## Antipatterns and idiomatic Julia versions

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#### Introduction

How to use multiple dispatch to structure your code Some common patterns and anti-patterns

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#### Code reuse

- Julia is excellent on code reuse
  - Interoperability between packges and types
  - In your own code
- Requires good and thoughtful design!

```
class Shape:
   @property
   def name(self):
        return self.__class__
class Rectangle(Shape): pass
class Ellipse(Shape): pass
def intersect(s1, s2):
   if isinstance(s1, Rectangle) and isinstance(s2, Ellipse):
        print('Rectangle x Ellipse [names s1=%s, s2=%s]' % (s1.name, s2.name))
   elif isinstance(s1, Rectangle) and isinstance(s2, Rectangle):
        print('Rectangle x Rectangle [names s1=%s, s2=%s]' % (s1.name, s2.name))
   else:
        # Generic shape intersection.
        print('Shape x Shape [names s1=%s, s2=%s]' % (s1.name, s2.name))
```

Drawback: To implement a new geometry, the user has to modify the source code pf intersect

Can only dispatch based on one argument

```
abstract type AbstractShape end
struct Rectangle <: AbstractShape end
struct Ellipse <: AbstractShape end</pre>
```

```
intersect(s1::Rectangle, s2::Ellipse) = do_something...
intersect(s1::Rectangle, s2::Rectangle) = do_something...
intersect(s1, s2) = do something...
```

Benefit: The user can send in ar arbitrary existing subtype of AbstractShape as well as creating new such subtypes without modifying the function intersect

Can dispatch based on both types.

## Dispatch on strings

Antipatter

```
function process(data, preprocess="sumtol")
   if preprocess == "sumtol"
      data = data ./ sum(data)
   elseif preprocess == "norm1"
      data = data ./ norm(data)
   elseif preprocess == "filter"
      data = filter(data)
   end
   do_something_with(data)
end
```

Drawback: To implement a new form of preprocessing, the user has to modify the source code pf process

## Dispatch on strings

Functional approac

```
function process(data, preprocess)
   data = preprocess(data)
   do_something_with(data)
end
```

Benefit: The user can send in an arbitrary function

```
abstract type AbstractPreprocesser end
struct SumToOne <: AbstractPreprocesser end</pre>
preprocess(::SumToOne, data) = data ./ sum(data)
struct NormOne <: AbstractPreprocesser end</pre>
preprocess(::NormOne, data) = data ./ norm(data)
struct Filter <: AbstractPreprocesser</pre>
    cutoff
end
preprocess(f::Filter, data) = filter(data, f.cutoff)
function process(data, processor)
    data = preprocess(processor, data)
    do something_with(data)
end
```

Benefit: The user can send in an arbitrary existing subtype of AbstractPreprocesser as well as creating new such subtypes without modifying the function preprocess.

### Several names for the same function

Antipatter

```
function optimize qd(problem, x)
    for i in iterations
        x = take qd step(x, problem)
        convergence check x(x) && break
        convergence check gradient(x, problem) && break
        convergence check funval(x) && break
   end
    х
end
function optimize bfqs(problem, x)
    for i in iterations
        x = take bfgs step(x, problem)
        convergence check x(x) && break
        convergence check gradient(x, problem) && break
        convergence check funval(x) && break
   end
    x
end
function optimize newton(problem, x)
    for i in iterations
        x = take newton step(x, problem)
        convergence check x(x) && break
        convergence check gradient(x, problem) && break
        convergence check funval(x) && break
```

Drawback: The *function* is the same, it find the optimum, what differs is the *method*.

The different names are only used for dispatch. Lots of code is repeated, all algorithms have the same structure.

### Several names for the same function

Multiple dispatch approach

```
abstract type AbstractOptimizer end
struct GradientDescent <: AbstractOptimizer</pre>
   stepsize
end
struct BFGS <: AbstractOptimizer end</pre>
struct Newton <: AbstractOptimizer</pre>
   preconditioner
end
step(::GradientDescent, x, problem) = take qd step(x, problem)
step(::BFGS, x, problem) = take bfgs step(x, problem)
step(f::Newton, x, problem) = take newton step(x, problem)
function process(problem, x, algorithm)
   for i in iterations
        x = step(algorithm, x, problem)
        convergence check x(x) && break
        convergence check gradient(x, problem) && break
        convergence check funval(x) && break
   end
```

Benefit: The outer algorithm is on implemented once, the behaviour differs is the step, dispatched using

No need to copy the code in outer to implement a new optimization

end

## Other antipatterns

#### Antipatterns

```
repmat(v,1,10) .* A
for i ∈ collect(1:100)
randn(10,1)
0
Vector{typeof(x)}(undef, length(x))
mean(x.^2)
f(x::Float64) = x^2
middle(x::Vector) = x[end+2]
```

Functions that operate elementwise over arrays Rolling your own types

### Nice patterns

```
v .* A
for i ∈ 1:100
randn(10)
zero(x)
similar(x)
mean(abs2, x)
f(x) = x^2
middle(x::AbstractVector) = x[end÷2]
```

Broadcast a scalar function Reusing ecosystem types

# Common Julia idioms and types

condition && return x

### Packages implementing commonly used types

- Colors.jl
- Distances.jl
- RecipesBase.jl
- ChainRules.jl