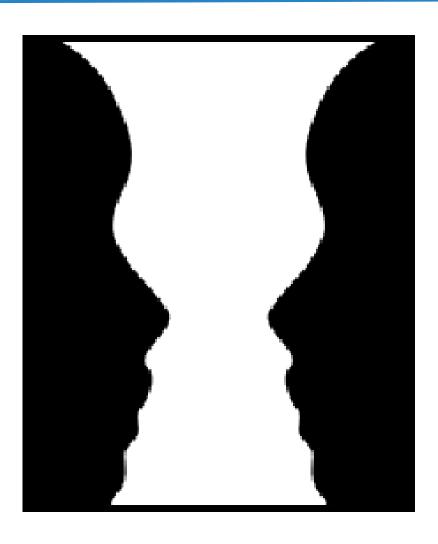
BY UMANG KEJRIWAL

- Image Processing is a method to perform some operations on an image, in order to get an enhanced image or to extract some useful information from it. It is a type of signal processing in which input is an image and output may be image or characteristics/features associated with that image.
- Computer Vision is a field of computer science that works on enabling computers to see, identify and process images in the same way that human vision does, and then provide appropriate output. It is like imparting human intelligence and instincts to a computer. In reality though, it is a difficult task to enable computers to recognize images of different objects.

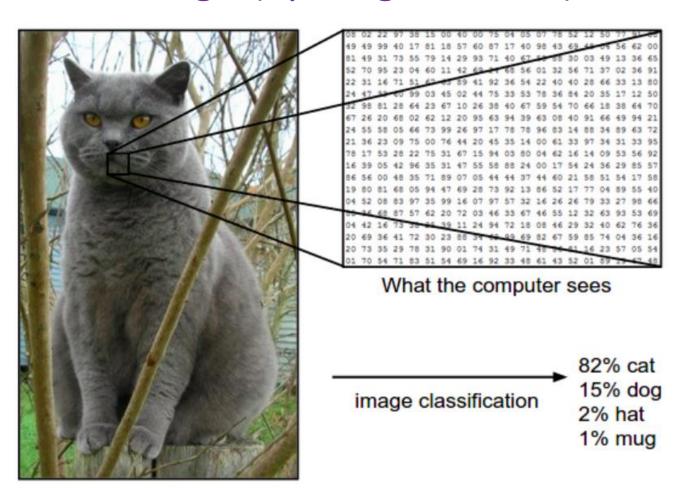




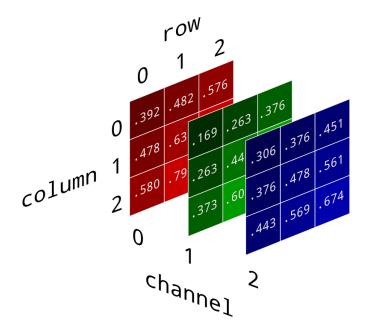
But, the question arise, how will be learning in this stage? Let's understand the learning first about kids!



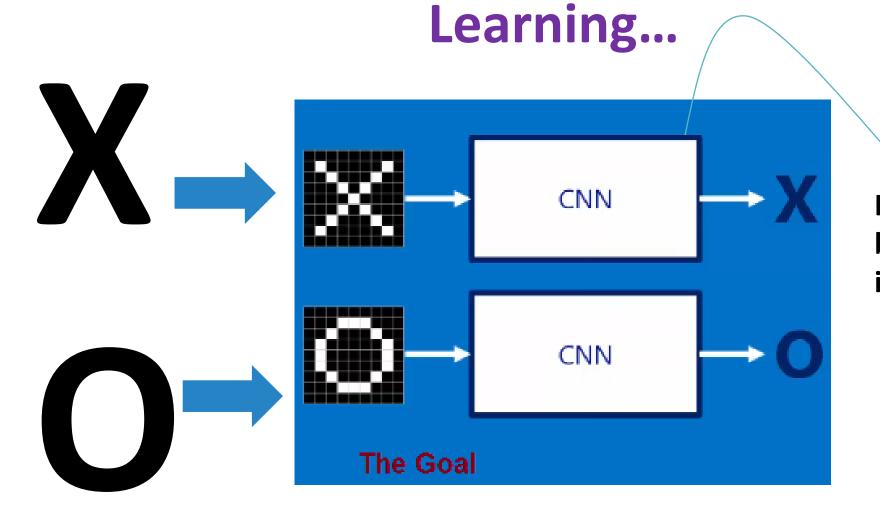
# So, what about the Computer? CNN? Learning... (by image features)



#### **Gray scale image or RGB image**

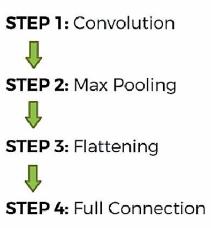


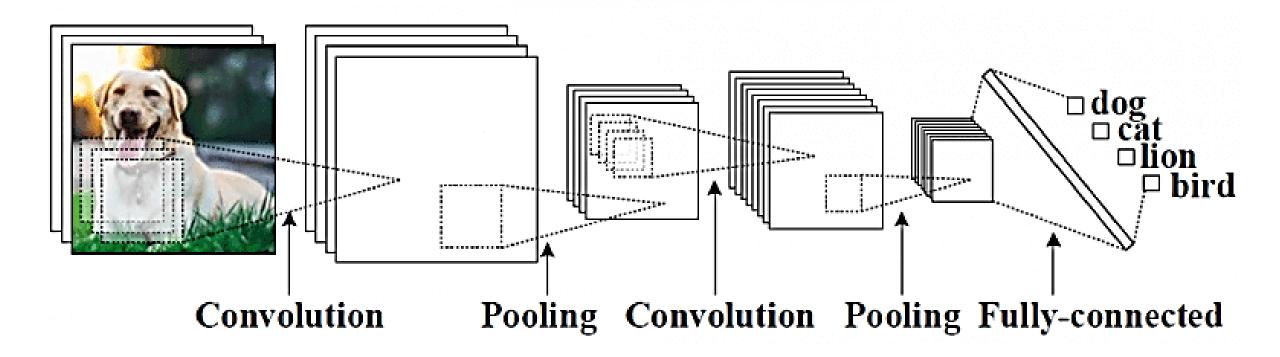
# So, What about the Computer? CNN?



Here CNN work as like black box, so what is inside the black box!

#### Steps in CNN





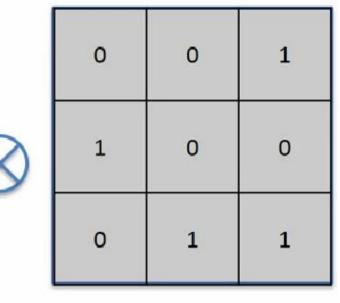
0	0	0	0	0	0	0
0	1	0	0	0	1	0
0	0	0	0	0	0	0
0	0	0	1	0	0	0
0	1	0	0	0	1	0
0	0	1	1	1	0	0
0	0	0	0	0	0	0

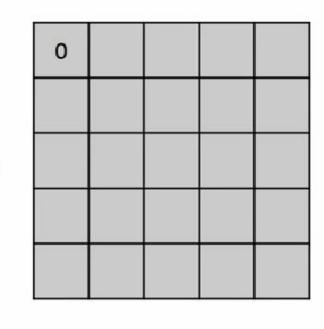
0	0	1
1	0	0
0	1	1

Input Image

Feature Detector

0	0	0	0	0	0	0
0	1	0	0	0	1	0
0	0	0	0	0	0	0
0	0	0	1	0	0	0
0	1	0	0	0	1	0
0	0	1	1	1	0	0
0	0	0	0	0	0	0

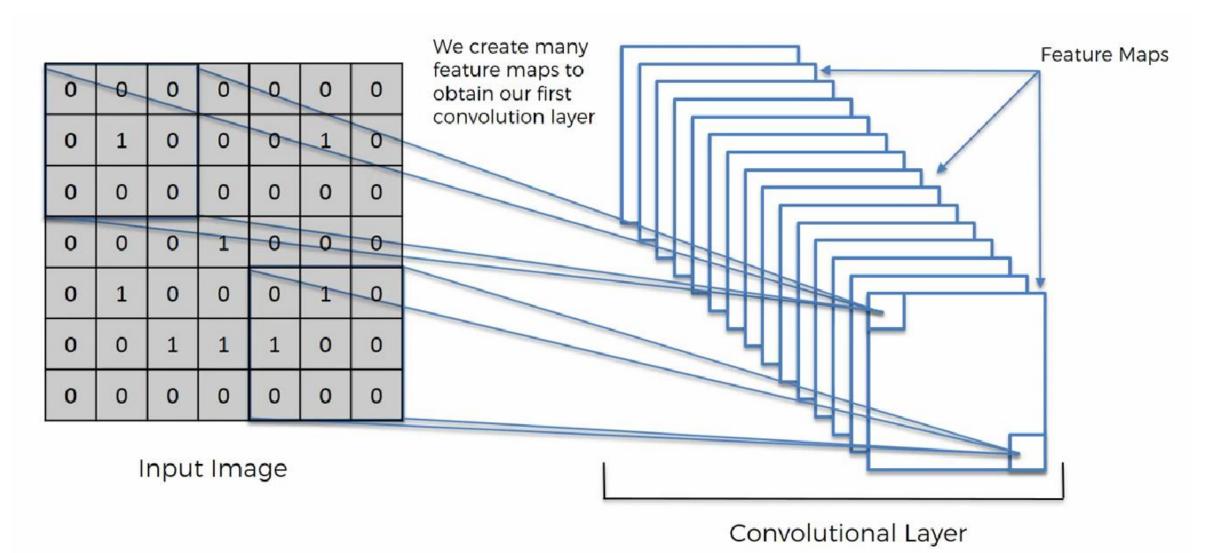


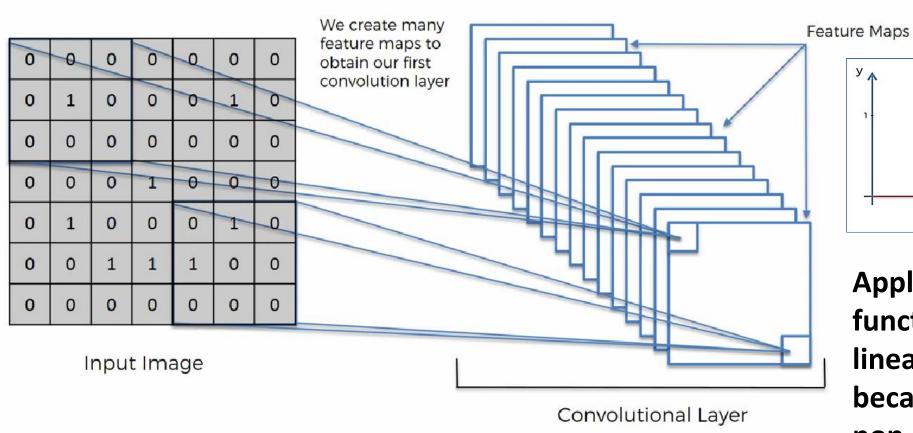


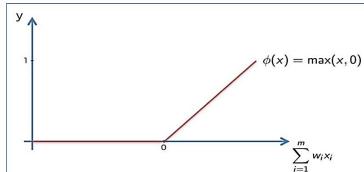
Input Image

Feature Detector

Feature Map







Appling ReLu Activation function to decrease the linearity in the image, because the image originally non linear!

Different kind of filters / kernels in image processing!

http://setosa.io/ev/image-kernels/

#### 2. Pooling

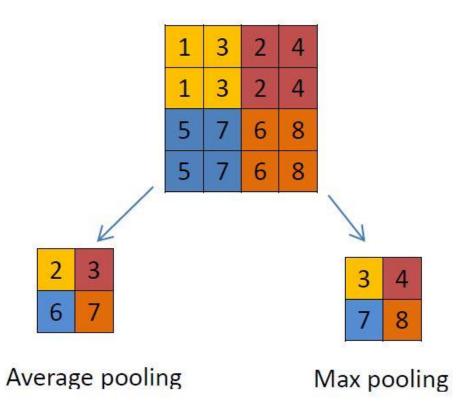
A **pooling** layer is another building block of a **CNN**. Its function is to progressively reduce the spatial size of the representation to reduce the amount of parameters and computation in the network. **Pooling** layer operates on each feature map independently. The most common approach used in **pooling** is max **pooling**.

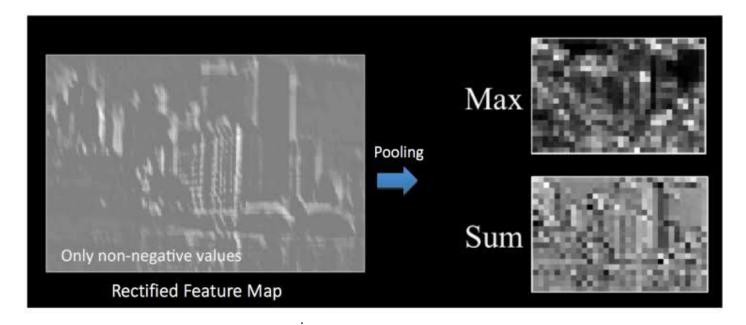
0	1	0	0	0			
0	1	1	1	0	Max Pooling		
1	0	1	2	1			
1	4	2	1	0			
0	0	1	2	1			

Feature Map

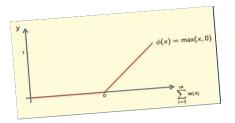
Pooled Feature Map

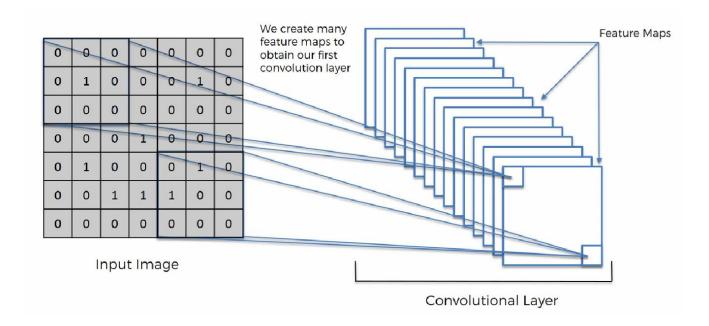
## Max / Avg. Pooling

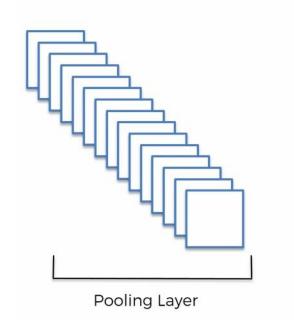




## Pooling...







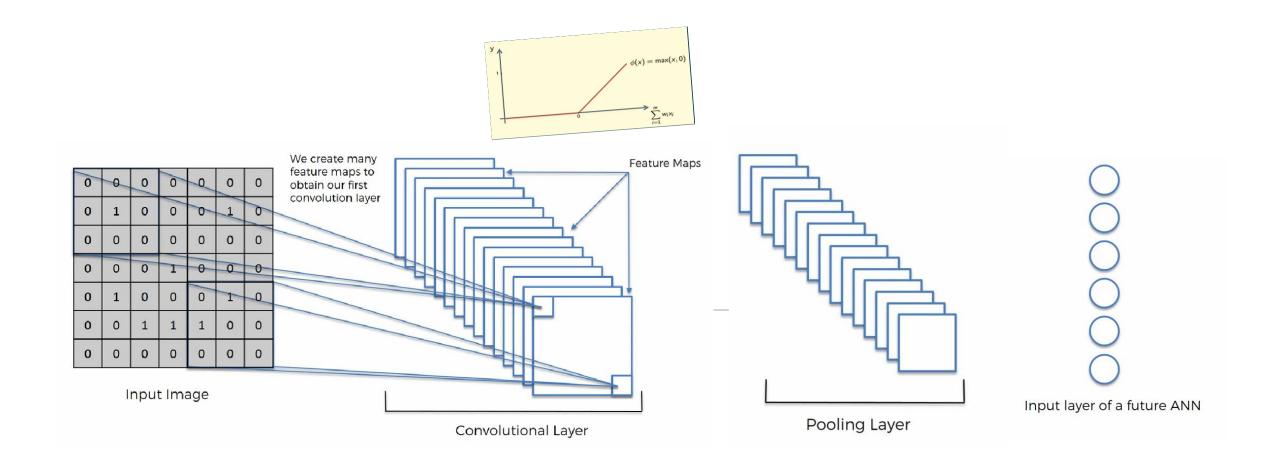
#### 3. Flattening

**Flattening** is converting the data into a 1-dimensional array for inputting it to the next layer. We **flatten** the output of the convolutional layers to create a single long feature vector. And it is connected to the final classification model, which is called a fully-connected layer

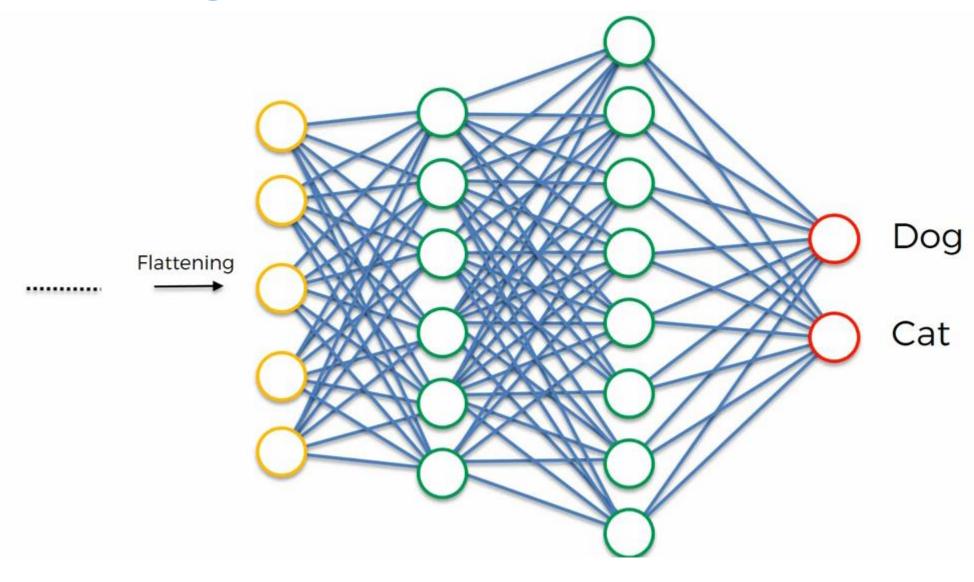
1	1	0
4	2	1
0	2	1

Pooled Feature Map

### Flattening ...



## 4. Fulling Connection



## **Complete CNN in one View**

