at a location chosen uniform at random. Denote the second breaking location by Y , then $Y|X=x \sim \text{Unif}[x, 1]$.

- Find the estimator of X given Y that minimizes the MSE $E[(\hat{X} - X)^2]$.
- Find the conditional MSE given $Y = y$ for the estimator you find in part (a).
- Find the covariance $\text{Cov}(X, Y)$.
- Find the linear LMS estimator of X given Y .
- Find the MSE for the estimator you find in part (d)



$$X \sim \text{Unif}[0, 1], \quad Y|X=x \sim \text{Unif}[x, 1]$$

a) Estimator of X given Y minimizing MSE $E[(\hat{X} - X)^2]$

$$\hat{X}(y) = E[X|Y=y]$$

$$f_{X|Y}(x|y) = \frac{f(y|x)f(x)}{f(y)} = \frac{(\frac{1-x}{1-y}) \cdot \frac{1}{1-x}}{\int_{-\infty}^{\infty} f_Z(z)f_{Y|X}(y|x=z)dz} \rightarrow 0 \leq x \leq y \leq 1$$

$$= \frac{\frac{1}{1-x}}{\int_0^y \frac{1}{1-x} dz} = \frac{1}{1-x}$$

$$\therefore \hat{X}_{\text{LMS}} = E[X|Y=y] = \int_x f(x|y)dx = \int_0^y \frac{1}{-\ln(y-1)} dx = \frac{y}{\ln(y-1)} + 1$$

$$\hookrightarrow \text{MSE}_{\text{LMS}} = E[(X - \hat{X}_{\text{LMS}})^2] = \dots$$

$$= \frac{y}{\ln(y-1)} + 1$$

b) Conditional MSE given $Y=y \rightarrow E[(x-\hat{x})^2 | Y=y]$

$$E[x^2 | Y=y] = \int_0^y \frac{x^2 \cdot \frac{1}{x}}{-\ln(y-1)} dx = \frac{-y^2}{2\ln(y-1)}$$

$$\hookrightarrow -2\hat{x}(y) E[x | Y=y] = -2(\hat{x}_{LMS}(y))^2 = -2\left(\frac{y}{-\ln(y-1)}\right)^2$$

$$(\hat{x}_{LMS}(y))^2 = \left(\frac{y}{-\ln(y-1)}\right)^2$$

$$\therefore MSE = \frac{-y}{2\ln(y-1)} - 2\left(\frac{y}{-\ln(y-1)}\right)^2 + \left(\frac{y}{-\ln(y-1)}\right)^2$$

c) $\text{Cov}(X, Y) = E[XY] - E[X]E[Y]$

$$E[XY] = E_Y[E[XY|X]] = E_Y[E[X]E[Y|X]]$$

$$= E_Y\left[\frac{x+1}{2} \cdot x\right] \rightarrow \frac{x^2+x}{2}$$

$$= \frac{1}{2} [E_Y(x) + E_Y(x^2)]$$

$$= \frac{1}{2} \left(\frac{1}{2} + \frac{1}{3}\right)$$

$$= \frac{5}{12}$$

d) $\text{Var}(Y) = E[\text{Var}(Y|X)] + \text{Var}(E[Y|X])$

$$= E\left[\frac{(1-x)^2}{12}\right] + \text{Var}\left(\frac{1+x}{2}\right)$$

$$= \frac{1}{36} + \frac{1}{4} \cdot \frac{1}{2}$$

$$= \frac{7}{144}$$

$$e) \rho_{xy} = \frac{\frac{1}{24}}{\sqrt{\frac{1}{12} \cdot \frac{7}{144}}}$$

$$MSE = \frac{1}{12} \left(1 - \frac{\frac{1}{24}}{\sqrt{\frac{1}{12} \cdot \frac{7}{144}}}\right) = \frac{1}{21}$$

4. Estimation based on a function of the observation. Let Θ be a positive random variable, with known mean μ and variance σ^2 , to be estimated on the basis of a measurement X of the form $X = \sqrt{\Theta}W$. We assume that W is independent of Θ with zero mean, unit variance, and known fourth moment $E[W^4]$. Thus, the conditional mean and variance of X given Θ are 0 and Θ , respectively, so we are essentially trying to estimate the variance of X given an observed value.

(a) Find the linear LMS estimator of Θ based on $X = x$.

(b) Let $Y = X^2$. Find the linear LMS estimator of Θ based on $Y = y$.

$$\text{Cov}(\Theta, X) = E[\Theta^2 W] - E[\Theta]E[X] = 0$$

a) $\Theta_{LMS} \rightarrow \hat{\Theta} = \mu$

\hookrightarrow does not make use of observation $x=x$

b) For $Y = X^2 = \Theta W^2$ $\hat{\Theta} = aY + b$

$$E[Y] = E[\Theta W^2] = E[\Theta]E[W^2] = \mu$$

$$E[\Theta Y] = E[\Theta^2 W^2] = E[\Theta^2]E[W^2] = \sigma^2 + \mu^2$$

$$\text{Cov}(\Theta, Y) = E[\Theta Y] - E[\Theta]E[Y] = (\sigma^2 + \mu^2) - \mu^2 = \sigma^2$$

$$\text{Var}(Y) = E[\Theta^2 W^4] - E[Y]^2 = (\sigma^2 + \mu^2)E[W^4] - \mu^2$$

$$\Theta_{LMS}(\Theta | Y=y) \rightarrow \hat{\Theta} = \mu + \frac{\sigma^2}{(\sigma^2 + \mu^2)E[W^4] - \mu^2} (y - \sigma^2)$$

5. Neural net. Let $Y = X + Z$, where the signal $X \sim \text{Unif}[-1, 1]$ and noise $Z \sim N(0, 1)$ are independent. We want to estimate $\text{sgn}(X)$, where

$$\text{sgn}(x) = \begin{cases} -1 & x \leq 0 \\ +1 & x > 0. \end{cases}$$

(a) Find the function $g(y)$ that minimizes

$$MSE = E[(\text{sgn}(Y) - g(Y))^2]$$

- (a) Find the function $g(y)$ that minimizes

$$\text{MSE} = E[(\text{sgn}(X) - g(Y))^2].$$

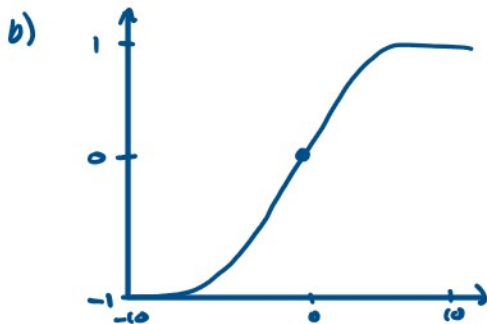
Express your answer in terms of the cumulative distribution function of $N(0, 1)$

$$\Phi(z) \triangleq \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx.$$

- (b) Plot $g(y)$ as a function of y .

$$\begin{aligned} f_X(x) &= \begin{cases} 1/2, & -1 \leq x \leq 1 \\ 0, & \text{otherwise} \end{cases} \\ f_{Y|X}(y|x) &= f_X(y-x) \rightarrow [Y|X=x] \sim N(x, 1) \\ f_Y(y) &= \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx = \int_{-1}^1 \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} \cdot \frac{1}{2} dx \\ &= \frac{1}{2} \left[\int_{-1}^y \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} dx + \int_y^1 \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} dx \right] \\ &= \frac{1}{2} [Q(y-1) - Q(y+1)] \end{aligned}$$

$$\begin{aligned} a) \quad g(y) &= E[\text{sgn}(X) | Y=y] = \int_{-\infty}^{\infty} \text{sgn}(x) f(x|y) dx \\ &= \int_{-1}^1 \text{sgn}(x) \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}}}{Q(y-1) - Q(y+1)} dx = \frac{1}{Q(y-1) - Q(y+1)} \left[\int_0^1 \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} dx + \int_{-1}^0 \frac{1}{\sqrt{2\pi}} e^{-\frac{(y-x)^2}{2}} dx \right] \\ &= \frac{Q(y-1) - Q(y+1)}{Q(y-1) - Q(y+1)} [Q(y-1) - Q(y) + Q(y) - Q(y+1)] \\ &= \frac{Q(y-1) + Q(y+1) - 2Q(y)}{Q(y-1) - Q(y+1)} \end{aligned}$$



6. *Communication in Gaussian noise.* In a communication system, a transmitter wants to send some signal to a receiver over a noisy medium. Suppose the signal Θ is a Gaussian distributed random variable $\Theta \sim \mathcal{N}(0, \sigma_\Theta^2)$. The noise in the medium is modeled as a Gaussian distributed random variable $W \sim \mathcal{N}(0, \sigma_W^2)$ independent of the signal. The receiver observes $X = 2\Theta + W$.

- (a) Find the estimator of Θ given X that minimizes the MSE $E[(\hat{\Theta} - \Theta)^2]$.
- (b) Find the MSE for the estimator you found in part (a).
- (c) Find the linear LMS estimator of Θ given X .
- (d) Find the MSE for the estimator you found in part (c).
- (e) Find the LMS estimator of Θ^2 given X .
- (f) Find the linear LMS estimator of Θ^2 given X .

a) estimator of Θ given $X \rightarrow \text{MSE } E[(\hat{\Theta} - \Theta)^2]$

LLMS of gaussian noise = LMS

$$\hat{x}_{\text{LLMS}} = \frac{\text{Cov}(X, \Theta)}{\text{Var}(X)} (X - E[X]) + E[\Theta]$$

$$\text{Var}(X) = \text{Var}(2\Theta + W)$$

$$\text{Cov}(X, \Theta) = E[X\Theta] - E[X]E[\Theta] = E[(2\Theta + W)\Theta] = E[2\Theta^2 + W\Theta]$$

$$E[\Theta] = 0, \quad X = 2\Theta + W$$

$$E[X] = E[2\Theta + W] = 2E[\Theta] + E[W] = 0$$

$$E[W] = 0,$$

$$E[W^2] = \text{Var}(W) + 0 = \sigma_W^2$$

$$E[X\Theta] = E[(2\Theta + W)\Theta] = 2E[\Theta^2] + E[W\Theta] = 2\sigma_\Theta^2 + 0 = 2\sigma_\Theta^2$$

$$\begin{aligned}
 E[\omega] &= 0 \\
 E[\omega^2] &= \text{Var}(\omega) + 0 = \sigma_\omega^2 \\
 \hookrightarrow E[\theta x] &= E[2\theta^2 + \omega\theta] = E[\theta^2]E[x] + E[\omega\theta] \\
 &= 2E[\theta^2] + E[\omega]E[\theta] = 2\sigma_\theta^2 \\
 \hookrightarrow E[\theta^2] &= \text{Var}(\theta) + E^2[\theta] = \sigma_\theta^2
 \end{aligned}$$

$$\begin{aligned}
 \therefore \text{Cov}(\theta, \theta) &= 2\sigma_\theta^2 \\
 \text{Var}(x) &= E[x^2] - E^2[x] \\
 \hookrightarrow x^2 &= 4\theta^2 + 4\theta\omega + \omega^2 \\
 E[x^2] &= 4E[\theta^2] + 4E[\theta]E[\omega] + E[\omega^2] \\
 &= 4\sigma_\theta^2 + \sigma_\omega^2 \\
 \therefore \text{Var}(x) &= 4\sigma_\theta^2 + \sigma_\omega^2 \\
 \therefore \text{LLMS} &= \frac{2\sigma_\theta^2}{4\sigma_\theta^2 + \sigma_\omega^2} x = \text{LMS}
 \end{aligned}$$

$$\begin{aligned}
 \text{b) MSE} &= \text{Var}(\theta) - \frac{(\text{Cov}(\theta, x))^2}{\text{Var}(x)} \\
 &= \sigma_\theta^2 - \frac{(\sigma_\theta^2 x)^2}{4\sigma_\theta^2 + \sigma_\omega^2}
 \end{aligned}$$

$$\begin{aligned}
 \text{c) } \therefore \text{LLMS} &= \text{LMS} \\
 \therefore \text{LMS} &= \frac{2\sigma_\theta^2}{4\sigma_\theta^2 + \sigma_\omega^2} x
 \end{aligned}$$

$$\text{d) MSE} = \sigma_\theta^2 - \frac{(\sigma_\theta^2 x)^2}{\text{Var}(x)}$$

$$\begin{aligned}
 \text{e) LMS of } \theta^2 \text{ given } x \\
 \text{LMS} &= E[\theta^2 | x] \left(\frac{\text{Cov}(\theta^2, \theta)}{\text{Var}(\theta^2)} (\theta - E[\theta^2]) + E[\theta^2] \right) \\
 \hookrightarrow \theta | x &= x \sim N \left(\frac{\text{Cov}(\theta, \theta)}{\text{Var}(\theta)} (x - E[\theta]) + E[\theta], \text{Var}(\theta) - \frac{(\text{Cov}(\theta, \theta))^2}{\text{Var}(\theta)} \right) \\
 \hookrightarrow E[\theta | x = x] &= \frac{x}{\sigma_\omega^2} \\
 \hookrightarrow \text{Var}(\theta | x) &= E[\theta^2 | x] - E[\theta | x]^2 \\
 E[\theta^2 | x] &= \text{Var}(\theta | x) + E[\theta | x]^2 \\
 \hookrightarrow E[\theta | x = x] &= \frac{x}{\sigma_\omega^2} \\
 \hookrightarrow \text{Var}(\theta | x = x) &= \frac{1}{\frac{1}{\sigma_\theta^2} + \frac{1}{\sigma_\omega^2}} = \frac{\sigma_\theta^2 \sigma_\omega^2}{\sigma_\theta^2 + \sigma_\omega^2} \\
 \therefore \text{LMS} &= E[\theta^2 | x] = \frac{\sigma_\theta^2 \sigma_\omega^2}{\sigma_\theta^2 + \sigma_\omega^2} + \left(\frac{x \sigma_\theta^2}{\sigma_\omega^2 + \sigma_\theta^2} \right)^2
 \end{aligned}$$

$$\begin{aligned}
 \text{f) LLMS} &= \frac{\text{Cov}(\theta^2, x)}{\text{Var}(x)} (x - E[x]) + E[\theta^2] \\
 \text{Cov}(\theta^2, x) &= E[\theta^2 x] - E[\theta^2]E[x] \\
 &= E[\theta^2 (2\theta + \omega)] - 2E[\theta^2]E[\omega] \\
 &= 2 \int_{-\infty}^{\infty} \theta^3 f_\theta(\theta) d\theta \\
 &= 0 \rightarrow \text{by symmetry} \\
 \therefore \text{LLMS} &= 0
 \end{aligned}$$