

### QUESTION 3

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(I) With the cross-entropy error given by

$$(1) \quad E(\mathbf{w}) = - \sum_{n=1}^N (t_n \ln y_n + (1 - t_n) \ln(1 - y_n))$$

we have

- Gradient of the error:

$$\nabla E(\mathbf{w}) = \sum_{n=1}^N (y_n - t_n) \phi_n = \Phi^T (\mathbf{y} - \mathbf{t})$$

- The Hessian:

$$\nabla \nabla E(\mathbf{w}) = \sum_{n=1}^N y_n (1 - y_n) \phi_n \phi_n^T = \Phi^T \mathbf{R} \Phi$$

where  $\mathbf{R}$  is the diagonal matrix given by  $R_{nn} = y_n(1 - y_n)$

- Update function:

$$(2) \quad \begin{aligned} \mathbf{w}^{(new)} &= \mathbf{w}^{(old)} - \mathbf{H}^{-1} \nabla E(\mathbf{w}) \\ \mathbf{w}^{(new)} &= \mathbf{w}^{(old)} - \mathbf{H}^{-1} \nabla E(\mathbf{w}) \\ &= \mathbf{w}^{(old)} - (\Phi^T \mathbf{R} \Phi)^{-1} \Phi^T (\mathbf{y} - \mathbf{t}) \\ &= (\Phi^T \mathbf{R} \Phi)^{-1} \left( \Phi^T \mathbf{R} \Phi \mathbf{w}^{(old)} - \Phi^T (\mathbf{y} - \mathbf{t}) \right) \\ &= (\Phi^T \mathbf{R} \Phi)^{-1} \Phi^T \mathbf{R} \mathbf{z} \end{aligned}$$

with

$$\mathbf{z} = \Phi \mathbf{w}^{(old)} - \mathbf{R}^{-1} (\mathbf{y} - \mathbf{t})$$

where  $\Phi$  is the  $N \times M$  design matrix, whose  $n$ 'th row is given by  $\phi_n^T$ , and  $y_n = \sigma(\mathbf{w}^T \phi_n)$ .

The algorithm for update, implemented in python:

```
import numpy as np
def update(w, Phi, t):
    y = np.array([sigmoid(p @ w) for p in Phi])
    R = np.diag(y * (1 - y))
    z = Phi @ w - np.linalg.inv(R) @ (y - t)
    return np.linalg.inv(Phi.T @ R @ Phi) @ Phi.T @ R @ z
```

(II)

(III) The weighing matrix  $R$  is not constant, but depends on the parameter vector  $\mathbf{w}$ .

Thus, we must apply the normal equations iteratively, each time using the new weight vector  $\mathbf{w}$  to compute a revised weighing matrix  $R$ . So, the algorithm is known as iterative reweighted least squares (IRLS).