Assignment - 1

1. Modern system still rely on OS because:
→ Abstraction: OS hides hardware complexity (device, CPU, memory) so apps run on many platforms.
→ Resource managment: OS schedules CPU, memory, I/o.

2. Real time embedded OS (RTOS) is used because of predictable timing, low power footprint, small memory/CPU, deterministic interrupt handling.

3. While building a new kernel we should avoid microkernel if raw performance is the only goal. Microkernels give modularity and safety but add IPC overhead because many services run in user space.

4. OS structure doesn't matter as long as process run. Refute because of structure affects :-
→ Performance
→ Reliability/security
→ Maintainability and extensibility
→ Feature support.

5.i) • PCB stores saved registers, PC, stack pointer, state bits
   • PCB's saved PC points to an unexpected address, the next resume will jump to wrong code.

ii) • Save current CPU context into its PCB
   • Change process state to waiting and enqueue on wait queue.
   • Update memory mapping
   • Scheduler selects next process

iii). Use asynchronous non-blocking I/O when you don't want the task to block and you want responsiveness.
- If task must wait for I/O result before proceeding, use blocking synchronous set calls.

6. Save state = 2ms
   Load state = 3ms
   Scheduler overhead = 1ms

a) Total context switching time = 2 + 3 + 1 = 6ms
b) Impact on multitasking:
→ Every switch costs 6ms of CPU. High context-switch rate reduces effective CPU for user work.
→ Frequent switching increases cache.

7. Single threaded total time = 40s
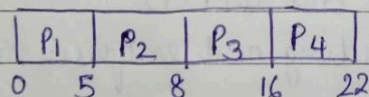   Threads per process = 2

- Estimate execution time = $\frac{40}{2}$ = 20 seconds

- Multithreading helps allows parallelism on multiple core and hides latency by overlapping I/O with computation.
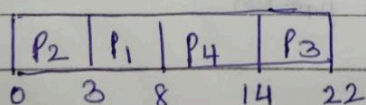
8. Process P_1 P_2 P_3 P_4
   Time(ms)   5   3   8   6

a) Gantt chart
- FCFS

P_1	P_2	P_3	P_4
0 5	8	16	22

- SJF

P_2	P_1	P_4	P_3
0 3	8	14	22

- Round Robin (Quantum = 4ms)

P_1	P_2	P_3	P_4	P_1	P_3	P_4
0	4	7	11	15	16	20	22

b) Waiting time = Start time - arrival time

TAT - burst

Turnaround time = Finish time - arrival time

FCFS : $P_1 = 5$, $P_2 = 8$, $P_3 = 16$, $P_4 = 22$

TAT = 5 + 8 + 16 + 22 = 51

$= \dfrac{51}{4}$ = 12.75

waiting time = TAT - burst

= 0 + 5 + 8 + 16 = 29.

Avg. WT = $\dfrac{29}{4}$ = 7.25

SJF $P_2 = 3$, $P_1 = 8$, $P_4 = 14$, $P_3 = 22$

TAT = 8 + 3 + 22 + 14 = 47

$= \dfrac{47}{4}$ = 11.75

waiting time = TAT - burst

$\left. \begin{array}{l} = 8 - 5 = 3 \\ 3 - 3 = 0 \\ 22 - 8 = 14 \\ 14 - 6 = 8 \end{array} \right\}$ Sum = 25

Avg. WT = $\dfrac{25}{4}$ = 6.25

Round Robin $P_1 = 16$, $P_2 = 7$, $P_3 = 20$, $P_4 = 22$

TAT = 16 + 7 + 20 + 22 = 65.

Avg. TAT = $\frac{65}{4}$ = 16.25

Waiting time = TAT - burst =

$\left.\begin{array}{l} 16 - 5 = 11 \\ 7 - 3 = 4 \\ 20 - 8 = 12 \\ 22 - 6 = 16 \end{array}\right\}$ Sum = 43

Avg. WT = $\frac{43}{4}$ = 10.75

c) SJF gives lowest average turnaround 11.75 and lowest avg. waiting 6.25 among the three.

9 i)a) Microkernel or modular layered architecture is preffered for scalibility and security.

• Microkernel : small trusted core, most services run in user space.
• Layered modular : It is designed also aids maintainiblity and clear separation.

b)• Isolation : each virtual machine has separate guest OS and virtual hardware.

• Management : Virtual machine support snapshots, cloning, living migration, templates for rapid deployment.

• Reduce optimisation : Hypervisors multiplex CPU/memory/ disk across virtual machine support overcommit, dynamic scaling and scheduler - level QoS.

ii)a) Ensuring high priority tasks are handled without delay.
- Priority - based scheduling :- Assign high priority to intrusion detection tasks.

- Real-time scheduling : Use ~~Rate~~ Real time scheduler for critical tasks so deadlines are met.

- Priority inheritance : Avoid priority inversion when lower-priority tasks hold resources needed by high-priority tasks.

b)• Rate Monotonic Scheduling (RMS) : Good for periodic hard-real time tasks with fixed periods.

- Earliest Deadline First (EDF) : Optimal for dynamic deadlines and mixed workloads - better CPU utilization if tasks have different deadlines.

- Hybrid approach : Use real-time scheduler (RMS) for safety/critical tasks.

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