

Continuity and Differentiability of Eigenvalues of Laplacian with respect to Domain Perturbations

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Motivation

Let $\Omega := (0, 1) \times (0, 1)$, and

$$\mathcal{T}_t(x) = x + \left(t + \frac{1}{2}t^2\right) \begin{pmatrix} x_1 + x_2 \\ -x_1 - x_2 \end{pmatrix}, \quad -0.1 \leq t \leq 0.1.$$

Then, $\Omega_t := \mathcal{T}_t(\Omega)$ looks like

We consider the eigenvalue problem

$$-\Delta u = \lambda u \quad \text{in} \quad \Omega_t, \quad u = 0 \quad \text{on} \quad \partial\Omega_t.$$

It has eigenvalues

$$0 < \lambda_1(t) \leq \lambda_2(t) \leq \cdots \leq \lambda_k(t) \leq \cdots.$$

Motivation 2

We would like to know if $\lambda_k(t)$ is continuous and differentiable.

Hadamard considered the problem under the conditions that $\partial\Omega$ is sufficiently smooth, and the perturbation is written as $t\rho(s)\boldsymbol{\nu}$, where $s \in \partial\Omega$, and $\boldsymbol{\nu}$ is the outer unit normal vector.

He found that $\lambda_1'(0)$ exists and is written as

$$\lambda_1'(0) = - \left\langle \frac{\partial u_1(0)}{\partial \boldsymbol{\nu}}, \rho \frac{\partial u_1(0)}{\partial \boldsymbol{\nu}} \right\rangle_{\partial\Omega}.$$

This is called the **Hadamard's variational formula** for the first eigenvalue. (P.R. Garabedian, *Partial Differential Equations*, 2nd edition, Chelsea. New York, 1986.)

We would like to consider this problem for any $\lambda_k(t)$ under the condition that $\partial\Omega$ is Lipschitz and the perturbation is in general form.

The Domain perturbations

$\Omega \subset \mathbb{R}^n$: a bounded domain with the Lipschitz (or $C^{0,1}$) boundary $\partial\Omega$ ($n \geq 2$).

$\mathcal{T}_t : \Omega \rightarrow \mathbb{R}^n$: bi-Lipschitz (or $C^{0,1}$) diffeomorphism such that

- $\mathcal{T}_0(x) = x$: identity map.
- \mathcal{T}_t is twice continuously differentiable w.r.t. t , and has the Taylor expansion

$$\mathcal{T}_t(x) = x + tS(x) + \frac{1}{2}t^2R(x) + o(t^2),$$

where S and R are Lipschitz vector fields.

Set $\Omega_t := \mathcal{T}_t(\Omega)$. Let $\tilde{\Omega} \subset \mathbb{R}^n$ be a sufficiently large domain such that $\Omega_t \subset \tilde{\Omega}$ for t , $|t| < \varepsilon$.

Let $\gamma^0, \gamma^1 \subset \partial\Omega$ such that $\overline{\gamma^0} \cup \overline{\gamma^1} = \partial\Omega$, $\gamma^0 \cap \gamma^1 = \emptyset$. We set

$$\gamma_t^i := \mathcal{T}_t(\gamma^i), \quad i = 0, 1.$$

The eigenvalue problem of Laplacian on Ω_t

We consider the eigenvalue problem of Laplacian:

$$\begin{aligned} -\Delta u_t &= \lambda(t)u_t \quad \text{in } \Omega_t, \\ u_t &= 0 \quad \text{on } \gamma_t^0, \quad \frac{\partial u_t}{\partial \nu} = 0 \quad \text{on } \gamma_t^1. \end{aligned}$$

There exist the eigenvalues

$$0 < \lambda_1(t) \leq \lambda_2(t) \leq \cdots,$$

and the corresponding eigenfunctions $u_k(t)$ with $\|u_k(t)\|_{L^2(\Omega_t)} = 1$.

Main Questions

- (1) Are $\lambda_k(t)$ and $u_k(t)$ continuous and differentiable with respect to t ?
- (2) If so, how do we compute $\lambda'_k(t)$ and $\lambda''_k(t)$?

Weak form

The weak form of

$$-\Delta u_t = \lambda(t)u_t \text{ in } \Omega_t, \quad u_t = 0 \text{ on } \gamma_t^0, \quad \frac{\partial u_t}{\partial \nu} = 0 \text{ on } \gamma_t^1$$

is

$$\int_{\Omega_t} \nabla u \cdot \nabla v \, dx = \lambda \int_{\Omega_t} uv \, dx, \quad \forall v \in V_t \text{ with } \|u\|_{L^2(\Omega_t)} = 1,$$
$$V_t := \{v \in H^1(\Omega_t) \mid v|_{\gamma_t^0} = 0\}.$$

To make the problem easier, we pullback the weak form to Ω as

$$u \in V, \quad A_t(u, v) = \lambda B_t(u, v), \quad \forall v \in V, \quad B_t(u, u) = 1,$$
$$A_t(u, v) := \int_{\Omega} Q_t[\nabla u, \nabla v] \det D\mathcal{T}_t \, dx, \quad B_t(u, v) := \int_{\Omega} uv \det D\mathcal{T}_t \, dx,$$
$$V := \{v \in H^1(\Omega) \mid v|_{\gamma^0} = 0\}, \quad Q_t := (D\mathcal{T}_t)^{-1}(D\mathcal{T}_t)^{-\top}.$$

General framework

In the following, we consider the eigenvalue problem in the general framework.

Let $X := L^2(\Omega)$ and $I \subset \mathbb{R}$ be an open interval.

Let $A_t : V \times V \rightarrow \mathbb{R}$ and $B_t : X \times X \rightarrow \mathbb{R}$ be symmetric bilinear forms depends on $t \in I$ with

$$\begin{aligned} |A_t(u, v)| &\leq C \|u\|_V \|v\|_V, & A_t(v, v) &\geq \delta \|v\|_V^2, & \forall u, v \in V, \\ |B_t(u, v)| &\leq C |u|_X |v|_X, & B_t(v, v) &\geq \delta |v|_X^2, & \forall u, v \in X. \end{aligned}$$

We consider the following eigenvalue problem:

$$u \in V, \quad A_t(u, v) = \lambda B_t(u, v), \quad \forall v \in V, \quad B_t(u, u) = 1.$$

The known results

We reformulate the problem in the general framework, many known results are available.



S.-N. Chow and J.K. Hale, *Methods of Bifurcation Theory*, Springer-Verlag, New York, 1982.



T. Kato, *Perturbation Theory for Linear Operators*, second edition, Springer-Verlag, Berlin, 1976.



F. Rellich, *Perturbation Theory of Eigenvalue Problems*, Lecture Notes, New York Univ. 1953.

However, the proofs of the known results are quite complicated and difficult to follow. Our aim is to give a simpler proof for the continuity and differentiability of eigenvalues.

Continuity of the eigenvalues

Theorem

Suppose that the symmetric bilinear forms A_t and B_t satisfy

$$\lim_{h \rightarrow 0} \sup_{\|u\|_V \leq 1, \|v\|_V \leq 1} |(A_{t+h} - A_t)(u, v)| = 0,$$

$$\lim_{h \rightarrow 0} \sup_{|u|_X \leq 1, |v|_X \leq 1} |(B_{t+h} - B_t)(u, v)| = 0$$

for any $t \in I$. Then, the eigenvalues $\lambda_k(t)$ is continuous with respect to t :

$$\lim_{h \rightarrow 0} \lambda_k(t+h) = \lambda_k(t), \quad \forall t \in I, \quad k = 1, 2, \dots$$

Let $u_k(t)$ be the eigenfunction of $\lambda_k(t)$. In general, $u_k(t)$ is **NOT** continuous with respect to t even if $\lambda_k(t)$ is simple. We need to consider on “the continuity of the space $\text{span}\{u_k(t)\}$ ”.

Differentiability of the eigenvalues, Numerical Example 1

We expect that $\lambda_k(t)$ is differentiable with respect to t .

However, this is **NOT** the case in general. Let $\Omega := (0, 1) \times (0, 1)$, and

$$\mathcal{T}_t(x) = x + \left(t + \frac{1}{2}t^2\right) \begin{pmatrix} x_1 + x_2 \\ -x_1 - x_2 \end{pmatrix}, \quad -0.1 \leq t \leq 0.1.$$

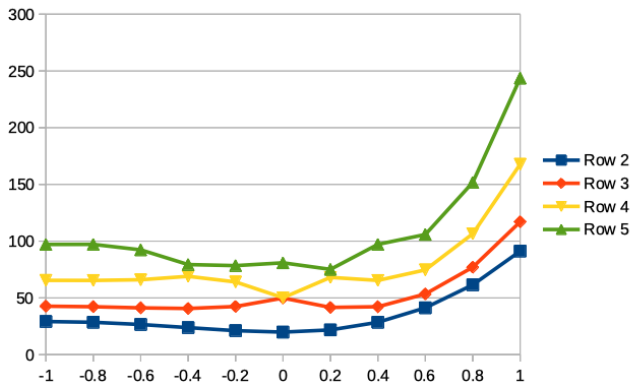
Then, $\Omega_t := \mathcal{T}_t(\Omega)$ looks like

We consider the eigenvalue problem

$$-\Delta u = \lambda u \quad \text{in} \quad \Omega_t, \quad u = 0 \quad \text{on} \quad \partial\Omega_t.$$

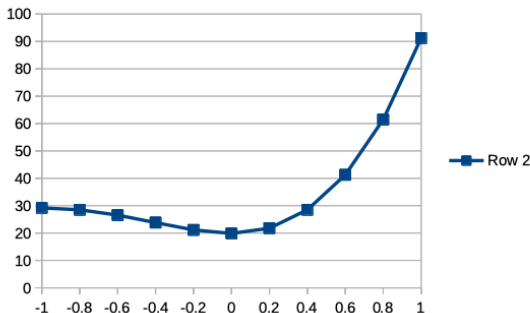
Differentiability of the eigenvalues, Numerical Example 1

The profile of the eigenvalues is following:



Differentiability of the eigenvalues, Numerical Example 1

The profile of the first eigenvalue is following:



Differentiability of the eigenvalues, Numerical Example 1

Let $(\lambda_1(t), u_1(t))$ be the first eigen pair.

The approximated value of the Hadamard variation

$$\lambda_1'(0) = - \left\langle \frac{\partial u_1(0)}{\partial \boldsymbol{\nu}}, (S \cdot \boldsymbol{\nu}) \frac{\partial u_1(0)}{\partial \boldsymbol{\nu}} \right\rangle_{\partial\Omega} .$$

is $-1.18\text{E-}16$. (Note that the original form of the Hadamard variation cannot be applied to this case.)

Differentiability of the eigenvalues, 1

Define

$$\dot{A}_t(u, v) := \frac{d}{dt}A_t(u, v), \quad \dot{B}_t(u, v) := \frac{d}{dt}B_t(u, v)$$

We suppose that the bilinear forms A_t, B_t satisfy the assumption of Theorem 1 (continuity) and the followings (differentiability):

$$|\dot{A}_t(u, v)| \leq C\|u\|_V\|v\|_V, \quad u, v \in V,$$

$$|\dot{B}_t(u, v)| \leq C|u|_X|v|_X, \quad u, v \in X,$$

$$\lim_{h \rightarrow 0} \frac{1}{h} \sup_{\|u\|_V \leq 1, \|v\|_V \leq 1} |(A_{t+h} - A_t - h\dot{A}_t)(u, v)| = 0,$$

$$\lim_{h \rightarrow 0} \frac{1}{h} \sup_{|u|_X \leq 1, |v|_X \leq 1} |(B_{t+h} - B_t - h\dot{B}_t)(u, v)| = 0.$$

Differentiability of the eigenvalues, 2

Theorem

Suppose that A_t, B_t satisfy the above conditions. Let $\lambda_k(t)$ be of multiplicity $m \geq 1$. Then, there exists

$$\dot{\lambda}_j^{\pm}(t) := \lim_{h \rightarrow \pm 0} \frac{\lambda_j(t+h) - \lambda_j(t)}{h},$$

and we have

$$\dot{\lambda}_j^+ = \mu_{j-k+1}^{\lambda}, \quad \dot{\lambda}_j^- = \mu_{k+m-j}^{\lambda}, \quad k \leq j \leq k+m-1,$$

where $\mu_1^{\lambda} \leq \mu_2^{\lambda} \leq \dots \leq \mu_m^{\lambda}$ are the eigenvalues of

$$u \in Y_{\lambda}, \quad (\dot{A}_t - \lambda \dot{B}_t)(u, v) = \mu B_t(u, v), \quad \forall v \in Y_{\lambda},$$

and Y_{λ} is the m -dimensional subspace spanned by the eigenfunctions of $\lambda := \lambda_k(t)$.

Differentiability of the eigenvalues, 3

Corollary

(1) Suppose that $\lambda_k(t)$ is a simple eigenvalue. Then, $\lambda_k(t)$ is differentiable at t : there exists

$$\lambda'_j(t) := \lim_{h \rightarrow 0} \frac{\lambda_j(t+h) - \lambda_j(t)}{h}.$$

(2) Suppose that $\lambda_k(t)$ is of multiplicity 2. Define $\tilde{\lambda}_{k+p}$, for $p = 0, 1$, by

$$\tilde{\lambda}_{k+p}(s) := \begin{cases} \lambda_{k+p}(s) & s \geq t \\ \lambda_{k+1-p}(s) & s \leq t \end{cases}, \quad p = 0, 1.$$

Then, $\tilde{\lambda}_i(s)$ is differentiable at t , and we have, with $\lambda := \lambda_k(t)$,

$$\tilde{\lambda}'_{k+p}(t) := \lim_{h \rightarrow 0} \frac{\tilde{\lambda}_{k+p}(t+h) - \lambda}{h} = \dot{\lambda}_{k+p}^+(t), \quad p = 0, 1.$$

Differentiability of the eigenvalues, 4

Corollary

Suppose that $\lambda_k(t)$ is of multiplicity 3.

(1) Then, $\lambda_{k+1}(t)$ is differentiable at t .

(2) Define $\tilde{\lambda}_{k+p}$, for $p = 0, 2$, by

$$\tilde{\lambda}_{k+p}(s) := \begin{cases} \lambda_{k+p}(s) & s \geq t \\ \lambda_{k+2-p}(s) & s \leq t \end{cases}, \quad p = 0, 2.$$

Then, $\tilde{\lambda}_i(s)$ is differentiable at t , and we have, with $\lambda := \lambda_k(t)$,

$$\tilde{\lambda}'_{k+p}(t) := \lim_{h \rightarrow 0} \frac{\tilde{\lambda}_{k+p}(t+h) - \lambda}{h} = \dot{\lambda}_{k+p}^+(t), \quad p = 0, 2.$$

Continuity of the derivatives, 1

Theorem

Suppose that A_t, B_t satisfy the assumptions of Theorem 2. Suppose also that A_t, B_t satisfy

$$\lim_{h \rightarrow 0} \sup_{\|u\|_V \leq 1, \|v\|_V \leq 1} |(\dot{A}_{t+h} - \dot{A}_t)(u, v)| = 0,$$

$$\lim_{h \rightarrow 0} \sup_{|u|_X \leq 1, |v|_X \leq 1} |(\dot{B}_{t+h} - \dot{B}_t)(u, v)| = 0.$$

Then, the one-sided derivatives $\dot{\lambda}_i^\pm(s)$ are one-sided continuous. That is,

$$\lim_{h \rightarrow +0} \dot{\lambda}_k^+(t+h) = \dot{\lambda}_k^+(t), \quad \lim_{h \rightarrow -0} \dot{\lambda}_k^-(t+h) = \dot{\lambda}_k^-(t)$$

hold.

Continuity of the derivatives, 2

Theorem

Let $I \subset \mathbb{R}$ be an open interval.

Suppose that A_t, B_t satisfy the assumptions of Theorem 3 for any $t \in I$. Then, defining $\tilde{\lambda}_k(t)$ by appropriate rearrangements (change of the order) of $\lambda_k(t)$ at most countably many times, $\tilde{\lambda}_k(t)$ are of $C^1(I)$.

Higher derivatives 1

Define

$$\ddot{A}_t(u, v) := \frac{d^2}{dt^2} A_t(u, v), \quad \ddot{B}_t(u, v) := \frac{d^2}{dt^2} B_t(u, v).$$

We suppose that the bilinear forms A_t, B_t satisfy the assumption of Theorem 3 and the followings:

$$|\ddot{A}_t(u, v)| \leq C \|u\|_V \|v\|_V, \quad u, v \in V,$$

$$|\ddot{B}_t(u, v)| \leq C |u|_X |v|_X, \quad u, v \in X,$$

$$\lim_{h \rightarrow 0} \frac{1}{h^2} \sup_{\|u\|_V \leq 1, \|v\|_V \leq 1} \left| \left(A_{t+h} - A_t - h \dot{A}_t - \frac{h^2}{2} \ddot{A}_t \right) (u, v) \right| = 0,$$

$$\lim_{h \rightarrow 0} \frac{1}{h^2} \sup_{|u|_X \leq 1, |v|_X \leq 1} \left| \left(B_{t+h} - B_t - h \dot{B}_t - \frac{h^2}{2} \ddot{B}_t \right) (u, v) \right| = 0.$$

Higher derivatives 2

Theorem

Let $I \subset \mathbb{R}$ be an open interval.

Suppose that A_t, B_t satisfy the assumptions of Theorem 3 for any $t \in I$. Suppose also that the above mentioned conditions hold. Then, defining $\tilde{\lambda}_k(t)$ by appropriate rearrangements (change of the order) of $\lambda_k(t)$ at most countably many times, $\tilde{\lambda}_k(t)$ are of $C^2(I)$.

Summary of the first part

- If a perturbation is continuous, the perturbed eigenvalues are continuous wrt the perturbation.
- If a perturbation is continuously differentiable, the perturbed eigenvalues with appropriate rearrangements (change of the order) are continuously differentiable wrt the perturbation.
- If a perturbation is of C^2 , the perturbed eigenvalues with appropriate rearrangements (change of the order) are of C^2 wrt the perturbation.
- We have given a simple proof of these facts.
- Therefore, with respect to general domain perturbations of C^2 the perturbed eigenvalues with appropriate rearrangements (change of the order) are of C^2 as well,

T. Suzuki, T. Tsuchiya, Hadamard variation of eigenvalues with respect to general domain perturbations, *to appear in* [Journal of Mathematical Society of Japan](#). [arXiv:2309.00273](#)

The convexity of the first eigenvalue.

In the paper

Garabedian, Schiffer, Convexity of domain functionals, J. Anal. Math., 2 (1952-53) 281–368,

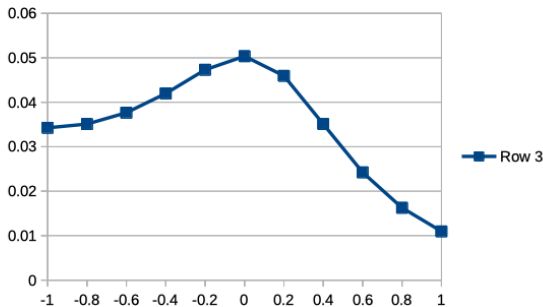
Garabedian and Schiffer claimed that in some cases we have

$$\frac{d^2}{dt^2} \left(\frac{1}{\lambda_1(t)} \right) \geq 0,$$

that is, the reciprocal of the first eigenvalue is convex with respect to t . We would like to know the sufficient conditions for the convexity.

The reciprocal of the first eigenvalue, Numerical Example 1

The profile of the reciprocal of the first eigenvalue is following.
Clearly, the reciprocal of the first eigenvalue is not convex with respect to t .



First Theorem

Theorem

Let $\lambda_t(t)$ be the first eigenvalue and ϕ_t is the eigen function of $\lambda_1(t)$ with $\int_{\Omega} \phi_t^2 d\mathbf{x}$, and

$$\dot{A} := \dot{A}_t(\phi_1, \phi_1), \quad \ddot{A} := \ddot{A}_t(\phi_1, \phi_1), \quad \dot{B} := \dot{B}_t(\phi_1, \phi_1), \quad \ddot{B} := \ddot{B}_t(\phi_1, \phi_1).$$

Then,

$$\dot{\lambda} = \dot{A} - \lambda \dot{B}, \quad \ddot{\lambda} \leq \ddot{A} - \lambda \ddot{B} - 2\dot{\lambda} \dot{B}.$$

Sufficient condition for the convexity

Theorem

Let $\lambda_t(t)$ be the first eigenvalue and ϕ_t is the eigen function of $\lambda_1(t)$ with $\int_{\Omega} \phi_t^2 d\mathbf{x}$, and

$$\dot{A} := \dot{A}_t(\phi_1, \phi_1), \quad \ddot{A} := \ddot{A}_t(\phi_1, \phi_1), \quad \dot{B} := \dot{B}_t(\phi_1, \phi_1), \quad \ddot{B} := \ddot{B}_t(\phi_1, \phi_1).$$

Then,

$$\dot{\lambda} = \dot{A} - \lambda \dot{B}, \quad \ddot{\lambda} \leq \ddot{A} - \lambda \ddot{B} - 2\dot{\lambda} \dot{B}.$$

Sufficient condition for the convexity

Because

$$\frac{d^2}{dt^2} \left(\frac{1}{\lambda_1(t)} \right) = -\frac{\ddot{\lambda}\lambda^2 - 2\lambda\dot{\lambda}}{\lambda^2},$$

we have the following theorem.

Theorem

Suppose that

$$2\dot{A}^2 + \lambda^2\ddot{B} \geq \lambda(\ddot{A} + 2\dot{A}\dot{B}).$$

Then, we have

$$\frac{d^2}{dt^2} \left(\frac{1}{\lambda_1(t)} \right) \geq 0.$$

For the case of conformal transformations, $n = 2$.

Let $n = 2$, and $\mathcal{T}_t : \Omega \rightarrow \Omega_t$ is conformal. Then, we have the following theorem.

Theorem

If

$$\frac{d^2}{dt^2} \det D\mathcal{T}_t \geq 0 \quad \text{in } \Omega,$$

then, we have

$$\frac{d^2}{dt^2} \left(\frac{1}{\lambda_1(t)} \right) \geq 0.$$

For the case of conformal transformations, $n = 2$.

Lemma

Let $\mathbb{R}^2 \cong \mathbb{C}$, and $\mathcal{T}_t(z) := z + a_2 t z^2 + a_3 t^2 z^3 + \cdots$.

If $2|a_2|^2 \geq 3|a_3|$, then $\frac{d^2}{dt^2} \det D\mathcal{T}_t \geq 0$ in Ω .

Lemma

Let $D = \{z \in \mathbb{C} \mid |z| < 1\}$ be the unit disk, and

$$f(z) = a_0 + a_1 z + a_2 z^2 + \cdots, \quad a_1 \in \mathbb{R}$$

be univalent in D . If we define the transformation by

$$\mathcal{T}_t(z) = (1-t)z + tf(z), \text{ then } \frac{d^2}{dt^2} \det D\mathcal{T}_t \geq 0.$$

For the case of conformal transformations, $n = 2$.

Theorem

Let $D = \{z \in \mathbb{C} \mid |z| < 1\}$ be the unit disk, and

$$f(z) = a_0 + a_1 z + a_2 z^2 + \cdots, \quad a_1 \in \mathbb{R}$$

be univalent in D . If we define the transformation by $\mathcal{T}_t(z) = (1-t)z + tf(z)$, then we have

$$\frac{d^2}{dt^2} \det D\mathcal{T}_t \geq 0,$$
$$\lambda_1(D) \geq \lambda_1(\mathcal{T}_t(D)) \left(2 \int_D \phi_1^2 \operatorname{Re} f'(z) dz - 1 \right).$$

Suzuki, Tsuchiya, Hadamard's variational formula for simple eigenvalues, *in preparation*.

Convexity of the first eigenvalue, Numerical Example 2

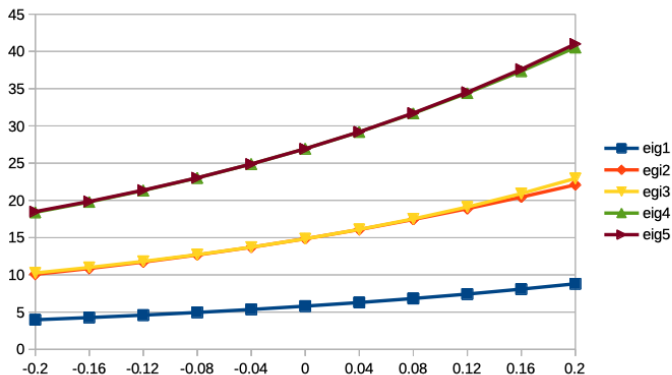
Let $D \subset \mathbb{C}$ be the unit disk, and

$$\mathcal{T}_t(z) = (1 - t)z + t \cos z.$$

Then, $\Omega_t := \mathcal{T}_t(D)$ looks like

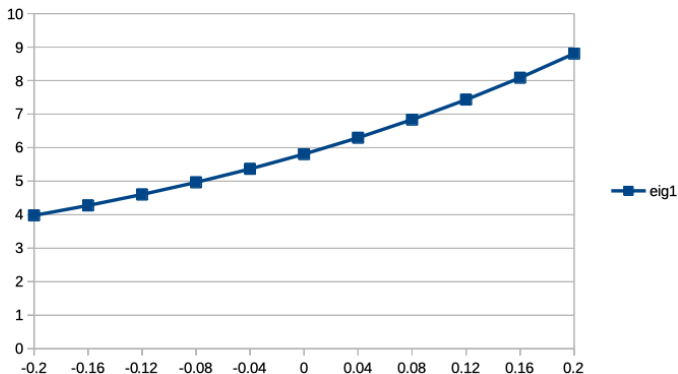
Convexity of the first eigenvalue, Numerical Example 2

The profile of the eigenvalues is following:



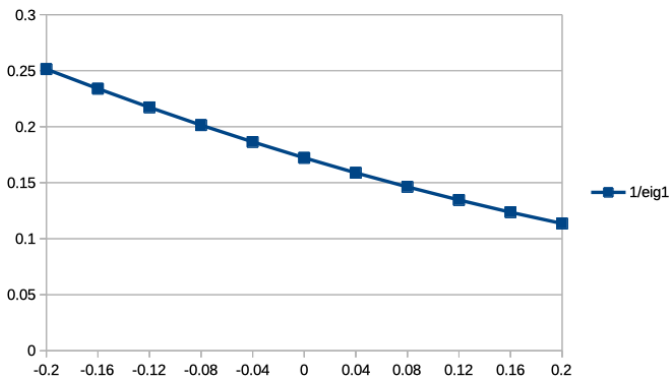
Convexity of the first eigenvalue, Numerical Example 2

The profile of the first eigenvalues is following:



Convexity of the first eigenvalue, Numerical Example 2

The profile of the reciprocal of the first eigenvalues is following:



Convexity of the first eigenvalue, Numerical Example 3

Let $D \subset \mathbb{C}$ be the unit disk, and

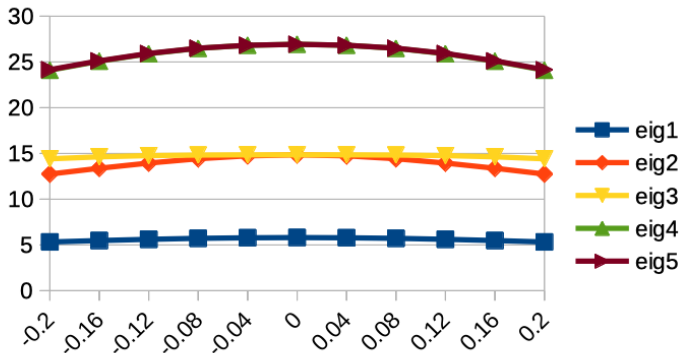
$$\mathcal{T}_t(z) = z + a_2 t z^2 + a_3 t^2 z^3 + a_4 t^3 z^4 + a_5 t^4 z^5$$

with $a_2 = 1 + 0.5i$, $a_3 = -a_2$, $a_4 = 1 + i$, and $a_5 = -a_4$. Then, $\Omega_t := \mathcal{T}_t(D)$ looks like

Note that this transformation does not satisfy the sufficient condition.

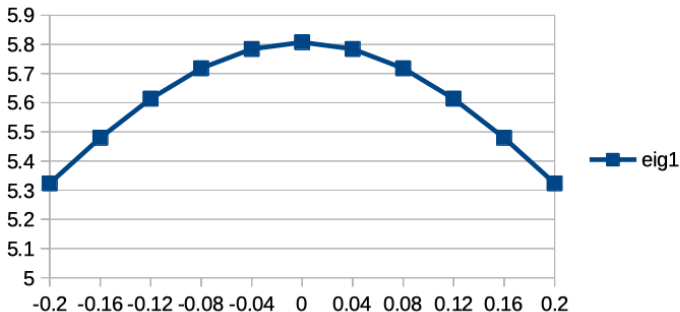
Differentiability of the eigenvalues, Numerical Example 3

The profile of the eigenvalues is following:



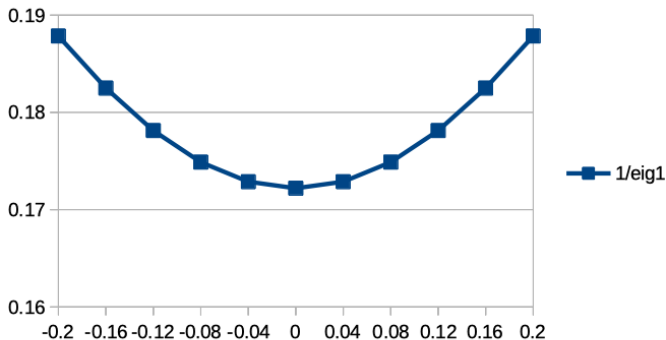
Differentiability of the eigenvalues, Numerical Example 3

The profile of the first eigenvalue is following:








Differentiability of the eigenvalues, Numerical Example 3

The profile of the reciprocal of the first eigenvalue is following:



References

-  S.-N. Chow and J.K. Hale, *Methods of Bifurcation Theory*, Springer-Verlag, New York, 1982.
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