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INTRODUCTION

In this session we study some methods that accelerate the convergence of some iterative algorithms to their limit.

These methods combine iterates of the algorithms to produce a another sequence in parallel, that sometimes converges faster to the limit.

1 AITKEN'S Δ^2 PROCESS

1.1 Presentation

Aitken's process is one of the simplest of these methods. We consider a sequence $(x_k)_{k \in \mathbb{N}} \in \mathbb{R}^{\mathbb{N}}$. The idea is to locally model the sequence as a first-order autoregressive sequence, which means finding, for each $k \in \mathbb{R}$, two numbers a_k and b_k , such that :

$$\begin{cases} x_{k+1} = a_k x_k + b_k \\ x_{k+2} = a_k x_{k+1} + b_k \end{cases}$$

and then compute the limit of the sequence $(y_i^k)_{i \in \mathbb{N}}$ defined by

$$y_{i+1}^k = a_k y_i^k + b_k \quad (1)$$

we note l_k the limit of $(y_i^k)_{i \in \mathbb{N}}$. This defines another sequence $(l_k)_{k \in \mathbb{N}}$, that might converge faster to the limit of $(x_k)_{k \in \mathbb{N}}$, if this limit exists.

Note that in order to observe an acceleration, this model does not need to be exact, it can also be true only asymptotically.

1.2 Equations

Exercise 1 : Assuming that if iterate is different $x_k \neq x_{k+1}$, solve the linear system defining the locally auto-regressive process for a given k (which means find a_k and b_k)

Exercise 2 : For a given k , what would be a sufficient condition that ensures that the sequence $(y_i^k)_{i \in \mathbb{N}}$ has a limit ?

1.3 Simulation

We will apply Aitken's method to the Leibniz formula, a method to approximate π as the limit of the following sequence :

$$x_k = 4 \sum_{j=0}^k \frac{(-1)^j}{2j+1} \quad (2)$$

this is one of the most famous applications of the method.

Exercise 3 : Is the condition from question 2 verified ?

Exercise 4 : Run a simulation that applies the method to the sequence $(x_k)_{k \in \mathbb{N}}$. You should observe something like figure 1, i.e. an acceleration of the convergence to the limit.

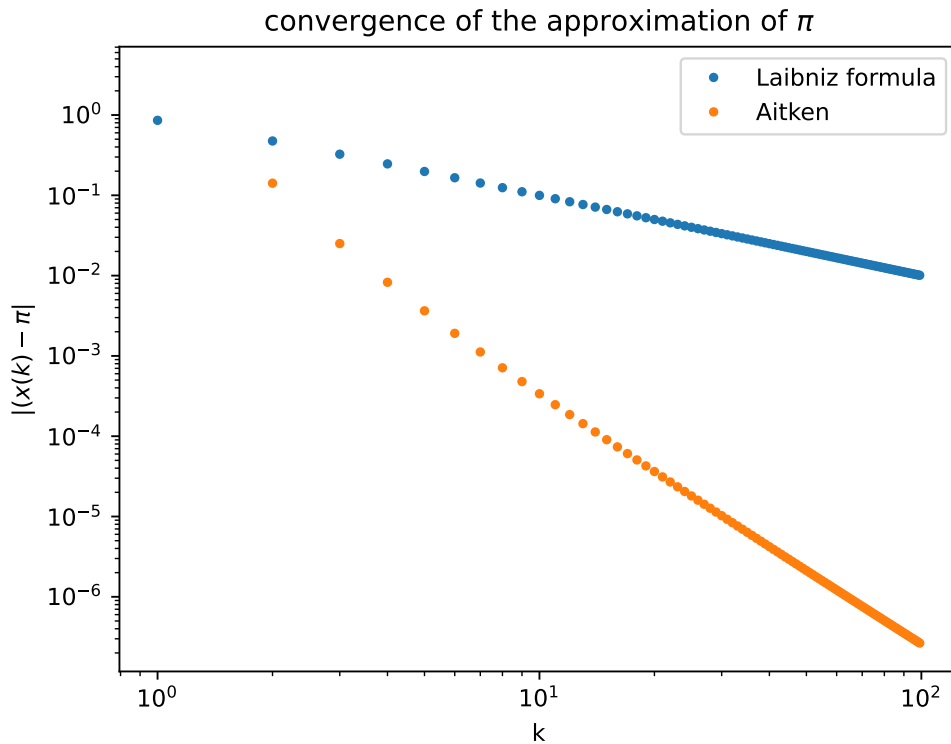


FIGURE 1 – Aitken's Δ^2 process accelerates the convergence to the π .

2 RICHARDSON EXTRAPOLATION

2.1 Presentation

We consider $(x_k)_{k \in \mathbb{N}}$ of points of \mathbb{R}^d and we assume that

$$x_k = x_* + \frac{1}{k} \Delta + \mathcal{O}\left(\frac{1}{k^2}\right) \quad (3)$$

Whith $\Delta \in \mathbb{R}^d$. Hence, $(x_k)_{k \in \mathbb{N}} \rightarrow x_*$.

Exercise 5: Show that for k even :

$$2x_k - x_{k/2} = x_* + \mathcal{O}\left(\frac{1}{k^2}\right) \quad (4)$$

Hence, the sequence defined by $y_k = 2x_k - x_{k/2}$ might converge faster to the limit x_* . This method is called Richardson extrapolation. This method is called Richardson extrapolation.

Exercise 6: Can Richardson extrapolation have a strong negative impact? what is the worst-case loss of performance?

2.2 Simulation in \mathbb{R}^2

Exercise 7: To get familiar with the method, apply it to your own sequence of points in \mathbb{R}^2 .

2.3 Application to logistic regression

When performing gradient descent, for instance on logistic regression, it is possible to average the obtained iterates $x_j \in \mathbb{R}^d$.

$$z_k = \frac{1}{k} \sum_{j=0}^{k-1} x_j \quad (5)$$

This provides robustness to noise, however the initial conditions are not forgotten very fast. A workaround is **tail-averaging**, which means only taking the last half of the iterates. If k is even, we then define a new sequence t_k .

$$t_k = \frac{1}{k/2} \sum_{j=k/1}^{k-1} x_j \quad (6)$$

Exercise 8: What is the link with Richardson extrapolation?

2.3.1 Simulation

Exercise 9: In some contexts, like logistic regression, as explained in [Bach, 2021], it is possible to show that the sequence z verifies 3. Run a simulation that applied the method and look for a configuration where Richardson extrapolation accerlerates convergence.

You have some useful functions for logistic regression in TP4.

RÉFÉRENCES

[Bach, 2021] Bach, F. (2021). On the Effectiveness of Richardson Extrapolation in Data Science. SIAM Journal on Mathematics of Data Science, 3(4) :1251–1277.