FOML Assignment 1

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Question 4

For logistic regression, there is no longer a closed-form solution, due to the nonlinearity of the logistic sigmoid function. The error function can be minimized by an efficient iterative technique based on the **Newton-Raphson iterative optimization scheme**.

Part A

Provide the expressions of the gradient, Hessian, and update equations for the Newton-Raphson optimization technique used to obtain the parameters in the logistic regression model.

Provide an algorithm describing the methodology.

Solution

The cost function for logistic regression is given by:

$$E(\theta) = -\sum_{n=1}^{N} [t_n \log y_n + (1 - t_n) \log(1 - y_n)]$$

where:

- $y_n = y(x_n, \theta)$ is the model prediction for input x_n and θ is the set of parameters of the model.
- t_n is the target value for input x_n .

The gradient of the cost function is given by:

$$\nabla E(\theta) = \left[\frac{\partial E(\theta)}{\partial \theta_1}, \frac{\partial E(\theta)}{\partial \theta_2}, \dots, \frac{\partial E(\theta)}{\partial \theta_N}\right]^T$$

$$\Rightarrow \frac{\partial E(\theta)}{\partial \theta_{j}} = -\sum_{n=1}^{N} \left[t_{n} \frac{1}{y_{n}} \frac{\partial y_{n}}{\partial \theta_{j}} + (1 - t_{n}) \frac{1}{1 - y_{n}} \frac{\partial (1 - y_{n})}{\partial \theta_{j}} \right]$$

$$\Rightarrow \frac{\partial E(\theta)}{\partial \theta_{j}} = -\sum_{n=1}^{N} \left[t_{n} \frac{1}{y_{n}} \frac{\partial y_{n}}{\partial \theta_{j}} - (1 - t_{n}) \frac{1}{1 - y_{n}} \frac{\partial y_{n}}{\partial \theta_{j}} \right]$$

$$\Rightarrow \frac{\partial E(\theta)}{\partial \theta_{j}} = -\sum_{n=1}^{N} \left[\frac{t_{n}}{y_{n}} - \frac{1 - t_{n}}{1 - y_{n}} \right] \frac{\partial y_{n}}{\partial \theta_{j}}$$

$$\Rightarrow d \frac{\partial E(\theta)}{\partial \theta_{j}} = -\sum_{n=1}^{N} \left[\frac{t_{n} - y_{n}}{y_{n}(1 - y_{n})} \right] \frac{\partial y_{n}}{\partial \theta_{j}}$$

$$y_{n} = \frac{1}{1 + \exp(-\theta^{T}x_{n})}$$

$$\Rightarrow \frac{\partial y_{n}}{\partial \theta_{j}} = \frac{\exp(-\theta^{T}x_{n})}{(1 + \exp(-\theta^{T}x_{n}))^{2}} \frac{\partial}{\partial \theta_{j}} (-\theta^{T}x_{n})$$

$$\Rightarrow \frac{\partial y_{n}}{\partial \theta_{j}} = \frac{\exp(-\theta^{T}x_{n})}{(1 + \exp(-\theta^{T}x_{n}))^{2}} (-x_{nj})$$

$$\Rightarrow \frac{\partial y_{n}}{\partial \theta_{j}} = y_{n}(1 - y_{n})(-x_{nj})$$

$$\frac{\partial E(\theta)}{\partial \theta_{j}} = -\sum_{n=1}^{N} \left[\frac{t_{n} - y_{n}}{y_{n}(1 - y_{n})} \right] y_{n}(1 - y_{n})(-x_{nj})$$

$$\Rightarrow \frac{\partial E(\theta)}{\partial \theta_{j}} = \sum_{n=1}^{N} (y_{n} - t_{n})x_{nj}$$

Let:

$$X = [x_1, x_2, \dots, x_N]^T$$
$$Y - T = [y_1 - t_1, y_2 - t_2, \dots, y_N - t_N]^T$$

$$\implies \nabla E(\theta) = X^T (Y - T)$$

The Hessian of the cost function is given by:

$$H = \nabla^{2}E(\theta) = \begin{bmatrix} \frac{\partial^{2}E(\theta)}{\partial\theta_{1}^{2}} & \frac{\partial^{2}E(\theta)}{\partial\theta_{1}\partial\theta_{2}} & \dots & \frac{\partial^{2}E(\theta)}{\partial\theta_{1}\partial\theta_{N}} \\ \frac{\partial^{2}E(\theta)}{\partial\theta_{2}\partial\theta_{1}} & \frac{\partial^{2}E(\theta)}{\partial\theta_{2}^{2}} & \dots & \frac{\partial^{2}E(\theta)}{\partial\theta_{2}\partial\theta_{N}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^{2}E(\theta)}{\partial\theta_{N}\partial\theta_{1}} & \frac{\partial^{2}E(\theta)}{\partial\theta_{N}\partial\theta_{2}} & \dots & \frac{\partial^{2}E(\theta)}{\partial\theta_{N}^{2}} \end{bmatrix}$$

$$H_{ij} = \frac{\partial^{2}E(\theta)}{\partial\theta_{i}\partial\theta_{j}} = \frac{\partial}{\partial\theta_{i}} \left(\frac{\partial E(\theta)}{\partial\theta_{j}} \right)$$

$$\implies H_{ij} = \sum_{n=1}^{N} \frac{\partial}{\partial\theta_{i}} \left((y_{n} - t_{n})x_{nj} \right)$$

$$\implies H_{ij} = \sum_{n=1}^{N} \frac{\partial}{\partial\theta_{i}} \left((y_{n} - t_{n})x_{nj} \right)$$

$$\implies H_{ij} = \sum_{n=1}^{N} \frac{\partial}{\partial\theta_{i}} (1 - y_{n})x_{ni}x_{nj}$$

$$\implies H_{ij} = \sum_{n=1}^{N} y_{n}(1 - y_{n})x_{ni}x_{nj}$$

$$\implies H = \sum_{n=1}^{N} y_{n}(1 - y_{n})x_{ni}x_{nj}$$

Let:

$$S = \begin{bmatrix} y_1(1 - y_1) & 0 & \dots & 0 \\ 0 & y_2(1 - y_2) & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & y_N(1 - y_N) \end{bmatrix}$$
$$\implies H = X^T S X$$

The update equation for the Newton-Raphson optimization technique is given by:

$$\theta^{(new)} = \theta^{(old)} - H^{-1} \nabla E(\theta^{(old)})$$

$$\Longrightarrow \left[\theta^{(new)} = \theta^{(old)} - (X^T S X)^{-1} X^T (Y - T)\right]$$

where:

- $\theta^{(new)}$ is the new value of θ .
- $\theta^{(old)}$ is the old value of θ .
- H is the Hessian of the cost function.
- $\nabla E(\theta)$ is the gradient of the cost function.

Algorithm:

```
Input: X, t, theta
Output: theta
while (Not Converged):
    g = gradient(X, t, theta)
    H = hessian(X, t, theta)
    theta = theta - inverse(H) * g
```

return theta

Part B

Show that the Newton-Raphson update scheme is related to the weighted least squares problem described in question 3(c) and explain why it is called the **iterative reweighted least squares** method.

Solution

The Newton-Raphson update scheme is given by:

$$\theta^{(new)} = \theta^{(old)} - H^{-1} \nabla E(\theta)$$

where:

• $\theta^{(new)}$ is the new value of θ .

- $\theta^{(old)}$ is the old value of θ .
- H is the Hessian of the cost function.
- $\nabla E(\theta)$ is the gradient of the cost function.

$$\implies \theta^{(new)} = \theta^{(old)} - (X^T S X)^{-1} X^T (Y - T)$$

$$\implies \theta^{(new)} = (X^T S X)^{-1} (X^T S X \theta^{(old)} - X^T (Y - T))$$

$$\implies \theta^{(new)} = (X^T S X)^{-1} X^T S (X \theta^{(old)} - S^{-1} (Y - T))$$

Let $\tilde{Y} = X\theta^{(old)} - S^{-1}(Y - T)$.

$$\theta^{(new)} = (X^T S X)^{-1} X^T S \tilde{Y}$$

This update scheme is related to the weighted least squares problem described in question 3(c) because the weighted least squares problem is given by:

$$\theta^{(new)} = (X^T R X)^{-1} X^T R Y$$

The matrix S and \tilde{Y} are recalculated in each iteration of the Newton-Raphson update scheme. Hence, it is called the **iterative reweighted least squares method**.

Part C

Show that the error function of the logistic regression is a convex function of w and hence has a unique minimum with the help of the Hessian matrix.

Solution

If a function f has a Hessian matrix H such that H is positive semidefinite, then f is a convex function

A matrix H is positive semidefinite if:

$$P^T H P \ge 0 \quad \forall P \in \mathbb{R}^n - \{0\}$$

The Hessian matrix of the error function of the logistic regression is given by:

$$H = X^T S X$$

 $P^T H P = P^T X^T S X P$

$$\implies P^T H P = (XP)^T S(XP)$$

$$\implies P^T H P = \sum_{n=1}^{N} (XP)_n^2 S_{nn}$$

 S_{nn} is positive because y_n is a probability and hence $y_n \in [0,1]$.

$$\implies P^T H P \ge 0 \quad \forall P \in \mathbb{R}^n - \{0\}$$

Hence, the error function of the logistic regression is a convex function of w and hence has a unique global minimum and provides the optimal solution.