

Syllabus

- 1) Vector spaces
- 2) Linear Transformation
- 3) Inner product space (IPS)
- 4) Matrix norms
- 5) Diagonalization (Eigen vector & Eigen value)
- 6) Singular value decomposition (SVD).

► Matrix & its types

- ① Matrix: Arrangement of $m \times n$ numbers into rectangular array.
 - Arrangement of m -dimensional vector in n -columns in a rectangular array.
 - Vector is a vertical arrangement of scalars.
- ② Types
 - ① Row matrix - the matrix in which only one row is present.
 $A = [a_{11} \ a_{12} \ \dots \ a_{1n}]_{1 \times n}$
 - ② column matrix - the matrix in which only one column is present.
 $A = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}_{m \times 1}$
 - ③ square matrix: The matrix in which equal no. of rows & columns are present.
 $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}_{n \times n} = [a_{ij}] \quad \forall i, j = 1, 2, \dots, n$
 - ④ zero Matrix (Null matrix): All entries are zero
 $A = [0_{ij}]_{n \times m} \quad \forall i, j$
 - ⑤ Diagonal Matrix: It is defined as and
$$A = \begin{cases} d_{ii} & ; \quad \forall i = j \\ 0 & ; \quad i \neq j \end{cases}$$

$$A = \begin{bmatrix} d_{11} & 0 & 0 & 0 \\ 0 & d_{22} & \dots & 0 \\ 0 & \vdots & d_{33} & \vdots \\ 0 & \ddots & \dots & d_{nn} \end{bmatrix}_{n \times n}$$

⑥ Scalar matrix: If it is diagonal matrix and it is given by,

$$A = \begin{cases} d & ; i=j \\ 0 & ; i \neq j \end{cases} \quad A = \begin{bmatrix} d & 0 & 0 & 0 \\ 0 & d & \dots & \\ 0 & \dots & \dots & d \end{bmatrix}_{n \times n}$$

⑦ Identity matrix

⑧ Lower triangular

⑨ Upper triangular

⑩ Symmetric $\underline{[A = A^T]}$

⑪ Skew symmetric $A = -A^T$

Note: every square matrix can be written as sum of symmetric & skew-symmetric matrix.

⑫ Conjugate $A = [(x+iy)_{ij}]_{n \times n}$ conjugate $[(x-iy)_{ij}]_{n \times n}$

⑬ Hermitian
↳ square matrix, if $A = A^*$ where $A^* = (\bar{A})^T$

⑭ Skew-Hermitian

$$A^* = -A$$

⑮ Orthogonal

If A is invertible \rightarrow orthogonal $\Rightarrow A^T = A^{-1}$ i.e. $AA^T = A^TA = I$

⑯ Idempotent

$$\text{if } A^2 = A$$

⑰ Involuntary

Let A be invertible \rightarrow involuntary $\Rightarrow A^2 = I$ ($A = A^{-1}$)

⑱ Nilpotent $A^n = 0_{n \times n}$ \hookrightarrow index of nilpotent

⑲ Unitary matrix

Let A be square complex matrix & invertible

$$\text{if } A^* = A^{-1}$$

$$\text{⑳ } A^*A = AA^* = I$$

$$\begin{bmatrix} 1 + i/2 & 1 - i/2 \\ 1 - i/2 & 1 + i/2 \end{bmatrix} \begin{bmatrix} \sqrt{3} & (1+i)/\sqrt{3} \\ (1-i)/\sqrt{3} & -1/\sqrt{3} \end{bmatrix}$$

㉑ Normal matrix

A is called normal if

$$A^*A = AA^*$$

Vector Space

Binary operation on a Set

Let A be the any non-empty set. we say $*$ is Binary operation on set A if $*$ is mapping / function from

$$A \times A \rightarrow A$$

$$(*: \underbrace{A \times A}_{\text{Cartesian product of set } A} \rightarrow A)$$

↳ Cartesian product of set A .

$$(a, b) \rightarrow c, c \in A$$

i.e. $a * b \in A$

eg. ① $A = \mathbb{N}$, $* = +$
(usual addition)

Soln: If $a, b \in \mathbb{N}$

$$\hookrightarrow a * b = a + b \in \mathbb{N} \quad \forall a, b \in \mathbb{N}$$

$* = +$ is a binary operation on set \mathbb{N}

② $A = \mathbb{Z}$, $* = -$

$-$ is binary operation on \mathbb{Z} , since

$$a, b \in \mathbb{Z}$$

$$a * b = a - b \in \mathbb{Z}$$

③ $A = \mathbb{Q}$, $* = \div$

$$a \neq 0, b \neq 0$$

$1 * 0 = 1 \div 0$ is not defined

so if $A = \mathbb{Q} \setminus \{0\}$ then $* = \div$ is binary operation on set A .

④ $A = \mathbb{Q}^c$, $* = +$

$$a = \sqrt{2}, b = -\sqrt{2}$$

$$a * b = (\sqrt{2}) + (-\sqrt{2}) = 0 \notin \mathbb{Q}^c$$

⑤ $A = \mathbb{R}$, $a * b = a^b \quad \forall a, b \in A$

$$a = -1, b = 1/2$$

$$a * b = a^b = (-1)^{1/2} = i \in \mathbb{R}$$

⑥ $A = P(N)$, $* = \cup$
 $M, N \in P(N) \wedge M, N$
 $M \cup N \subseteq M \in P(N)$

D Identity element of a set:
Let, A be the any non-empty set $e \in A$ is said to be an identity element if $*$ is binary operation on A then e is identity element of A if

$$a * e = e * a = a \quad \forall a \in A$$

eg ① $A = \mathbb{R}$, $* = +$
clearly 0 is the identity of \mathbb{R} since

$$a + 0 = 0 + a = a, \forall a \in \mathbb{R}$$

Here, 0 is called as additive identity of \mathbb{R} .

② $A = \mathbb{R}$, $* = \times$
then 1 is the identity element of \mathbb{R} w.r.t. binary operation ' \times ', since $a \times 1 = 1 \times a = a$
(1 is called as multiplicative identity of \mathbb{R})

③ $A = M_n(\mathbb{R})$, $* = +$
↳ Null matrix

$A = M_n(\mathbb{R})$, $* = \times$
(Null matrix, $2, 0$)

④ $A = P(N)$, $* = \cup$
Here, identity element of a set $P(N)$ is \emptyset .
since, $M \cup \emptyset = \emptyset \cup M = M \quad \forall M \in P(N)$

⑤ $A = P(N)$, $* = \cap$
 N is identity element of $P(N)$ w.r.t. Binary operation ' \cap '
since, $N \cap A = A \cap N = A \quad \forall A \in P(N)$

▷ Associative & commutative Binary operation on set:

Let A be the any non-empty set and $*$ be any binary operation on A then $*$ is said to be commutative binary operation.

If $a * b = b * a \quad \forall a, b \in A$ and $*$ is associative if

$$(a * b) * c = a * (b * c) \quad \forall a, b, c \in A$$

e.g. ① $A = M_n(\mathbb{R})$, $*$ = \times

It is not commutative but associative

▷ Inverse of a element:

Let A be the any non-empty set and $*$ is the binary operation on A , b is said to be inverse of a w.r.t. binary operation $*$ if,

$$a * b = b * a = e$$

(where, e is identity element of A w.r.t. B.O. $*$)

e.g. ① $A = \mathbb{R}$, $*$ = $+$

$\forall a \in \mathbb{R}$ then exist an inverse.

w.r.t. B.O. ' $+$ ', $b = -a$

such that, $a * b = a + (-a) = 0$
 $(-a) + a = 0$

② $A = \mathbb{R}$, $*$ = \times

$\forall a \in \mathbb{R}$, there exist an inverse

w.r.t. B.O. ' \times ', $b = \frac{1}{a}$

such that, $a * b = a \times \frac{1}{a} = 1$

$$\frac{1}{a} \times a = 1$$

e.g. let $A = \mathbb{R}$, $* \rightarrow$ B.O. on $A = \mathbb{R}$ and it is defined as

$$a * b = a + b + a \cdot b \quad \forall a, b \in \mathbb{R}$$

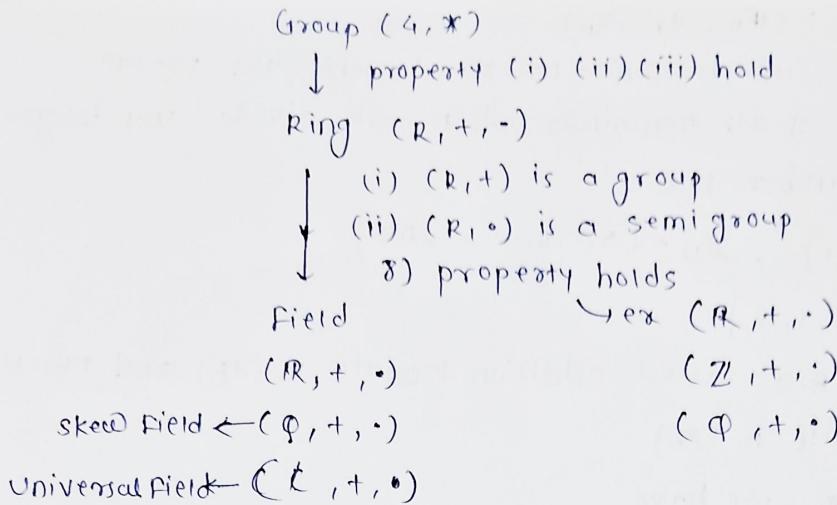
Find ① Identity element w.r.t. $*$

② Inverse of element (possible) in \mathbb{R} .

► Field : Let $\Phi = F$ be any set together with binary operations addition (+) and multiplication (\cdot) is said to be field if following

properties are satisfied :

- 1) $a + (b + c) = (a + b) + c \quad \forall a, b, c \in F$
(Associativity w.r.t. +)
- 2) $a + 0 = 0 + a = a \dots$ (Existence of additive identity)
- 3) $a + (-a) = (-a) + a = 0 \dots$ (Existence of additive inverse)
- 4) $a + b = b + a \quad \forall a, b \in F \dots$ (commutativity)
- 5) $a \cdot (b \cdot c) = (a \cdot b) \cdot c \dots$ (Associativity w.r.t. \cdot)
- 6) $a \cdot 1 = 1 \cdot a = a \dots$ (Existence of multiplication identity)
- 7) $a \cdot b = b \cdot a = 1 \dots$ (Existence of multiplicative inverse)
(given $b=1$ or $b=a^{-1}$) ($0 \neq a$)
- 8) $a \cdot (b+c) = a \cdot b + a \cdot c \quad \forall a, b, c \in F \rightarrow$ (left distribution)
 $(a+b) \cdot c = a \cdot c + b \cdot c \quad \forall a, b, c \in F \rightarrow$ (right distribution)
- 9) $a \cdot b = b \cdot a \quad \forall a, b \in F$ (commutativity)



Group

- (1) $a * (b * c) = (a * b) * c$
 - (2) $a * e = e * a = a$
 - (3) $a * b = b * a = e$
 - (4) $a * b = b * a$

ex : $(\mathbb{R}, +)$, $(\mathbb{Z}, +)$
 $(\mathbb{Q}, +)$, $(\mathbb{C}, +)$
 (\mathbb{R}^n, \times)

D Alternative definition of field

Let $\phi = F$ be any set with two binary operation addition ($+$) and multiplication (\cdot) is field if following properties are satisfied.

- (i) $a \cdot b = b \cdot a \quad \forall a, b \in \text{IF}$ (commutativity)
 - (ii) Existence of inverse of each non-zero element in IF.
 i.e.; $\forall 0 \neq a \in \text{IF}, \exists b \in \text{IF}$
 s.t. $a \cdot b = b \cdot a = 1$

$\Rightarrow b$ is called inverse of a and it is defined by

$$b = a^{-1} \text{ or } b = \frac{1}{a}$$

Ex : \mathbb{Q} , \mathbb{R} , \mathbb{C} are standard Fields
(infinite)

D Finite Field : $(\mathbb{F}_p, +_n, \times_n)$

The field in which finite no. of elements are present.

\mathbb{Z}_n = set of all remainder when we divide any integer by a number $n \in \mathbb{Z}^+$.

$$\mathbb{Z}_2 = \{0, 1\}, \mathbb{Z}_n = \{0, 1, 2, \dots, n-1\}$$

$$\mathbb{Z}_3 = \{0, 1, 2\}$$

We define B.O called addition module n (+_n) and multiplication module n (_n).

$\forall a, b \in \mathbb{Z}_n$ we have,

$a +_n b =$ least +ve remainder when we divide $a+b$ by n .

$a \times_n b =$ least +ve remainder when we divide $a * b$ by n .

$$\text{ex: } \mathbb{Z}_3 = \{0, 1, 2\} \quad 1 +_3 2 = 0 = \text{rem}\left(\frac{1+2}{3}\right)$$

5 min. 10 min. 1 hr.

~~8~~ H.W. find all additive inverse and multiplicative inverse for all elements in \mathbb{Z}_{11} .

Vector Spaces ($V(\mathbb{F})$)

Let, V be a non-empty set of objects on which two binary operations i.e. addition (+) and multiplication (\cdot) are defined. We say V is a vector space over a field \mathbb{F} if following properties/conditions are satisfied for all $u, v, w \in V$ and $k, m \in \mathbb{F}$.

1) If u, v are the objects in V then $u+v$ is in V

$$\because (\forall, u, v \in V \Rightarrow u+v \in V)$$

2) $u+(v+w) = (u+v)+w$ (vector addition must be associative)

3) There is an object 0 in V called zero vector such that $0+u=u$, $\forall u \in V$ (existence of zero vector)

4) For each u in V , there is an object $-u$ such that $u+(-u) = (-u)+u = 0$

$\triangleright (V, +)$ is a group

5) If k is any scalar in \mathbb{F} and u is any object in V then $k \cdot u$ is in V

$$(\text{i.e. } \forall k \in \mathbb{F}, u \in V \Rightarrow ku \in V)$$

6) $k(u+v) = ku+kv$ distributes over vector addition

7) $(k+m)u = ku+mu$ distributes over scalar addition

8) $k(mu) = (km)u$

Abelian group $\Rightarrow (V, +)$

9) $1 \cdot u = u$, $\forall u \in V$

\downarrow multiplicative identity in \mathbb{F}

10) $u+v = v+u$ $\forall u, v \in V$ (commutative)

\triangleright Where, objects in the V are called as vectors and the elements in the \mathbb{F} (field) are called as scalars.

e.g. ① $V = \{0\}$ forms a vector space over \mathbb{R} (Field).

Set of Real Numbers. \mathbb{R} .

① $V = \mathbb{R}^n$, $\mathbb{F} = \mathbb{R}$

$$\mathbb{R}^n = \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \mid x_1, \dots, x_n \in \mathbb{R} \right\}$$

$\mathbb{R}^n (\mathbb{R})$ forms a vector space over coordinate wise addition

(+) scalar multiplication defined by,

$$\text{If } u = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} \text{ and } v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}, k \in \mathbb{R}$$

$$u+v = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} + \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$$

$$= \begin{bmatrix} u_1 + v_1 \\ \vdots \\ u_n + v_n \end{bmatrix}, \quad ku = k \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} = \begin{bmatrix} ku_1 \\ \vdots \\ ku_n \end{bmatrix}$$

* HW. show that $\mathbb{R}^n (\mathbb{R})$ is vector space

② $V = \text{Set of } 2 \times 2 \text{ matrices over } \mathbb{R}$, $\mathbb{F} = \mathbb{R}$

$$u = \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix}, v = \begin{bmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{bmatrix}, w = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{bmatrix}, k \in \mathbb{R}$$

Forms vector space w.r.t. operation $+$ and scalar multiplication defined by

$$u+v = \begin{bmatrix} u_{11}+v_{11} & u_{12}+v_{12} \\ u_{21}+v_{21} & u_{22}+v_{22} \end{bmatrix} \text{ and } ku = \begin{bmatrix} ku_{11} & ku_{12} \\ ku_{21} & ku_{22} \end{bmatrix}$$

③ $V = \mathbb{R}$, $\mathbb{F} = \mathbb{Q}$

\mathbb{R} forms a vector space.

$\mathbb{R}(\mathbb{Q})$ forms a vector space

w.r.t usual addition and usual multiplication

④ $V = \mathbb{Q}$, $\mathbb{F} = \mathbb{R}$

$$k = \sqrt{2}, v = \frac{1}{2}$$

$$ku = \frac{\sqrt{2}}{2} = \frac{1}{\sqrt{2}} \notin \mathbb{Q}$$

$\mathbb{Q}(\mathbb{R})$ does not form vector space

⑤ $\mathbb{Q}(\mathbb{Q})$ is forms vector space.

⑥ $V = \mathbb{Z}_p$, $\mathbb{F} = \mathbb{Z}_p$ ($\mathbb{Z}_p + n/x_n$)

\mathbb{Z}_p forms a vector space

$$\mathbb{Z}_p(\mathbb{Z}_p)$$

HW.

V = set of all polynomials of degree $\leq n$ with coefficient from \mathbb{R} .

$$V = \left\{ a_0 + a_1x + a_2x^2 + \dots + a_nx^n \mid a_i \in \mathbb{R}, i=1, \dots, n \right\}$$

$P_n(\mathbb{R})$, $\mathbb{F} = \mathbb{R}$

Prove that $P_n(\mathbb{R})$ forms a vector space with respect to operation

+ and multiplication (scalar) defined by

For $p_1(x), p_2(x) \in P_n(\mathbb{R})$

$$\Rightarrow p_1(x) + p_2(x)$$

$$\Rightarrow k \cdot p_1(x)$$

Here,

$$\text{let } V_1 = \left\{ a_0 + a_1x + a_2x^2 + \dots + a_nx^n \right\}$$

$$V_2 = \left\{ b_0 + b_1x + b_2x^2 + \dots + b_mx^m \right\}$$

$$\therefore V_1 + V_2 = \left\{ (a_0 + b_0) + (a_1 + b_1)x + (a_2 + b_2)x^2 + \dots + (a_n + b_m)x^n \right\} \subset \mathbb{R}$$

closed under vector addition

let k be any scalar

$$\therefore kV_1 = \left\{ ka_0 + ka_1x + ka_2x^2 + \dots + ka_nx^n \right\} \subset \mathbb{R}$$

closed under scalar multiplication

Thus $P_n(\mathbb{R})$ forms a vector space.

① $V = \mathbb{C}$, $\mathbb{F} = \mathbb{R}$

$C(\mathbb{R})$ forms a vector space under usual vector addition and usual multiplication

② $V = \mathbb{R}$, $\mathbb{F} = \mathbb{C}$

$\mathbb{R}(\mathbb{C})$ does not form a vector space.

$$k \cdot u = \mathbb{R}$$

$$i \in \mathbb{C}, u = 100 \in \mathbb{R}$$

$$\Rightarrow i \cdot 100 = 100i \notin \mathbb{R}$$

* Field is a vectorspace over its subfield

$$\phi \in \mathbb{R} \in \mathbb{C}$$

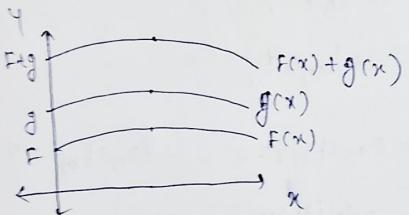
- The field \mathbb{F} forms a vector space over its subfield.
- $\mathbb{F}(\mathbb{F})$ forms a vector space,
 \mathbb{F} is subfield of \mathbb{F} .

⑨ V = set of all real valued functions $F: \mathbb{R} \rightarrow \mathbb{R}$

$$V = \{F: \mathbb{R} \rightarrow \mathbb{R} \mid F \text{ is real valued}\} \text{ and } \mathbb{F} = \mathbb{R}$$

\Rightarrow forms a vector space under operations

- i) $(F+g)(x) = F(x) + g(x), \forall F, g \in V$
- ii) $(kf)(x) = kF(x) \quad \forall k \in \mathbb{R}, F \in V$



Q. $V = \mathbb{R}^+$, $\mathbb{F} = \mathbb{R}$ in \mathbb{R}^+ 0 is the value of 0.

$$u+v=uv$$

$$\begin{cases} ku=u^k \\ \text{in this } 0=1 \end{cases}$$

eg. ① Let $V = \mathbb{R}^2$ and define addition and scalar multiplication as follows

IF $u, v \in \mathbb{R}^2$ and $k \in \mathbb{R}$

$$u = (u_1, u_2)$$

$$v = (v_1, v_2)$$

$$u+v = (u_1+v_1, u_2+v_2)$$

$$k \cdot u = (k \cdot u_1, 0)$$

$$u = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, v = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

$$u+v = \begin{bmatrix} u_1+v_1 \\ u_2+v_2 \end{bmatrix}$$

$$\text{given, } ku = (ku_1, 0)$$

$$\text{but } 1 \cdot u = (u_1, u_2) \neq (u_1, 0)$$

Thus, \mathbb{R}^2 does not form vector space.

② $V = \text{set of all positive real numbers } (\mathbb{R}^+)$ (unusual vectorspace)

$$F = \mathbb{R}$$

let $u, v \in V, k \in \mathbb{R}$

we define operations on V as follows,

$$u+v = u \cdot v \text{ (usual mult.)}$$

& $k \cdot u = u^k$ (usual exponential) V , forms a vector space?

Soln

$$k(u+v) = ku + kv$$

$$\text{LHS} = k(u+v)$$

$$= (u+v)^k$$

$$= (u \cdot v)^k \dots (u+v = u \cdot v)$$

$$= u^k \cdot v^k$$

$$= (ku) (kv)$$

$$= ku + kv$$

$$= \text{RHS}$$

This forms a vector space.

To find additive inverse and multi. inverse of each element in $(\mathbb{Z}_{19}, +_{19}, \times_{19})$ $\mathbb{Z}_{19} = \{0, 1, 2, 3, \dots, 18\}$

The additive inverse of each element in \mathbb{Z}_{19}

$$a +_{19} b = b +_{19} a = 0$$

$$\text{Let } a = 0, b = 0$$

$$a = 1, b = 18 \Rightarrow \frac{1+18}{19} = \frac{19}{19} \quad [\text{rem}=0]$$

$$a = 2, b = 17$$

$$a = 3, b = 16$$

$$a = 4, b = 15$$

$$a = 5, b = 14$$

$$a = 6, b = 13$$

$$a = 7, b = 12$$

$$a = 8, b = 11$$

$$a = 9, b = 10$$

$$a = 10, b = 9$$

$$a +_{n} b = r \left(\frac{a+b}{n} \right), r = \text{least remainder}$$

* Multiplicative inverse

We want $b \in \mathbb{Z}_{19}$ for each non-zero element $a \in \mathbb{Z}_{19}$ such that

$$ax_{19}b = 1$$

$$a = 1, ax_{19}b = 1, b = 1$$

$$\frac{1 \times 1}{19} : \text{rem} = 1$$

$$a = 2, \frac{2x_{19}b}{19} = 1, b = 10$$

$$2x_{19}10 : \text{rem} = 1$$

$$a = 3, \frac{3x_{19}b}{19} = 1$$

$$\frac{3x_{19}b}{19} = 1, b = 13, \frac{3x_{19}13}{19} = \frac{39}{19} : \text{rem} = 1$$

Theorem ①

Let V be the vector space over a field \mathbb{F} and k be the any scalar, then

$$(1) 0 \cdot u = 0$$

$$(2) k \cdot 0 = 0$$

$$(3) (-1) \cdot u = -u$$

$$(4) \text{ If } k \cdot u = 0 \text{ then } k=0 \text{ or } u=0$$

↳ integral property

PROOF: (1) To prove: $0 \cdot u = 0$

since $0+0=0$, $0 \in \mathbb{F}$

$$(0+0) \cdot u = 0$$

$$0u+0u = 0 \quad (\text{By 8})$$

Adding $-0u$ on both sides

$$0u+0u+(-0u) = 0+(-0u)$$

$$0 \cdot u + (0 \cdot u + (-0 \cdot u)) = -0 \cdot u$$

$$0 \cdot u + 0 = -0 \cdot u$$

$$\text{LHS} = 0 \cdot u = (0+0)u$$

$$(0+0)u = 0 \cdot u$$

$$0 \cdot u + 0 \cdot u = 0 \cdot u \quad \dots \text{ By property 7 }$$

$$0u+0 \cdot u+(-0 \cdot u) = 0 \cdot u+(-0 \cdot u) \quad \dots \text{ By property 4 }$$

$$0 \cdot u + 0 = 0$$

$$0 \cdot u = 0$$

(2) To prove: $k \cdot 0 = 0$

$$k \cdot 0 = (0+0)k$$

$$(0+0)k = 0 \cdot k$$

$$0 \cdot k + 0 \cdot k = 0 \cdot k$$

$$0 \cdot k + 0 \cdot k + (-0 \cdot k) = 0 \cdot k + (-0 \cdot k)$$

$$0 \cdot k = 0$$

(3) To prove : $(-1)u = -u$

Let $(-1)u = -u$

$$\begin{aligned} \text{i.e. } u + (-1)u &= 1 \cdot u + (-1)u \\ &= (1 + (-1)) u \\ &= 0 \cdot u \end{aligned}$$

$$u + (-1)u = 0$$

$(-1)u$ is additive inverse of u .

$$\boxed{(-1)u = -u}$$

(4) Here, $k \cdot u = 0$ — $\textcircled{*}$

Suppose $k \neq 0$, $k \in F$

$$\Rightarrow \exists k^{-1} \in F$$

$$\therefore k^{-1} \cdot k \cdot u = k^{-1} \cdot 0$$

$$(1) \cdot u = 0 \rightarrow$$

$$\therefore u = 0 \text{ — by property } \textcircled{②}$$

If $k = 0$

$$k \cdot u = 0$$

$$\therefore 0 \cdot u = 0$$

$$\boxed{u = 0} \text{ — by property } \textcircled{①}$$

Prob(T/F)

- i) Is there a vector space with exactly two elements (distinct)?
Yes.

e.g. \mathbb{Z}_2 (\mathbb{Z}_2), \mathbb{R} (\mathbb{R}) = {0, 1}

Every field is vector space over its subfield.

D Subspace (W)

- i) Let, W be the subset of a vector space V is called a subspace of V if W itself forms a vector space over the field \mathbb{F} under the same addition and scalar multiplication defined on V .

Note: $\emptyset (\mathbb{R}) \rightarrow$ does not form vector space
 \leftarrow \mathbb{F} superset
subset \Leftrightarrow field forms V : s. over subfield
i.e. $\mathbb{R}(\emptyset) \rightarrow$ form a sub vector space.

Theorem: Let W be the non-empty subspace of vector space V then W is a subspace of V if and only if following conditions are holding.

- i) If $u, v \in W$ then $u+v \in W$
- ii) If $k \in \mathbb{F}$ (any scalar). $\forall u \in W$ then $k \cdot u \in W$

Proof: Suppose W is a subspace of V

By defn W is a vector space.

Obviously (i), (ii) will hold in W .

Conversely

Assume that, (a) & (b) are hold in W

i.e. $u+v \in W$, $\forall u, v \in W$

$k \cdot u \in W$, $\forall u \in W$, $k \in \mathbb{F}$.

As $k \cdot u \in W$

If $k = 0 \in \mathbb{F}$

$0 \cdot u = 0 \in W$

Let $k = -1 \in \mathbb{F}$

$$k \cdot u = (-1) \cdot u = -u \in W$$

$\Rightarrow W$ is a vector space $\Rightarrow W \subseteq V$

Thus W is a subspace of V .

Properties ①, ③, ④, ⑥ are satisfied.

① $u+v \in W$

③ $u+0=0+u=u$

④ $u+(-u)=(-u)+(u)=0$

⑤ $ku \in V$

Other properties are inhibited by W from V .

Ex-

① Let $W = \{0\} \subseteq V$ over the field \mathbb{F} .

W is a subspace of V

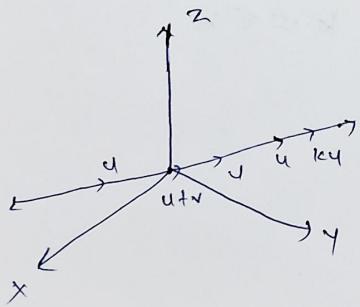
✓ $0+0=0 \in W$

✓ $k \cdot 0=0 \in W$

zero subspace. passing through origin.

② Show that, if W is a line in \mathbb{R}^3 , then W is a subspace of \mathbb{R}^3 .

Let $W = ax + by$



W is closed under vector addition.

$$u+v \in W$$

closed under scalar multiplication

H.W. $W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x=at, y=bt, z=ct \right. \left. \begin{array}{c} \\ \\ c, a, b \in \mathbb{R} \end{array} \right\}$

forming subspace in \mathbb{R}^3 ?

If forms.

③ If W is a plane passing through origin in \mathbb{R}^3 then W forms a subspace of \mathbb{R}^3 .

$ax+by+cz=0$ eqn of plane passing through origin.

HLD

$$W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid ax+by+cz=0 \right\}$$

Yes, it forms.

Let W is a subset of \mathbb{R}^2 defined by $W = \{[x_1] \in \mathbb{R}^2 \mid x_1 \geq 0\}$
Is W is subspace of $V = \mathbb{R}^2$?

i) If $u = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}, v = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \in W$

$$\Rightarrow u+v = \begin{bmatrix} x_1+x_2 \\ y_1+y_2 \end{bmatrix} \in W$$

ii) Let $k \in \mathbb{R}$ and $u = \begin{pmatrix} x \\ 1 \end{pmatrix} \in W$

$$k \cdot u \notin W \text{ take } (k=-1) \quad -u \notin W$$

It is not ~~subspace~~ subspace.

④ Let W be the set of all symmetric matrices. Show that W is a subspace of $M_{n \times n}$. (set of all $n \times n$ matrices).

Given, $W = \{A \in M_{n \times n} \mid A = A^T\}$

Let $A, B \in W$

$$A = A^T \quad \& \quad B = B^T$$

$$(A+B)^T = A^T + B^T \\ = A + B$$

Hence, $(A+B)^T = (A+B)$ is a symmetric matrix $\in W$

Let $k \in \mathbb{R}$, $A \in W \Rightarrow A = A^T$
Any scalar

$$(k \cdot A)^T = k \cdot A^T = kA \quad \& \text{ a symmetric matrix } \in W.$$

Thus, W is a subspace of $M_{n \times n}$.

Q. ① $W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x = at, y = bt, z = ct \right\}$ is subspace in \mathbb{R}^3 ?

We have,

$$\text{Let } \begin{array}{l} x = 0 \\ y = 0 \\ z = 0 \end{array}$$

$$\therefore \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \in \mathbb{R}^3$$

Now,

$$x_1 = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} at \\ bt \\ ct \end{bmatrix} = t \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\text{Let } x_2 = t \begin{bmatrix} a_2 \\ b_2 \\ c_2 \end{bmatrix}$$

$$x_1 + x_2 = t \begin{bmatrix} a_1 + a_2 \\ b_1 + b_2 \\ c_1 + c_2 \end{bmatrix} \in \mathbb{R}^3$$

$$\text{Let } \alpha \in \mathbb{R}$$

$$\therefore \alpha x_1 = \alpha t \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$= t \begin{bmatrix} \alpha a \\ \alpha b \\ \alpha c \end{bmatrix} \in \mathbb{R}$$

thus W forms a subspace.

Q. ②

$$W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 \mid ax + by + cz = 0 \right\}$$
 is subspace in \mathbb{R}^3 ?

Soln

Let $x = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

* ① $V = m \times n$ = set of all $n \times n$ matrices W = set of all skew-symmetric matrices

It forms a subspace

② set of all lower triangular matrices } forms a subspace.

③ set of all upper triangular matrices } forms a subspace.

④ set of all matrices with zero determinant.

↳ Not a subspace

e.g., $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$, $B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

$$|A|=0 \quad |B|=0$$

$$\text{But } |A+B|=1 \neq 0$$

Thus It does not form subspace.

⑤ set of all matrices whose trace is zero.

Forms a subspace.

$$\text{Trace}(A) = 0 \quad \text{Trace}(B) = 0$$

then

$$\text{Trace}(A+B) = 0$$

(*) Let C be the set of all continuous real valued function.
and defined on \mathbb{R} .

D be the set of all differentiable functions
defined on \mathbb{R} .

Show that, C and D are the subspaces of vector space V ,
real valued function.

Soln

$$C = \{F: \mathbb{R} \rightarrow \mathbb{R} \mid F \text{ is continuous}\}$$

$$D = \{F: \mathbb{R} \rightarrow \mathbb{R} \mid F \text{ is differentiable function}\}$$

$$V = \{F: \mathbb{R} \rightarrow \mathbb{R}\}$$

Let $F_1, F_2 \in C$

F_1 and F_2 are continuous

By algebra of functions

$\Rightarrow F_1 + F_2$ is also continuous

$$F_1 + F_2 \in C.$$

Now let $k \in \mathbb{R}$

$\therefore kF_1$ is also continuous

$$kF_1 \in C$$

Thus C forms a subspace of V .

Hence proved.

Let $F_1, F_2 \in D$

F_1 and F_2 are differentiable.

By algebra of functions

$F_1 + F_2$ is also differentiable.

$$F_1 + F_2 \in D.$$

Let $k \in \mathbb{F}$

$$k f_1 \in D$$

Thus D is subspace of $\mathbb{V} \times \mathbb{F}$.

eg. ① Set of all non-continuous & non-differentiable function
one is not subspace.

f_1 and $-f_1$ are not differentiable

then $f_1 + (-f_1) = 0$ and 0 is differentiable thus
it does not form subspace.

② P = set of all polynomials forms a subspace.

$$P \underset{\text{subspace}}{\subset} C \underset{\text{subspace}}{\subset} D \underset{\text{subspace}}{\subset} \mathbb{F}$$

③ Let S be the set of all ~~solutions~~ of differential equations $y'' + y = 0$ then show that S is a subspace of F . (set of real valued functions).

$$S = \{f \in F \mid f \text{ is solution of } y'' + y = 0\}$$

Let $f_1, f_2 \in S$

$\exists f_1$ and f_2 are solutions of $y'' + y = 0$

$$\Rightarrow f_1'' + f_1 = 0 \quad \text{---(1)} \quad \text{and} \quad f_2'' + f_2 = 0 \quad \text{---(2)}$$

Adding eqn (1) and (2)

$$f_1'' + f_1 + f_2'' + f_2 = 0$$

$$(f_1'' + f_2'') + (f_1 + f_2) = 0$$

$$(f_1 + f_2)'' + (f_1 + f_2) = 0$$

thus, $f_1 + f_2$ is a solution of $y'' + y = 0$
 $f_1 + f_2 \in S$.

$$e^{ix} = \cos x + i \sin x$$

$$y = c_1 e^{ix} + c_2 \bar{e}^{ix}$$

$$y = c_1 \cos x + c_2 \sin x$$

$$c_1, c_2 \in \mathbb{C}$$

$$y'' + y = 0 \quad \text{(1)}$$

$r^2 + 1 = 0$ (auxiliary equation)

$$r^2 = -1$$

$$r = \pm i$$

$r = \pm i \Rightarrow$ for complex solution

$$y = c_1 e^{ix} + c_2 e^{-ix}$$

put $y = \cos x$ in (1) $\cos''x + \cos x = 0$
 $-\cos x + \cos x = 0$ (satisfied)

HW show that following are subspaces of given vector spaces.

a) $W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x=y, z=-t \right\} \quad V = \mathbb{R}^4$

b) $W = \left\{ a+bx-bx^2+ax^3 \mid a, b \in \mathbb{R} \right\}$

c) $W = \left\{ \begin{bmatrix} a & b \\ -a & a \end{bmatrix} \mid a, b \in \mathbb{R} \right\} \quad V = M_{2 \times 2}$

d) $W = \left\{ \begin{bmatrix} a & a+1 \\ 0 & b \end{bmatrix} \mid a, b \in \mathbb{R} \right\} \quad V = M_{2 \times 2}$

▷ Linear combination and co-ordinate vector

Let v_1, v_2, \dots, v_k be the vector in V (V is a vector space over field \mathbb{F}) then we say $u \in V$ is in linear combination of v_1, v_2, \dots, v_k if there are constant / scalars $c_1, c_2, \dots, c_k \in \mathbb{F}$ such that

$$u = c_1 v_1 + c_2 v_2 + \dots + c_k v_k$$

e.g. ① $W = \{1, x, x^2\}$

$$\text{span}(W) = \{a_0 1 + a_1 x + a_2 x^2 \mid a_0, a_1, a_2 \in \mathbb{R}\}$$

↳ set of all 2 degree polynomial.

② $W = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right\}$

$$\text{span}(W) = \left\{ \alpha \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \beta \begin{bmatrix} 1 \\ -1 \end{bmatrix} \mid \alpha, \beta \in \mathbb{R} \right\}$$

↳ \mathbb{R}^2

$u \in V(\mathbb{F})$, $S = \{v_1, v_2, \dots, v_k\} \subseteq V$ if $\exists c_1, c_2, \dots, c_k \in \mathbb{F}$ such that $[u = c_1 v_1 + c_2 v_2 + \dots + c_k v_k]$ and the co-ordinate vector of u with respect to vector v_1, v_2, \dots, v_k is given by,

$$[u] = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_k \end{bmatrix}$$

② $V = M_2 \times \mathbb{R}$

$$U = \begin{bmatrix} 1 & -2 \\ 1 & 0 \end{bmatrix}, A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, B = \begin{bmatrix} -2 & 1 \\ 0 & 1 \end{bmatrix}, C = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, D = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

linear

$$\text{combination} = U = c_1A + c_2B + c_3C + c_4D$$

③ $P(x) = 1+x^2$

$$P_1(x) = 1+x$$

$$P_2(x) = 1-x^2$$

$$P(x) = c_1P_1(x) + c_2P_2(x)$$

} do not form linear combination.

$$1+x^2 \notin (c_1+c_2) + c_1x - c_2x^2$$

$$c_1 + c_2 = 1$$

$$-c_2 = 1$$

$$c_1 = 2 \quad (c_1 = -1)$$

$$c_2 = -1$$

but $c_1 = 0$ (constant)

► Spanning set of a vector space V

If $S = \{v_1, v_2, \dots, v_k\}$ is the set of vectors in a vector space V , then the set of all linear combinations of v_1, v_2, \dots, v_k is called span of v_1, v_2, \dots, v_k .

and it is denoted by span of (v_1, v_2, \dots, v_k) or $\langle v_1, v_2, \dots, v_k \rangle$ or $\text{span}(S)$ and if $\text{span}(S) = V$ then 'S' is called a spanning set of V .

$$\text{Span}(S) = \left\{ c_1v_1 + c_2v_2 + \dots + c_kv_k \mid c_1, c_2, \dots, c_k \in \mathbb{R} \right\}$$

$$\text{eg. } \text{span}(\{1\}) = \left\{ c_1 \cdot 1 \mid c_1 \in \mathbb{R} \right\} = \mathbb{R}$$

In general,

the spanning set of \mathbb{R}^n is $\left\{ \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0_n \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} \right\}$

e.g. ① Show that the polynomials $1, x, x^2$ spans $P_2(\mathbb{R})$.

$$\text{span}(S) = \left\{ c_1 \cdot 1 + c_2 x + c_3 x^2 \mid c_1, c_2, c_3 \in \mathbb{R} \right\} = P_2(\mathbb{R}).$$

$(1, x, x^2)$

In general, the spanning set of $P_n(\mathbb{R})$ is $(1, x, x^2, \dots, x^n)$

② $V = M_{2 \times 3}$, what is spanning set of V ?

$$*\quad \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}_{2 \times 3} = a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} + e \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} + f \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Elementary
matrices

$$E_{ij} = \begin{cases} 1 & \text{if } (i, j)^{\text{th}} \text{ entry} \\ 0 & \text{otherwise.} \end{cases}$$

③ In P_2 , Determine whether $r(x) = 1 - 4x + 6x^2$ is in the span
of $(p(x), q(x))$. where $p(x) = 1 - x + x^2$, $q(x) = 2 + x - 3x^2$.

$$r(x) = c_1 p(x) + c_2 q(x)$$

$$1 - 4x + 6x^2 = c_1(1 - x + x^2) + c_2(2 + x - 3x^2)$$

$$1 - 4x + 6x^2 = (c_1 + c_2) + (-c_1 + c_2)x + (c_1 - 3c_2)x^2$$

$$\therefore c_1 + c_2 = 1$$

$$+ \cancel{c_1 + c_2 = -4}$$

$$3c_2 = 5 - 3$$

$$c_2 = -1$$

$$+ \cancel{-1 - 2c_2}$$

$$= +10$$

$$c_1 = 1 + 2$$

$$\cancel{c_1 = -9}$$

$$c_1 = 3$$

$$\text{Thus, } c_1 = 3 \text{ and } c_2 = -1$$

$$\therefore \cancel{c_1 = -9} \text{ and } c_2 = 5$$

Q) In F, is $\sin 2x$ is in span of $(\sin x, \cos x)$

By definition,

$$\sin 2x = a \sin x + b \cos x$$

$$2 \sin x \cos x = a \sin x + b \cos x$$

$$x=0 \quad \text{put } x=0$$

$$\textcircled{i} \quad c_1(0) + c_2(1) = 0$$

$$c_2(0)$$

$$\textcircled{ii} \quad x=\frac{\pi}{2}$$

$$0 = c_1(1) + c_2(0)$$

$$c_1 = 0$$

$$\textcircled{iii} \quad \pi/4 = x$$

$$\sin 2x \cdot \frac{\pi}{4} = a \sin \frac{\pi}{4} + b \cos \frac{\pi}{4}$$

$$\sin \frac{\pi}{4} = a \frac{1}{\sqrt{2}} + b \frac{1}{\sqrt{2}}$$

$$1 = \frac{1}{\sqrt{2}} a + \frac{1}{\sqrt{2}} b$$

$\sin 2x$ is not in span of $(\sin x, \cos x)$

$$\alpha + \beta = a$$

$\beta = d$

$$\alpha + r = c$$

$\alpha = a - d$

$$\alpha + r = b$$

$$\beta = d$$

$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & a \\ 1 & 0 & 1 & c \\ 1 & 0 & 1 & b \\ 0 & 1 & 0 & d \end{array} \right]$$

In $M_{2 \times 2}$ find the span of $m = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $c = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

Here, $M = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, $c = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \in M_{2 \times 2}$

Now, let α & γ be any scalars.

thus, we can write m in linear combination of B and c .

Thus, $m = \alpha B + \gamma c$

$$\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} = \alpha \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \gamma \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} x & 0 \\ 0 & x \end{bmatrix} + \begin{bmatrix} 0 & y \\ y & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} x+y & y \\ y & x \end{bmatrix}$$

Comparing both sides,

$$x=1, 0$$

$$y=1$$

$$\therefore \text{span}(M_{2 \times 2}) = \left\{ m = \alpha \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \gamma \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \mid x+y \in \text{IR} \right\}.$$

M does not form linear combination with B & c thus does not form span.

$$\Rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \alpha \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \beta \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + r \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} \alpha + \beta & \alpha + r \\ \alpha + r & \beta \end{bmatrix}$$

$$\text{Span}\{m, B, c\} = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mid \right.$$

Q. Find the span of the vector $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\} \subseteq \mathbb{R}^3$

$$\text{Let } \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$\exists \alpha, \beta$ such that

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \beta \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\alpha - \beta = x$$

$$2\alpha = y$$

$$3\alpha + \beta = z$$

$$\left[\begin{array}{cc|c} 1 & -1 & x \\ 2 & 0 & y \\ 3 & 1 & z \end{array} \right]$$

$$R_2 \rightarrow R_2 - 2R_1$$

$$R_3 \rightarrow R_3 - 3R_1$$

$$\left[\begin{array}{cc|c} 1 & -1 & x \\ 0 & 2 & y - 2x \\ 0 & 4 & z - 3x \end{array} \right] \xrightarrow{\frac{R_2}{2}} \left[\begin{array}{cc|c} 1 & -1 & x \\ 0 & 1 & \frac{y - 2x}{2} \\ 0 & 4 & z - 3x \end{array} \right]$$

$$R_3 - 4R_2$$

$$\left[\begin{array}{cc|c} 1 & -1 & x \\ 0 & 1 & \frac{y - 2x}{2} \\ 0 & 0 & \frac{z - 3x}{4} - \frac{4(y - 2x)}{2} \end{array} \right]$$

Above system has solution if and only if

$$\frac{z - 3x}{4} - \frac{4(y - 2x)}{2} = 0$$

$$2 - 3x - 2y + 4x = 0$$

$$x + 2 - 2y = 0$$

$$x - 2y + 2 = 0$$

$$\text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x - 2y + 2 = 0 \right\}$$

Linear dependence and linear independence

Defⁿ: let $S = \{v_1, v_2, \dots, v_k\}$ be the set of vectors in a vector space V , we say v_1, v_2, \dots, v_k are linearly dependent if atleast one scalar is non-zero such that $c_1v_1 + c_2v_2 + \dots + c_kv_k = 0$, where c_i 's are the scalars.

Otherwise if $c_1 = c_2 = \dots = c_k = 0$ i.e. all scalars are zero such that $c_1v_1 + c_2v_2 + \dots + c_kv_k = 0$ (c_i = scalars) then v_1, v_2, \dots, v_k are linearly independent.

Ex: ① $S = \{0\}$ subset of V

\Rightarrow linearly dependent (if we multiplied 0 by any scalar let $k \cdot 0 = 0$ so there exist atleast one scalar such that linear combi-

② $S = \{u, u_2, 0\} \subseteq \mathbb{R}^2$
 $u_1, u_2 \neq 0$

(if we multiplied 0 by any scalar let $k \cdot 0 = 0$ so there exist atleast one scalar such that linear combi-

$$\alpha u + \beta u_2 + k \cdot 0 = 0$$

$\forall \gamma \rightarrow$ atleast one constant is non-zero \Rightarrow satisfied linear dependent.

③ $S = \{u, v, \alpha u + \beta v\} \subseteq \mathbb{R}^3$

$\mathbb{R}^2 \rightarrow$ not field

linearly dependent.

$K \rightarrow$ forms field

④ $S = \{1+x, x+x^2, 1+x^2\} \subseteq P_2(\mathbb{R}) \Rightarrow$ linearly independent

$$x+x^2 = \alpha(1+x) + \beta(1+x^2)$$

$$x+x^2 = \alpha + \alpha x + \beta + \beta x^2$$

$$(\alpha+\beta) + \alpha x + \beta x^2 = x + x^2$$

comparing both sides

$$\alpha+\beta=0, \alpha=1, \beta=-1$$

let a, b, c such that

$$a(1+x) + b(x+x^2) + c(1+x^2) = 0$$

$$a+ax+bx+bx^2+c+cx^2=0$$

$$(a+c) + (ax+bx) + (bx^2+cx^2) = 0$$

$$(ax+c) + (a+b)x + (b+c)x^2 = 0$$

$$\begin{array}{l} a+c=0 \\ a+b=0 \\ b+c=0 \\ \hline a=0 \\ b=-c \end{array}$$

$$a=b=c=0$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{array} \right]$$

$$\text{as } a=b=c=0$$

Thus s is linearly independent.

$$\textcircled{5} \quad S = \emptyset \subseteq V$$

empty set in $V \rightarrow$ linearly independent (always)

$$\textcircled{6} \quad A = \begin{bmatrix} 1 & -1 \\ 2 & 0 \end{bmatrix}, B = \begin{bmatrix} 2 & -1 \\ 2 & 2 \end{bmatrix}, C = \begin{bmatrix} -1 & -2 \\ 0 & -2 \end{bmatrix} \text{ are in } M_{2 \times 2}$$

$$\text{(a)} \quad \begin{bmatrix} a & b \\ c & d \end{bmatrix} = x \begin{bmatrix} 1 & -1 \\ 2 & 0 \end{bmatrix} + y \begin{bmatrix} 2 & -1 \\ 2 & 2 \end{bmatrix} + z \begin{bmatrix} -1 & -2 \\ 0 & -2 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} x & -x \\ 2x & 0 \end{bmatrix} + \begin{bmatrix} 2y & -y \\ 2y & 2y \end{bmatrix} + \begin{bmatrix} -z & -2z \\ 0 & -2z \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} x+2y-2 & -x-y-2z \\ 2x+2y & 2y-2z \end{bmatrix}$$

$$a=b=c=d=0$$

$$\therefore x+2y-2=0 \quad \textcircled{1}$$

$$-x-y-2z=0 \quad \textcircled{2}$$

$$2x+2y=0 \quad \textcircled{3}$$

$$2y-2z=0$$

$$2y = 2z$$

$$y = z$$

eqn ②,

$$2x - x - 2z = 0$$

linearly independent.

$$\left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ -1 & -1 & -2 & 0 \\ 2 & 2 & 0 & 0 \\ 0 & 2 & -2 & 0 \end{array} \right] \xrightarrow{\substack{R_2 + R_3 + R_1 \\ R_3 \rightarrow R_3 - 2R_1}} \left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & -2 & 2 & 0 \\ 0 & 2 & -2 & 0 \end{array} \right] \xrightarrow{\substack{R_3 \rightarrow R_3 + R_2 \\ R_4 \rightarrow R_4 - 2R_2}} \left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$R_3 \rightarrow R_3 - 2R_2 \left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - R_2} \left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \therefore z = 0 \quad \therefore y - 3z = 0 \\ \therefore y = 0$$

$$\text{As } x = y = z = 0 \quad \therefore x = 0$$

A, B, C are linearly independence

⑥ $S = \{1 - x + x^2, -1 + x - x^2, 3 - x^2\}$ in P_2 , S is L.I or LD

Let a, b, c such that,

$$a(1 - x + x^2) + b(-1 + x - x^2) + c(3 - x^2) = 0$$

$$a - ax + ax^2 - b + bx - bx^2 + 3c - cx^2 = 0$$

$$(a - b + 3c) + (-a + b)x + (a - b - c)x^2 = 0$$

$$a - b + 3c = 0 \Rightarrow a - b + 3c = 0 \Rightarrow a + 3c = 1$$

$$-a + b = 0 \quad \therefore b = a$$

$$a - b - c = 0 \Rightarrow a - 1 - c = 0 \Rightarrow a - c = 1$$

$$\begin{aligned} a + 3c &= 1 \\ -a + c &= -1 \\ 2c &= 0 \\ c &= 0 \end{aligned}$$

$$\begin{aligned} \therefore a &= 1 + c \\ &\neq 1 + 0 \\ a &= 1 \end{aligned}$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & -1 & -1 & 0 \end{array} \right]$$

$$R_2 + R_2 + R_1 ; R_3 \rightarrow R_3 - R_1$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & -4 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & -1 & 3 & 0 \\ a & a & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$c = 0$$

$$a - b + 3c = 0$$

$$a - b + 0 = 0$$

$$a - b = 0$$

$$a = b$$

the linear combination is,

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = a \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

so above vectors in P_2 are linearly dependent.

⑦ $S = \{\sin x, \cos x, \sin(2x)\} \subseteq F$

HW

Is S is L.I. or L.D. in $\{ \text{set of all } f : \mathbb{R} \rightarrow \mathbb{K} \}$

we cannot write $\sin(2x)$ in L.C. of $\sin x$ & $\cos x$
thus they are linearly independent.

⑧ $S = \{x, |x|\} \subseteq F$

HW

so S is L.I or L.D.

▷ Basis for a vector space (minimal generating set)

Let B be any non empty set in V . We say B is a Basis for V if and only if it satisfies following conditions.

(a) $\text{span}(B) = V$

(b) B is L.I.

▷ Dimensions of vector space

If B is Basis for V then dimensions of vector space is number of element in the B .

e.g. ① Is $B = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$ a Basis for \mathbb{R}^2 ?

$\text{Span}(B) = \mathbb{R}^2$

And B is linearly independent.

② $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 4 \end{bmatrix} \right\} \rightarrow$ Not a basis.

span They are linearly dependent (2 eqn + 3 variables)

Note: If B is a basis for vector space V then it is minimal generating set and maximal linearly independent set.

▷ Dimension of \mathbb{R}^n is n .

HW: Let, $s = \{v_1, v_2, \dots, v_k\} \subseteq V$ is a vector space over \mathbb{R} .

Show that

(a) $\text{span}(s)$ is subspace of V

(b) $\text{span}(s)$ is a smallest subspace of V containing v_1, v_2, \dots, v_k .

(a) $\text{span}(s) = c_1v_1 + c_2v_2 + \dots + c_kv_k$ where $c_i \in \mathbb{R}$ and are scalars.

as $c_1v_1 \in \mathbb{R}$

and $c_1v_1 + c_2v_2 \in \mathbb{R}$

(b) $\text{span}(s)$ is a subspace of V .

(b)

Basis and Dimension

$$\begin{aligned}\mathbb{R}^n &= \left\{ \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \mid x_1, \dots, x_n \in \mathbb{R} \right\} \\ &= \left\{ x_1 \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \dots + x_n \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix} \mid x_1, x_2, \dots, x_n \in \mathbb{R} \right\} \\ &= \{x_1 e_1 + x_2 e_2 + \dots + x_n e_n \mid x_1, x_2, \dots, x_n \in \mathbb{R}\} \\ &= \text{span}\{e_1, e_2, \dots, e_n\}\end{aligned}$$

$\mathbb{R}^n = \langle e_1, e_2, \dots, e_n \rangle$ (generating set)

Also e_1, e_2, \dots, e_n are linearly independent.
standard basis for \mathbb{R}^n

($\hookrightarrow B = \{e_1, e_2, \dots, e_n\}$ is a standard basis of \mathbb{R}^n .)

e.g. Basis for $\mathbb{R}^2 = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$
 \rightarrow linearly independent.

↳ ordered Basis (Basis other than standard basis)

e.g. ① $B = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ Basis for \mathbb{R}^2 .

② $B = \left\{ \begin{bmatrix} \pi \\ e \end{bmatrix}, \begin{bmatrix} e \\ \pi \end{bmatrix} \right\}$ Basis for \mathbb{R}^2 .

(3) $P_n(\mathbb{R}) = \{a_0 + a_1 x + \dots + a_n x^n \mid a_0, a_1, \dots, a_n \in \mathbb{R}\}$

$= \text{span}\{1, x, x^2, x^3, \dots, x^n\}$ \hookleftarrow linearly independent

$P_1(\mathbb{R}) = \{a_0 + a_1 x \mid a_0, a_1 \in \mathbb{R}\}$
 $= \{1, x\}$

\downarrow
since
 $c_1 \cdot 1 + c_2 x + \dots + c_n x^n = 0$
iff ($c_1 = c_2 = \dots = c_n = 0$)

Sanudii ❤

$$\alpha \cdot 1 + \beta \cdot x = 0$$

$$\frac{d}{dx} (\alpha \cdot 1 + \beta \cdot x) = 0$$

$$\begin{aligned}0 + \beta &= 0 \\ \beta &= 0\end{aligned}$$

Wrong scale

$$w(\phi_1, \phi_2) = \begin{vmatrix} \phi_1 & \phi_2 \\ \phi_1' & \phi_2' \end{vmatrix} = \begin{vmatrix} 1 & x \\ 0 & 1 \end{vmatrix} = 1 - 0 = 1 \neq 0$$

so linearly independent.

$$\rightarrow y = c_1 \phi_1(x) + c_2 \phi_2(x)$$

solution

$$y'' - 2y' + y = 0$$

$$x^2 - 2x + 1 = 0$$

$$(x-1)^2 = 0$$

$$x = 1, 1$$

General solution,

$$y = c_1 e^{x} + c_2 x e^{x}$$

$$\begin{vmatrix} e^x & x \cdot e^x \\ e^x & x e^x + e^x \end{vmatrix} \neq 0$$

Dimension of $P_n(\mathbb{R})$ is $n+1$

e.g. ① What is the standard basis for $P_4(\mathbb{R})$

$$B = \{1, x, x^2, x^3, x^4\}$$

Dimension = $n+1 = 4+1=5$

② Basis for $M_{n \times n}(\mathbb{R})$, vector space of matrices

$$M_{n \times n}(\mathbb{R}) = \left\{ \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \mid a_{ij} \in \mathbb{R} \right\}$$

$$M_{n \times n}(\mathbb{R}) = \left\{ a_{11} E_{11} + a_{12} E_{12} + \dots + a_{nn} E_{nn} \mid a_{ij} \in \mathbb{R} \right\}$$

where $E_{\alpha\beta} = \begin{cases} 1 & \text{if } \alpha = i, \beta = j \\ 0 & \text{otherwise} \end{cases} \forall i, j = 1, 2, \dots, n$

eg. $E_{34} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ (3,4)

elementary matrix

eg. ① $\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + a_{12} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + a_{21} \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + a_{22} \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

$$M_{n \times n}(\mathbb{R}) = \text{span} \{E_{11}, E_{12}, \dots, E_{nn}\}$$

Also $P = \{E_{11}, E_{12}, \dots, E_{nn}\}$ is linearly independent

P is standard basis for $M_{n \times n}(\mathbb{R})$

$\dim(M_{n \times n}(\mathbb{R}))$ is $n \times n = n^2$

(Similarly ~~dim~~ Basis of $M_{m \times n}(\mathbb{R})$) = $\{E_{11}, \dots, E_{mn}\}$

$\dim(M_{m \times n}(\mathbb{R}))$ is $m \times n$

② what is dimension of vector space $\mathbb{C}(\mathbb{R})$?
Basis $z = x + iy$

$$\mathbb{C} = \{x+iy \mid x, y \in \mathbb{R}\}$$

$$\mathbb{C} = \text{span}\{1, i\}$$

$$x+iy=0, x, y \in \mathbb{R}$$

$$x=y=0$$

also $\{1, i\}$ is linearly independent in \mathbb{C} .

Basis \hookrightarrow dimension of $\mathbb{C}(\mathbb{R}) = 2$ (as two elements are in span)

$$\mathbb{C} = \{z \mid z \text{ is of the form } x+iy, x, y \in \mathbb{C}\}$$

$\{1, i\}$ is linearly dependent in $\mathbb{C}(\mathbb{C})$

$\{1\}$ is a standard basis for $\mathbb{C}(\mathbb{C})$.

what is dimension of $\mathbb{C}^2(\mathbb{R})$

$$\text{standard Basis } (\mathbb{C}^2(\mathbb{R})) = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} i \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ i \end{bmatrix} \right\}$$

Dimension of $\mathbb{C}^2(\mathbb{R})$ is 4.

$$\text{Similarly in general, } \boxed{\dim(\mathbb{C}^n(\mathbb{R})) = 2n}$$

$$\text{dimension } (M_{m \times n}(\mathbb{C})(\mathbb{R})) = 2n^2$$

$$\text{dimension } (M_{m \times n}(\mathbb{C})(\mathbb{R})) = 2m \cdot n$$

► Dimension of vector space $\mathbb{R}(\mathbb{Q})$?

$$B = \left\{ \sqrt{1}, \sqrt{2}, \sqrt{3}, \dots, \sqrt{p}, \dots \right\} \rightarrow \text{linearly independent}$$

$$\alpha_1 \cdot 1 + \alpha_2 \sqrt{2} + \dots + \alpha_n \sqrt{p} + \dots = 0$$

$$\{1, \sqrt{2}\}$$

Dimensions $\mathbb{R}(\mathbb{Q}) = \text{Infinite } (\infty)$

$$\alpha \cdot 1 + \beta \cdot \sqrt{2} = 0$$

$$\alpha = \beta = 0 \quad L.I.$$

HW Find the dimension of following subspaces.

1) $W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x-y=0, z=0, V=\mathbb{R}^3 \right\}$

2) $W = \left\{ A \in M_{n \times n}(\mathbb{R}) \mid A^T = A \right\}, V = M_{n \times n}(\mathbb{R})$

3) $W = \left\{ p(x) \in P_3(\mathbb{R}) \mid p(3)=0 \right\}, V = P_3(\mathbb{R})$

4) $W = \left\{ A \in M_{n \times n}(\mathbb{R}) \mid \text{tr}(A) = 0 \right\}, V = M_{n \times n}(\mathbb{R})$

1) $W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \mid x-y=0, z=0, V=\mathbb{R}^3 \right\}$

$$x-y=0$$

$$z=0$$

$$\therefore \left[\begin{array}{ccc|c} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Dimension 4+e $\left[\begin{array}{c} 1 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} -1 \\ 1 \\ 0 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 1 \end{array} \right]$

e.g. ① $V = \mathbb{C}(t)$

$$\text{span}\{1\} = \{\alpha \cdot 1 \mid \alpha \in \mathbb{C}\} = \mathbb{C}$$

also $\{1\}$ is linearly independent.

$$(\dim(\mathbb{C}(t)) = 1)$$

② $V = \mathbb{C}(IR)$

$$= \{x \cdot 1 + iy \mid x, y \in IR\}$$

$$= \text{span}\{1, i\} \quad B = \{1, i\} \Rightarrow \dim(\mathbb{C}(IR)) = 2$$

also $\{1, i\}$ is linearly independent.

e.g. ③

$$W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in IR^3 \mid \begin{array}{l} x+y+z=0 \\ x-y-z=0 \end{array} \right\}$$

$$V = IR^3(IR) \quad \dim(W) = ?$$

$$x+y+z=0$$

$$x-y-z=0$$

Augmented matrix

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 - R_1} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & -2 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$R_2 \rightarrow \frac{R_2}{-2} \left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - R_2} \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$x=0$$

$$\therefore y = -z$$

$$y+z=0$$

$$\text{let } z=t$$

$$\therefore \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ -t \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \quad t \in IR$$

$$W = \left\{ t \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \mid t \in IR \right\} = \text{span} \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}$$

Also $\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$ is linearly independent so

$B = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$ is basis for W .

Dimensions for W is 1.

HW ②

$$W = \{ \text{dop}(x) \in P_3(\mathbb{R}) \mid p(1) = 0 \}$$

and where $V = P_3(\mathbb{R})$

$$W = \{ a + bx + cx^2 + dx^3 \mid p(1) = 0 \}$$

also

$$\therefore a + b + c + d = 0$$

$$\therefore a = -b - c - d$$

$$W = \{ -b - c - d + bx + cx^2 + dx^3 \mid a, b, c, d \in \mathbb{R} \}$$

$$W = \{ b(x-1) + c(x^2-1) + d(x^3-1) \mid b, c, d \in \mathbb{R} \}$$

$$\hookrightarrow \text{span} \{ (x-1), (x^2-1), (x^3-1) \}$$

It forms basis as it is linearly independent.

As the powers are different of each term we cannot write one term into linear combination of other.

Dimension of $W = 3$ (As there are three vectors present in basis)

HW ② $W = \{ A \in M_{n \times n}(\mathbb{R}) \mid A^T = A \}$ $V = M_{n \times n}(\mathbb{R})$

For $n=2$

$$A = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$$

no. of linearly independent choices are $= 3$

$$= \frac{2(2+1)}{2}$$

$n=3$

$$A = \begin{bmatrix} a & b & c \\ b & \alpha & \beta \\ c & \beta & \gamma \end{bmatrix}$$

no. of L.I. choices are $= 6 = \frac{3(3+1)}{2}$

By induction we can say

$$\dim(W) = \frac{n(n+1)}{2}$$

dimension of lower & upper triangular matrix.

$$V = \mathbb{R}^n(\mathbb{R})$$

$$W \subseteq V$$

$$\dim(W) = n - (\text{no. of L.I. restrictions})$$

4 conditions

③ $W = \{ A \in M_{n \times n}(\mathbb{R}) \mid \text{trace}(A) = 0 \}$, trace

$$n=2$$

$$A = \begin{bmatrix} -a & a \\ b & a \end{bmatrix} \quad n^2-1$$

$$a-1 = b$$

$$\dim(W) = n^2-1$$

$$n=3$$

$$A = \begin{bmatrix} a+b & c & d \\ e & -a & h \\ f & g & -b \end{bmatrix}$$

$$\begin{aligned} \text{by 8 vectors} \quad n^2-1 \\ &= 3^2-1 \\ &= 9-1=8 \end{aligned}$$

Ex. ① $W = \{ f \in F \mid f \text{ is differentiable} \}$

$$N = F, \dim(W) = ?$$

by infinite

$$B = \{ 1, x, \sin x, \cos x, \log x, e^x, x^2, \sin^2 x, \dots \}$$

by infinite elements in basis.

Thus dimensions for W is infinite.

Note:-

If dimension of V and V' , $V = V'$ then V and V' are the isomorphic vector spaces.

$$\text{eg. } M_{2 \times 2}(\mathbb{R}) \cong \mathbb{R}^4$$

$$P_n(\mathbb{R}) \cong \mathbb{R}^{n+1}$$

① $W = \{ p(x) \in P_2 \mid xp'(x) = px \}$ Find $\dim(W)$, where $p'(x) = \frac{d}{dx}(px)$

Soln

$$V = P_2(\mathbb{R})$$

$$p(x) = a_0 + a_1x + a_2x^2$$

$$p'(x) = a_1 + 2a_2x$$

$$xp'(x) - p(x) = 0$$

$$x(a_1 + 2a_2x) - (a_0 + a_1x + a_2x^2) = 0$$

$$\cancel{a_1x} + 2a_2x^2 - a_0 - \cancel{a_1x} - a_2x^2 = 0$$

$$-a_0 + a_2x^2 = 0$$

$$a_0 = a_2x^2 = 0$$

This implies $\{1, x^2\}$ are linearly independent.

$$a_0 = a = a_2$$

$$p(x) = a_1x$$

$$W = \{ a_1x \mid a_1 \text{ is scalar} \} = \text{span}(x)$$

so $\{x\}$ is linearly independent

$$\Rightarrow (\dim(W) = 1)$$

② $W = \{ A \in \mathbb{R}^{n \times n} \mid A^T = A \}$. Find $\dim(W) = ?$

► Co-ordinates

Let $B = \{v_1, v_2, \dots, v_n\}$ be a basis for vector space V . Then let v be a vector in V ($v \in V$) and write $v = c_1v_1 + c_2v_2 + \dots + c_nv_n$ then c_1, c_2, \dots, c_n are called co-ordinates w.r.t. B of v w.r.t. basis B , and the n -column vector

$[v]_B = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$ is called as co-ordinate vector w.r.t. basis B .

Q.1) $P(x) = 1 - 2x + x^2$ Find co-ordinate w.r.t. the Basis $B = \{1, x, x^2\}$ of P_2

$$\text{Soln } P(x) = 1 - 2x + x^2 = 1(1) + (-2)x + 1 \cdot x^2$$

$$[P(x)]_B = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

also consider $B' = \{x^2, x, 1\}$ ordered basis.

$$[P(x)]_{B'} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

Q. $B' = \{1+x, x+x^2, 1+x^2\}$ Find co-ordinate vector w.r.t. B'

$$\begin{aligned} P(x) &= 1 - 2x + x^2 = (1+1) + [(-2)+(-2)^2]x + [1+1^2]x^2 \\ &= 2 - 2x + x^2 \end{aligned}$$

$$\begin{aligned} P(x) &= av_1 + bv_2 + cv_3 \quad (\text{a}) \\ 1 - 2x + x^2 &= a(1+x) + b(x+x^2) + c(1+x^2) \\ &= a + ax + bx + bx^2 + c + cx^2 \\ &= (a+c) + (a+b)x + (b+c)x^2 \end{aligned}$$

Comparing,

$$\begin{aligned} a+c &= 1 \\ a+b &= -2 \\ b+c &= 1 \\ c &= 1-b \end{aligned}$$

$$\begin{aligned} a+1-b &= 1 \\ a-b &= 0 \\ a+b &= -2 \\ \hline 2a &= -2 \\ a &= -1 \end{aligned}$$

Here a, b, c are

scalar in co-ordinate

vector.

$$\therefore b = -1$$

$$\begin{aligned} c &= 1 - (-1) & \therefore [P(x)]_{B'} &= \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \in \mathbb{R}^3 \\ c &= 2 \end{aligned}$$

Q. $P(x) = -1 \in P_n$, find co-ordinate w.r.t. standard Basis for P_n .

Soln: $-1 = (-1)1 + 0x + 0x^2 + \dots + 0x^n$

$$[-1]_B = \begin{bmatrix} -1 \\ 0 \\ 0 \\ \vdots \\ 0_n \end{bmatrix} \in \mathbb{R}^{n+1} \text{ Dimensions: } n+1$$

* $B = \{1, x, \dots, x^n\}$, $P(x) = -x+1 \in P_n(\mathbb{R})$

Theorem: Let V be the vector space and B be the basis for then V for every vector v in V there is exactly one way to write v as the linear combination of basis vectors in B .

Proof: Here,

V be the vectorspace and B be the basis for.

Let $B = \{v_1, v_2, \dots, v_n\}$ be the basis for a vector space V

$$v = c_1 v_1 + c_2 v_2 + c_3 v_3 + \dots + c_n v_n$$

Let us assume we can write $v \in V$ in two different ways of linear combination of basis vectors.

$$\text{of } v = c_1 v_1 + c_2 v_2 + c_3 v_3 + \dots + c_n v_n$$

$$\text{and } v = c'_1 v_1 + c'_2 v_2 + c'_3 v_3 + \dots + c'_n v_n$$

$$\Rightarrow v = v$$

$$\text{Thus } c_1 v_1 + c_2 v_2 + \dots + c_n v_n = c'_1 v_1 + c'_2 v_2 + \dots + c'_n v_n$$

$$(c_1 - c'_1) v_1 + (c_2 - c'_2) v_2 + \dots + (c_n - c'_n) v_n = 0$$

as above vector Basis is linearly independent.

$$\therefore c_1 - c'_1 = 0 \quad \text{i.e. } c_1 = c'_1$$

$$c_2 - c'_2 = 0 \quad c_2 = c'_2$$

$$\vdots \quad \vdots$$

$$c_n - c'_n = 0 \quad c_n = c'_n$$

Hence proved.

For every vector v in V there is exactly one way to write v as the linear combination of basis vectors in B .