

2024 Symposium on Numerical Methods for Spectral Problems: Theory and Application, Guiyang, China

Construction of fractional pseudospectral differentiation matrices with applications

Tinggang Zhao
jointed with Wenbin Li and Hongjun Ma

¹School of Mathematics and Statistics
Shandong University of Technology

Aug 2024



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

1. Motivation
2. Preliminaries
3. Fraction Pseudospectral Differentiation/Integration Matrix
4. Applications
5. Summary



- ◆ Fractional Calculus shows potential applications such as anomalous diffusion
- ◆ Numerical solutions are challenging caused by singularity and nonlocality
- ◆ Fast, higher-order numerical method is needed
- ◆ Spectral collocation method is popular



Related works

- ♠ Spectral method: Li and Xu (2009, SIAM Numer Anal; 2010, Commun Comput Phys); Chen, Shen and Wang (2016, Math Comput); Mao and Shen (2016, J Comput Phys); Mao, Chen and Shen (2016, Appl Numer Math); Mao and Karniadakis (2018, SIAM Numer Anal)
- ♠ Spectral collocation method: Li, Zeng and Liu (2012, FCAA); Doha, Bhrawy and Ezz-Eldien (2012, Appl Math Modelling); Tian, Deng and Wu (2014, Numer Method PDEs); Zayernouri and Karniadakis (2014, SIAM J Sci Comput; 2015, J Comput Phys); Zayernouri, Ainsworth and Karniadakis (2015, Comput Meth Appl Mech Engng); Zeng and Karniadakis (2015, 2017, SIAM J Sci Comput); Jiao, Wang and Huang (2016, J Comput Phys)
- ♠ Spectral element method (Multi-domain spectral method): Xu and Hesthaven (2014, J Comput Phys); Chen, Xu and Hesthaven (2015, J Comput Phys); Mao and Shen (2018, Adv Comput Math); Zhao, Mao and Karniadakis (2019, Comput Meth Appl Mech Engng)



- ★ The main contribution of this work is to represent some fractional differentiation matrices as a product of several special matrices
- ★ This representation gives not only a direct, fast and stable algorithm of fractional differentiation matrices
- ★ but also more information which can be used for inverse or preconditioning



2.1 Definitions of Fractional Calculus

Definition (left- and right-sided Riemann–Liouville integrals)

For a function $f(x)$ on $(a, b) \subseteq \mathbb{R}$, the μ th order left- and right-sided Riemann–Liouville integrals are defined, respectively, as

$${}_R\mathcal{D}_{a,x}^{-\mu}f(x) = \frac{1}{\Gamma(\mu)} \int_a^x (x - \eta)^{\mu-1} f(\eta) d\eta, \quad \mu > 0, \quad (1)$$

and

$${}_R\mathcal{D}_{x,b}^{-\mu}f(x) = \frac{1}{\Gamma(\mu)} \int_x^b (\eta - x)^{\mu-1} f(\eta) d\eta, \quad \mu > 0. \quad (2)$$



Definitions of Fractional Calculus

Definition (left- and right-sided Riemann–Liouville derivatives)

For a function $f(x)$ on $(a, b) \subseteq \mathbb{R}$, the μ th order left- and right-sided Riemann–Liouville derivatives are defined as

$${}_R L D_{a,x}^{\mu} f(x) = \frac{1}{\Gamma(m-\mu)} \left(\frac{d}{dx} \right)^m \int_a^x (x-\eta)^{m-\mu-1} f(\eta) d\eta, \quad (3)$$

and

$${}_R L D_{x,b}^{\mu} f(x) = \frac{1}{\Gamma(m-\mu)} \left(-\frac{d}{dx} \right)^m \int_x^b (\eta-x)^{m-\mu-1} f(\eta) d\eta, \quad (4)$$

respectively. Here and in the subsequent sections, m is a positive integer satisfying $m-1 < \mu < m$, $m \in \mathbb{N}$.



Definitions of Fractional Calculus

Definition (left- and right-sided Caputo derivative)

For a function $f(x)$ defined on $(a, b) \subseteq \mathbb{R}$, the μ th order left- and right-sided Caputo derivative is defined, respectively, as

$${}_CD_{a,x}^{\mu}f(x) = \frac{1}{\Gamma(m-\mu)} \int_a^x (x-\eta)^{m-\mu-1} f^{(m)}(\eta) d\eta, \quad (5)$$

and

$${}_CD_{x,b}^{\mu}f(x) = \frac{(-1)^m}{\Gamma(m-\mu)} \int_x^b (\eta-x)^{m-\mu-1} f^{(m)}(\eta) d\eta, \quad (6)$$

Definition (Riesz derivative)

Let $0 < \mu < 2, \mu \neq 1$. The Riesz derivative is defined as

$${}_{RZ}D_x^{\mu}f(x) = -\frac{1}{2\cos\left(\frac{\pi\mu}{2}\right)} \left[{}_{RL}D_{a,x}^{\mu}f(x) + {}_{RL}D_{x,b}^{\mu}f(x) \right]. \quad (7)$$

2.2 Jacobi Polynomials

Jacobi polynomials $P_n^{\alpha,\beta}(s)$, $s \in I$ with parameters $\alpha, \beta \in \mathbb{R}$ are defined as

$$P_n^{\alpha,\beta}(s) = \frac{(\alpha+1)_n}{n!} + \sum_{j=1}^{n-1} \frac{(n+\alpha+\beta+1)_j (\alpha+j+1)_{n-j}}{j!(n-j)!} \left(\frac{s-1}{2}\right)^j + \frac{(n+\alpha+\beta+1)_n}{n!} \left(\frac{s-1}{2}\right)^n, \quad n \geq 1, \quad (8)$$

and $P_0^{\alpha,\beta}(s) = 1$.

The well-known three-term recurrence relationship of Jacobi polynomials $P_n^{\alpha,\beta}(s)$ with parameters $\alpha, \beta \in \mathbb{R}$ is fulfilled for $-(\alpha+\beta+1) \notin \mathbb{N}^+$:

$$P_{n+1}^{\alpha,\beta}(s) = (A_n^{\alpha,\beta}s - B_n^{\alpha,\beta})P_n^{\alpha,\beta}(s) - C_n^{\alpha,\beta}P_{n-1}^{\alpha,\beta}(s), \quad n \geq 1 \quad (9)$$

$$P_0^{\alpha,\beta}(s) = 1, \quad P_1^{\alpha,\beta}(s) = \frac{\alpha+\beta+2}{2}s + \frac{\alpha-\beta}{2}$$

where

$$\begin{cases} A_n^{\alpha,\beta} = \frac{(2n+\alpha+\beta+1)(2n+\alpha+\beta+2)}{2(n+1)(n+\alpha+\beta+1)} \\ B_n^{\alpha,\beta} = \frac{(\beta^2-\alpha^2)(2n+\alpha+\beta+1)}{2(n+1)(n+\alpha+\beta+1)(2n+\alpha+\beta)} \\ C_n^{\alpha,\beta} = \frac{(n+\alpha)(n+\beta)(2n+\alpha+\beta+2)}{(n+1)(n+\alpha+\beta+1)(2n+\alpha+\beta)} \end{cases}$$



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Jacobi-Jacobi transformation

In [7], Shen, Wang and Xia (2019, Math Comput) proposed an algorithm of [Fast structured Jacobi-Jacobi transforms](#).

Theorem

Let $\alpha_1, \beta_1 > -1$. If

$$\sum_{k=0}^n a_k P_k^{\alpha_1, \beta_1}(s) = \sum_{k=0}^n b_k P_k^{\alpha_2, \beta_2}(s),$$

then there exists a unique transform matrix $\mathbf{T}_n^{J_2 \rightarrow J_1}$ with $J_1 = (\alpha_1, \beta_1)$ and $J_2 = (\alpha_2, \beta_2)$ such that

$$\mathbf{a} = \mathbf{T}_n^{J_2 \rightarrow J_1} \mathbf{b},$$

where $\mathbf{a} = [a_0, \dots, a_n]^T$, $\mathbf{b} = [b_0, \dots, b_n]^T$ and the (i, j) -th entry, denoted as $t_{i,j}^{J_1, J_2}$, of $\mathbf{T}_n^{J_2 \rightarrow J_1}$ can be generated by

Jacobi-Jacobi transformation(continuous)

Theorem

$$t_{i,j}^{J_1,J_2} = 0, \quad j < i,$$

$$t_{i,j}^{J_1,J_2} = \tilde{a}_{i,j}^{J_1,J_2} t_{i+1,j-1}^{J_1,J_2} + \tilde{b}_{i,j}^{J_1,J_2} t_{i,j-1}^{J_1,J_2} + \tilde{c}_{i,j}^{J_1,J_2} t_{i-1,j-1}^{J_1,J_2} - C_{j-1}^{J_2} t_{i,j-2}^{J_1,J_2}, \quad j \geq i \geq 1,$$

$$t_{0,j}^{J_1,J_2} = \tilde{a}_{0,j}^{J_1,J_2} t_{1,j-1}^{J_1,J_2} + \tilde{b}_{0,j}^{J_1,J_2} t_{0,j-1}^{J_1,J_2} - C_{j-1}^{J_2} t_{0,j-2}^{J_1,J_2}, \quad j \geq 1,$$

$$t_{0,1}^{J_1,J_2} = \tilde{b}_{0,1}^{J_1,J_2} t_{0,0}^{J_1,J_2}, \quad t_{0,0}^{J_1,J_2} = 1$$

with

$$\tilde{a}_{i,j}^{J_1,J_2} = A_{j-1}^{J_2} \frac{1}{A_i^{J_1}} \frac{\gamma_{i+1}^{J_1}}{\gamma_i^{J_1}} = \frac{2(i + \alpha_1 + 1)(i + \beta_1 + 1)}{(2i + \alpha_1 + \beta_1 + 2)(2i + \alpha_1 + \beta_1 + 3)} A_{j-1}^{J_2},$$

$$\tilde{b}_{i,j}^{J_1,J_2} = A_{j-1}^{J_2} \frac{B_i^{J_1}}{A_i^{J_1}} - B_{j-1}^{J_2} = \frac{\beta_1^2 - \alpha_1^2}{(2i + \alpha_1 + \beta_1)(2i + \alpha_1 + \beta_1 + 2)} A_{j-1}^{J_2} - B_{j-1}^{J_2},$$

$$\tilde{c}_{i,j}^{J_1,J_2} = A_{j-1}^{J_2} \frac{C_i^{J_1}}{A_i^{J_1}} \frac{\gamma_{i-1}^{J_1}}{\gamma_i^{J_1}} = \frac{2i(i + \alpha_1 + \beta_1)}{(2i + \alpha_1 + \beta_1 - 1)(2i + \alpha_1 + \beta_1)} A_{j-1}^{J_2}.$$

Lemma (Spectral relationships)

Let $\mu > 0, \alpha \in \mathbb{R}, \beta > -1$. Then, the following relations are true

$$\begin{aligned} {}_{RL}D_{-1,s}^{-\mu} \{(1+s)^\beta P_n^{\alpha,\beta}(s)\} &= \frac{\Gamma(n+\beta+1)}{\Gamma(n+\beta+\mu+1)} (1+s)^{\beta+\mu} P_n^{\alpha-\mu,\beta+\mu}(s), \\ {}_{RL}D_{-1,s}^\mu \{(1+s)^{\beta+\mu} P_n^{\alpha-\mu,\beta+\mu}(s)\} &= \frac{\Gamma(n+\beta+\mu+1)}{\Gamma(n+\beta+1)} (1+s)^\beta P_n^{\alpha,\beta}(s), \end{aligned} \quad (10)$$

and the following relations are true for $\alpha > -1, \beta \in \mathbb{R}$

$$\begin{aligned} {}_{RL}D_{s,1}^{-\mu} \{(1-s)^\alpha P_n^{\alpha,\beta}(s)\} &= \frac{\Gamma(n+\alpha+1)}{\Gamma(n+\alpha+\mu+1)} (1-s)^{\alpha+\mu} P_n^{\alpha+\mu,\beta-\mu}(s), \\ {}_{RL}D_{s,1}^\mu \{(1-s)^{\alpha+\mu} P_n^{\alpha+\mu,\beta-\mu}(s)\} &= \frac{\Gamma(n+\alpha+\mu+1)}{\Gamma(n+\alpha+1)} (1-s)^\alpha P_n^{\alpha,\beta}(s). \end{aligned} \quad (11)$$



3.1 Pseudospectral Differentiation/Integration Matrix

Pseudospectral Differentiation/Integration Matrix Setup

- ★ Collocation points: Gauss-type quadrature nodes $\{x_j\}_{j=0}^N \subseteq [a, b]$ (e.g., Gauss-Lobatto, Gauss-Radau)
- ★ Interpolate using Lagrange basis functions

$$f(x) \approx f_N(x) = \sum_{j=0}^N f(x_j) L_j(x), \quad (12)$$

with $L_j(x) = \prod_{i=0, i \neq j}^N \left(\frac{x - x_i}{x_j - x_i} \right)$, $j = 0, 1, \dots, N$.

- ★ Apply integral/derivative operator on $L_j(x)$ at nodes $\{x_j\}_{j=0}^N$:

$$(\mathbf{F}^\mu)_{ij} = [\mathbf{F}^\mu L_j](x_i), \quad i, j = 0, 1, \dots, N.$$



We have 7 fractional Differentiation/Integration matrices as:

- $({}_{RL}\mathbf{D}_l^{-\mu})_{ij} = [{}_{RL}D_{-1,x}^{-\mu}L_j](x_i)$ –Left Riemann-Liouville integral.
- $({}_{RL}\mathbf{D}_r^{-\mu})_{ij} = [{}_{RL}D_{x,1}^{-\mu}L_j](x_i)$ –Right Riemann-Liouville integral.
- $({}_{RL}\mathbf{D}_l^{\mu})_{ij} = [{}_{RL}D_{-1,x}^{\mu}L_j](x_i)$ –Left Riemann-Liouville derivative.
- $({}_{RL}\mathbf{D}_r^{\mu})_{ij} = [{}_{RL}D_{x,1}^{\mu}L_j](x_i)$ –Right Riemann-Liouville derivative.
- $({}_C\mathbf{D}_l^{\mu})_{ij} = [{}_CD_{-1,x}^{\mu}L_j](x_i)$ –Left Caputo derivative.
- $({}_C\mathbf{D}_r^{\mu})_{ij} = [{}_CD_{x,1}^{\mu}L_j](x_i)$ –Right Caputo derivative.
- $({}_{RZ}\mathbf{D}^{\mu})_{ij} = [{}_{RZ}D_x^{\mu}L_j](x_i)$ –Riesz derivative.



Pseudospectral Differentiation/Integration Matrix

Theorem

The first row of ${}_{RL}\mathbf{D}_l^{-\mu}$, ${}_C\mathbf{D}_l^{\mu}$ and the last row of ${}_{RL}\mathbf{D}_r^{-\mu}$, ${}_C\mathbf{D}_r^{\mu}$ are all zeros, e.g., for $j = 0, \dots, N$

$$({}_{RL}\mathbf{D}_l^{-\mu})_{0,j} = ({}_{RL}\mathbf{D}_r^{-\mu})_{N,j} = ({}_C\mathbf{D}_l^{\mu})_{0,j} = ({}_C\mathbf{D}_r^{\mu})_{N,j} = 0,$$

and $({}_{RL}\mathbf{D}_l^{\mu})_{0,0} = ({}_{RL}\mathbf{D}_r^{\mu})_{N,N} = \infty$. Moreover, if $0 < \mu < 1$, we have

$$({}_{RL}\mathbf{D}_l^{\mu})_{i,j} = ({}_C\mathbf{D}_l^{\mu})_{i,j}, \quad j \neq 0, \quad (13)$$

and

$$({}_{RL}\mathbf{D}_r^{\mu})_{i,j} = ({}_C\mathbf{D}_r^{\mu})_{i,j}, \quad j \neq N. \quad (14)$$



Pseudospectral Differentiation/Integration Matrix

For $j = 0, 1, \dots, N$, we expand $L_j(x)$ as

$$L_j(x) = \sum_{k=0}^N h_{kj} (x+1)^k = \sum_{k=0}^N \bar{h}_{kj} (1-x)^k. \quad (15)$$

We collect the coefficients two matrices \mathbf{H}_l and \mathbf{H}_r as

$$(\mathbf{H}_l)_{ij} = h_{ij}, \quad (\mathbf{H}_r)_{ij} = \bar{h}_{ij}. \quad (16)$$

Let us introduce three $(N+1)$ -element vectors as

$$(\mathbf{v}_l^\mu)_i = (x_i + 1)^\mu, \quad (\mathbf{v}_r^\mu)_i = (1 - x_i)^\mu, \quad (\mathbf{c}^\mu)_i = \frac{\Gamma(i+1)}{\Gamma(i+\mu+1)}, \quad (17)$$

and two $(N+1) \times (N+1)$ matrices

$$(\mathbf{B}_l)_{ij} = (1 + x_i)^j, \quad (\mathbf{B}_r)_{ij} = (1 - x_i)^j. \quad (18)$$



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Pseudospectral Differentiation/Integration Matrix

Theorem

The following representations of the pseudospectral integration matrix are valid,

$$\begin{aligned} {}_{RL}\mathbf{D}_l^{-\mu} &= \text{diag}(\mathbf{v}_l^{\mu})\mathbf{B}_l\text{diag}(\mathbf{c}^{\mu})\mathbf{H}_l, \\ {}_{RL}\mathbf{D}_r^{-\mu} &= \text{diag}(\mathbf{v}_r^{\mu})\mathbf{B}_r\text{diag}(\mathbf{c}^{\mu})\mathbf{H}_r, \end{aligned} \quad (19)$$

where $\text{diag}(\cdot)$ is a diagonal matrix with the vector in brackets as its diagonal line. Similarly, by replacing $-\mu$ with μ , the following representations of the pseudospectral differentiation matrix are found to be valid

$$\begin{aligned} {}_{RL}\mathbf{D}_l^{\mu} &= \text{diag}(\mathbf{v}_l^{-\mu})\mathbf{B}_l\text{diag}(\mathbf{c}^{-\mu})\mathbf{L}_l, \\ {}_{RL}\mathbf{D}_r^{\mu} &= \text{diag}(\mathbf{v}_r^{-\mu})\mathbf{B}_r\text{diag}(\mathbf{c}^{-\mu})\mathbf{L}_r. \end{aligned} \quad (20)$$

Pseudospectral Differentiation/Integration Matrix

In fact, since the Lagrange basis function $L_j(x)$ satisfies $L_j(x_i) = \delta_{ij}$, we also have the inverse relation as

$$\mathbf{B}_l \mathbf{H}_l = \mathbf{I}, \quad \mathbf{B}_r \mathbf{H}_r = \mathbf{I}, \quad (21)$$

where \mathbf{I} is the identity matrix of $(N+1) \times (N+1)$. Noting that $(\text{diag}(\mathbf{v}_l^\mu))^{-1} = \text{diag}(\mathbf{v}_l^{-\mu})$, from the above Theorem and the relation (21), the inverse of the pseudospectral integration/differentiation matrix may be formally written as

$$\begin{aligned} ({}_{RL}\mathbf{D}_l^{-\mu})^{-1} &= \mathbf{B}_l(\text{diag}(\mathbf{c}^\mu))^{-1} \mathbf{L}_l \text{diag}(\mathbf{v}_l^{-\mu}), \\ ({}_{RL}\mathbf{D}_r^{-\mu})^{-1} &= \mathbf{B}_r(\text{diag}(\mathbf{c}^\mu))^{-1} \mathbf{L}_r \text{diag}(\mathbf{v}_r^{-\mu}), \end{aligned} \quad (22)$$

and

$$\begin{aligned} ({}_{RL}\mathbf{D}_l^\mu)^{-1} &= \mathbf{B}_l(\text{diag}(\mathbf{c}^{-\mu}))^{-1} \mathbf{L}_l \text{diag}(\mathbf{v}_l^\mu), \\ ({}_{RL}\mathbf{D}_r^\mu)^{-1} &= \mathbf{B}_r(\text{diag}(\mathbf{c}^{-\mu}))^{-1} \mathbf{L}_r \text{diag}(\mathbf{v}_r^\mu). \end{aligned} \quad (23)$$



Remark

Some remarks are listed as follows:

- It is worth noting that

$$(\text{diag}(\mathbf{c}^{-\mu}))^{-1} \neq (\text{diag}(\mathbf{c}^{\mu})), \quad (\text{diag}(\mathbf{c}^{\mu}))^{-1} \neq (\text{diag}(\mathbf{c}^{-\mu})).$$

- We point out that the two matrices \mathbf{B}_l and \mathbf{B}_r are Vandermonde's type.
- From the above Theorem, the first entry of \mathbf{v}_l^{μ} and the last entry of \mathbf{v}_r^{μ} are illogical for $\mu < 0$, which indicates the endpoint singularity of the fractional differential operator. In order to avoid this issue, the nodes $\{x_j\}_{j=0}^N$ are altered to the Jacobi–Gauss type.
- As stated above, the matrices $\text{diag}(\mathbf{v}_l^{\mu})$ and $\text{diag}(\mathbf{v}_r^{\mu})$ are singular (or some of their entries are not well-defined). Thus, the inverse of the singular matrix in (22) and (23) should be considered as a generalized inverse or a pseudo-inverse.



3.2 Riemann-Liouville Fractional Integral and Derivative

Consider expanding $L_j(x)$ as

$$L_j(x) = \sum_{k=0}^N l_{kj}^{\alpha,\beta} P_k^{\alpha,\beta}(x) = \sum_{k=0}^N l_{kj}^{0,0} P_k^{0,0}(x). \quad (24)$$

where $P_k^{\alpha,\beta}(x)$ is Jacobi orthogonal polynomial of degree k .

Denote

$$(\mathbf{L}^{\alpha,\beta})_{ij} = l_{ij}^{\alpha,\beta}, \quad (\mathbf{L}^{0,0})_{ij} = l_{ij}^{0,0}, \quad (\mathbf{P}^{\alpha,\beta})_{ij} = P_j^{\alpha,\beta}(x_i). \quad (25)$$

From the previous Theorem , we have

$$\mathbf{L}^{0,0} = \mathbf{T}_N^{(\alpha,\beta) \rightarrow (0,0)} \mathbf{L}^{\alpha,\beta}. \quad (26)$$

We also have

$$l_{ij}^{\alpha,\beta} = \frac{P_j^{\alpha,\beta}(x_i)\omega_i}{\gamma_j^{\alpha,\beta}}, \quad j = 0, 1, \dots, N-1, \quad l_{iN}^{\alpha,\beta} = \frac{P_N^{\alpha,\beta}(x_i)\omega_i}{\left(2 + \frac{\alpha+\beta+1}{N}\right) \gamma_N^{\alpha,\beta}},$$

Additionally, it is easy to have that

$$[\mathbf{L}^{\alpha,\beta}]^{-1} = [\mathbf{P}^{\alpha,\beta}]^T.$$



3.2 Riemann-Liouville Fractional Integral and Derivative

Theorem

The following representations of the pseudospectral integration matrices are valid for $\alpha, \beta > -1$

$$\begin{aligned} {}_{RL}\mathbf{D}_l^{-\mu} &= \text{diag}(\mathbf{v}_l^\mu) \mathbf{P}^{-\mu, \mu} \text{diag}(\mathbf{c}^\mu) \mathbf{T}_N^{(\alpha, \beta) \rightarrow (0, 0)} \mathbf{L}^{\alpha, \beta}, \\ {}_{RL}\mathbf{D}_r^{-\mu} &= \text{diag}(\mathbf{v}_r^\mu) \mathbf{P}^{\mu, -\mu} \text{diag}(\mathbf{c}^\mu) \mathbf{T}_N^{(\alpha, \beta) \rightarrow (0, 0)} \mathbf{L}^{\alpha, \beta}. \end{aligned} \quad (28)$$

Moreover, the differentiation matrices are valid for $\alpha, \beta > -1$

$$\begin{aligned} {}_{RL}\mathbf{D}_l^\mu &= \text{diag}(\mathbf{v}_l^{-\mu}) \mathbf{P}^{\mu, -\mu} \text{diag}(\mathbf{c}^{-\mu}) \mathbf{T}_N^{(\alpha, \beta) \rightarrow (0, 0)} \mathbf{L}^{\alpha, \beta}, \\ {}_{RL}\mathbf{D}_r^\mu &= \text{diag}(\mathbf{v}_r^{-\mu}) \mathbf{P}^{-\mu, \mu} \text{diag}(\mathbf{c}^{-\mu}) \mathbf{T}_N^{(\alpha, \beta) \rightarrow (0, 0)} \mathbf{L}^{\alpha, \beta}. \end{aligned} \quad (29)$$



Riemann-Liouville Fractional Integral and Derivative

Theorem

Let $\mathbf{P} := \mathbf{P}^{\alpha,\beta}$, $\mathbf{L} := \mathbf{L}^{\alpha,\beta}$ and $\alpha, \beta > -1$. The representations of the inverses of the pseudospectral integration matrices are valid

$$\begin{aligned}({}_{RL}\mathbf{D}_l^{-\mu})^{-1} &= \mathbf{P}^T \mathbf{T}_N^{(0,0) \rightarrow (\alpha,\beta)} (\text{diag}(\mathbf{c}^\mu))^{-1} \mathbf{T}_N^{(-\mu,\mu) \rightarrow (\alpha,\beta)} \mathbf{L}^T \text{diag}(\mathbf{v}_l^{-\mu}), \\({}_{RL}\mathbf{D}_r^{-\mu})^{-1} &= \mathbf{P}^T \mathbf{T}_N^{(0,0) \rightarrow (\alpha,\beta)} (\text{diag}(\mathbf{c}^\mu))^{-1} \mathbf{T}_N^{(\mu,-\mu) \rightarrow (\alpha,\beta)} \mathbf{L}^T \text{diag}(\mathbf{v}_r^{-\mu}).\end{aligned}\quad (30)$$

Moreover, the pseudospectral differentiation matrices are valid

$$\begin{aligned}({}_{RL}\mathbf{D}_l^\mu)^{-1} &= \mathbf{P}^T \mathbf{T}_N^{(0,0) \rightarrow (\alpha,\beta)} (\text{diag}(\mathbf{c}^{-\mu}))^{-1} \mathbf{T}_N^{(\mu,-\mu) \rightarrow (\alpha,\beta)} \mathbf{L}^T \text{diag}(\mathbf{v}_l^\mu), \\({}_{RL}\mathbf{D}_r^\mu)^{-1} &= \mathbf{P}^T \mathbf{T}_N^{(0,0) \rightarrow (\alpha,\beta)} (\text{diag}(\mathbf{c}^{-\mu}))^{-1} \mathbf{T}_N^{(-\mu,\mu) \rightarrow (\alpha,\beta)} \mathbf{L}^T \text{diag}(\mathbf{v}_r^\mu).\end{aligned}\quad (31)$$



3.3 Caputo Derivative

Theorem

The following representations of the pseudospectral differentiation matrix are valid for $\alpha, \beta > -1$

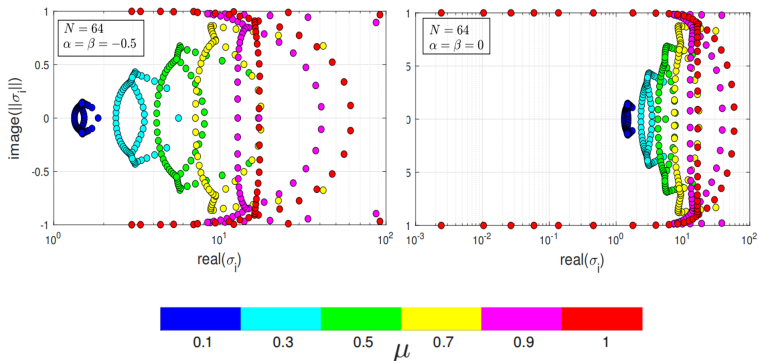
$$\begin{aligned} {}_c\mathbf{D}_l^\mu &= \text{diag}(\mathbf{v}_l^{m-\mu}) \bar{\mathbf{P}}^{\mu-m, m-\mu} \text{diag}(\bar{\mathbf{c}}^{m-\mu}) \mathbf{T}_{N-m}^{(\alpha+m, \beta+m) \rightarrow (0,0)} \bar{\mathbf{D}}^m \bar{\mathbf{L}}^{\alpha, \beta}, \\ {}_c\mathbf{D}_r^\mu &= \text{diag}(\mathbf{v}_r^{m-\mu}) \bar{\mathbf{P}}^{m-\mu, \mu-m} \text{diag}(\bar{\mathbf{c}}^{m-\mu}) \mathbf{T}_{N-m}^{(\alpha+m, \beta+m) \rightarrow (0,0)} \bar{\mathbf{D}}^m \bar{\mathbf{L}}^{\alpha, \beta}, \end{aligned} \quad (32)$$

where $\bar{\mathbf{D}}^m = \text{diag}([d_{m,m}^{\alpha, \beta}, d_{m+1,m}^{\alpha, \beta}, \dots, d_{N,m}^{\alpha, \beta}])$ with $d_{k,m}^{\alpha, \beta} = \frac{\Gamma(k+m+\alpha+\beta+1)}{2^m \Gamma(k+\alpha+\beta+1)}$,
 $(\bar{\mathbf{P}}^{\alpha, \beta})_{i,j} = P_j^{\alpha, \beta}(x_i)$ and $(\bar{\mathbf{L}}^{\alpha, \beta})_{j,i} = l_{j+m,i}^{\alpha, \beta}$ for $i = 0, \dots, N; j = 0, \dots, N-m$.



Eigenvalue of Fractional Differentiation Matrix

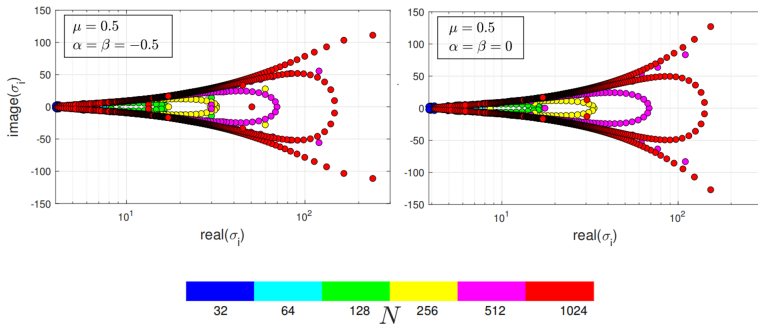
Eigenvalues: Chebyshev vs Legendre(${}_C\mathbf{D}^\mu, N = 64$)



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Eigenvalue of Fractional Differentiation Matrix

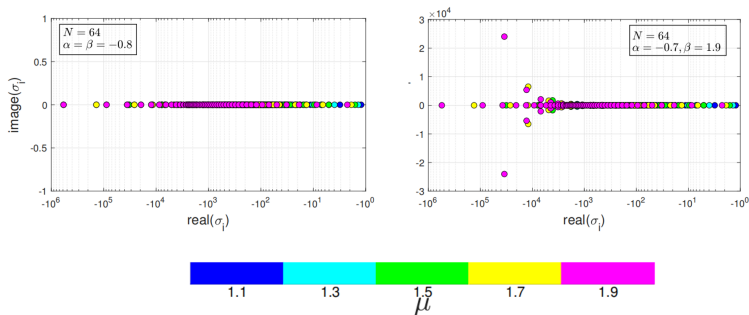
Eigenvalues: Chebyshev vs Legendre(${}_C D^{0.5}$)



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Eigenvalue of Fractional Differentiation Matrix

Eigenvalues: Symmetry vs non-symmetric(${}_{RZ}\mathbf{D}^\mu, N = 64$)



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Application of fractional eigenvalue problems

Example (1)

Let $1 < \mu < 2$. Consider the boundary value problem

$$\begin{aligned} {}_C D_{0,x}^{\mu} u(x) + \lambda u(x) &= 0, \\ pu(0) - ru'(0) &= 0, \quad qu(1) + su'(1) = 0. \end{aligned} \tag{33}$$

where $p, q, r, s \geq 0$ such that $p^2 + r^2 \neq 0$ and $q^2 + s^2 \neq 0$

This problem is also solved in [3, 6, 5, 4].



Results of fractional eigenvalue problems

Table: The first 9 eigenvalues of example (1), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5$) with $\mu = 1.8$ and $N = 200$.

λ	Our method	[6]	[4]	[5]	[3]
λ_1	9.45685689126	9.4568568891	9.4568568892	9.4997	9.4569
λ_2	28.47687912479	28.4768791170	28.4768791186	28.5116	28.4769
λ_3	62.20037779983	62.2003777331	62.2003777529	62.3239	62.2004
λ_4	97.06323747284	97.0632373708	97.0632377552	97.0896	97.0632
λ_5	155.45013805266	155.4501373840	155.4499080962	155.6972	-
λ_6	196.59593024267	196.5959302453	196.5986985127	196.5152	-
λ_7	301.52706976868	-	-	304.19+3.00i	-
λ_8	306.72685026127	-	-	304.19+3.00i	-
λ_9	461.179+43.050i	-	-	461.24+43.29i	-



Results of fractional eigenvalue problems

Table: The first 6 eigenvalues of example (1), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5$) with $\mu = 1.6$ and $N = 200$.

λ	Our method	[6]	[4]	[3]
λ_1	13.420474051	13.42047399	13.4204739885	13.4205
λ_2	14.645442473	14.64544252	14.6454425351	14.6454
λ_3	47.292859+18.850956i	47.292858+18.850956i	-	-
λ_4	91.705190+43.625498i	91.705189+43.625496i	-	-
λ_5	145.569415+75.805031i	145.569416+75.805025i	-	-
λ_6	207.859129+114.486222i	207.859147+114.486204i	-	-

Table: The first 6 eigenvalues of example (1), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5$) with $N = 200$.

λ	$\mu = 1.9$	$\mu = 1.9$ [6]	$\mu = 1.999$	$\mu = 1.999$ [5]
λ_1	9.5141431295	9.5141431288	9.8648626632	9.8648
λ_2	33.5956714125	33.5956714089	39.4139459491	39.4139
λ_3	73.0390172335	73.0390172163	88.6441581077	88.6442
λ_4	124.4185311384	124.4185311250	157.5323069955	157.5325
λ_5	191.1460514291	191.1460515330	246.0882332022	246.0886
λ_6	267.9451997398	267.9452006460	354.2916713396	354.2922



Results of fractional eigenvalue problems

Table: The first 6 eigenvalues of example (1), computed with the CCM ($\alpha = \beta = -0.5, N = 200$).

λ	$\mu = 1.1$	$\mu = 1.3$	$\mu = 1.5$
λ_1	1.3531852+7.2497408i	5.4727766+8.2732647i	11.1466676+6.1222836i
λ_2	2.8098353+15.7308531i	13.3926574+21.8112244i	33.3136683+23.1298984i
λ_3	4.3033960+24.6907235i	22.3712536+37.9533918i	61.1959645+46.6510167i
λ_4	5.8291184+33.9686708i	32.1686781+55.9626406i	93.8181576+75.3667762i
λ_5	7.3824934+43.4883769i	42.6472214+75.4712271i	130.5448587+108.4998614i
λ_6	8.9599335+53.2043853i	53.7149929+96.2501648i	170.9467051+145.5427194i

Table: The first 6 eigenvalues of example (1), computed with the CCM ($\alpha = \beta = -0.5, N = 200$).

λ	$\mu = 1.9999$	$\mu = 1.99999$	$\mu = 1.999999$	$\mu = 2$	error
λ_1	9.8691292203	9.8695568729	9.8695996482	9.86960440108	1.073e-11
λ_2	39.4719645919	39.4777722446	39.4783530678	39.47841760434	1.995e-11
λ_3	88.8081881526	88.8246142309	88.8262570696	88.82643960980	7.148e-12
λ_4	157.8754859530	157.9098514892	157.9132885198	157.91367041743	8.527e-14
λ_5	246.6748284659	246.7335809315	246.7394571083	246.74011002723	1.336e-12
λ_6	355.2042026720	355.2956013900	355.3047427196	355.30575843924	2.035e-11

Example (2)

Let $1 < \mu < 2$. Consider the boundary value problem

$$\begin{aligned} {}_{RZ}D_x^\mu u(x) + \lambda u(x) &= 0, \\ u(-1) &= 0, \quad u(1) = 0. \end{aligned} \tag{34}$$

The same problem has been studied using the Jacobi-Galerkin spectral method [2].



Results of fractional eigenvalue problems

Table: The first 5 eigenvalues of example (2), computed with the Legendre collocation method ($\alpha = \beta = 0, N = 200$).

λ	$\mu = 1.2$		$\mu = 1.4$	
	Our method	[2]	Our method	[2]
λ_1	1.297024021884	1.296995777	1.483262055566	1.4832334320
λ_2	3.486806460504	3.486730536	4.458260013435	4.4581739838
λ_3	5.911808693986	5.911679975	8.150874006594	8.1507167266
λ_4	8.534627231336	8.534441423	12.424593370123	12.424353637
λ_5	11.292675855564	11.29243001	17.162678802344	17.162347657

Table: The first 5 eigenvalues of example (2), computed with the Legendre collocation method ($\alpha = \beta = 0, N = 200$).

λ	$\mu = 1.6$		$\mu = 1.8$	
	Our method	[2]	Our method	[2]
λ_1	1.728321890005	1.72829595710	2.048752746738	2.04873498313
λ_2	5.756434650807	5.75634828003	7.503181981160	7.50311692608
λ_3	11.312063027525	11.3118933010	15.800031154322	15.7998941633
λ_4	18.177615608424	18.1773428791	26.724474991011	26.7242432849
λ_5	26.187596954514	26.1872040516	40.114581604547	40.1142338051

Application of fractional initial value problems

The basic fractional initial value problem:

$$\begin{aligned} {}_CD_{a,x}^{\mu}u(x) &= f(u, x), \quad m-1 < \mu < m, \\ u^{(k)}(a) &= u_k, \quad k = 0, \dots, m-1. \end{aligned} \quad (35)$$

Example (3)

Let $0 < \mu < 1$. Consider the scalar linear fractional differential equation

$${}_CD_{0,t}^{\mu}u(t) = f(t), \quad t \in (0, T], \quad u(0) = u_0. \quad (36)$$

The term $f(t)$ is chosen so that the exact solution satisfies:

C11. $u(t) = \sum_{k=1}^5 \frac{t^{k\sigma}}{k}, \quad \sigma > 0, \quad t \in (0, 2], \quad u_0 = 0.$

C12. $u(t) = t \sin(t), \quad t \in (0, 2\pi], \quad u_0 = 0.$

C13. $u(t) = E_{\mu,1}(-t^{\mu}), \quad t \in (0, 3], \quad u_0 = 1.$

Results of fractional initial value problems

Table: The error E_∞ and convergence order CO of C11 in example (3), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5, \sigma = 2.5$)

N	$\mu = 0.2$		$\mu = 0.4$		$\mu = 0.6$		$\mu = 0.8$	
	E_∞	CO	E_∞	CO	E_∞	CO	E_∞	CO
12	6.434e-06	-	1.329e-05	-	2.627e-05	-	5.384e-05	-
20	2.356e-07	6.47	5.692e-07	6.17	1.109e-06	6.20	1.968e-06	6.48
28	4.373e-08	5.01	1.055e-07	5.01	2.055e-07	5.01	3.648e-07	5.01
36	1.244e-08	5.00	2.998e-08	5.01	5.840e-08	5.01	1.037e-07	5.01
44	4.559e-09	5.00	1.099e-08	5.00	2.140e-08	5.00	3.800e-08	5.00
52	1.977e-09	5.00	4.764e-09	5.00	9.280e-09	5.00	1.648e-08	5.00
60	9.664e-10	5.00	2.328e-09	5.00	4.536e-09	5.00	8.054e-09	5.00
68	5.168e-10	5.00	1.245e-09	5.00	2.426e-09	5.00	4.307e-09	5.00



Results of fractional initial value problems

Table: The error E_∞ and convergence order CO of C11 in example (3), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5, \mu = 0.5$).

N	$\sigma = 0.5$		$\sigma = 1.2$		$\sigma = 1.8$		$\sigma = 2.2$	
	E_∞	CO	E_∞	CO	E_∞	CO	E_∞	CO
8	4.044e-02	-	1.236e-03	-	1.263e-03	-	7.994e-02	-
16	2.036e-02	0.99	2.410e-04	2.36	1.811e-05	6.12	4.055e-06	14.27
24	1.359e-02	1.00	9.146e-05	2.39	4.193e-06	3.61	6.775e-07	4.41
32	1.020e-02	1.00	4.591e-05	2.40	1.487e-06	3.60	1.908e-07	4.41
40	8.158e-03	1.00	2.689e-05	2.40	6.658e-07	3.60	7.143e-08	4.40
48	6.799e-03	1.00	1.737e-05	2.40	3.453e-07	3.60	3.201e-08	4.40
56	5.828e-03	1.00	1.200e-05	2.40	1.982e-07	3.60	1.624e-08	4.40
64	5.100e-03	1.00	8.708e-06	2.40	1.226e-07	3.60	9.024e-09	4.40



Results of fractional initial value problems

Table: The error E_∞ of C12 in example (3), computed with the Chebyshev collocation method ($\alpha = \beta = -0.5$).

N	$\mu = 0.1$	$\mu = 0.3$	$\mu = 0.5$	$\mu = 0.7$	$\mu = 0.9$	$\mu = 0.99$
6	9.557e-03	2.978e-02	5.208e-02	8.299e-02	1.377e-01	1.931e-01
10	7.758e-06	2.475e-05	4.212e-05	6.440e-05	1.072e-04	1.626e-04
14	1.522e-09	4.709e-09	8.159e-09	1.212e-08	2.043e-08	3.113e-08
18	2.749e-13	5.519e-13	5.405e-13	1.002e-12	1.333e-12	2.055e-12
22	2.398e-13	5.959e-13	3.545e-14	1.024e-12	1.420e-13	1.631e-13



Results of fractional initial value problems

Table: The error E_∞ and convergence order CO of C13 in example (3), computed the Chebyshev collocation method ($\alpha = \beta = -0.5$).

N	$\mu = 0.7$		$\mu = 0.8$		$\mu = 0.9$		$\mu = 0.99$	
	E_∞	CO	E_∞	CO	E_∞	CO	E_∞	CO
4	9.283e-02	-	7.376e-02	-	4.563e-02	-	1.312e-02	-
8	3.180e-02	1.55	1.939e-02	1.93	8.566e-03	2.41	7.498e-04	4.13
16	1.144e-02	1.47	5.948e-03	1.70	2.268e-03	1.92	1.754e-04	2.10
32	4.247e-03	1.43	1.918e-03	1.63	6.379e-04	1.83	4.370e-05	2.01
64	1.597e-03	1.41	6.280e-04	1.61	1.821e-04	1.81	1.103e-05	1.99
128	6.032e-04	1.40	2.066e-04	1.60	5.221e-05	1.80	2.793e-06	1.98
256	2.283e-04	1.40	6.811e-05	1.60	1.499e-05	1.80	7.077e-07	1.98
512	8.647e-05	1.40	2.246e-05	1.60	4.303e-06	1.80	1.794e-07	1.98



Applications of Fractional Boundary Value Problems

Let $1 < \mu < 2$. As a benchmark fractional boundary value problem, we consider the one-dimensional fractional Helmholtz equation as

$$\lambda^2 u(x) - D_x^\mu u(x) = f(x), \quad x \in (a, b), \quad u(a) = u(b) = 0, \quad (37)$$

Example (4)

Consider Equation(37) with the Caputo derivative: $D_x^\mu = {}_C D_{a,x}^\mu$. The source term $f(x)$ is chosen so that the exact solution satisfies one of the following cases:

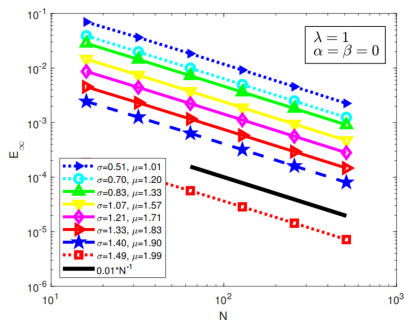
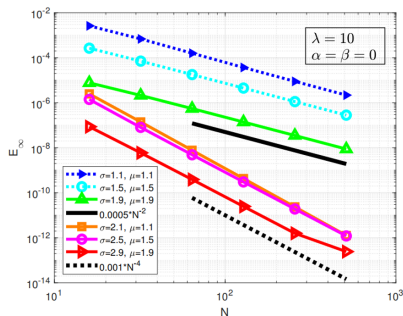
C21. $u(x) = x^\sigma - x^{2\sigma}, \quad \sigma > 0, \quad a = 0, b = 1.$

C22. $u(x) = \sin(\pi x), \quad a = -1, b = 1.$



Results of Fractional Boundary Value Problems

Convergence order: C21 of Example (4)



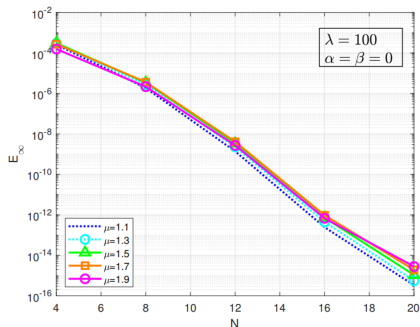
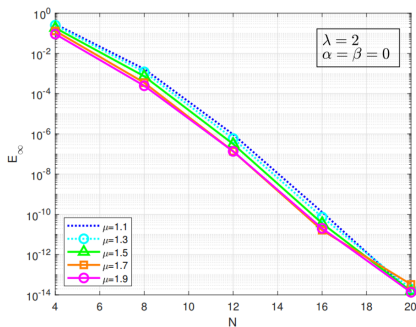
Limited convergence order!!!



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Results of Fractional Boundary Value Problems

Convergence order: C22 of Example (4)



Spectral accuracy!!



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Example (5)

Consider Equation (37) with the Riesz derivative $D_x^\mu = {}_{RZ}D_x^\mu$. The numerical test is performed for the fractional Poisson equation of two cases:

C31. $f(x) = 1, \lambda = 0, a = -1, b = 1$.

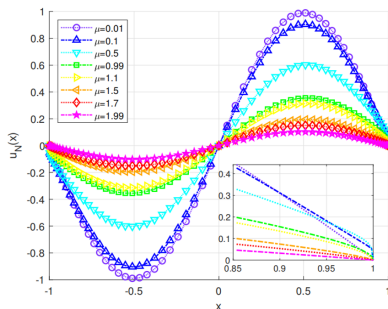
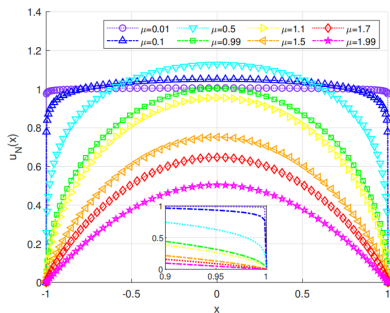
C32. $f(x) = \sin(\pi x), \lambda = 0, a = -1, b = 1$.

We solve the fractional Poisson problems with the Riesz derivative by employing the Legendre spectral collocation method ($\alpha = \beta = 0$) with $N = 64$. The profiles of the numerical solutions are plotted in the next Figure.



Results of Fractional Boundary Value Problems

Numerical solution: C31(left) and C32(right) of Example (5)



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Application of Fractional Initial Boundary Value Problems

The fractional Burgers equations (FBEs):

$$\partial_t u + u \partial_x u = \epsilon D_x^\mu u, \quad (x, t) \in (a, b) \times (0, T] \quad (38)$$

with the boundary condition $u(a, t) = u(b, t) = 0$ and the initial profile $u(x, 0) = u_0(x)$.

For the time discretization, we employ a semi-implicit time discretization scheme with step size τ , namely the two-step Crank–Nicolson/leapfrog scheme. Then, the full discretization scheme reads:

$$\begin{cases} (\mathbf{I} - \epsilon \tau \mathbf{D}^\mu) \mathbf{u}^{n+1} = (\mathbf{I} + \epsilon \tau \mathbf{D}^\mu) \mathbf{u}^{n-1} - 2\tau(\text{diag}(\mathbf{u}^n) \mathbf{D}) \mathbf{u}^n, & n \geq 1, \\ \mathbf{u}^1 = (\mathbf{I} + \epsilon \tau \mathbf{D}^\mu) \mathbf{u}^0 - \tau(\text{diag}(\mathbf{u}^0) \mathbf{D}) \mathbf{u}^0 \\ \mathbf{u}^0 = u_0(\mathbf{x}), \end{cases} \quad (39)$$

where \mathbf{D} is the first-order differentiation matrix. In the following examples, we always take $\alpha = \beta = 0$, $N = 360$ and $\tau = 10^{-3}$.



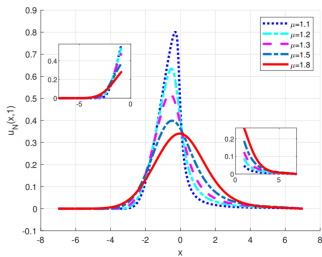
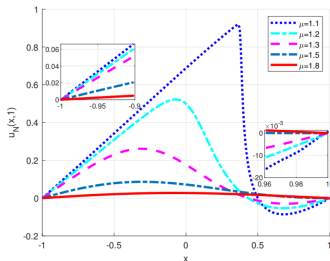
山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Example (6)

Consider Equation (38) with the Caputo derivative: $D_x^\mu = {}_C D_x^\mu$. The numerical test is performed for two cases of initial profiles:

C41. $u_0(x) = \sin(\pi x)$, $a = -1$, $b = 1$.

C42. $u_0(x) = \exp(-2x^2)$, $a = -7$, $b = 7$.

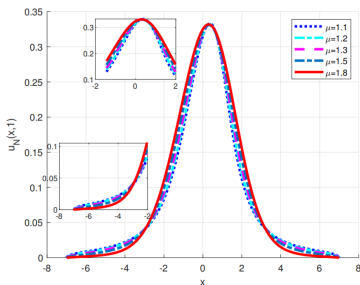
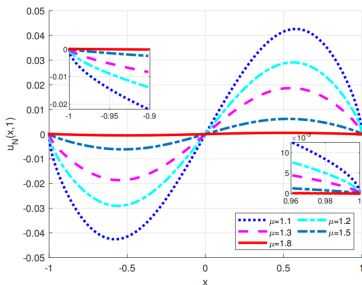


Example (7)

Consider equation (38) with the Riesz derivative: $D_x^\mu = {}_{RZ}D_x^\mu$. The numerical test is performed for two cases of initial profiles:

C51. $u_0(x) = \sin(\pi x)$, $a = -1$, $b = 1$.

C52. $u_0(x) = \exp(-2x^2)$, $a = -7$, $b = 7$.



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY

Summary

We present a new algorithm to evaluate the fractional differentiation matrix.

† Advantages:








- 1 High-accuracy, Fast
- 2 Applicable to solve various fractional differential equations
- 3 Provide more information on fractional differentiation matrix, for, such as, preconditioning

† Disadvantages:

- 1 Can not deal with variable-order case
- 2 Need to explore application of the method to fractional differential equations on high dimensional domains.

The main body of this presentation is from the paper [1].

References

-  Li WB, Ma HJ, Zhao TG. *Construction of fractional pseudospectral differentiation matrices with applications*. Axioms, **13**: 305 (2024)
-  Chen LZ, Mao ZP, Li HY. *Jacobi-Galerkin spectral method for eigenvalue problems of Riesz fractional differential equations*. 10.48550/arXiv.1803.03556
-  Duan JS, Wang Z, Liu YL, Qiu X. *Eigenvalue problems for fractional ordinary differential equations*. Chaos, Solitons and Fractals **46**: 46–53 (2013)
-  Reutskiy SY. *A novel method for solving second order fractional eigenvalue problems*. J Comput Appl Math **306**: 133–153 (2016)
-  He Y, Zuo Q. *Jacobi-Davidson method for the second order fractional eigenvalue problems*. Chaos, Solitons and Fractals **143**: 110614 (2021)
-  Gupta S, Ranta S. *Legendre wavelet based numerical approach for solving a fractional eigenvalue problem*. Chaos, Solitons and Fractals **155**: 111647 (2022)
-  Shen J, Wang YW, Xia JL. *Fast structured Jacobi-Jacobi transforms*. Math Comput **88**(318): 1743–1772. (2019)



Thanks for your attention!



山东理工大学
SHANDONG UNIVERSITY OF TECHNOLOGY