

### QUESTION 3

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- (I) Derive the expression of likelihood and prior for a heteroscedastic setting for a single data point with input  $\mathbf{x}_n$  and output  $t_n$ .

Consider the following formula for the target variable:

$$t = \mathbf{w}^T \phi(\mathbf{x}) + \epsilon(\mathbf{x})$$

where  $\epsilon$  is a zero mean Gaussian random variable with precision  $\beta(\mathbf{x})$  and  $\phi$  is a deterministic function. Due to heteroscedasticity, the Gaussian noise is dependent on the input  $\mathbf{x}$ .

Due to the properties of Gaussian distribution,  $t$  is also normal, with its distribution i.e. the likelihood function given by:

$$p(t_n | \mathbf{x}_n, \mathbf{w}, \beta) = \sqrt{\frac{\beta_n}{2\pi}} \exp \left\{ -\frac{\beta_n}{2} (t_n - \mathbf{w}^T \phi(\mathbf{x}_n))^2 \right\}$$

So, we can say

$$p(t_n | \mathbf{x}_n, \mathbf{w}, \beta) = \mathcal{N}(t_n | \mathbf{w}^T \phi(\mathbf{x}_n), \beta^{-1})$$

The prior is given by:

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_0, \mathbf{S}_0)$$

Here,  $\mathbf{m}_0$  is the mean of the prior distribution and  $\mathbf{S}_0$  is the covariance matrix.

- (II) Provide the expression for the objective function that you will consider for the ML and MAP estimation of the parameters considering a data set of size  $N$ .

- (a) To express this more succinctly, we define the design matrix

$$\Phi = \begin{pmatrix} \phi(\mathbf{x}_1) \\ \vdots \\ \phi(\mathbf{x}_n) \end{pmatrix}$$

the data set  $\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$  and the weighing matrix  $\mathbf{R}$  with  $R_{ii} = \beta_i$ .

Thus, the objective function for ML estimation is given by:

$$\begin{aligned} p(\mathbf{t} | \mathbf{X}, \mathbf{w}, \beta) &= \prod_{n=1}^N p(t_n | \mathbf{x}_n, \mathbf{w}, \beta) \\ &= \prod_{n=1}^N \mathcal{N}(t_n | \mathbf{w}^T \phi(\mathbf{x}_n), \beta_n^{-1}) \\ &= \exp \left\{ -\frac{1}{2} \sum_{n=1}^N \beta_n (t_n - \mathbf{w}^T \phi(\mathbf{x}_n))^2 \right\} \\ &= \exp \left\{ -\frac{1}{2} (\mathbf{t} - \Phi^T \mathbf{w})^T \mathbf{R} (\mathbf{t} - \Phi^T \mathbf{w}) \right\} \\ &= \mathcal{N}(\mathbf{t} | \Phi \mathbf{w}, \mathbf{R}^{-1}) \end{aligned} \tag{1}$$

(b) Given

$$p(\mathbf{w}) = \mathcal{N}(w|\mathbf{m}_0, \mathbf{S}_0)$$

and

$$p(\mathbf{t}|\mathbf{w}) = \mathcal{N}(\Phi\mathbf{w}, \mathbf{R}^{-1})$$

The objective function for MAP estimation is given by the normal distribution with mean  $\boldsymbol{\mu}$  and variance  $\boldsymbol{\Sigma}$  where

- $\boldsymbol{\Sigma} = (\mathbf{S}_0^{-1} + \Phi^T \mathbf{R} \Phi)^{-1}$
- $\boldsymbol{\mu} = \boldsymbol{\Sigma}(\mathbf{S}_0^{-1} \mathbf{m}_0 + \Phi^T \mathbf{R} \mathbf{t})$

This can be derived using the quantity  $\mathbf{z} = \begin{pmatrix} \mathbf{w} \\ \mathbf{t} \end{pmatrix}$  as follows:

$$\begin{aligned} \ln p(\mathbf{z}) &= \ln p(\mathbf{w}) + \ln p(\mathbf{t}|\mathbf{w}) \\ &= -\frac{1}{2}(\mathbf{w} - \mathbf{m}_0)^T \mathbf{S}_0^{-1}(\mathbf{w} - \mathbf{m}_0) \\ &\quad - \frac{1}{2}(\mathbf{t} - \Phi\mathbf{w})^T \mathbf{R}(\mathbf{t} - \Phi\mathbf{w}) + \text{constant} \end{aligned} \tag{2}$$

Furthermore, due to linearity of expectation, we have

$$\mathbb{E}[\mathbf{z}] = \begin{pmatrix} \mathbb{E}[\mathbf{w}] \\ \mathbb{E}[\mathbf{t}] \end{pmatrix}$$

from which

$$\text{cov}[\mathbf{z}] = \begin{pmatrix} \text{var}[\mathbf{w}] & \text{cov}[\mathbf{w}, \mathbf{t}] \\ \text{cov}[\mathbf{t}, \mathbf{w}] & \text{var}[\mathbf{t}] \end{pmatrix}$$

From 2, it is clear that  $p(\mathbf{z})$  is a Gaussian distribution. Now we complete the square.

To find the covariance of  $\mathbf{w}|\mathbf{t}$ , we consider the single term of second order in  $\mathbf{w}$  from 2:

$$\frac{1}{2}\mathbf{w}^T \boldsymbol{\Sigma}^{-1} \mathbf{w} = \frac{1}{2}\mathbf{w}^T (\mathbf{S}_0^{-1} + \Phi^T \mathbf{R} \Phi) \mathbf{w}$$

We treat  $\mathbf{t}$  as a constant.

Thus, the covariance is given by

$$\boldsymbol{\Sigma} = (\mathbf{S}_0^{-1} + \Phi^T \mathbf{R} \Phi)^{-1}$$

Similarly, we may obtain  $\boldsymbol{\mu}$  using the terms of 2 of first order in  $\mathbf{w}$ . We have

$$\mathbf{w}^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu} = \mathbf{w}^T \mathbf{S}_0^{-1} \mathbf{m}_0 + \mathbf{w}^T \Phi^T \mathbf{R} \mathbf{t}$$

which yields

$$\boldsymbol{\mu} = \boldsymbol{\Sigma}(\mathbf{S}_0^{-1} \mathbf{m}_0 + \Phi^T \mathbf{R} \mathbf{t})$$

(III) Show

$$E_{\mathcal{D}} = \sum_{n=1}^N r_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\}^2$$

and find  $\mathbf{w}$  that minimizes  $E_{\mathcal{D}}$ .

Reframing 1 in the style of the homoscedastic case, we have

$$-\ln p(\mathcal{D}|\mathbf{w}) = \frac{N}{2} \ln \beta_n - \frac{N}{2} \ln(2\pi) - E_{\mathcal{D}}$$

whence it is evident that

$$E_{\mathcal{D}} = \frac{1}{2} \sum_{n=1}^N \beta_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\}^2$$

Setting  $r_n = \frac{\beta_n}{2}$ , we obtain the desired equation.

Now, we may obtain the  $\mathbf{w}$  that minimizes  $E_{\mathcal{D}}$  by differentiating **(III)** and setting the derivative to zero like so:

$$\sum_{n=1}^N \beta_n \{t_n - \mathbf{w}^T \phi(\mathbf{x}_n)\} \phi(\mathbf{x}_n)^T = 0$$

Whence

$$\sum_{n=1}^N t_n \beta_n \phi_n^T = \mathbf{w}^T \sum_{n=1}^N \beta_n \phi(\mathbf{x}_n) \phi(\mathbf{x}_n)^T$$

Let the matrix  $\mathbf{R}$  be a diagonal matrix with  $R_{ii} = \beta_i$ . Then, we have

$$\Phi^T R \mathbf{t} = (\Phi^T R \Phi) \mathbf{w} \tag{3}$$

$$\implies \mathbf{w}_{\text{ML}} = (\Phi^T \mathbf{R} \Phi)^{-1} \Phi^T \mathbf{R} \mathbf{t} \tag{4}$$