Efficient spectral collocation method for tempered fractional differential equation

赵廷刚

山东理工大学数学与统计学院

2023年8月7日





- Motiviations and Aims
- 2 Definitions

- 3 Spectral collocation Method
- 4 Numerical tests
- **5** Summary
- 6 References

- 1 Motiviations and Aims
- 2 Definitions

0000

- 3 Spectral collocation Method
- 4 Numerical tests
- **5** Summary
- 6 References

- Why "tempered"? The fractional sub-diffusive and/or superdiffusive models, based on the continuous time random walk (CTRW) model with the power law waiting time distribution having divergent first moment and/or the power law jump length distribution having divergent second moment.
- Efficient numerical method are required to solve the tempered equation, then to extend and dig out the potential applications of the tempered dynamics.
- Mathematically, the common-used fractional calculus is the special case of the tempered fractional calculus with the parameter $\kappa=0$.



Related works

Motiviations and Aims

- (2015) F. Sabzikar, M.M. Meerschaert, J.H. Chen, Tempered fractional calculus, J. Comput. Phys. ;...
- FDM/FEM: Li and Deng(Adv. Comput. Math. 2016); Wang and Li(Appl. Math. Lett. 2022); Deng and Zhang(NMPDEs. 2018); Chen and Deng(Appl. Math. Lett. 2017); Ding and Li(J. Sci. Comput. 2019); Guo et al. (SIAM J. Sci. Comput. 2019); Cao et al.(J. Sci. Comput. 2020);...
- LDG: Sun et al.(Appl. Math. Comput. 2020); Safari et al.(J. Sci. Comput. 2022);
- Multigrid: Bu and Oosterlee(Fractal Fract. 2021);...
- Spectral method: M. Zayernourt, M. Ainsworkth, G.E. Karniadakis (SIAM J. Sci. Comput. 2015); Hanert and Piret(SIAM J. Sci. Comput. 2015); Chen et al.(J. Sci. Comput. 2018); Huang et al.(J. Sci. Comput. 2018)...
- Others ...



5 / 47

Aims

Motiviations and Aims

we aim to develop a high accuracy spectral collocation method which uses the tempered fractional Jacobi functions (TFJFs) as the basis functions for solving TFD equations. The main contributions of this work are as follows:

- [†] We define the TFJFs and derive the approximation results of orthogonal projection and interpolation based on the TFJFs.
- † We derive the differentiation matrix of the tempered fractional Caputo derivative and give a fast and stable evaluation method based on recurrence relationship.
- † We demonstrate the effectiveness of the proposed spectral collocation method for the initial or boundary value problems, i.e., the fractional Helmholtz equation, and the fractional Burgers equation.



- 2 Definitions

- **5** Summary

For $\kappa \geq 0$, the left and right tempered fractional integrals of function u(t) on (a,b) of order $\mu>0$ are defined, respectively, by

$$_{a}\mathrm{I}_{t}^{\mu,\kappa}u(t):=rac{1}{\Gamma(\mu)}\int_{a}^{t}rac{e^{-\kappa(t-s)}u(s)}{(t-s)^{1-\mu}}\mathrm{d}s,$$

and

Motiviations and Aims

$$_{t}\mathrm{I}_{b}^{\mu,\kappa}u(t):=rac{1}{\Gamma(\mu)}\int_{t}^{b}rac{e^{-\kappa(s-t)}u(s)}{(s-t)^{1-\mu}}\mathrm{d}s,$$

where $\Gamma(\cdot)$ is the Euler Gamma function.



定义 (tempered R-L, Caputo fractional derivatives)

For $\kappa \geq 0$, the left and right tempered Riemman-Liouville, Caputo fractional derivatives of function u(t) on (a,b) of order $\mu>0$ are defined, respectively, by

$$\begin{array}{lll}
R_{a}^{\mu,\kappa}D_{t}^{\mu,\kappa}u(t):&=&\frac{e^{-\kappa t}}{\Gamma(n-\mu)}\frac{\mathrm{d}^{n}}{\mathrm{d}t^{n}}\int_{a}^{t}\frac{e^{\kappa s}u(s)}{(t-s)^{\mu-n+1}}\mathrm{d}s, \\
R_{t}^{\mu,\kappa}D_{b}^{\mu,\kappa}u(t):&=&\frac{e^{\kappa t}}{\Gamma(n-\mu)}\frac{\mathrm{d}^{n}}{\mathrm{d}t^{n}}\int_{t}^{b}\frac{e^{-\kappa s}u(s)}{(s-t)^{\mu-n+1}}\mathrm{d}s, \\
C_{a}^{\mu,\kappa}D_{t}^{\mu,\kappa}u(t):&=&\frac{e^{-\kappa t}}{\Gamma(n-\mu)}\int_{a}^{t}\frac{(e^{\kappa s}u(s))^{(n)}}{(t-s)^{\mu-n+1}}\mathrm{d}s, \\
C_{t}^{\mu,\kappa}D_{b}^{\mu,\kappa}u(t):&=&\frac{(-1)^{n}e^{\kappa t}}{\Gamma(n-\mu)}\int_{t}^{b}\frac{(e^{-\kappa s}u(s))^{(n)}}{(s-t)^{\mu-n+1}}\mathrm{d}s
\end{array}$$

where $n-1 < \mu \leq n$.



If $\kappa \equiv 0$, then the left and right tempered fractional calculus reduce to the left and right (non-tempered) fractional calculus, denoted by ${}_a I_t^\mu, \ {}_t I_b^\mu, \ {}_a^R D_t^\mu, \ {}_t^R D_b^\mu, \ {}_a^C D_t^\mu$ and ${}_t^C D_b^\mu$, respectively. Then we have

$$\label{eq:local_substitute} \begin{split} {}_{a}\mathrm{I}_{t}^{\mu,\kappa}u(t) &= e^{-\kappa t} \ {}_{a}\mathrm{I}_{t}^{\mu}(e^{\kappa t}u(t)), \qquad {}_{t}\mathrm{I}_{b}^{\mu,\kappa}u(t) = e^{\kappa t} \ {}_{t}\mathrm{I}_{b}^{\mu}(e^{-\kappa t}u(t)), \\ {}_{a}^{R}\mathrm{D}_{t}^{\mu,\kappa}u(t) &= e^{-\kappa t} \ {}_{a}^{R}\mathrm{D}_{t}^{\mu}(e^{\kappa t}u(t)), \quad {}_{t}^{R}\mathrm{D}_{b}^{\mu,\kappa}u(t) = e^{\kappa t} \ {}_{t}^{R}\mathrm{D}_{b}^{\mu}(e^{-\kappa t}u(t)), \\ {}_{a}^{C}\mathrm{D}_{t}^{\mu,\kappa}u(t) &= e^{-\kappa t} \ {}_{a}^{C}\mathrm{D}_{t}^{\mu}(e^{\kappa t}u(t)), \quad {}_{t}^{C}\mathrm{D}_{b}^{\mu,\kappa}u(t) = e^{\kappa t} \ {}_{t}^{C}\mathrm{D}_{b}^{\mu}(e^{-\kappa t}u(t)). \end{split}$$

Similar to the corresponding non-tempered case, for $0<\mu<1$ and u(t) be absolutely continuous in [a,b], the relations between Riemann-Liouville and Caputo derivatives are

$${}_{a}^{R}D_{t}^{\mu,\kappa}u(t) = {}_{a}^{C}D_{t}^{\mu,\kappa}u(t) + \frac{1}{\Gamma(1-\mu)}e^{-\kappa t}(t-a)^{-\mu}u(a), \qquad (1)$$

and

Motiviations and Aims

$${}_{t}^{R} \mathcal{D}_{b}^{\mu,\kappa} u(t) = {}_{t}^{C} \mathcal{D}_{b}^{\mu,\kappa} u(t) + \frac{1}{\Gamma(1-\mu)} e^{-\kappa t} (b-t)^{-\mu} u(b). \tag{2}$$

4 D > 4 A > 4 B > 4 B > B = 990

Denote $\mathbb{P}_N(I)$ the space of all algebraic polynomials with degree at most N defined on I =: (-1,1). Let $P_n^{\alpha,\beta}(s)$ $(\alpha,\beta > -1), s \in I$ be the Jacobi orthogonal polynomials satisfying:

$$\int_{-1}^{1} P_{n}^{\alpha,\beta}(s) P_{m}^{\alpha,\beta}(s) \omega^{\alpha,\beta}(s) ds = \gamma_{n}^{\alpha,\beta} \delta_{mn}, \tag{3}$$

定义 (Tempered Fractional Jacobi Function)

Define the TFJFs by

$$J_{n,l}^{\alpha,\beta,\delta,\kappa}(s) =: e^{-\kappa s} (1+s)^{\delta} P_n^{\alpha,\beta}(s), \quad J_{n,r}^{\alpha,\beta,\delta,\kappa}(s) =: e^{\kappa s} (1-s)^{\delta} P_n^{\alpha,\beta}(s),$$

for $s \in I$, $n = 0, 1, \cdots$.



The tempered fractional derivatives of the TFJFs can also be represented by the same class of functions.

定理

Motiviations and Aims

For n > 0, there holds

$$\begin{array}{l}
R_{-1}D_{s}^{\mu,\kappa}\left(J_{n,l}^{\alpha,\beta,\beta,\kappa}(s)\right) = \lambda_{n}^{\beta,\mu}J_{n,l}^{\alpha+\mu,\beta-\mu,\beta-\mu,\kappa}(s), \quad \alpha \in \mathbb{R}, \ \beta > \mu - 1. \\
R_{s}D_{1}^{\mu,\kappa}\left(J_{n,r}^{\alpha,\beta,\alpha,\kappa}(s)\right) = \lambda_{n}^{\alpha,\mu}J_{n,r}^{\alpha-\mu,\beta+\mu,\alpha-\mu,\kappa}(s), \quad \alpha > \mu - 1, \ \beta \in \mathbb{R}.
\end{array}$$

where

$$\lambda_n^{\beta,\mu} = \frac{\Gamma(n+\beta+1)}{\Gamma(n+\beta-\mu+1)}.$$



山东理工大学数学与统计学院

- Spectral collocation Method
- **5** Summary

Numerical tests

- Motiviations and Aims
- 2 Definitions
- 3 Spectral collocation Method Projections and Interpolations Differentiation Matrix
- 4 Numerical tests
- Summary
- 6 References



Discrete subspace

We introduce the (N + 1)-dimensional spaces of the TFJFs as:

$$\mathbb{F}_{N,l}^{\delta,\kappa} := e^{-\kappa s} (1+s)^{\delta} \mathbb{P}_N = \text{span} \left\{ J_{0,l}^{\alpha,\beta,\delta,\kappa}, J_{1,l}^{\alpha,\beta,\delta,\kappa}, \cdots, J_{N,l}^{\alpha,\beta,\delta,\kappa} \right\},$$

and

$$\mathbb{F}_{N,r}^{\delta,\kappa} := e^{\kappa s} (1-s)^{\delta} \mathbb{P}_N = \operatorname{span} \left\{ J_{0,r}^{\alpha,\beta,\delta,\kappa}, J_{1,r}^{\alpha,\beta,\delta,\kappa}, \cdots, J_{N,r}^{\alpha,\beta,\delta,\kappa} \right\}.$$

山东理工大学数学与统计学院

Let $\alpha, \beta > -1$. Denote $\mathbf{P}_{N,I}^{\delta,\kappa}: L^2_{\varpi_i^{\alpha,\beta,\delta,\kappa}}(I) \to \mathbb{F}_{N,I}^{\delta,\kappa}$ as the orthogonal projection such that

$$(\mathbf{P}_{N,I}^{\delta,\kappa}u-u,v)_{\varpi_{I}^{\alpha,\beta,\delta,\kappa}}=0\quad\forall v\in\mathbb{F}_{N,I}^{\delta,\kappa},\tag{4}$$

and $\mathbf{P}_{N,r}^{\delta,\kappa}: L^2_{-\alpha,\beta,\delta,\kappa}(I) \to \mathbb{F}_{N,r}^{\delta,\kappa}$ as the orthogonal projection such that

$$(\mathbf{P}_{N,r}^{\delta,\kappa}u-u,v)_{\varpi_r^{\alpha,\beta,\delta,\kappa}}=0\quad\forall v\in\mathbb{F}_{N,r}^{\delta,\kappa}.$$
 (5)

Error of the projections

For describe the projection error, we define

$$\begin{split} \check{\mathcal{B}}^{\nu}_{\alpha,\beta,\delta,l}(I) &:= \left\{ u \in L^{2}_{\varpi_{l}^{\alpha},\beta,\delta,\kappa}(I) : {}^{R}_{-1}\mathrm{D}^{\mu,\kappa}_{s}u \in L^{2}_{\varpi_{l}^{\alpha+\mu},\beta-\mu,\delta-\mu,\kappa}(I), \quad 0 \leq \mu \leq \nu \right\}, \\ \check{\mathcal{B}}^{\nu}_{\alpha,\beta,\delta,r}(I) &:= \left\{ u \in L^{2}_{\varpi_{r}^{\alpha},\beta,\delta,\kappa}(I) : {}^{R}_{s}\mathrm{D}^{\mu,\kappa}_{1}u \in L^{2}_{\varpi_{r}^{\alpha-\mu},\beta+\mu,\delta-\mu,\kappa}(I), \quad 0 \leq \mu \leq \nu \right\}. \end{split}$$

定理 (Error estimate of the projections)

Let
$$\alpha > -1, \beta > \nu - 1, 0 \le \mu \le \nu$$
. For any $u \in \check{B}^{\nu}_{\alpha,\beta,\beta,l}(I)$,

$$\|_{-1}^R \mathrm{D}_s^{\mu,\kappa} (\mathbf{P}_{N,l}^{\beta,\kappa} u - u)\|_{\varpi_l^{\alpha+\mu,\beta-\mu,\beta-\mu,\kappa}} \leq c N^{\mu-\nu} \|_{-1}^R \mathrm{D}_s^{\nu,\kappa} u\|_{\varpi_l^{\alpha+\nu,\beta-\nu,\beta-\nu,\kappa}}.$$

and for
$$\alpha > \nu - 1, \beta > -1, u \in \check{B}^{\nu}_{\alpha,\beta,\alpha,r}(I)$$
,

$$\|_s^R \mathrm{D}_1^{\mu,\kappa} (\mathbf{P}_{N,r}^{\alpha,\kappa} u - u)\|_{\varpi_r^{\alpha-\mu,\beta+\mu,\alpha-\mu,\kappa}} \leq c N^{\mu-\nu} \|_s^R \mathrm{D}_1^{\nu,\kappa} u\|_{\varpi_r^{\alpha-\nu,\beta+\nu,\alpha-\nu,\kappa}}.$$

Interpolations

Motiviations and Aims

Denote $\{\xi_i\}_{i=0}^N$ as the Jacobi-Gauss-Lobatto points(JGL) in \overline{I} . For a function $u(s) \in C(I)$ which satisfies that $e^{\kappa s}(1+s)^{-\delta}u(s)$ being continuous on \overline{I} for some $\delta > -1$, we define the interpolation operator $\Pi_{N,I}^{\delta,\kappa}: C(I) \to \mathbb{F}_{N,I}^{\delta,\kappa}$ at given nodes $\{\xi_i\}_{i=0}^N$ as

$$\Pi_{N,l}^{\delta,\kappa}u(s)=u(s), \quad s=\xi_i, \ i=0,1,\cdots,N. \tag{6}$$

Similarly, a function $u(s) \in C(I)$ which satisfies that $e^{-\kappa s}(1-s)^{-\delta}u(s)$ being continuous on \overline{I} for some $\delta > -1$, we define the interpolation operator $\Pi_{N,r}^{\delta,\kappa}:C(I)\to \mathbb{F}_{N,r}^{\delta,\kappa}$ at the same nodes $\{\xi_i\}_{i=0}^N$ as

$$\Pi_{N,r}^{\delta,\kappa}u(s)=u(s), \quad s=\xi_i, \ i=0,1,\cdots,N. \tag{7}$$



定理 (Error estimate of the interpolations)

For
$$\alpha, \beta > \nu - 1$$
 and $0 \le \mu \le \nu$. If $u \in \check{B}^{\nu}_{\alpha,\beta,\beta,l}(I)$, then

$$\|_{-1}^{R} \mathrm{D}_{s}^{\mu,\kappa} (\Pi_{N,I}^{\beta,\kappa} u - u)\|_{\varpi_{I}^{\alpha+\mu,\beta-\mu,\beta-\mu,\kappa}} \leq c N^{\mu-\nu} \|_{-1}^{R} \mathrm{D}_{s}^{\nu,\kappa} u\|_{\varpi_{I}^{\alpha+\nu,\beta-\nu,\beta-\nu,\kappa}},$$

and if
$$u \in \check{B}^{\nu}_{\alpha,\beta,\alpha,r}(I)$$
, then

$$\|_{s}^{R} \mathrm{D}_{1}^{\mu,\kappa} (\Pi_{N,r}^{\alpha,\kappa} u - u)\|_{\varpi_{r}^{\alpha-\mu,\beta+\mu,\alpha-\mu,\kappa}} \leq c N^{\mu-\nu} \|_{s}^{R} \mathrm{D}_{1}^{\nu,\kappa} u\|_{\varpi_{r}^{\alpha-\nu,\beta+\nu,\alpha-\nu,\kappa}}.$$

Definitions

- 3 Spectral collocation Method Projections and Interpolations Differentiation Matrix
- 4 Numerical tests
- Summary
- 6 References



The tempered fractional Lagrange interpolate basis

Let $\{L_i(s)\}_{i=0}^N$ be the Lagrange interpolation basis functions with respect to the nodes $\{\xi_i\}_{i=0}^N$. The tempered fractional Lagrange interpolation basis functions are defined by

$$F_{i,l}^{\delta,\kappa}(s) := e^{-\kappa(s-\xi_i)} \left(\frac{1+s}{1+\xi_i}\right)^{\delta} L_i(s), \quad i = 0, 1, 2, \cdots, N, \quad (8)$$

which satisfies $F_{i,l}^{\delta,\kappa}(\xi_k) = \delta_{ik}$.

The tempered fractional Lagrange interpolation basis functions are defined by

$$F_{i,r}^{\delta,\kappa}(s) := e^{\kappa(s-\xi_i)} \left(\frac{1-s}{1-\xi_i}\right)^{\delta} L_i(s), \quad i = 0, 1, 2, \cdots, N, \quad (9)$$

which satisfies $F_{i,r}^{\delta,\kappa}(\xi_k) = \delta_{ik}$.



The differentiation matrix of left tempered Caputo derivative is:

The differentiation matrix of left tempered Caputo derivative is

$$\left[\mathbf{D}_{s,l}^{\mu,\kappa}\right]_{(N+1)\times(N+1)} := \left({}^{\mathsf{C}}_{-1} \mathrm{D}_{s}^{\mu,\kappa} \mathsf{F}_{i,l}^{\delta,\kappa}(\xi_{k}) \right)_{k,i=0}^{N}.$$

$${}^{C}_{-1}\mathrm{D}^{\mu,\kappa}_{s}F^{\delta,\kappa}_{i,l}(s) = \frac{e^{\kappa\xi_{i}}}{(1+\xi_{i})^{\delta}} \sum_{j=0}^{N} I_{ij} {}^{C}_{-1}\mathrm{D}^{\mu,\kappa}_{s}J^{\alpha,\beta,\delta,\kappa}_{i,l}(s). \tag{10}$$

where
$$I_{ij}=rac{P_j^{lpha,eta}(\xi_i)\omega_i}{\gamma_j^{lpha,eta}}(j=0,1,\cdots,N-1), \quad I_{iN}=rac{P_N^{lpha,eta}(\xi_i)\omega_i}{\left(2+rac{lpha+eta+1}{N}
ight)\gamma_N^{lpha,eta}}.$$

The differentiation matrix of right tempered Caputo derivative is:

$$\left[\mathbf{D}_{s,r}^{\mu,\kappa}\right]_{(N+1)\times(N+1)} := \left(\begin{smallmatrix} c \\ s \end{smallmatrix} \mathbf{D}_{1}^{\mu,\kappa} F_{i,r}^{\delta,\kappa}(\xi_{k})\right)_{k,i=0}^{N}.$$

We have the similar formula as (10) for right case.



Fast evaluation of the DM

Denote

$$S_{n,\alpha,\beta,l}^{\delta,\kappa,\mu}(s) := {}_{-1}I_s^{\mu,\kappa}\left(J_{n,l}^{\alpha,\beta,\delta,\kappa}(s)\right)$$

$$= \frac{1}{\Gamma(\mu)} \int_{-1}^{s} (s-t)^{\mu-1} e^{-\kappa(s-t)} J_{n,l}^{\alpha,\beta,\delta,\kappa}(t) dt.$$
(11)

Numerical tests

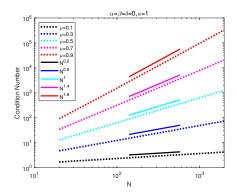
定理 (Recurrence relationship)

Let
$$\alpha, \beta, \delta > -1$$
 and $\mu > 0, s \in I$. Then $S_{n,l} := S_{n,\alpha,\beta,l}^{\delta,\kappa,\mu}(s)$ and $\widehat{S}_{n,l} := \mu S_{n,\alpha,\beta,l}^{\delta,\kappa,\mu+1}(s)$ satisfy

$$S_{n+1,l} = (A_n^{\alpha,\beta} s - B_n^{\alpha,\beta}) S_{n,l} - C_n^{\alpha,\beta} S_{n-1,l} - A_n^{\alpha,\beta} \widehat{S}_{n,l}, \ n \ge 1$$

$$\widehat{S}_{n+1,l} = \widetilde{A}_n \widehat{S}_{n,l} - \widetilde{B}_n \widehat{S}_{n-1,l} + (1+s) \left(\widetilde{a}_n S_{n-1,l} + \widetilde{b}_n S_{n,l} + \widetilde{c}_n S_{n+1,l} \right), \ n \geq 1$$

with the starting terms $S_{0,I}$, $\widehat{S}_{0,I}$, $S_{1,I}$, $\widehat{S}_{1,I}$.



S 1: Condition number of DMLTCD with $0 < \mu < 1, \alpha = \beta = 0, \delta = 0, \kappa = 1$.



- 4 Numerical tests
- **5** Summary

Application to Fractional ordinary differential equation

Let $0<\mu<1.$ We apply the spectral collocation method to the initial value problem of nonlinear fractional ordinary differential equation

$$\begin{cases}
 ^{C}D_{x}^{\mu,\kappa}u(x) = f(x,u), & 0 < x \leq T, \\
 u(0) = u_{0}.
\end{cases}$$
(12)

The spectral collocation method based on the TFJFs for (12) is to find $u_N \in \mathbb{F}_{N,l}^{\delta,\kappa}$ such that for $x = x_j^{\alpha,\beta} = \frac{T(1+\xi_j)}{2}, \quad j=1,2,\cdots,N,$

$${}_{0}^{C}\mathrm{D}_{x}^{\mu,\widetilde{\kappa}}u_{N}(x)=f(x,u_{N}(x)),\tag{13}$$

and

$$u_N(0) = u_0. (14)$$



Application to Fractional ordinary differential equation

The above two equations lead to the following system

$$\left(\frac{2}{T}\right)^{\mu} \overline{\mathbf{D}}_{s,l}^{\mu,\widetilde{\kappa}} \mathbf{u} = \mathbf{f}(\mathbf{u}), \tag{15}$$

Numerical tests

Consider (12) and $f(x, u) = g(x) - u^2$, where g(x) is determined by

$$g(x) = u^2 + {}_0^C D_x^{\mu,\kappa} u(x).$$

In this example, the Newton method is applied to solving the nonlinear system (15), which takes the following form:

$$\mathbf{u}^{n+1} = \mathbf{u}^n + (\mathbf{D} + 2\operatorname{diag}(\mathbf{u}^n))^{-1} (\mathbf{D}\mathbf{u}^n + \mathbf{u}^n \cdot \mathbf{u}^n - \mathbf{g}), \quad n = 0, 1, \dots,$$

where
$$\mathbf{g} = [g(x_1^{\alpha,\beta}), g(x_2^{\alpha,\beta}), \cdots, g(x_N^{\alpha,\beta})]^T$$
 and $\mathbf{D} = (\frac{2}{T})^{\mu} \overline{\mathbf{D}}_{s,I}^{\mu,\widetilde{\kappa}}$.

Numerical results to fractional ordinary differential equation

C1.
$$u(x) = e^{-\kappa x}(x^2 - x)$$
 with $T = 5$.

C2.
$$u(x) = e^{-\kappa x} \left(x^8 - 3x^{4+\mu/2} + \frac{9}{4}x^{\mu} \right)$$
 with $T = 1$.

表 1: The numerical errors E_0 with C2 solution $(lpha=0,eta=0,\kappa=1)$

N(1/h)	$\mid~\mu=\text{0.2[5]}$	$\mu =$ 0.2	$\mu=0.5[5]$	$\mu = 0.5$	$\mu=0.9[5]$	$\mu=$ 0.9
10	5.81e-1	1.09e-07	2.44e-2	8.41e-07	7.77e-3	1.40e-06
20	2.00e-1	5.17e-10	6.38e-3	2.85e-09	1.44e-3	3.32e-09
40	6.50e-2	3.87e-13	2.82e-3	7.41e-12	6.00e-4	7.58e-12
80	8.35e-3	1.23e-13	3.84e-4	3.65e-13	1.52e-4	1.14e-13
160	4.72e-4	1.82e-11	2.23e-5	1.52e-12	1.54e-5	1.71e-13



Application to Helmholtz equation

Let $1<\mu<2$. We apply the spectral collocation method to the following fractional Helmholtz equation

$$\begin{cases} \lambda^2 u(x) - {}_a^C D_x^{\mu,\kappa} u(x) = f(x), & a < x < b, \\ u(a) = u_a, & u(b) = u_b. \end{cases}$$
 (16)

The spectral collocation method based on the TFJFs for (16) is to find $u_N \in \mathbb{F}_N^{\delta,\kappa}$ such that

$$\lambda^2 u_N(x) - {}^C_a D_x^{\mu,\kappa} u_N(x) = f(x), \quad x = x_j^{\alpha,\beta}, \quad j = 1, 2, \dots, N-1,$$
(17)

and

$$u_N(a) = u_a, \quad u_N(b) = u_b.$$
 (18)



Numerical errors for fractional Helmholtz equation

The source term f(x) is chosen such that the problem satisfies one of the following two cases:

- C1. Smooth solution: $u(x) = e^{-\kappa x} \sin(\pi x)$.
- C2. Solution with low regularity: $u(x) = e^{-\kappa x} \left[2^{\sigma+1} x^{\sigma} x^{2\sigma+1} \right]$.

表 2: The numerical errors E_0 with C1 solution $(\alpha=\beta=0,\delta=0,\kappa=1,\lambda=0)$

N	$\mu=1.1$	$\mu=$ 1.3	$\mu=1.5$	$\mu=1.7$	$\mu=$ 1.9	$\mu=$ 1.99
4	1.781e-01	1.191e-01	9.844e-02	1.091e-01	9.028e-02	4.519e-02
8	5.110e-04	3.488e-04	2.818e-04	2.931e-04	2.610e-04	4.833e-05
12	2.173e-07	1.373e-07	1.016e-07	1.448e-07	1.699e-07	3.235e-08
16	2.618e-11	1.550e-11	1.160e-11	1.732e-11	2.501e-11	5.182e-12
20	1.200e-14	1.299e-14	1.241e-14	1.474e-14	1.302e-14	1.258e-14

◆ロト ◆問 ト ◆ 恵 ト ◆ 恵 ・ 釣 へ ⊙

Numerical errors for fractional Helmholtz equation

表 3: The numerical errors E_0 with C1 solution $(\mu=1.4,\delta=0,\kappa=5,\lambda=2$

	N	$\alpha=\beta=0$	$\alpha = \beta =5$	$\alpha = -\beta = .5$	$(\alpha,\beta)=(3,.8)$	$\alpha=\beta=1$
	4	2.282e-02	2.901e-02	1.322e-02	2.338e-02	1.605e-02
	8	9.931e-05	5.828e-05	2.701e-05	3.397e-04	1.821e-04
	12	3.315e-08	2.504e-08	1.210e-08	1.889e-07	1.075e-07
	16	3.008e-12	2.379e-12	1.493e-12	2.353e-11	1.419e-11
:	20	1.174e-14	2.498e-15	1.443e-15	1.282e-14	2.776e-14

Numerical errors for fractional Helmholtz equation

表 4: The numerical errors E_0 with C1 solution $(\mu=1.6,\alpha=\beta=0,\delta=0,\lambda=1000)$

N	$ \kappa = 1$	$\kappa = 2$	$\kappa = 3$	$\kappa=5$	$\kappa = 8$	$\kappa=10$
4	2.131e-06	1.509e-06	1.068e-06	5.353e-07	1.900e-07	9.521e-08
8	3.355e-08	3.035e-08	2.745e-08	2.247e-08	1.663e-08	1.361e-08
12	3.806e-11	3.632e-11	3.467e-11	3.158e-11	2.745e-11	2.500e-11
16	9.076e-15	8.868e-15	8.618e-15	8.188e-15	7.522e-15	7.119e-15
20	2.220e-16	1.110e-16	1.110e-16	5.551e-17	2.082e-17	2.776e-17



Numerical errors for fractional Helmholtz equation

表 5: The numerical errors E_0 and the order of convergence Ord with C2 solution ($\sigma=1.4, \alpha=\beta=0, \delta=0, \kappa=1, \lambda=1$)

	$\mu = 1.1$		$\mu = 1.3$		$\mu = 1.5$		$\mu = 1.9$	
N	$ E_0 $	Ord	E ₀	Ord	E_0	Ord	<i>E</i> ₀	Ord
8	3.74e-2	-	4.30e-2	-	4.54e-2	-	2.32e-2	-
16	6.84e-3	2.45	8.42e-3	2.35	1.33e-2	1.77	1.35e-2	0.78
32	1.07e-3	2.67	1.88e-3	2.16	3.97e-3	1.75	7.14e-3	0.92
64	1.61e-4	2.74	4.12e-4	2.19	1.15e-3	1.79	3.63e-3	0.97
128	2.48e-5	2.69	8.96e-5	2.20	3.33e-4	1.79	1.83e-3	0.99
256	3.95e-6	2.65	1.95e-5	2.20	9.59e-5	1.80	9.17e-4	1.00
512	6.37e-7	2.63	4.25e-6	2.20	2.76e-5	1.80	4.59e-4	1.00

- 4ロト 4団ト 4 差ト 4 差ト 差 りQの

Numerical errors for fractional Helmholtz equation

表 6: The numerical errors E_0 and the order of convergence Ord with C2 solution ($\sigma=1.4, \alpha=\beta=0, \delta=0.4, \kappa=1, \lambda=1$)

	$\mu = 1.1$		$\mu = 1.3$		$\mu = 1.5$		$\mu = 1.9$	
N	E ₀	Ord	E_0	Ord	E ₀	Ord	E ₀	Ord
8	4.53e-05	-	1.45e-05	-	9.69e-06	-	5.74e-06	-
16	5.36e-07	6.40	1.07e-07	7.09	5.75e-08	7.40	3.73e-08	7.27
32	1.06e-08	5.66	7.20e-10	7.21	3.76e-10	7.26	2.17e-10	7.43
64	1.07e-10	6.63	4.43e-12	7.34	2.13e-12	7.47	1.18e-12	7.52
128	7.94e-14	10.40	6.14e-14	6.17	5.21e-14	5.35	4.95e-14	4.58



Application to Fractional Burgers equation

Consider the fractional Burgers equation (FBE),

$$\partial_t u(x,t) + u(x,t)\partial_x u(x,t) = \epsilon \, {}_{a}^{C} \operatorname{D}_{x}^{\mu,\kappa} u(x,t), \tag{19}$$

subject to $u(x,0) = u_0(x)$.

For time advancing, we employ Crank-Nicolson/leapfrog scheme. Then, the full discretization scheme reads as:

$$\begin{cases}
(\mathbb{I} - \epsilon \tau \widetilde{\mathbf{D}}) \mathbf{u}^{n+1} = (\mathbb{I} + \epsilon \tau \widetilde{\mathbf{D}}) \mathbf{u}^{n-1} - 2\tau (\operatorname{diag}(\mathbf{u}^n) \mathbf{D}) \mathbf{u}^n, & n \geq 1, \\
\mathbf{u}^1 = (\mathbb{I} + \epsilon \tau \widetilde{\mathbf{D}}) \mathbf{u}^0 - \tau (\operatorname{diag}(\mathbf{u}^0) \mathbf{D}) \mathbf{u}^0, \\
\mathbf{u}^0 = u_0(\mathbf{x}),
\end{cases} (20)$$

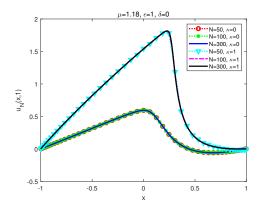
where **D** is the first-order differentiation matrix and $\widetilde{\mathbf{D}} = (\frac{2}{h-2})^{\mu} \widetilde{\mathbf{D}}_{\epsilon,I}^{\mu,\kappa}$. Consider (19) with the initial profile as one of the belows:

C1.
$$u_0(x) = \sin(\pi x), \quad x \in [-1, 1].$$

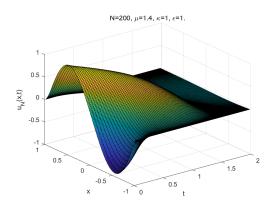
C2.
$$u_0(x) = e^{-4x^2}, x \in [-6, 6].$$

In the example, we always take $\alpha = \beta = 0, \tau = 10^{-3}$.



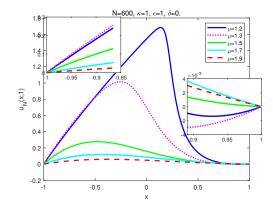




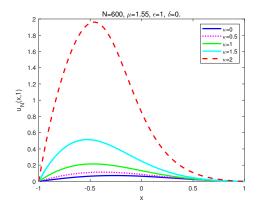


 \blacksquare 3: Numerical solutions of $u_0(x) = \sin(\pi x)$ with $\mu = 1.4, \epsilon = 1, N = 200, \alpha = \beta = 0, \tau = 10^{-3}$.

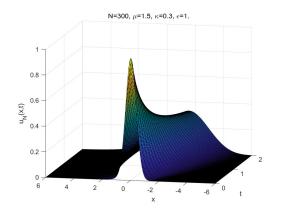




 \P 4: Numerical solutions at t=1 of $u_0(x)=\sin(\pi x)$ with $N=600, \epsilon=1, \alpha=\beta=0, \tau=10^{-3}$.

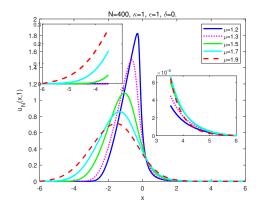


S 5: Numerical solutions at t=1 of $u_0(x)=\sin(\pi x)$ with $\epsilon=1, N=600, \alpha=\beta=0, \tau=10^{-3}$.



8 6: Numerical solutions of $u_0(x) = e^{-4x^2}$ with $N = 300, \mu = 1.5, \epsilon = 1, \alpha = \beta = 0, \tau = 10^{-3}$.

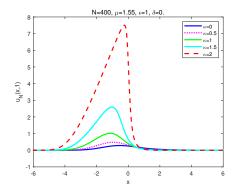




 \blacksquare 7: Numerical solutions at t=1 of $u_0(x)=e^{-4x^2}$ with $N=400, \kappa=1, \epsilon=1, \alpha=\beta=0, \tau=10^{-3}$.



Numerical tests



8 8: Numerical solutions at t = 1 of $u_0(x) = e^{-4x^2}$ with $N = 400, \mu = 1.55, \epsilon = 1, \alpha = \beta = 0, \tau = 10^{-3}$.



- 1 Motiviations and Aims
- 2 Definitions

- 3 Spectral collocation Method
- 4 Numerical tests
- **5** Summary
- 6 References

Summary

Motiviations and Aims

We present a spectral collocation method using the TFJFs as basis functions and obtain an efficient algorithm to solve tempered fractional differential equations. The key in implementing is to stably evaluate the collocation differentiation matrix by utilizing a recurrence relation.

- Advantages
 - High-accuracy, Fast
 - No difficulty for nonlinear problem, variable-order case
- Disadvantage
 - disable to deal with two-sided tempered fractional differential equation
 - hard to derive the error estimate.



- Motiviations and Aims
- 2 Definitions

- 3 Spectral collocation Method
- 4 Numerical tests
- **5** Summary
- **6** References

参考文献

- [1] Zhao TG. Efficient spectral collocation method for tempered fractional differential equation. *Fractal & Fractional* **2023**, 7, 27.
- [2] Shen J, Tang T, Wang LL. Spectral Methods: Algorithms, Analysis and Applications. Springer-Verlag, Berlin. (2011)
- [3] Zayernouri M, Ainsworth M, Karniadakis GE. Tempered fractional Sturm-Liouville eigenproblems. SIAM J. Sci. Comput. 2015, 37, A1777-A1800.
- [4] Chen S, Shen J, Wang LL. Generalized Jacobi functions and their applications to fractional differential equations. *Math. Comput.* **2016**, 85 (300), 1603-1638.
- [5] Deng JW, Zhao LJ, Wu YJ. Fast predictor-corrector approach for the tempered fractional differential equations. *Numer. Algor.* 2017, 74 (3), 717-754.
- [6] Li C, Deng WH, Zhao LJ. Well-posedness and numerical algorithm for the tempered fractional ordinary differential equations. *Disc. Cont. Dyn. Sys. B* **2019**, 24 (4), 1989-2015.

Thanks you!