

The background of the slide features a large, faint, circular seal of the University of Gothenburg. The seal contains a lion holding a sword and a book, with the Latin text "SIGILLVM • VNIVERSITATIS • GOTHORVM • CAROLINÆ • AD VT RVMQVE" and the year "1666".

# **Labs in Julia**

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# The goal (Educational)

- Allow students to actually write a controller
- Simple and understandable interface for a student
- Not locked to the LabComputers! It should be possible to run the same controller and code:
  - In simulation at home
  - With the hardware at the lab



# The goal (Developer perspective)

- Easy and understandable to implement code to run a lab
- Simple to define a new process
- Interface that works with different hardware interfaces:
  - Comedi.c
  - BeagleBone
  - Moberg
- Maintenance



# Interface for labs

- BallAndBeam (SysId lab)  
`gitlab.control.lth.se/processes/BallAndBeam.jl`
- LabProcesses (Implementation of processes)  
`gitlab.control.lth.se/processes/LabProcesses.jl`
- LabConnections (Communication protocol, branch julia1)  
`gitlab.control.lth.se/labdev/LabConnections.jl`
- Hardware Implementations

BallAndBeam.jl (Lab SysId)

**Exports:**

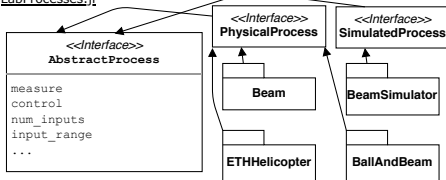
prbs\_experiment

**Code Example:**

```
P = Beam()

@periodically h begin
    y=measure(P)
    u=K*(r-y)
    control(P,u[i])
end
```

LabProcesses.jl

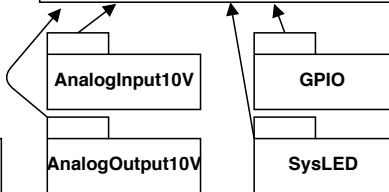
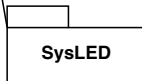
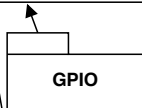
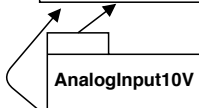
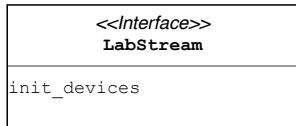


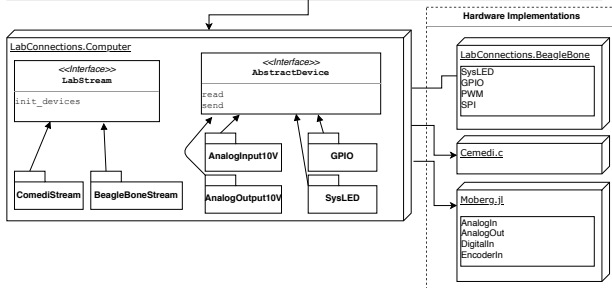
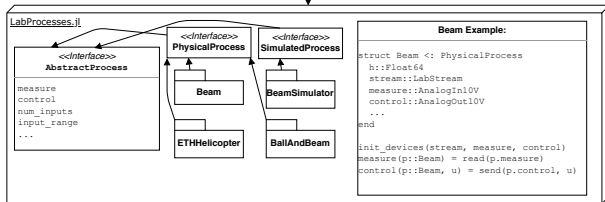
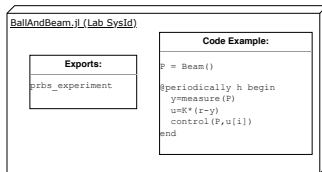
#### Beam Example:

```
struct Beam <: PhysicalProcess
    h::Float64
    stream::LabStream
    measure::AnalogIn10V
    control::AnalogOut10V
    ...
end

init_devices(stream, measure, control)
measure(p::Beam) = read(p.measure)
control(p::Beam, u) = send(p.control, u)
```

## LabConnections.Computer









What we have:

- Processes, what we have:
  - ETHHelicopter (julia 1?)
  - Beam/BallAndBeam/BeamSimulator
  - DoubleTank (in DoubleTankLab/DoubleTankSimulator, is it working? julia1? GUI exists)
- Ideas for more Processes:
  - Linear Servo with Pendulum (Already part of lab already in julia, needs hardware connection and MPC controller)
  - Furuta Pendulum (Needs everything)
  - Throttle (Needs everything)
  - Linear Servo (Martin H?)
- Other things:
  - Implement MobergStream
  - Your ideas?



## Other

Note: Building julia yourself can speed up computations!

Searching packages: `pkg.julialang.org`

Notable Packages (Not mentioned so far in course):

Documentation: `Documenter.jl`

Saving Data: `JLD.jl`, `HDF5.jl`, Matlab: `MAT.jl`

Data: `DataFrames.jl`, `Missings.jl`

3D graphics: `Makie.jl`

Plots: `Gadfly.jl`, `Winston.jl`

Graphs: `LightGraphs.jl`, `Graphs.jl`

Maths: `Interpolations.jl`

Reactive Programming: `Reactive.jl`

Web Servers: `Escher.jl`, `Genie.jl`

Calling Python: `PyCall.jl`

Calling C functions: `docs.julialang.org/en/v1/base/c/`

Sockets: `docs.julialang.org/en/v1/stdlib/Sockets`