

---

# SIGNAL PROCESSING

## Through GATE

---

**EE1205-TA Group**

*Author: Sayyam Palrecha*



Copyright ©2024 by Sayyam Palrecha

<https://creativecommons.org/licenses/by-sa/3.0/>

and

<https://www.gnu.org/licenses/fdl-1.3.en.html>

# Contents

Introduction	iii
<b>1 Harmonics</b>	<b>1</b>
<b>2 Filters</b>	<b>11</b>
<b>3 Z-transform</b>	<b>15</b>
<b>4 Systems</b>	<b>23</b>
<b>5 Sequences</b>	<b>39</b>
<b>6 Sampling</b>	<b>47</b>
<b>7 Contour Integration</b>	<b>49</b>
<b>8 Laplace Transform</b>	<b>51</b>
<b>9 Fourier transform</b>	<b>75</b>
<b>A Fourier transform</b>	<b>89</b>



# Introduction

This book provides solutions to signal processing problems in GATE.



# Chapter 1

## Harmonics

1.1 A damper with damping coefficient,  $c$ , is attached to a mass of 5 kg and spring of stiffness 5 kN/m as shown in figure. The system undergoes under-damped oscillations. If the ratio of the 3<sup>rd</sup> amplitude to the 4<sup>th</sup> amplitude of oscillations is 1.5, the value of  $c$  is ?

(GATE AE-62 (2022)) **Solution:**

Parameter	Value	Description
$c$	?	Damping Coefficient
$k$	5 kN/m	Stiffness
$r$	1.5	Ratio of 3 <sup>rd</sup> amplitude to 4 <sup>th</sup> amplitude of oscillations

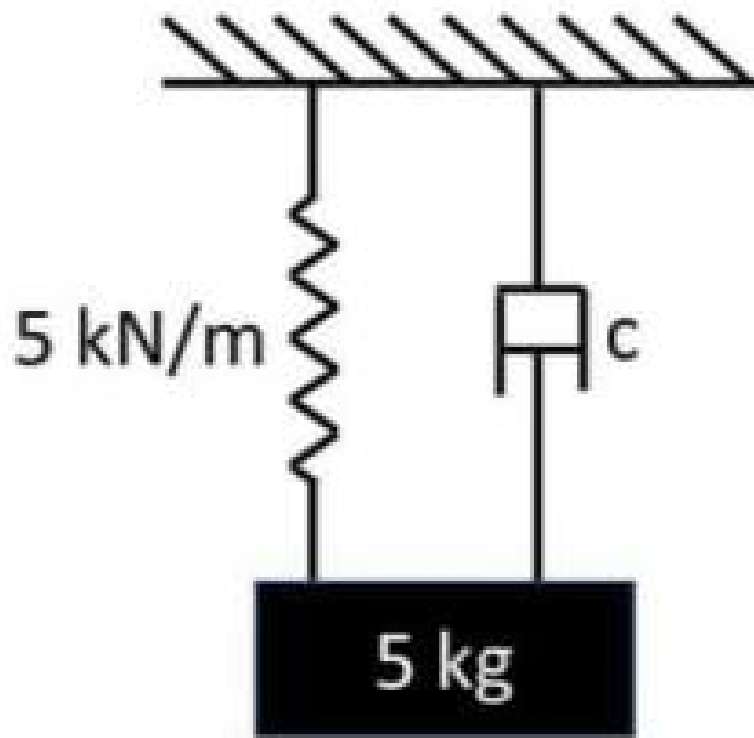
Table 1.1: Parameter Table (GATE AE-62)

Now, as the oscillation begins, from the Fig. 1.1 we write net force on the mass as,

$$F = F_1 + F_2 + mgu(t) \quad (1.1)$$

$$\Rightarrow m \frac{d^2x(t)}{dt^2} = -kx(t) - c \frac{dx(t)}{dt} + mgu(t) \quad (1.2)$$

$$\Rightarrow \frac{d^2x(t)}{dt^2} + \left(\frac{c}{m}\right) \frac{dx(t)}{dt} + \left(\frac{k}{m}\right) x(t) = gu(t) \quad (1.3)$$



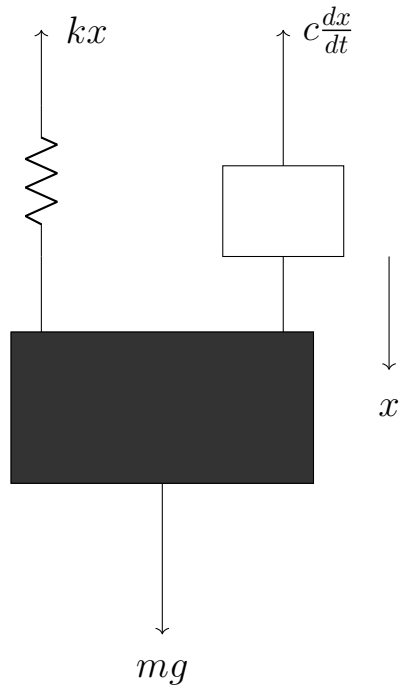
Now, taking the Laplace transform on both sides,

$$s^2 X(s) + \frac{c}{m} s X(s) + \frac{k}{m} X(s) = \frac{g}{s} \quad (1.4)$$

$$\Rightarrow X(s) = \frac{g}{s \left( s^2 + \frac{c}{m} s + \frac{k}{m} \right)} \quad (1.5)$$

$$\Rightarrow X(s) = \frac{g}{s(s - s_1)(s - s_2)} \quad (1.6)$$





Where

$$s_1 = -\frac{c}{2m} + \sqrt{\left(\frac{c}{2m}\right)^2 - \frac{k}{m}} \quad (1.7)$$

$$s_2 = -\frac{c}{2m} - \sqrt{\left(\frac{c}{2m}\right)^2 - \frac{k}{m}} \quad (1.8)$$

From (1.6) we get,

$$\begin{aligned} \Rightarrow X(s) = & \frac{g}{(s_1 - s_2)} \left[ \frac{1}{s_1(s - s_1)} - \frac{1}{s_2(s - s_2)} \right] \\ & - \frac{g}{s_1 s_2} \left( \frac{1}{s} \right) \end{aligned} \quad (1.9)$$

Now again taking the inverse Laplace transform we have,

$$x(t) = -\frac{g}{s_1 s_2} u(t) + \frac{g}{(s_1 - s_2)} \left[ \frac{1}{s_1} e^{s_1 t} - \frac{1}{s_2} e^{s_2 t} \right] u(t) \quad (1.10)$$

$$\begin{aligned} \Rightarrow x(t) = & -\sqrt{\left(\frac{mg}{k}\right)^2 + \left(\frac{gc}{2mk}\right)^2} e^{-ct/2m} u(t) \\ & \sin \left( \sqrt{\frac{k}{m} - \left(\frac{c}{2m}\right)^2} t + \tan^{-1} \left( \frac{2mg\sqrt{\frac{k}{m} - \left(\frac{c}{2m}\right)^2}}{gc} \right) \right) \\ & - \frac{mg}{k} u(t) \end{aligned} \quad (1.11)$$

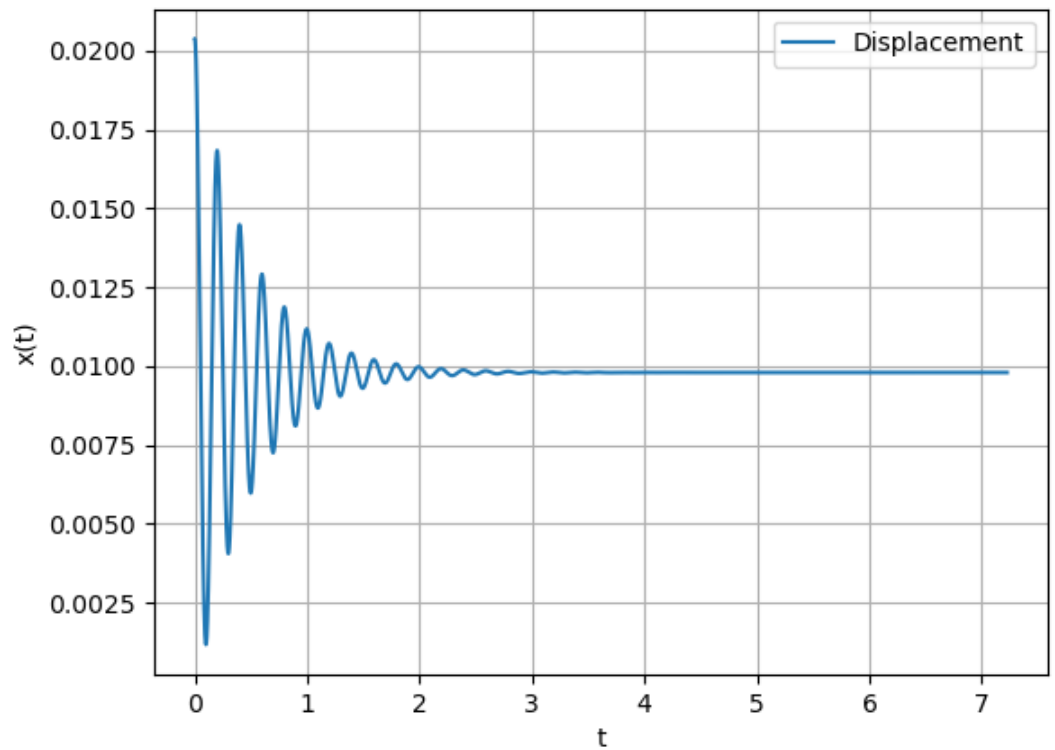
(Substituting the values of  $s_1$  and  $s_2$  from (1.7) and (1.8))

From (1.11), we have the ratio of 3<sup>rd</sup> to 4<sup>th</sup> amplitude,

$$\begin{aligned} & -\sqrt{\left(\frac{mg}{k}\right)^2 + \left(\frac{gc}{2mk}\right)^2} e^{-3cT/2m} = \\ & -\frac{3}{2} \sqrt{\left(\frac{mg}{k}\right)^2 + \left(\frac{gc}{2mk}\right)^2} e^{-4cT/2m} \end{aligned} \quad (1.12)$$

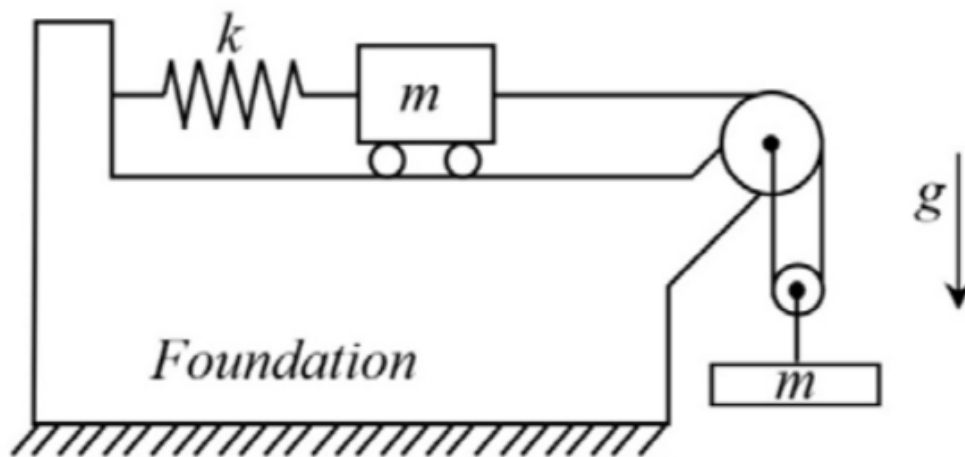
$$\Rightarrow e^{\pi c/\sqrt{mk}} = \frac{3}{2} \quad (1.13)$$

$$\Rightarrow c = \frac{\sqrt{mk} \ln \frac{3}{2}}{\pi} \quad (1.14)$$



1.2 A spring-mass system having a mass  $m$  and spring constant  $k$ , placed horizontally on a foundation, is connected to a vertically hanging mass  $m$  with the help of an inextensible string. Ignore the friction in the pulleys and also the inertia of pulleys, string and spring. Gravity is acting vertically downward as shown. The natural frequency of the system in rad/s is

- (A)  $\sqrt{\frac{4k}{3m}}$
- (B)  $\sqrt{\frac{k}{2m}}$
- (C)  $\sqrt{\frac{k}{3m}}$
- (D)  $\sqrt{\frac{4k}{5m}}$



(GATE XE 2022)

**Solution:**

Parameters	Description	Value
$x(t)$	Displacement of mass $m$ on foundation at time $t$	
$x(0)$	Displacement of mass $m$ on foundation at time $t = 0$	0
$x'(0)$	Velocity of mass $m$ on foundation at time $t = 0$	0

Table 1.2: Parameters

$$T - kx = m \frac{d^2 x}{dt^2} \quad (1.15)$$

$$mg - 2T = m \frac{d^2 \left(\frac{x}{2}\right)}{dt^2} \quad (1.16)$$

$$\implies mg - 2kx = \frac{5}{2} m \frac{d^2 x}{dt^2} \quad (1.17)$$

$$\frac{d^2 x}{dt^2} \xleftrightarrow{\mathcal{L}} s^2 X(s) - sx(0) - x'(0) \quad (1.18)$$

$$t^n \xleftrightarrow{\mathcal{L}} \frac{n!}{s^{n+1}} \quad (1.19)$$

From the Laplace transforms (1.18) and (1.19), we get

$$\frac{mg}{s} - 2kX(s) = \frac{5}{2} m (s^2 X(s) - sx(0) - x'(0)) \quad (1.20)$$

$$\implies X(s) = \frac{\frac{2g}{5}}{s \left(s^2 + \frac{4k}{5m}\right)} \quad (1.21)$$

$$= \frac{mg}{2ks} - \frac{mgs}{2k \left(s^2 + \frac{4k}{5m}\right)} \quad (1.22)$$

$$\cos at \xleftrightarrow{\mathcal{L}} \frac{s}{s^2 + a^2} \quad (1.23)$$

From the Laplace transforms (1.19) and (1.23), we get

$$x(t) = \frac{mg}{2k} \left( 1 - \cos \left( \sqrt{\frac{4k}{5m}} t \right) \right) u(t) \quad (1.24)$$

$$\implies \omega = \sqrt{\frac{4k}{5m}} \quad (1.25)$$

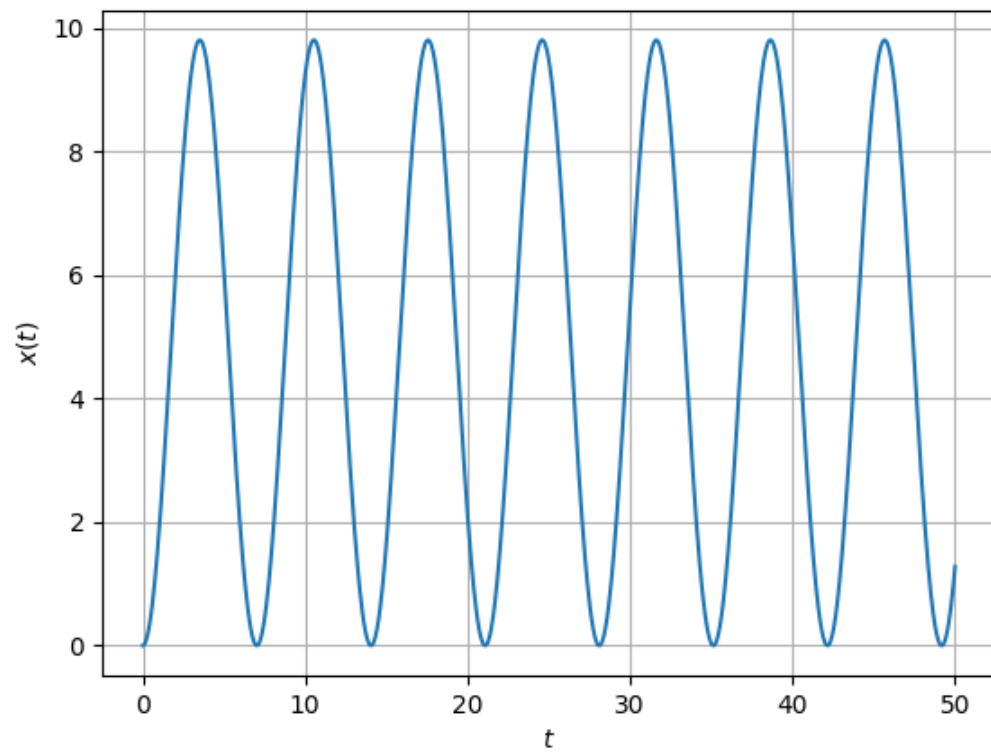


Figure 1.1: Plot of  $x(t)$  for  $m = 1kg$ ,  $k = 1N/m^2$

1.3 The time delay between the peaks of the voltage signals  $v_1(t) = \cos(6t + 60^\circ)$  and  $v_2(t) = -\sin(6t)$  is \_\_\_\_\_s

(A)  $\frac{300\pi}{360}$

(B)  $\frac{10\pi}{360}$

(C)  $\frac{50\pi}{360}$

(D)  $\frac{200\pi}{360}$

(GATE BM 2022 QUESTION 18)

**Solution:** From the values given in the Table 1.3:

Parameter	Description	Value
$v_1(t)$	Input voltage signal 1	$\cos(6t + 60^\circ)$
$v_2(t)$	Input voltage signal 2	$-\sin(6t)$
$\Delta\phi$	Phase difference between two input signals	?
$\Delta t$	Time difference between maxima of two input signals	?
$\omega$	angular frequency of input voltages	6

Table 1.3: input values

$$v_1(t) = \cos(6t + 60^\circ) \quad (1.26)$$

$$v_2(t) = -\sin(6t) \quad (1.27)$$

$$\implies v_2(t) = \cos(6t + 90^\circ) \quad (1.28)$$

From (1.27) and (1.28), phase difference between two voltage signals is  $30^\circ$ . From formula,

$$\Delta\phi = \frac{\Delta t}{\frac{2\pi}{\omega}} 360 \quad (1.29)$$

$$\therefore \Delta t = \frac{10\pi}{360} s \quad (1.30)$$

Hence, option B is correct.

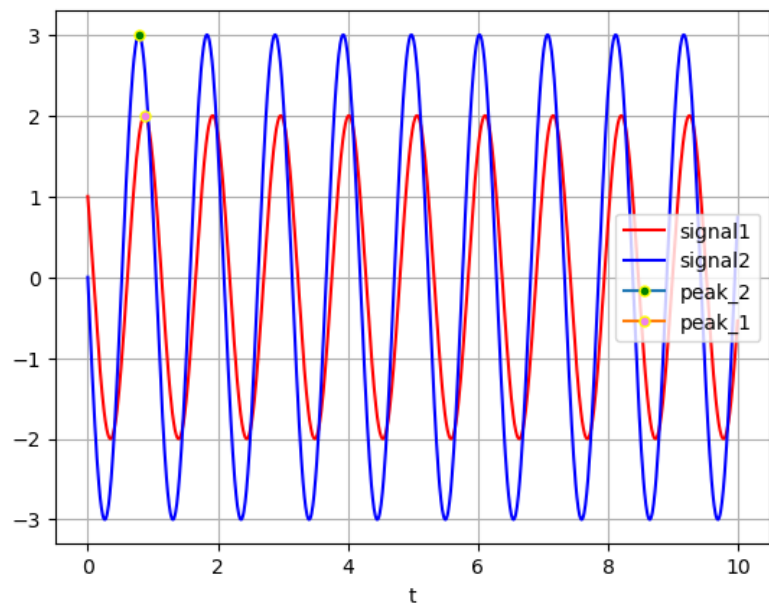


Figure 1.2: Figure of input voltage signals



## Chapter 2

# Filters

- 2.1 The network shown below has a resonant frequency of 150 kHz and bandwidth of 600 Hz. The Q-factor of the network is \_\_\_\_  
(rounded off to one decimal place).  
(GATE 2022 EC)

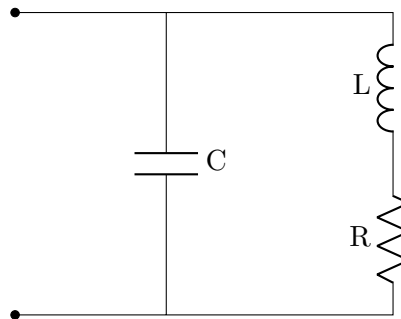


Figure 2.1: Circuit 1

**Solution:**

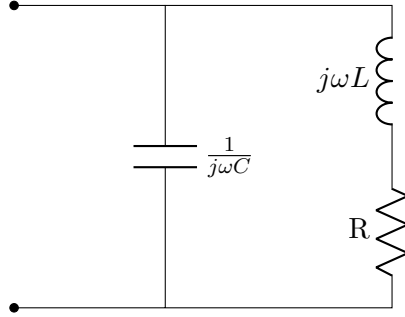


Figure 2.2: Circuit 2

Parameter	Description	Value
$f_0$	Resonant frequency	150 kHz
$B$	Bandwidth	600 Hz

Table 2.1: Parameters

At Resonance,

$$X_L = X_C \quad (2.1)$$

$$\omega_0 L = \frac{1}{\omega_0 C} \quad (2.2)$$

$$\omega_0 = \frac{1}{\sqrt{LC}} \quad (2.3)$$

$$2\pi f_0 = \frac{1}{\sqrt{LC}} \quad (2.4)$$

$$\Rightarrow f_0 = \frac{1}{2\pi\sqrt{LC}} \quad (2.5)$$

Parameter	Description	Formula
$Q$	Quality factor	$\frac{X_L}{R}$
$B$	Bandwidth	$\frac{R}{2\pi L}$
$\omega_0$	Radial resonant frequency	$2\pi f_0$
$X_L$	Inductive reactance	$\omega L$
$X_C$	Capacitive reactance	$\frac{1}{\omega C}$

Table 2.2: Formulae

Using Table 2.2,

$$Q = \frac{X_L}{R} \quad (2.6)$$

$$= \frac{\omega_0 L}{R} \quad (2.7)$$

$$= \left( \frac{1}{\sqrt{LC}} \right) \frac{L}{R} \quad (2.8)$$

$$\Rightarrow Q = \frac{1}{R} \sqrt{\frac{L}{C}} \quad (2.9)$$

From eq (2.5) and Table 2.2

$$\frac{f_0}{B} = \left( \frac{1}{2\pi\sqrt{LC}} \right) \frac{2\pi L}{R} \quad (2.10)$$

$$= \left( \frac{1}{\sqrt{LC}} \right) \frac{L}{R} \quad (2.11)$$

$$\Rightarrow \frac{f_0}{B} = \frac{1}{R} \sqrt{\frac{L}{C}} \quad (2.12)$$

From Table 2.1, eq (2.9) and eq (2.12),

$$Q = \frac{f_0}{B} \quad (2.13)$$

$$= \frac{150 \times 10^3}{600} \quad (2.14)$$

$$= 250 \quad (2.15)$$

∴ Q-factor is 250

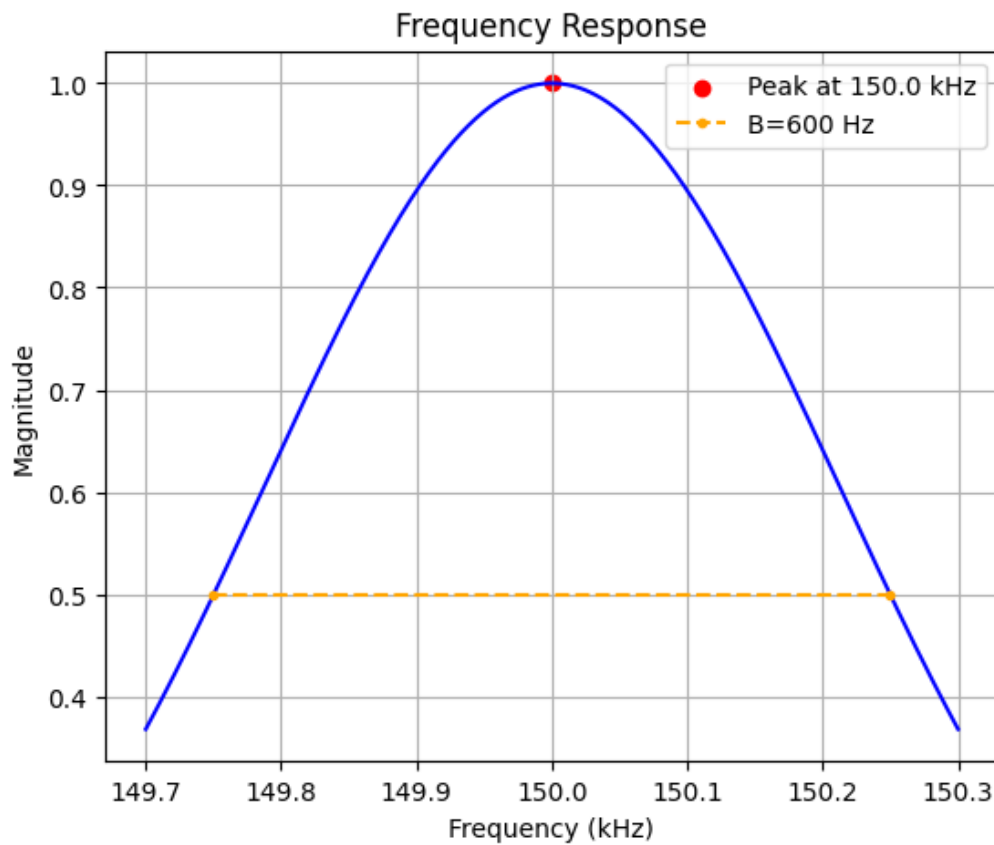


Figure 2.3: Plot of Q-factor

## Chapter 3

# Z-transform

3.1 Consider the following recursive iteration scheme for different values of variable  $P$  with the initial guess  $x_1 = 1$ :

$$x_{n+1} = \frac{1}{2} \left( x_n + \frac{P}{x_n} \right), \quad n = 1, 2, 3, 4, 5$$

For  $P = 2$ ,  $x_5$  is obtained to be 1.414, rounded off to 3 decimal places. For  $P = 3$ ,  $x_5$  is obtained to be 1.732, rounded off to 3 decimal places.

If  $P = 10$ , the numerical value of  $x_5$  is \_\_\_\_\_. (*round off to three decimal places*)  
(GATE CE 2022)

**Solution:**

Applying  $A.M \geq G.M$  inequality,

$$\frac{x_n + \frac{P}{x_n}}{2} \geq \sqrt{P} \tag{3.1}$$

$$\implies x_{n+1} \geq \sqrt{P} \tag{3.2}$$

Solving the equation,

$$2x_{n+1}x_n - x_n^2 - P = 0 \quad (3.3)$$

Applying  $Z$ -transform we get,

$$X(z) * X(z) = \frac{PZ^{-1}}{(1 - z^{-1})(2 - z^{-1})} \quad (3.4)$$

$$= P \left( \frac{z^{-1}}{1 - z^{-1}} - \frac{z^{-1}}{2 - z^{-1}} \right) \quad (3.5)$$

From the transformation pairs,

$$x_{n-a} \xleftrightarrow{\mathcal{Z}} z^{-a} X(z) \quad (3.6)$$

$$x_{n_1} \times x_{n_2} \xleftrightarrow{\mathcal{Z}} X_1(z) * X_2(z) \quad (3.7)$$

$$\frac{u(n-1)}{a^n} \xleftrightarrow{\mathcal{Z}} \frac{z^{-1}}{a - z^{-1}} \quad (3.8)$$

Now, applying inverse  $Z$ -transform,

$$x_n^2 = P \left( u(n-1) - \frac{u(n-1)}{2^n} \right) \quad (3.9)$$

$$\Rightarrow x_n^2 = P \left( 1 - \frac{1}{2^n} \right) \quad [\because n \geq 1] \quad (3.10)$$

Similarly,

$$x_{n+1}^2 = P \left( 1 - \frac{1}{2^{n+1}} \right) \quad (3.11)$$

$$\Rightarrow \lim_{n \rightarrow \infty} \frac{x_{n+1}}{x_n} = \lim_{n \rightarrow \infty} \sqrt{\frac{P \left( 1 - \frac{1}{2^n} \right)}{P \left( 1 - \frac{1}{2^{n+1}} \right)}} \quad (3.12)$$

$$= 1 \quad (3.13)$$

Hence, the system is convergent.

Now finding the limit of the sequence,

$$x^2 = \lim_{x \rightarrow \infty} P \left( 1 - \frac{1}{2^n} \right) \quad (3.14)$$

$$\implies x = \pm \sqrt{P} \quad (3.15)$$

From (3.2) and (3.15),

$$x_{n+1} = \sqrt{P} \quad (3.16)$$

Therefore, for  $P = 10$  the value of  $x_5$  is,

$$x_5 = \sqrt{10} \quad (3.17)$$

$$\therefore x_5 = 3.162 \quad (3.18)$$

3.2 The block diagram of a two-tap high-pass FIR filter is shown below. The filter transfer function is given by  $H(z) = Y(z)/X(z)$ .

If the ratio of maximum to minimum value of  $H(z)$  is 2 and  $|H(z)|_{max} = 1$ , the coefficients  $\beta_0$  and  $\beta_1$  are \_\_\_\_\_ and \_\_\_\_\_, respectively.

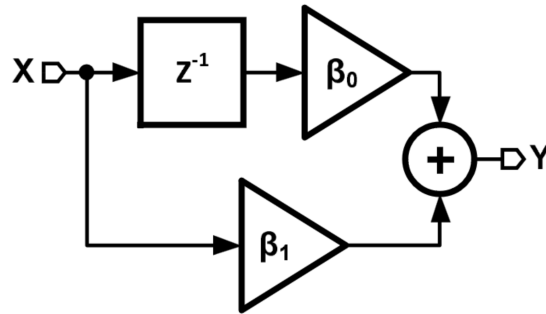


Figure 3.1: Block diagram

- (A) 0.75, -0.25
- (B) 0.67, 0.33
- (C) 0.60, -0.40
- (D) -0.64, 0.36

GATE BM 2022

**Solution:**

**Results and Proofs:**

Time Shift Property:

$$x(n) \xleftrightarrow{\mathcal{Z}} X(z) \quad (3.19)$$

$$x(n - n_0) \xleftrightarrow{\mathcal{Z}} z^{-n_0} X(z) \quad (3.20)$$

Proof:



Let

$$y(n) = x(n - n_0) \quad (3.21)$$

Taking z-transform

$$\mathcal{Z}(y(n)) = \mathcal{Z}(x(n - n_0)) \quad (3.22)$$

$$(3.23)$$

Simplifying LHS

$$Y(z) = \sum_{n=-\infty}^{\infty} y(n)z^{-n} \quad (3.24)$$

From (3.21)

$$Y(z) = \sum_{n=-\infty}^{\infty} x(n - n_0)z^{-n} \quad (3.25)$$

Let

$$n - n_0 = s \quad (3.26)$$

$$\implies n = s + n_0 \quad (3.27)$$

From (3.25) and (3.27)

$$Y(z) = \sum_{s=-\infty}^{\infty} x(s)z^{-(s+n_0)} \quad (3.28)$$

$$= z^{-n_0} \sum_{s=-\infty}^{\infty} x(s)z^{-s} \quad (3.29)$$

As variable in Z-transform is dummy, on replacing it, we get

$$Y(z) = z^{-n_0} \sum_{n=-\infty}^{\infty} x(n)z^{-n} \quad (3.30)$$

$$= z^{-n_0} X(z) \quad (3.31)$$

From (3.22) and (3.31)

$$\mathcal{Z}(x(n - n_0)) = z^{-n_0} X(z) \quad (3.32)$$

Hence proved

Result:

$$z^{-n_0} X(z) \xleftrightarrow{\mathcal{Z}^-} x(n - n_0) \quad (3.33)$$

**Sol:**

Variable	Description	Value
$H(z)$	Transfer Function	$\beta_0 z^{-1} + \beta_1$
$ H(z) _{max}$	Maximum value of Transfer Function	1
$ H(z) _{min}$	Minimum value of Transfer Function	$\frac{1}{2}$

Table 3.1: input parameters

In (3.33), put

$$n_0 = 1, \quad x(n) = \delta(n)$$

Since

$$1 \xleftrightarrow{\mathcal{Z}^-} \delta(n)$$

$$z^{-1} \xleftrightarrow{\mathcal{Z}^-} \delta(n-1) \quad (3.34)$$

This is a unit delay in discrete time and represents unit amplitude sinusoidal signal.  
So,

$$z^{-1} = e^{-jw} \quad (3.35)$$

$$\implies |z^{-1}| = 1 \quad (3.36)$$

Since  $H(z)$  is complex, on using Triangle Inequality, we get

$$|x + y| \leq |x| + |y| \quad (3.37)$$

And its corollary

$$||x| - |y|| \leq |x + y| \quad (3.38)$$

where x and y are complex numbers.

$$||z^{-1}\beta_0| - |\beta_1|| \leq |z^{-1}\beta_0 + \beta_1| \leq |z^{-1}\beta_0| + |\beta_1| \quad (3.39)$$

From Table 3.1

$$||z^{-1}\beta_0| - |\beta_1|| \leq |H(z)| \leq |z^{-1}\beta_0| + |\beta_1| \quad (3.40)$$

From (3.36)

$$||\beta_0| - |\beta_1|| \leq |H(z)| \leq |\beta_0| + |\beta_1| \quad (3.41)$$

So, we can conclude that

$$|H(z)|_{max} = |\beta_0| + |\beta_1| \quad (3.42)$$

Now from Table 3.1

$$1 = |\beta_0| + |\beta_1| \quad (3.43)$$

Similarly,

$$\frac{1}{2} = ||\beta_0| - |\beta_1|| \quad (3.44)$$

On solving (3.43) and (3.44), we get

$$|\beta_0| = 0.75, |\beta_1| = 0.25 \quad (3.45)$$

OR

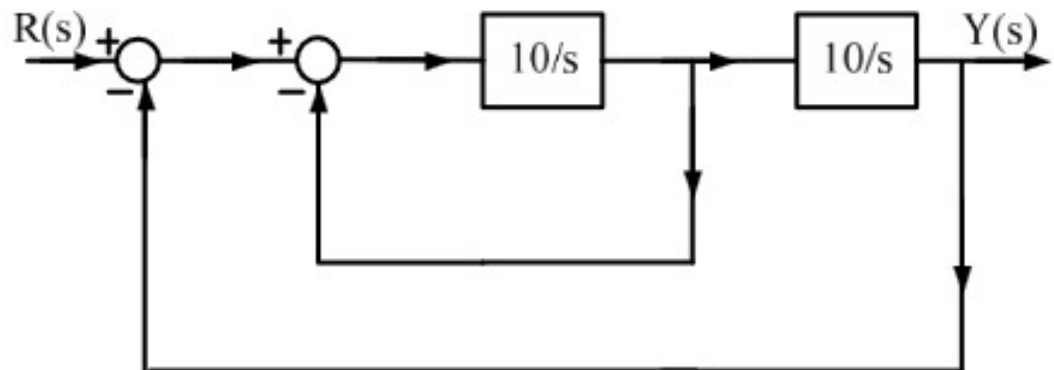
$$|\beta_0| = 0.25, |\beta_1| = 0.75 \quad (3.46)$$

Hence the correct answer is option (A)

## Chapter 4

## Systems

4.1 The damping ratio and undamped natural frequency of a closed loop system as shown in the figure, are denoted as  $\zeta$  and  $\omega_n$ , respectively. The values of  $\zeta$  and  $\omega_n$  are



- (a)  $\zeta = 0.5$  and  $\omega_n = 10$  rad/s
- (b)  $\zeta = 0.1$  and  $\omega_n = 10$  rad/s
- (c)  $\zeta = 0.707$  and  $\omega_n = 10$  rad/s
- (d)  $\zeta = 0.707$  and  $\omega_n = 100$  rad/s

(GATE EE 2022) **Solution:**

We will use Mason's Gain Formula to calculate the transfer function of this system.

Parameter	Description	Values
m	load of system	
k	stiffness of system	
$\omega_n$	Natural frequency	$\sqrt{\frac{k}{m}}$
$\zeta$	Damping ratio	$\frac{c}{2m\omega_n}$
$y(t)$	Output of system	
$x(t)$	Input to the system	
c	Damping coefficient	
$T(s)$	Transfer function of system	$\frac{Y(s)}{R(s)}$

Table 4.1: Parameter Table

First converting the given diagram to a signal flow graph :

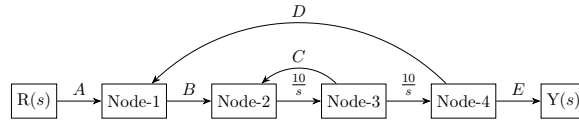


Figure 4.1: Signal Flow Diagram

Mason's Gain Formula is given by :

$$H(s) = \sum_{i=1}^N \left( \frac{P_i \Delta_i}{\Delta} \right) \quad (4.1)$$

This signal flow graph has only one forward path whose gain is given by :

$$P_1 = \frac{10}{s} \frac{10}{s} \quad (4.2)$$

$$= \frac{100}{s^2} \quad (4.3)$$

Parameter	Description
N	Number of forward paths
L	Number of loops
$P_k$	Forward path gain of $k^{th}$ path
$\Delta_k$	Associated path factor
$\Delta$	Determinant of the graph

Table 4.2: Parameter Table - Mason's Gain Law

Parameter	Formula
$\Delta$	$1 + \sum_{k=1}^L \left( (-1)^k \text{Product of gain of groups of k isolated loops} \right)$
$\Delta_k$	$\Delta$ part of graph that is not touching $k^{th}$ forward path

Table 4.3: Formula Table - Mason's Gain Law

The loop gain for loop between Node-2 and Node-3 is :

$$L_1 = \frac{10}{s} (-1) \quad (4.4)$$

$$= -\frac{10}{s} \quad (4.5)$$

The loop gain for loop between Node-1 and Node-4 is :

$$L_1 = \frac{10}{s} \frac{10}{s} (-1) \quad (4.6)$$

$$= -\frac{100}{s^2} \quad (4.7)$$

Using Table 4.3,  $\Delta$  is :

$$\Delta = 1 - \left( -\frac{10}{s} - \frac{100}{s^2} \right) \quad (4.8)$$

$$= 1 + \frac{10}{s} + \frac{100}{s^2} \quad (4.9)$$

There are no two isolated loops available. Hence all further terms will be zero.

As both the loops are in contact with the only forward path,

$$\Delta_1 = 1 \quad (4.10)$$

Using equation (4.1) :

$$H(s) = \frac{\frac{100}{s^2}}{1 + \frac{10}{s} + \frac{100}{s^2}} \quad (4.11)$$

$$= \frac{100}{s^2 + 10s + 100} \quad (4.12)$$

Referring to Table 4.1, the general equation of the damping system is second order and can be written as :

$$m\ddot{y}(t) + c\dot{y}(t) + ky(t) = x(t) \quad (4.13)$$

Take the Laplace transform and solve for  $\frac{Y(s)}{X(s)}$  :

$$\frac{Y(s)}{X(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (4.14)$$

$$\Rightarrow H(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2} \quad (4.15)$$



Comparing equations (4.12) and (4.15) ,

$$\omega_n^2 = 100 \quad (4.16)$$

$$\Rightarrow \omega_n = 10 \text{ rad/s} \quad (4.17)$$

$$2\zeta\omega_n = 10 \quad (4.18)$$

$$\Rightarrow \zeta = 0.5 \quad (4.19)$$

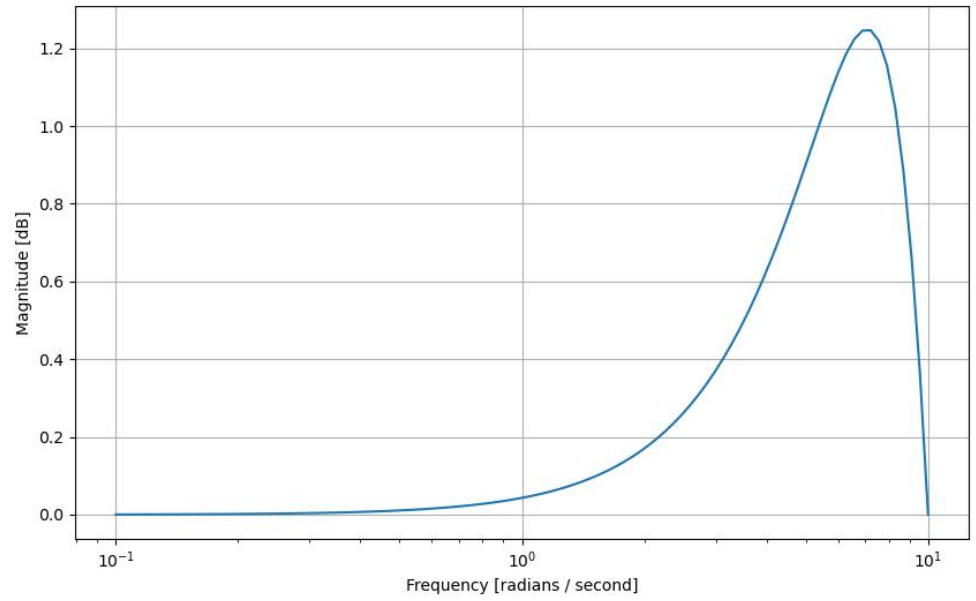


Figure 4.2: Magnitude plot

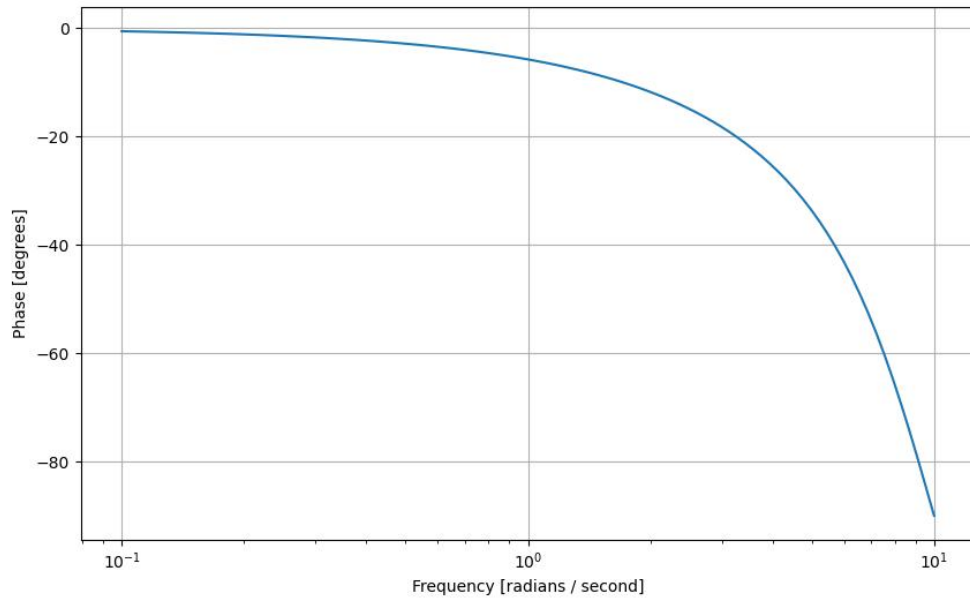
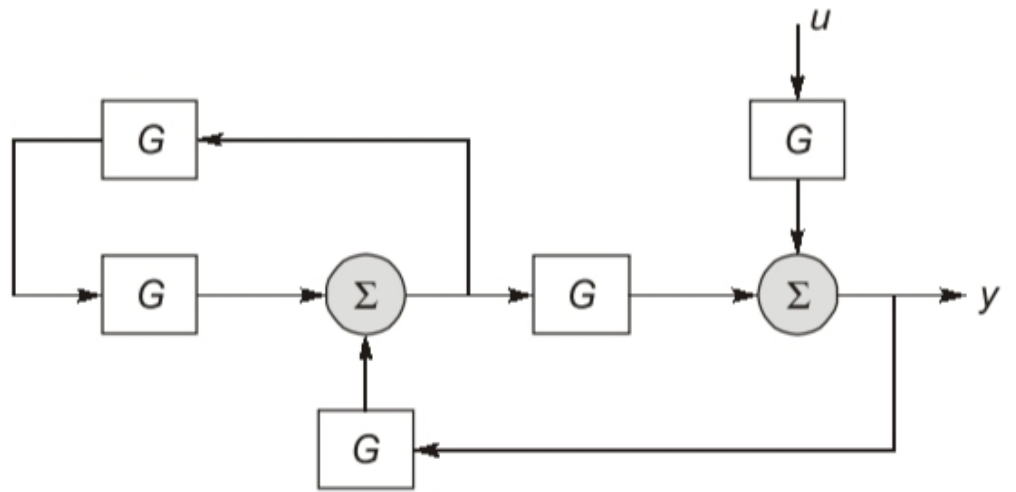


Figure 4.3: Phase plot

4.2 In the block diagram shown in the figure, the transfer function  $G = \frac{K}{\tau s + 1}$  with  $K > 0$  and  $\tau > 0$ . The maximum value of  $K$  below which the system remains stable is \_\_\_\_\_ (rounded off to two decimal places) (GATE CH 2022)

**Solution:**



Parameter	Value	Description
$G$	$\frac{K}{\tau s + 1}$	Transfer function shown in blocks
$Y$		Laplace transform of $y$ (output)
$U$		Laplace transform of $u$ (input)
$X, Z$		Laplace transform of $x$ and $z$
$T$	$\frac{Y}{U}$	Transfer function of complete system

Table 4.4: Parameters

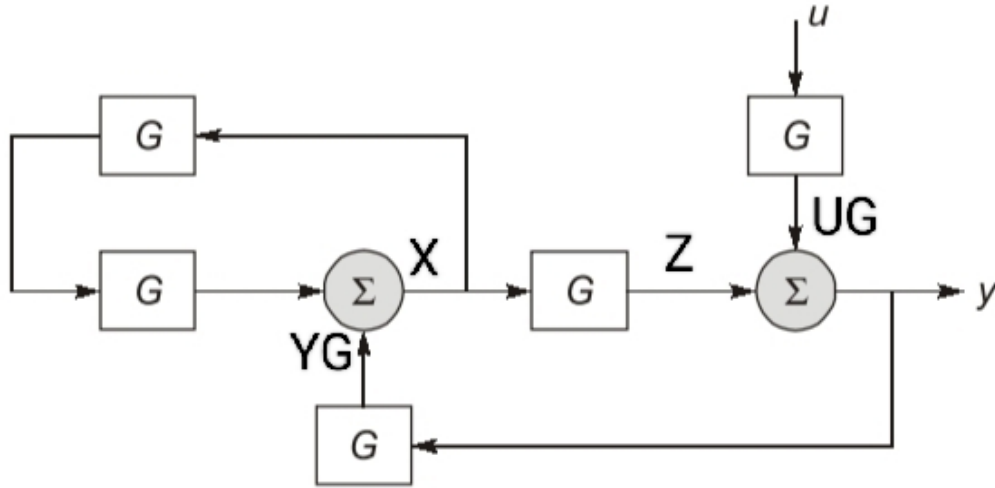


Figure 4.4: Block Diagram

$$X = XG^2 + YG \quad (4.20)$$

$$\Rightarrow X = \frac{YG}{1 - G^2} \quad (4.21)$$

$$Z = XG \quad (4.22)$$

$$Y = Z + UG \quad (4.23)$$

$$Y = XG + UG \quad (4.24)$$

$$Y = \frac{YG^2}{1 - G^2} + UG \quad (4.25)$$

$$\Rightarrow Y = \frac{UG(1 - G^2)}{1 - 2G^2} \quad (4.26)$$

From Table 4.4,

$$T = \frac{G(1 - G^2)}{1 - 2G^2} \quad (4.27)$$

$$= \frac{K \left(1 - \frac{K^2}{(\tau s + 1)^2}\right)}{\left(1 - \frac{2K^2}{(\tau s + 1)^2}\right) (\tau s + 1)} \quad (4.28)$$

$$= \frac{K(\tau^2 s^2 + 2\tau s + 1 - K^2)}{\tau^3 s^3 + 3\tau^2 s^2 + (3\tau - 2K^2\tau)s + 1 - 2K^2} \quad (4.29)$$

So, Characteristic equation :

$$\tau^3 s^3 + 3\tau^2 s^2 + (3\tau - 2K^2\tau)s + 1 - 2K^2 = 0 \quad (4.30)$$

For a characteristic equation  $a_0 s^n + a_1 s^{n-1} + a_2 s^{n-2} + \dots a_n = 0$ ,

$s^n$	$a_0$	$a_2$	$a_4$	...
$s^{n-1}$	$a_1$	$a_3$	$a_5$	...
$s^{n-2}$	$b_1 = \frac{a_1 a_2 - a_3 a_0}{a_1}$	$b_2 = \frac{a_1 a_4 - a_5 a_0}{a_1}$	...	..
$s^{n-3}$	$c_1 = \frac{b_1 a_3 - b_2 a_1}{b_1}$	$\vdots$		
$\vdots$	$\vdots$	$\vdots$		
$s^1$	$\vdots$	$\vdots$		
$s^0$	$a_n$			

Table 4.5: Routh Array

From Table 4.5:

$s^3$	$\tau^3$	$3\tau - 2K^2\tau$
$s^2$	$3\tau^2$	$1 - 2K^2$
$s^1$	$\frac{8}{3}\tau(1 - K^2)$	0
$s^0$	$1 - 2K^2$	

Table 4.6:

Given  $\tau > 0$  and  $K > 0$ , for system to be stable,

$$1 - K^2 > 0 \tag{4.31}$$

$$1 - 2K^2 > 0 \tag{4.32}$$

$$\implies 0 < K < \frac{1}{\sqrt{2}} \tag{4.33}$$

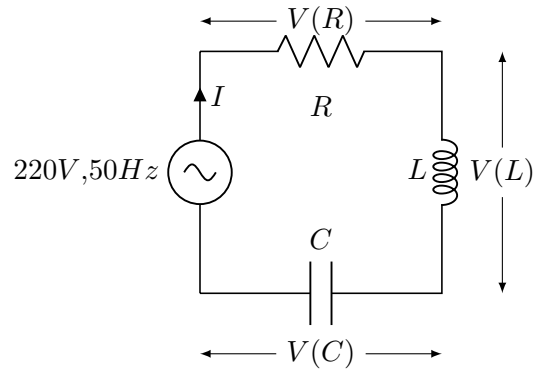
$$K_{max} \approx 0.71 \tag{4.34}$$

- 4.3 A series RLC circuit is connected to 220 V, 50 Hz supply. For a fixed a value of R and C, the inductor L is varied to deliver the maximum current. This value 0.4A and the corresponding potential drop across the capacitor is 330 V. The value of the inductor L is ? (Rounded off to two decimal places). (GATE BM 2022)

**Solution:**

Symbols	Description	Values
$V_s$	Input voltage	220 V and 50Hz
$\chi_L$	Impedance across inductor	$j\omega L$
$\chi_C$	Impedance across capacitor	$\frac{-j}{\omega C}$
$Z$	Impedance across the entire circuit	$R + j\omega L + \frac{-j}{\omega C}$

Table 4.7: Parameters, Descriptions, and Values



During maximum current  $|Z|$  is minimum .

$$I = \frac{V_s}{Z} \quad (4.35)$$

$$= \frac{V_s}{R + \chi_L + \chi_C} \quad (4.36)$$

$$= \frac{V_s}{R + j\omega L + \frac{1}{j\omega C}} \quad (4.37)$$

$$|I| = \frac{|V_s|}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}} \quad (4.38)$$

Varying  $L$  for maximum value of  $I$  :

$$\omega L = \frac{1}{\omega C} \quad (4.39)$$

Putting in (4.37):

$$I_{max} = \frac{V_s}{R} \quad (4.40)$$

$I_{max}$  has same phase as  $V_s$  (Assume  $\angle\phi$ ). For impedance across the capacitor :

$$V_C|_{I=I_{max}} = I_{max}\chi_C \quad (4.41)$$

$$-330\angle(90 + \phi) = (0.4\angle\phi)\chi_C \quad (4.42)$$

$$-330\angle90 = 0.4\chi_C \quad (4.43)$$

$$\implies \chi_C = -825j\Omega \quad (4.44)$$

For value of Capacitor and inductor, using (4.39) :

$$L = \frac{825}{100\pi}H \quad (4.45)$$

$$\approx 2.63H \quad (4.46)$$

$$C = 3.858 * 10^{-6}F \quad (4.47)$$



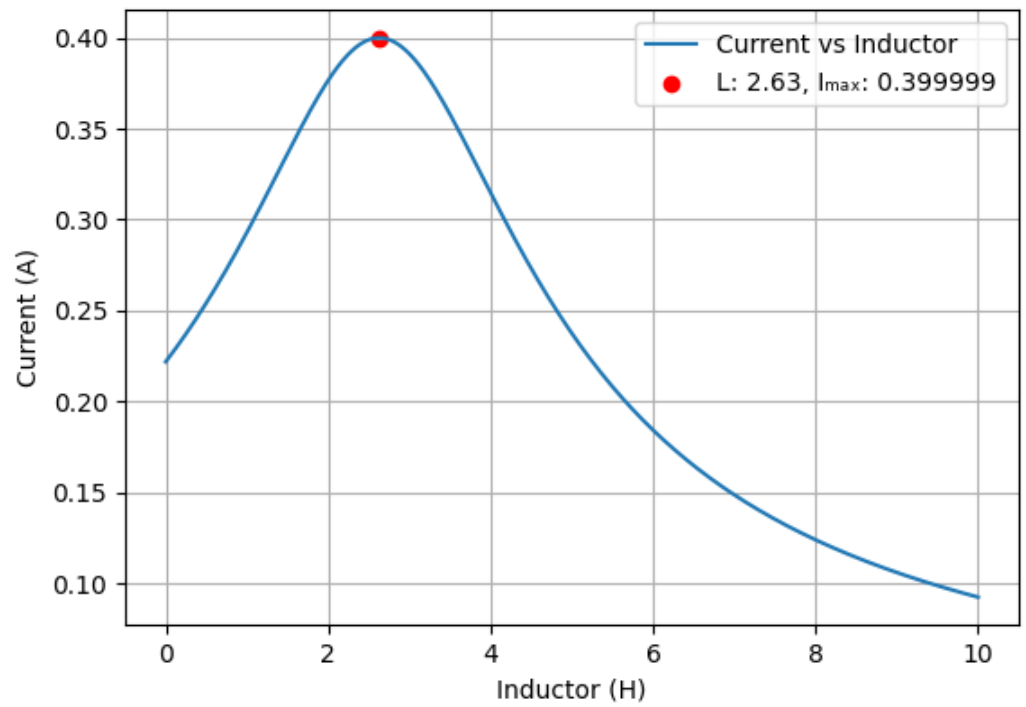


Figure 4.5:  $I$  vs  $L$

4.4 The open loop transfer function of a unity gain negative feedback system is given by

$G(s) = \frac{k}{s^2 + 4s - 5}$ . The range of  $k$  for which the system is stable, is (GATE EE 2022)

**Solution:**

Variable	Description	value
$G(s)$	Open loop transfer function	$\frac{k}{s^2 + 4s - 5}$
$1 + G(s)$	Characteristic equation	0

Table 4.8: A Table with input parameters

from Table4.8

Characteristic equation:

$$1 + G(s) = 0 \quad (4.48)$$

$$\Rightarrow 1 + \frac{k}{s^2 + 4s - 5} = 0 \quad (4.49)$$

$$\Rightarrow s^2 + 4s + (k - 5) = 0 \quad (4.50)$$

By routh table analysis, for a stable system:

$$\begin{array}{c|cc} s^2 & 1 & k-5 \\ s^1 & 4 & 0 \\ s^0 & \frac{4(k-5)-0}{4} & 0 \end{array}$$

$$\frac{4(k-5)-0}{4} > 0 \quad (4.51)$$

$$k - 5 > 0 \quad (4.52)$$

$$\Rightarrow k > 5 \quad (4.53)$$

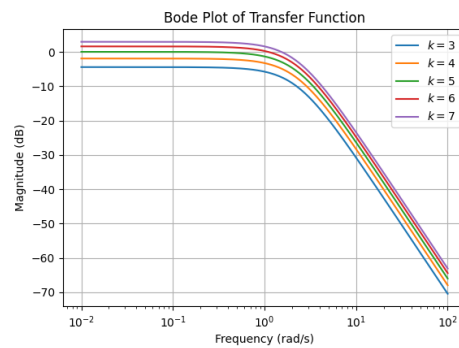


Figure 4.6: Graph showing  $k < 5, k = 5, k > 5$

For an open transfer function to be stable, its magnitude in the bode plot should be

positive for some positive frequency.

In the below graph we can observe that the above condition satisfies for  $k > 5$ .



## Chapter 5

# Sequences

5.1 Discrete signals  $x(n)$  and  $y(n)$  are shown below. The cross-correlation  $r_{xy}(0)$  is:

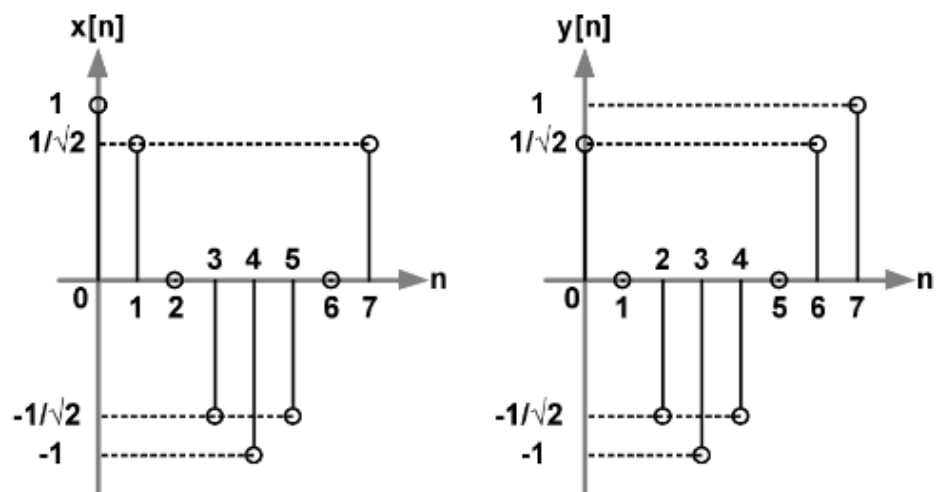


Figure 5.1: Question Figure

(GATE BM 2022)

**Solution:**

Parameter	Description	Value
$x(n)$	First Sequence	$x(n) = \begin{cases} 0 & ; n < 0 \\ \left(1, \frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}, -1, -\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}\right) & ; 0 \leq n \leq 7 \\ 0 & ; n > 7 \end{cases}$
$y(n)$	Second Sequence	$y(n) = \begin{cases} 0 & ; n < 0 \\ \left(\frac{1}{\sqrt{2}}, 0, -\frac{1}{\sqrt{2}}, -1, -\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}, 1\right) & ; 0 \leq n \leq 7 \\ 0 & ; n > 7 \end{cases}$
$r_{xy}(k)$	Cross-correlation	$\sum_{m=-\infty}^{\infty} x(m) y(m-k)$

Table 1: Parameter Table

It can be seen that :

$$y(n) = x(n+1) \quad (5.1)$$

From Table 1 :

$$r_{xy}(k) = \sum_{m=-\infty}^{\infty} x(m) y(m-k) \quad (5.2)$$

$$= x(k) * y(-k) \quad (5.3)$$

From (5.1):

$$r_{xy}(k) = x(k+1) * x(-k) \quad (5.4)$$

$$= \sum_{n=-\infty}^{\infty} x(n+1) x(n+k) \quad (5.5)$$

By definition of  $x(n)$  from Table 1:

$$r_{xy}(k) = \sum_{n=0}^6 x(n+1) x(n+k) \quad (5.6)$$

$$r_{xy}(0) = \sum_{n=0}^6 x(n+1) x(n) \quad (5.7)$$

Using values from Fig. 5.1:

$$r_{xy}(0) = 2\sqrt{2} \quad (5.8)$$

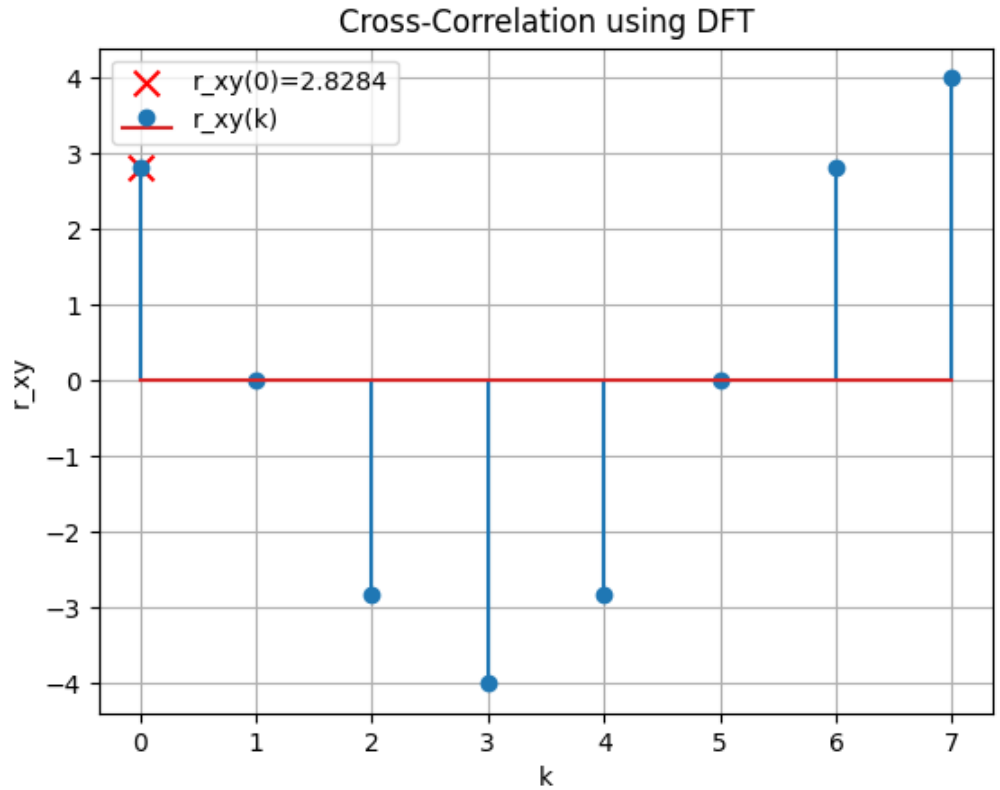


Figure 5.2: Verification of result by DFT

5.2 Which one of the following is the closed form for the generating function of the sequence  $\{a\}_{n \geq 0}$  defined below?

$$a_n = \begin{cases} n+1 & , n \text{ is odd} \\ 1 & \text{otherwise} \end{cases} \quad (5.9)$$

(A)  $\frac{x(1+x)^2}{(1-x^2)^2} + \frac{1}{1-x}$

(B)  $\frac{x(3-x^2)}{(1-x^2)^2} + \frac{1}{1-x}$

(C)  $\frac{2x}{(1-x^2)^2} + \frac{1}{1-x}$

(D)  $\frac{x}{(1-x^2)^2} + \frac{1}{1-x}$

(GATE CS 2022 QUESTION 36)

**Solution:** For the given sequence:

Parameter	Description	Value
$X(z)$	Generating function for a sequence $\{a_n\}$	?
$a_n$	$n^{th}$ term of the sequence	$(n+1)u(n)$ (when odd)
		$u(n)$ (when even)

Table 5.2: input values

$$X(z) = \sum_{k=-\infty}^{\infty} u(2k) z^{-2k} + \sum_{k=-\infty}^{\infty} ((2k+2)u(2k+1)) z^{-(2k+1)} \quad (5.10)$$

$$\implies X(z) = (1 + z^{-2} + z^{-4} + \dots) + (2z^{-1} + 4z^{-3} + 6z^{-5} + \dots) \quad (5.11)$$

$$\implies X(z) = \frac{1}{1-z^{-2}} + (2z^{-1} + 4z^{-3} + 6z^{-5} \dots) \quad |z| > 1 \quad (5.12)$$

$$\implies X(z) = \frac{1}{1-z^{-2}} + 2z^{-1} \left( \frac{1}{1-z^{-2}} + \frac{z^{-2}}{(1-z^{-2})^2} \right) \quad |z| > 1 \quad (5.13)$$



$$\therefore X(z) = \frac{1}{1-z^{-1}} + \frac{z^{-1}(1+z^{-2})}{(1-z^{-2})^2} \quad |z| > 1 \quad (5.14)$$

(5.14) is the closed form of generating function required in the question.

Hence, option (A) is correct.

$$X(z) = X_1(z) + X_2(z) \quad (5.15)$$

$$X_1(z) = \frac{1}{1-z^{-1}} \quad |z| > 1 \quad (5.16)$$

$$\implies x_1(n) = u(n) \quad (5.17)$$

$$\implies a_n = x_1(n) + x_2(n) \quad (5.18)$$

To find inverse z-transform of  $X_2(z)$  we use contour integration technique:

$$x_2(n) = \frac{1}{2\pi j} \oint_C X_2(z) z^{n-1} dz \quad (5.19)$$

$$= \frac{1}{2\pi j} \oint_C \frac{z^n (z^2 + 1)}{(z^2 - 1)^2} dz \quad (5.20)$$

We can observe that we have two poles at

$z = 1, -1$ . And poles are repeated twice, thus by applying residue theorem two times

for poles 1 and -1:

$$x_2(n) = \frac{1}{(1)!} \lim_{z \rightarrow 1} \frac{d}{dz} \left( (z-1)^2 X_2(z) \right) + \frac{1}{(1)!} \lim_{z \rightarrow -1} \frac{d}{dz} \left( (z+1)^2 X_2(z) \right) \quad (5.21)$$

$$\Rightarrow x_2(n) = \lim_{z \rightarrow 1} \frac{d}{dz} \left( (z-1)^2 \frac{z^n (z^2 + 1)}{(z^2 - 1)^2} \right) + \lim_{z \rightarrow -1} \frac{d}{dz} \left( (z+1)^2 \frac{z^n (z^2 + 1)}{(z^2 - 1)^2} \right) \quad (5.22)$$

$$\begin{aligned} \Rightarrow x_2(n) &= \lim_{z \rightarrow 1} \frac{(z+1)^2 (nz^{n-1} + (n+2)z^{n+1}) - 2z^n (1+z^2)(z+1)}{(z+1)^4} \\ &\quad + \lim_{z \rightarrow -1} \frac{(z-1)^2 (nz^{n-1} + (n+2)z^{n+1}) - 2z^n (1+z^2)(z-1)}{(z-1)^4} \end{aligned} \quad (5.23)$$

on simplification, we get

$$x_2(n) = \frac{n + n(-1)^{n-1}}{2} \quad (5.24)$$

$$\therefore a_n = u(n) + \frac{n + n(-1)^{n-1}}{2} u(n) \quad (5.25)$$

Which is the sequence given in the Question.

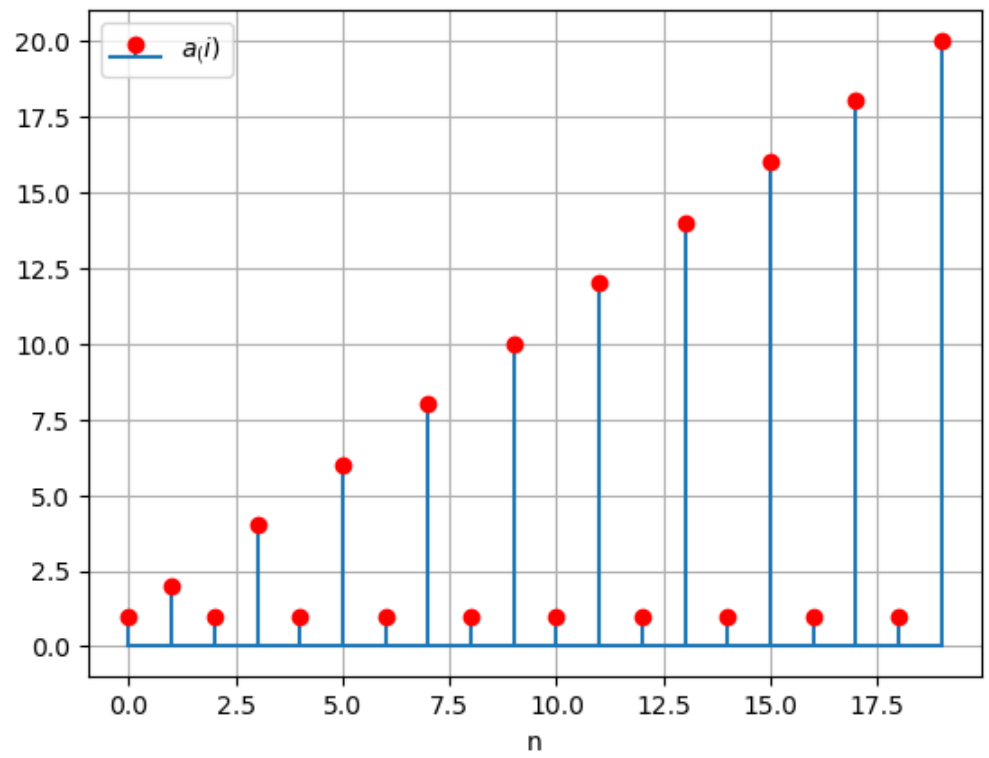


Figure 5.3: Terms of the sequence given



## Chapter 6

# Sampling

6.1



## Chapter 7

# Contour Integration

7.1 In the complex  $z$ -domain, the value of integral  $\oint_C \frac{z^3-9}{3z-i} dz$  is

- (a)  $\frac{2\pi}{81} - 6i\pi$
- (b)  $\frac{2\pi}{81} + 6i\pi$
- (c)  $-\frac{2\pi}{81} + 6i\pi$
- (d)  $-\frac{2\pi}{81} - 6i\pi$

(GATE 2022 BM)

**Solution:**

Simplyfying the Contour Integral to the standard form we get,

$$\oint_C \frac{z^3-9}{3z-i} dz = \frac{1}{3} \oint_C \frac{z^3-9}{z-\frac{i}{3}} dz \quad (7.1)$$

From Cauchy's residue theorem,

$$\oint_C f(z) dz = 2\pi i \sum R_j \quad (7.2)$$

We can observe a non-repeated pole at  $z = \frac{i}{3}$  and thus  $a = \frac{i}{3}$ ,

$$R = \lim_{z \rightarrow a} (z - a) f(z) \quad (7.3)$$

$$\Rightarrow R = \frac{1}{3} \lim_{z \rightarrow \frac{i}{3}} \left( z - \frac{i}{3} \right) \frac{z^3 - 9}{z - \frac{i}{3}} \quad (7.4)$$

$$= \frac{-i}{81} - 3 \quad (7.5)$$

Therefore, from (7.2) and (7.5)

$$\oint_C \frac{z^3 - 9}{3z - i} dz = \frac{2\pi}{81} - 6i\pi \quad (7.6)$$



## Chapter 8

# Laplace Transform

8.1 Consider the differential equation  $\frac{d^2y}{dx^2} - 2\frac{dy}{dx} + y = 0$ . The boundary conditions are  $y = 0$  and  $\frac{dy}{dx} = 1$  at  $x = 0$ . Then the value of  $y$  at  $x = \frac{1}{2}$  (GATE AE 2022)

**Solution:**

Parameters	Values	Description
$y(0)$	0	$y$ at $x = 0$
$y'(0)$	1	$\frac{dy}{dx}$ at $x = 0$

Table 8.1: Parameters

$$\frac{d^2y}{dx^2} \xleftrightarrow{\mathcal{L}} s^2Y(s) - sy(0) - y'(0) \quad (8.1)$$

$$\frac{dy}{dx} \xleftrightarrow{\mathcal{L}} sY(s) - y(0) \quad (8.2)$$

Applying Laplace Transform, using (8.1) and (8.2),

$$s^2Y(s) - sy(0) - y'(0) - 2(sY(s) - y(0)) + Y(s) = 0 \quad (8.3)$$

From Table 8.1,

$$(s^2 - 2s + 1)Y(s) - 1 = 0 \quad (8.4)$$

$$Y(s) = \frac{1}{(s-1)^2} \quad (8.5)$$

$$t^n \xleftrightarrow{\mathcal{L}} \frac{n!}{s^{n+1}} \quad (8.6)$$

$$e^{at}x(t) \xleftrightarrow{\mathcal{L}} X(s-a) \quad (8.7)$$

Taking Inverse Laplace Transform for  $Y(s)$ , using (8.6) and (8.7),

$$y(x) = xe^x \quad (8.8)$$

$$\implies y\left(\frac{1}{2}\right) = \frac{\sqrt{e}}{2} \quad (8.9)$$

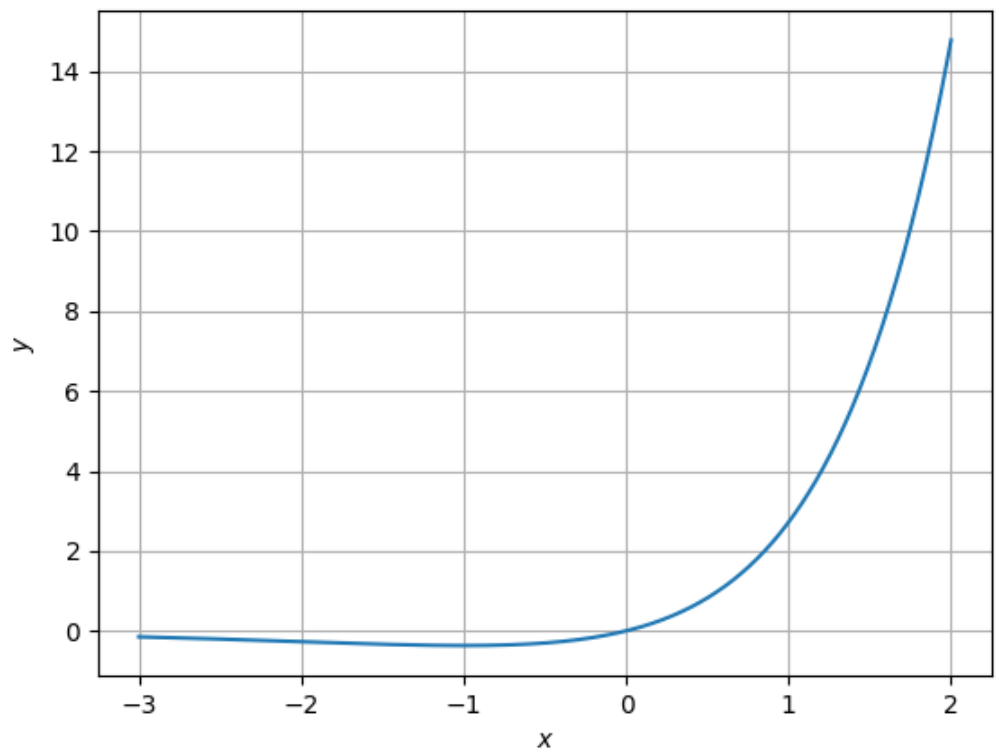


Figure 8.1: Plot of  $y(x)$

## 8.2 A process described by the transfer function

$$G_p(s) = \frac{(10s + 1)}{(5s + 1)}$$

is forced by a unit step input at time  $t = 0$ . The output value immediately after the unit step input (at  $t = 0^+$ ) is ? (Gate 2022 CH 34)

**Solution:**

Parameters	Description
$X(s)$	Laplace transform of $x(t)$
$Y(s)$	Laplace transform of $y(t)$
$G_p(s) = \frac{Y(s)}{X(s)}$	Transfer function
$x(t) = u(t)$	unit step function

Table 8.2: Given parameters

$$G_p(s) = \frac{Y(s)}{X(s)} = \frac{(10s + 1)}{(5s + 1)} \quad (8.10)$$

$$u(t) \xleftrightarrow{\mathcal{L}} \frac{1}{s} \quad (8.11)$$

From equation (8.11):

$$Y(s) = \frac{(10s + 1)}{s(5s + 1)} \quad (8.12)$$

$$= \frac{1}{s} + \frac{5}{5s + 1} \quad (8.13)$$

Taking inverse laplace transformation,

$$\frac{1}{s} \xleftrightarrow{\mathcal{L}^{-1}} u(t) \quad (8.14)$$

$$\frac{1}{s - c} \xleftrightarrow{\mathcal{L}^{-1}} e^{ct} u(t) \quad (8.15)$$

$$y(t) = \left(1 + e^{-\frac{t}{5}}\right) u(t) \quad (8.16)$$

$$y(0^+) = 2 \quad (8.17)$$

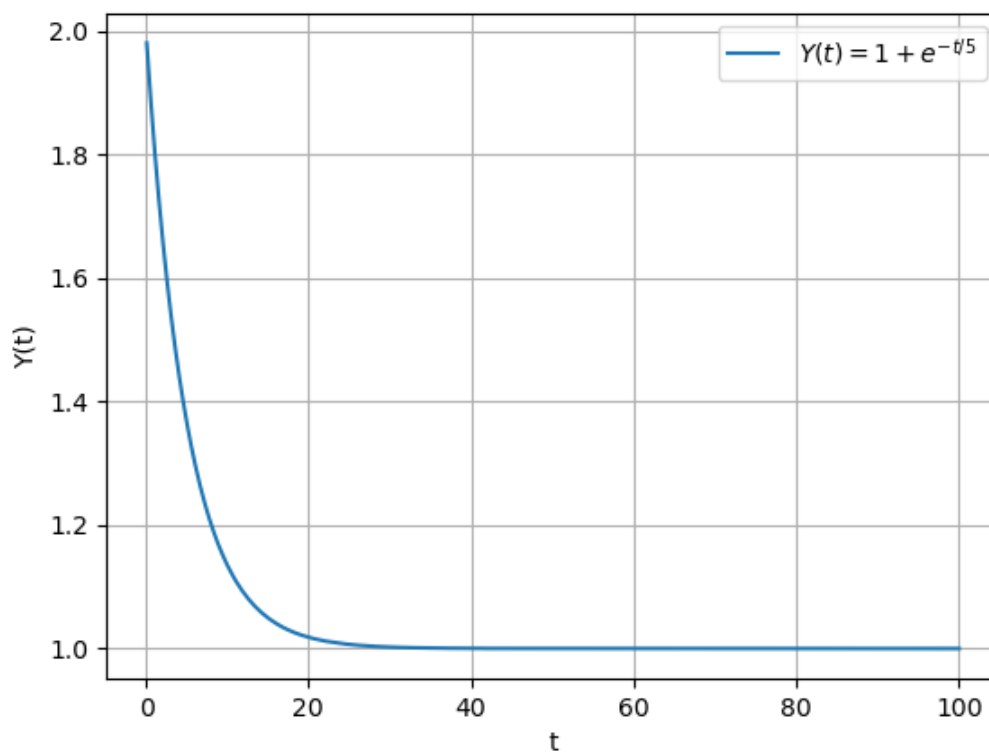


Figure 8.2: Graph of  $y(t)$

8.3 The transfer function of a real system  $H(S)$  is given as:

$$H(s) = \frac{As + B}{s^2 + Cs + D}$$

where  $A, B, C$  and  $D$  are positive constants. This system cannot operate as

- (A) Low pass filter
- (B) High pass filter
- (C) Band pass filter
- (D) An Integrator

(GATE EE 11 2022)

**Solution:** The transfer function  $H(s)$  is given by:

$$H(s) = \frac{As + B}{s^2 + Cs + D} \quad (8.18)$$

Put  $s = j\omega$  in (8.18):

$$H(j\omega) = \frac{A(j\omega) + B}{(j\omega)^2 + C(j\omega) + D} \quad (8.19)$$

$$|H(j\omega)| = \frac{\sqrt{(A\omega)^2 + B^2}}{\sqrt{(D - \omega^2)^2 + (\omega C)^2}} \quad (8.20)$$

a) Low Pass Filter:

At low frequency ( $\omega = 0$ ):

$$|H(\omega = 0)| = \frac{B}{D} \quad (8.21)$$

$\therefore H(s)$  can operate as Low pass filter.

Parameter	Description
Low Pass Filter	The gain should be finite at low frequency
High Pass Filter	The gain should be finite at high frequency
Band Pass Filter	Finite gain over frequency band
Integrator	Transfer function should have at least one pole at origin

Table 8.3: Conditions

b) High Pass Filter:

At high frequency ( $\omega = \infty$ ):

$$|H(\omega = \infty)| = 0 \quad (8.22)$$

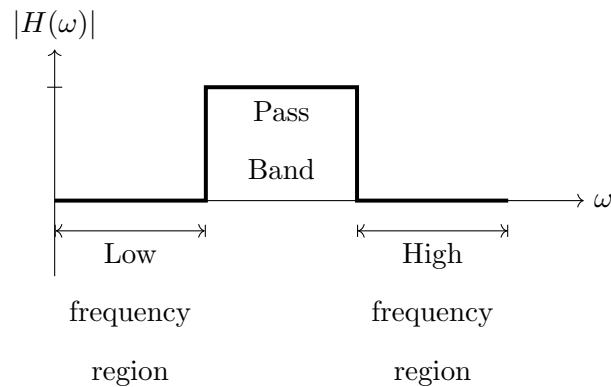
$\therefore H(s)$  cannot operate as High pass filter.

c) Band Pass Filter:

Assuming B is a very less positive valued constant as compared to others:

$$|H(j\omega)| = \frac{(A\omega)}{\sqrt{(D - \omega^2)^2 + (\omega C)^2}} \quad (8.23)$$

$$\implies |H(\omega = 0)| = 0 \text{ and } |H(\omega = \infty)| = 0 \quad (8.24)$$



$\therefore H(s)$  passes frequency be-

tween low and high frequencies.

$\therefore H(s)$  can operate as a band pass filter.

d) Integrator:

At very high value of frequency( $\omega \rightarrow \infty$ ):

$$H(s) \approx \frac{As}{s^2} \approx \frac{A}{s} \quad (8.25)$$

From Table 8.3:

$\therefore H(s)$  can operate as an Integrator.



8.4 In a circuit, there is a series connection of an ideal resistor and an ideal capacitor. The conduction current (in Amperes) through the resistor is  $2 \sin(t + \frac{\pi}{2})$ . The displacement current (in Amperes) through the capacitor is \_\_\_\_\_.

- (A)  $2 \sin(t)$
- (B)  $2 \sin(t + \pi)$
- (C)  $2 \sin(t + \frac{\pi}{2})$
- (D) 0

(GATE 2022 EC 24)

**Solution:**

Parameter	Description	Value
$I_c$	Conduction Current	$2 \sin(t + \frac{\pi}{2})$
$A$	Cross-sectional area	

Table 8.4: Parameters

Parameter	Description	Formula
$Q$	Charge	$\int I_c dt$
$D$	Electric Displacement	$\frac{Q}{A}$
$J_D$	Displacement current density	$\frac{\partial D}{\partial t}$
$I_D$	Displacement current	$J_D \times A$

Table 8.5: Formulae

S Domain	Time Domain
$\frac{1}{s}$	$u(t)$
$\frac{-s}{a^2+s^2}$	$-\cos(at)$
$\frac{a}{a^2+s^2}$	$\sin(at)$
$\frac{1}{s+a}$	$e^{-at}$

Table 8.6: Laplace transforms

$$\mathcal{L} \left[ \int f(t) dt \right] = \int_0^\infty \left[ \int f(t) dt \right] e^{-st} dt \quad (8.26)$$

$$= \int_0^\infty u dv \quad \text{where} \begin{cases} u = \int f(t) dt \\ dv = e^{-st} dt \end{cases} \quad (8.27)$$

$$= uv - v \int du \quad (8.28)$$

$$= \frac{1}{s} \int f(t) dt|_0 + \frac{1}{s} \int_0^\infty f(t) e^{-st} dt \quad (8.29)$$

$$\Rightarrow \frac{1}{s} \int f(t) dt|_0 + \frac{1}{s} F(s) \quad (8.30)$$

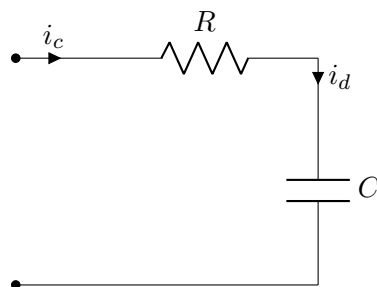


Figure 8.3: Circuit 1

From Table 8.5, Table 8.6 and eq (8.30)

$$I_c(s) = \frac{2s}{s^2 + 1} \quad (8.31)$$

$$Q_c(s) = \frac{2}{s(s^2 + 1)} \quad (8.32)$$

$$D(s) = \frac{1}{A} \left( \frac{2}{s(s^2 + 1)} \right) \quad (8.33)$$

$$J_D(s) = \frac{2}{A} \left( \frac{1}{s^2 + 1} \right) \quad (8.34)$$

$$I_D(s) = \frac{2}{s^2 + 1} \quad (8.35)$$

$$\Rightarrow I_D = 2 \sin t \quad (8.36)$$

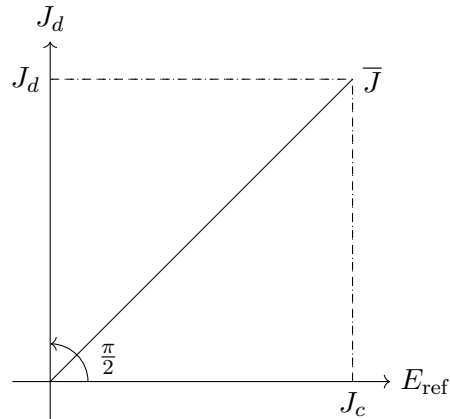


Figure 8.4: Phasor plot

From figure 8.4, phase of  $I_d$  is  $\frac{\pi}{2}$

$$\therefore I_d = 2 \sin \left( t + \frac{\pi}{2} \right) \quad (8.37)$$

$\therefore$  (C) is correct.

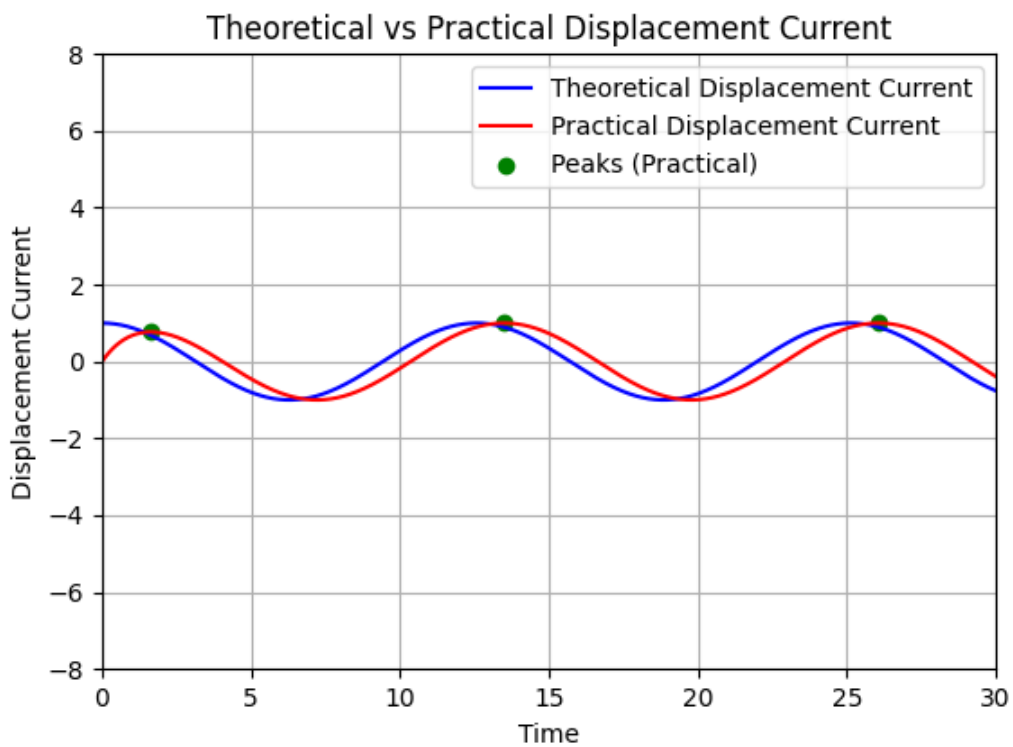


Figure 8.5: Thoritical vs Practical simulation

8.5 Given,  $y = f(x)$ ;  $\frac{d^2y}{dx^2} + 4y = 0$ ;  $y(0) = 0$ ;  $\frac{dy}{dx}(0) = 1$ . The problem is a/an

- (a) initial value problem having solution  $y = x$
- (b) boundary value problem having solution  $y = x$
- (c) initial value problem having solution  $y = \frac{1}{2} \sin 2x$
- (d) boundary value problem having solution  $y = \frac{1}{2} \sin 2x$

(GATE 2022 ES)

**Solution:**

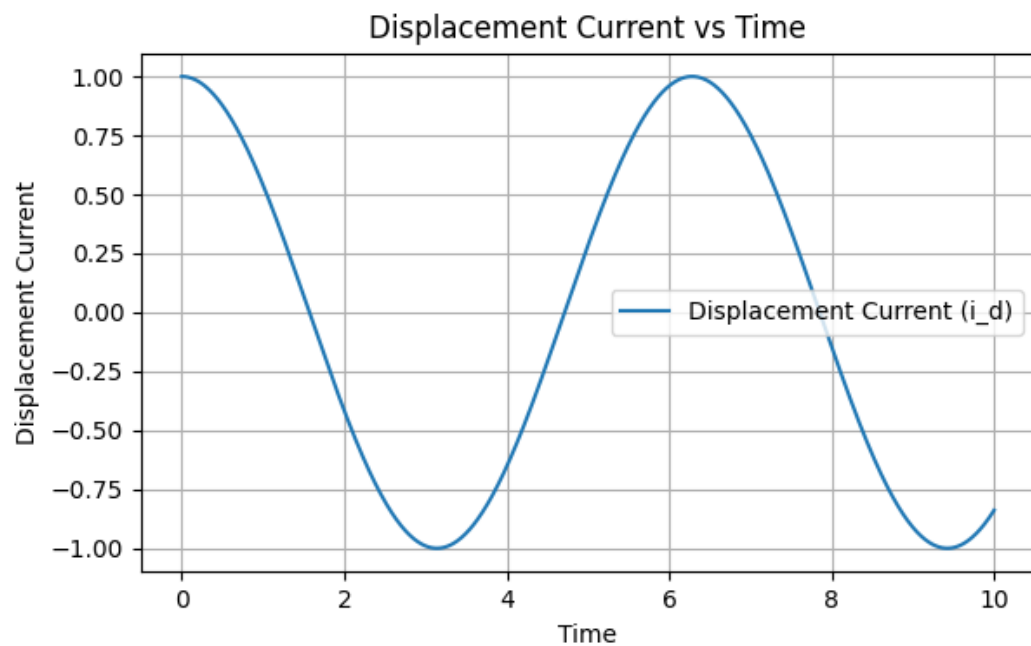


Figure 8.6: Displacement current

The above equation can be written as,

$$y''(t) + 4y(t) = 0 \quad (8.38)$$

Using the Laplace transformation pairs,

$$y''(t) \xleftrightarrow{\mathcal{L}} s^2 Y(s) - sy(0) - y'(0) \quad (8.39)$$

$$y(t) \xleftrightarrow{\mathcal{L}} Y(s) \quad (8.40)$$

$$\sin at \xleftrightarrow{\mathcal{L}} \frac{a}{a^2 + s^2} \quad (8.41)$$

Applying Laplace transform for the equation we get,

$$s^2 Y(s) - 1 + 4Y(s) = 0 \quad (8.42)$$

$$\implies Y(s) = \frac{1}{4 + s^2} \quad (8.43)$$

Now, applying inverse laplace transform we get,

$$y(t) = \frac{1}{2} \sin 2t \quad (\text{from (8.41)}) \quad (8.44)$$

Since, the conditions at the same point(0) are mentioned, it is an initial valued problem having solution  $y = \frac{1}{2} \sin 2x$ .

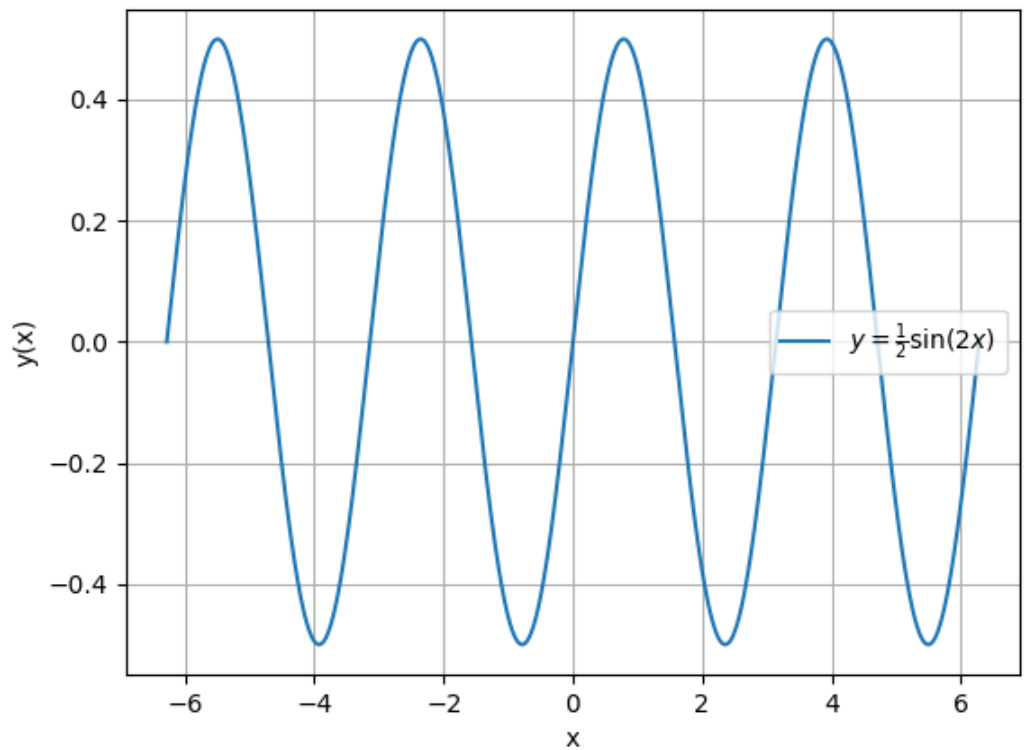


Figure 8.7:  $y(x)$  vs  $x$  graph

8.6 Let a causal LTI system be governed by the following differential equation,

$$y(t) + \frac{1}{4} \frac{dy}{dt} = 2x(t) \quad (8.45)$$

where  $x(t)$  and  $y(t)$  are the input and output respectively. It's impulse response is  
(GATE EE-2022)

**Solution: Solution:**

From (8.45), corresponding Laplace transform,

$$Y(s) + \frac{1}{4}(sY(s) - y(0)) = 2X(s) \quad (8.46)$$

Since it is causal LTI system,

$$y(0) = 0 \quad (8.47)$$

$$\Rightarrow Y(s) + \frac{1}{4}sY(s) = 2X(s) \quad (8.48)$$

$$\Rightarrow Y(s) = X(s) \frac{8}{4+s} \quad (8.49)$$

$$\Rightarrow H(s) = \frac{8}{4+s} \quad ROC : Re(s) > -4 \quad (8.50)$$

Taking inverse laplace transform and applying causality conditions

$$h(t) = 8e^{-4t}u(t) \quad (8.51)$$

8.7 Assuming  $s > 0$ ; Laplace transform for  $f(x) = \sin(ax)$  is

(A)  $\frac{a}{s^2+a^2}$

(B)  $\frac{s}{s^2+a^2}$

(C)  $\frac{a}{s^2-a^2}$

(D)  $\frac{s}{s^2-a^2}$

(GATE 2022 ES)



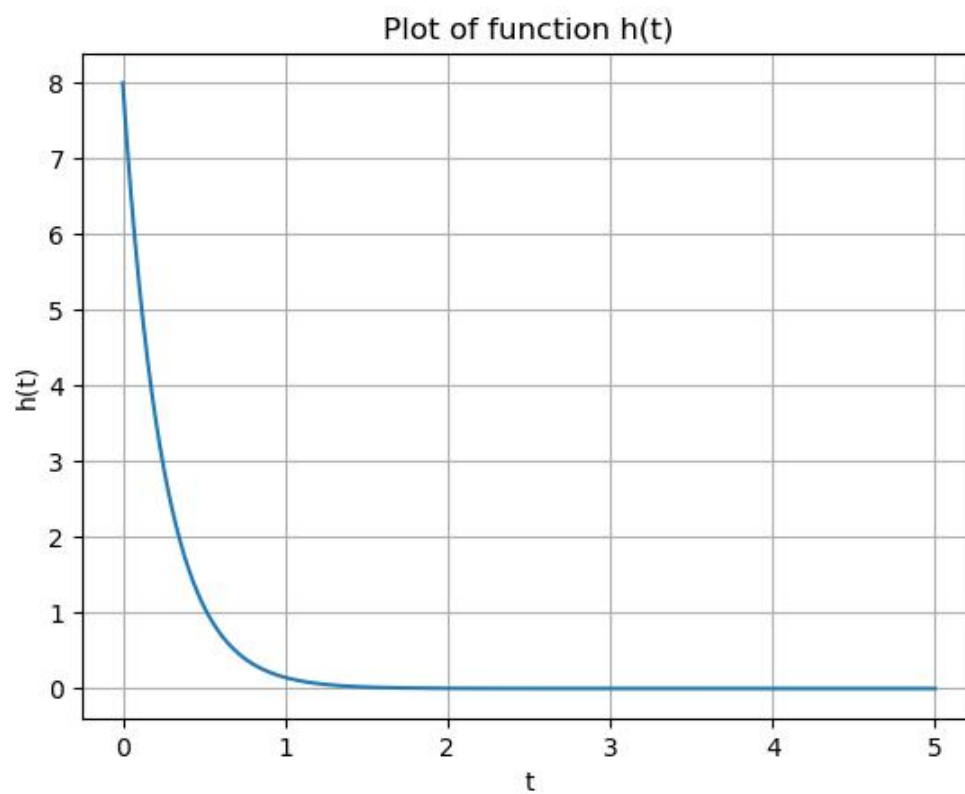


Figure 1: Plot of  $h(n)$ , taken from python3

**Solution:**

$$\mathcal{L}(f(x)) = \int_{-\infty}^{\infty} e^{-sx} f(x) dx \quad (8.52)$$

$$\text{We can write } \sin(ax) = \frac{e^{ax} - e^{-ax}}{2i} \quad (8.53)$$

From (8.53)

$$\mathcal{L}(\sin(ax)) = \int_0^\infty e^{-sx} \left( \frac{e^{iax} - e^{-iax}}{2i} \right) dx \quad (8.54)$$

$$= \frac{1}{2i} \int_0^\infty e^{-x(s-ia)} - e^{-x(s+ia)} dx \quad (8.55)$$

$$= \frac{1}{2i} \left( \frac{e^{-x(s-ia)}}{-(s-ia)} + \frac{e^{-x(s+ia)}}{-(s+ia)} \right) \Big|_0^\infty \quad (8.56)$$

$$= \frac{1}{2i} \left( \frac{1}{s-ia} - \frac{1}{s+ia} \right) \quad (8.57)$$

$$= \frac{a}{s^2 + a^2} \quad (8.58)$$

So, option (A) is correct.

8.8 The input  $x(t)$  to a system is related to its output  $y(t)$  as

$$\frac{dy(t)}{dt} + y(t) = 3x(t-3)u(t-3)$$

Here  $u(t)$  represents a unit-step function.

The transfer function of this system is

(A)  $\frac{e^{-3s}}{s+3}$

(B)  $\frac{3e^{-3s}}{s+1}$

(C)  $\frac{3e^{-(s/3)}}{s+1}$

(D)  $\frac{e^{-(s/3)}}{s+3}$

(GATE IN 2022)

**Solution:**

$$\frac{dy(t)}{dt} + y(t) = 3x(t-3)u(t-3) \quad (8.59)$$

By applying Laplace Transform on both sides

$$x(t) \xleftrightarrow{\mathcal{L}} X(s) \quad (8.60)$$

$$x(t - t_o) \xleftrightarrow{\mathcal{L}} X(s)e^{-st_o} \quad (8.61)$$

$$sY(s) + Y(s) = 3X(s)e^{-3s} \quad (8.62)$$

$$Y(s)(s + 1) = 3X(s)e^{-3s} \quad (8.63)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{3e^{-3s}}{s + 1} \quad (Re(s) > 0) \quad (8.64)$$

$$H(j\omega) = \frac{3e^{-3j\omega}}{1 + j\omega} \quad (8.65)$$

$$= \frac{3(\cos 3\omega - j\sin 3\omega)}{1 + j\omega} \quad (8.66)$$

$$|H(j\omega)| = \frac{3}{\sqrt{1 + \omega^2}} \quad (8.67)$$

$$phase = \tan^{-1} \left( \frac{\omega \cos(3\omega) + \sin(3\omega)}{\omega \sin(3\omega) - \cos(3\omega)} \right) \quad (8.68)$$

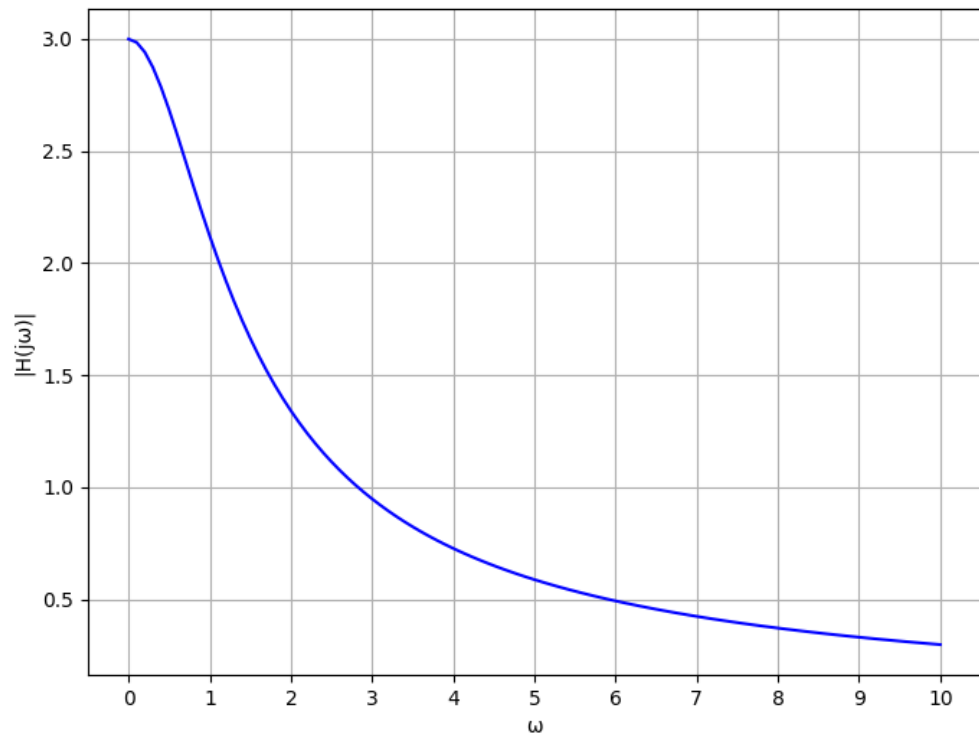


Figure 8.9: Plot for magnitude of transfer function

8.9 Let  $x_1(t) = e^{-t}u(t)$  and  $x_2(t) = u(t) - u(t-2)$ , where  $u(\cdot)$  denotes the unit step function. If  $y(t)$  denotes the convolution of  $x_1(t)$  and  $x_2(t)$ , then  $\lim_{t \rightarrow \infty} y(t) = \underline{\hspace{2cm}}$ .  
 (Rounded off to one decimal place)  
 (GATE EC 2022 )

**Solution:**

$$y(t) = x_1(t) * x_2(t) \quad (8.69)$$

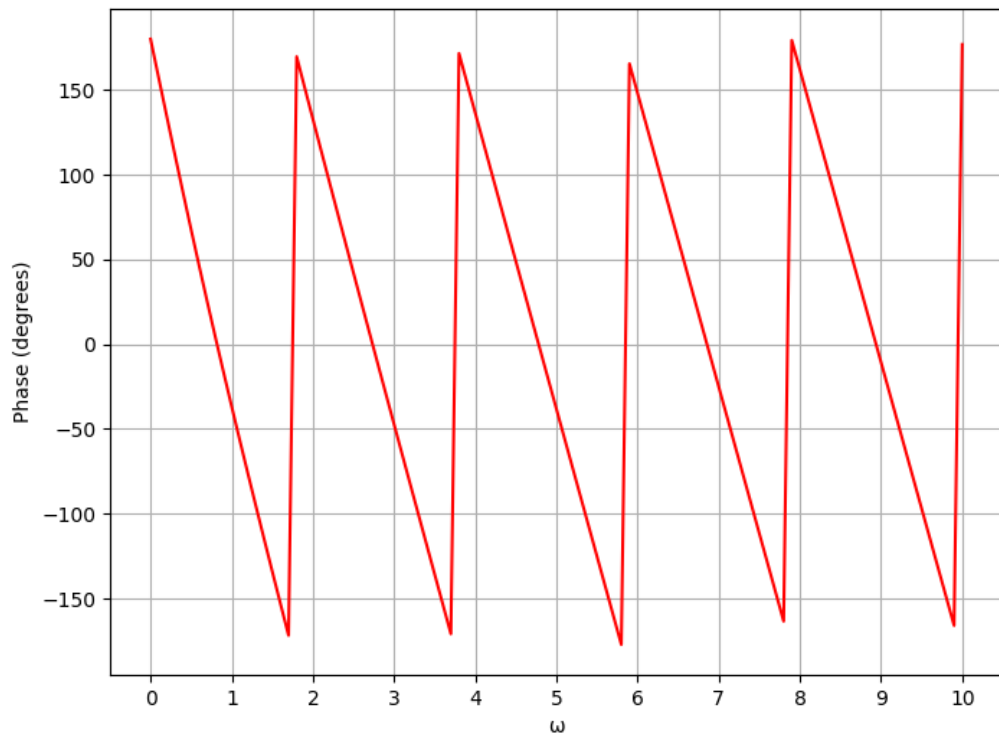


Figure 8.10: Plot for phase of transfer function

variable	value	description
$x_1(t)$	$e^{-t}u(t)$	given function 1
$x_2(t)$	$u(t) - u(t - 2)$	given function 2
$y(t)$	-	convolution of $x_1(t)$ and $x_2(t)$

Table 8.7: Table: Input Parameters

from Table 8.7

$$y(t) = e^{-t}u(t) * (u(t) - u(t - 2)) \quad (8.70)$$

By applying Laplace transform

$$Y(s) = X_1(s) \cdot X_2(s) \quad (8.71)$$

$$e^{-t}u(t) \xleftrightarrow{\mathcal{L}} \frac{1}{1+s}, \quad \operatorname{Re}(s) > -1 \quad (8.72)$$

$$u(t) - u(t-2) \xleftrightarrow{\mathcal{L}} \frac{1 - e^{-2s}}{s}, \quad \operatorname{Re}(s) > 0 \quad (8.73)$$

$$Y(s) = \left( \frac{1}{1+s} \right) \left( \frac{1 - e^{-2s}}{s} \right), \quad \operatorname{Re}(s) > 0 \quad (8.74)$$

$$= \frac{1 - e^{-2s}}{s(s+1)} \quad (8.75)$$

Final value theorem

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s) \quad (8.76)$$

$$(8.77)$$

Proof:

$$\mathcal{L}[x(t)] = X(s) = \int_0^{\infty} x(t) e^{-st} dt \quad (8.78)$$

$$\mathcal{L}\left[\frac{dx(t)}{dt}\right] = \int_0^{\infty} \frac{d}{dt} (x(t) e^{-st}) dt \quad (8.79)$$

$$= sX(s) - x(0^-) \quad (8.80)$$

$$\lim_{s \rightarrow 0} \left[ \int_0^{\infty} \frac{d}{dt} (x(t) e^{-st}) dt \right] = \lim_{s \rightarrow 0} [sX(s) - x(0^-)] \quad (8.81)$$

$$\int_0^{\infty} \frac{dx(t)}{dt} dt = \lim_{s \rightarrow 0} [sX(s) - x(0^-)] \quad (8.82)$$

$$[x(t)]_0^{\infty} = \lim_{s \rightarrow 0} [sX(s) - x(0^-)] \quad (8.83)$$

$$x(\infty) - x(0^-) = \lim_{s \rightarrow 0} [sX(s) - x(0^-)] \quad (8.84)$$

$$\implies x(\infty) = \lim_{s \rightarrow 0} sX(s) \quad (8.85)$$

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s) \quad (8.86)$$

By applying Final value theorem

$$\lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} sY(s) \quad (8.87)$$

$$= \lim_{s \rightarrow 0} s \left( \frac{1 - e^{-2s}}{s(s+1)} \right) \quad (8.88)$$

$$= \lim_{s \rightarrow 0} \left( \frac{1 - e^{-2s}}{(s+1)} \right) \quad (8.89)$$

$$= \left( \frac{1 - e^0}{0+1} \right) \quad (8.90)$$

$$\lim_{t \rightarrow \infty} y(t) = 0 \quad (8.91)$$



# Chapter 9

## Fourier transform

9.1 The Fourier transform  $X(j\omega)$  of the signal

$$x(t) = \frac{t}{(1+t^2)^2}$$
is \_\_\_\_\_.
GATE-2022-EC-15

- (A)  $\frac{\pi}{2j}\omega e^{-|\omega|}$
- (B)  $\frac{\pi}{2}\omega e^{-|\omega|}$
- (C)  $\frac{\pi}{2j}e^{-|\omega|}$
- (D)  $\frac{\pi}{2}e^{-|\omega|}$

**Solution:**

Symbol	Value	Description
$x(t)$	$\frac{t}{(1+t^2)^2}$	Signal
$X(\omega)$	$\int_{t=-\infty}^{\infty} x(t) e^{-j\omega t} dt$	Fourier transform of $x(t)$

Table 9.1: Variable description

The Fourier transform of the form  $x(t)=e^{-a|t|}$  is

$$x(t) \xleftrightarrow{\text{F.T.}} X(\omega) \quad (9.1)$$

$$X(\omega) = \frac{2a}{a^2 + \omega^2} \quad (9.2)$$

Consider,

$$x(t) = e^{-|t|} \quad (9.3)$$

$$X(\omega) = \frac{2}{1 + \omega^2} \quad (9.4)$$

By using differentiation property from (A.1.5),

$$tx(t) \xleftrightarrow{\text{F.T.}} j \frac{d}{d\omega} X(\omega) \quad (9.5)$$

$$tx(t) \xleftrightarrow{\text{F.T.}} j \left[ \frac{d}{d\omega} \left( \frac{2}{1 + \omega^2} \right) \right] \quad (9.6)$$

$$te^{-|t|} \xleftrightarrow{\text{F.T.}} \frac{-4j\omega}{(1 + \omega^2)^2} \quad (9.7)$$

Applying duality property from (A.2.3),

$$\frac{-4jt}{(1 + t^2)^2} \xleftrightarrow{\text{F.T.}} 2\pi(-\omega) e^{-|\omega|} \quad (9.8)$$

$$\frac{t}{(1 + t^2)^2} \xleftrightarrow{\text{F.T.}} \frac{-2\pi\omega e^{-|\omega|}}{-4j} \quad (9.9)$$

$$\frac{t}{(1 + t^2)^2} \xleftrightarrow{\text{F.T.}} \frac{\pi}{2j} \omega e^{-|\omega|} \quad (9.10)$$

9.2 For a vector  $\bar{x} = [x[0], x[1], \dots, x[7]]$ , the 8-point discrete Fourier transform (DFT) is denoted by  $\bar{X} = \text{DFT}(\bar{x}) = [X[0], X[1], \dots, X[7]]$ , where

$$X[k] = \sum_{n=0}^7 x[n] \exp \left( -j \frac{2\pi}{8} nk \right).$$

Here  $j = \sqrt{-1}$ . If  $\bar{x} = [1, 0, 0, 0, 2, 0, 0, 0]$  and  $\bar{y} = \text{DFT}(\text{DFT}(\bar{x}))$ , then the value of  $y[0]$  is.

GATE-2022-EC-55

**Solution:**

Parameter	Description	Value
$\bar{X}$	$\text{DFT}(\bar{x})$	—
$\bar{x}$	vector	$[1, 0, 0, 0, 2, 0, 0, 0]$
$\bar{y}$	$\text{DFT}(\text{DFT}(\bar{x}))$	—

Table 9.2: Given Parameters

DFT of  $\bar{x}$

$$X[k] = \sum_{n=0}^7 x[n] \exp \left( -j \frac{2\pi}{8} nk \right) \quad (9.11)$$

As the only non-zero values in  $x$  are  $x[0]$  and  $x[4]$ :

$$X[k] = x[0] + x[4] \exp(-j\pi k) \quad (9.12)$$

After substituting the values of  $k$  ranging from 0 to 7,

$$\bar{X} = \text{DFT}(\bar{x}) = [X[0], X[1], \dots, X[7]] \quad (9.13)$$

$$\bar{X} = [3, -1, 3, -1, 3, -1, 3, -1] \quad (9.14)$$

$$\bar{y} = \text{DFT}(\text{DFT}(\bar{x})) \quad (9.15)$$

$$\bar{y} = [3, -1, 3, -1, 3, -1, 3, -1] \quad (9.16)$$

$$y[0] = \sum_{n=0}^7 x[n] \quad (9.17)$$

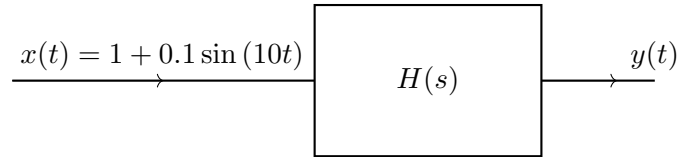
$$= x[0] + x[1] + \cdots + x[7] \quad (9.18)$$

$$= 3 - 1 + 3 - 1 + 3 - 1 + 3 - 1 = 8 \quad (9.19)$$

9.3 **Question:** An LTI system is shown in the figure where

$$H(s) = \frac{100}{s^2 + 0.1s + 10}$$

The steady state output of the system for an input  $x(t)$  is given by  $y(t) = a + b \sin(10t + \theta)$ . The values of ' $a$ ' and ' $b$ ' are



**Solution:**

Symbol	Value	Description
$x(t)$	$1 + 0.1 \sin(10t)$	Input Signal
$y(t)$	?	Output of the system
$H(s)$	$\frac{100}{s^2 + 0.1s + 10}$	Impulse Response

Table 9.3: Given Information

(a) **Theory:** If a sinusoidal input is given to a system, whose transfer function is known, the output can be calculated as follows

$$y(t) = h(t) * x(t) \quad (9.20)$$

$$Y(s) = H(s)X(s) \quad (9.21)$$

Let  $s = j\omega$

$$Y(j\omega) = H(j\omega)X(j\omega) \quad (9.22)$$

If  $\Phi$  is the phase of  $H(j\omega)$ ,

$$H(j\omega) = |H(j\omega)| e^{j\Phi(\omega)} \quad (9.23)$$

If  $x(t) = \cos(\omega_0 t)$ ,

$$X(j\omega) = \pi (\delta(\omega - \omega_0) + \delta(\omega + \omega_0)) \quad (9.24)$$

Now,

$$Y(j\omega) = (\delta(\omega - \omega_0) + \delta(\omega + \omega_0)) |H(j\omega)| e^{j\Phi(\omega)} \quad (9.25)$$

$$(9.26)$$

Since  $|H(j\omega)| \delta(\omega - \omega_0)$  is zero everywhere except at  $\omega_0$

$$Y(j\omega) = |H(j\omega_0)| e^{j\Phi(\omega_0)} \delta(\omega - \omega_0) \quad (9.27)$$

$$+ |H(-j\omega_0)| e^{j\Phi(-j\omega_0)} \delta(\omega + \omega_0) \quad (9.28)$$

As  $h(t)$  is real,

$$H(\omega) = H^*(-\omega)$$

$$\Phi(-\omega_0) = -\Phi(\omega_0)$$

Hence

$$Y(\omega) = |H(\omega_0)| \left( e^{j\Phi(\omega_0)} \delta(\omega - \omega_0) + e^{-j\Phi(\omega_0)} \delta(\omega + \omega_0) \right) \quad (9.29)$$

Taking Inverse Fourier Transform,

$$\delta(\omega - \omega_0) \xleftrightarrow{\mathcal{F}} \frac{1}{2} e^{j\omega_0 t} \quad (9.30)$$

$$\implies y(t) = |H(\omega_0)| \frac{1}{2} \left( e^{j(\omega_0 t + \Phi(\omega_0))} + e^{-j(\omega_0 t + \Phi(\omega_0))} \right) \quad (9.31)$$

$$\implies y(t) = |H(\omega_0)| \cos(\omega_0 t + \Phi(\omega_0)) \quad (9.32)$$

(b) The given input can be assumed to be a superposition of  $u(t)$  and  $0.1 \sin(\omega_0 t)u(t)$ .

$$\omega_0 = 0 \text{ and } \omega_0 = 10$$

for the constant input and the sinusoidal input respectively.

$$y(t) = |H(0)| + |H(10)| \sin(10t + \Phi(10)) \quad (9.33)$$

Here

$$H(\omega) = \frac{100}{(j\omega)^2 + 0.1(j\omega) + 10} \quad (9.34)$$

$$\implies H(\omega) = \frac{100}{10 - \omega^2 + j(0.1\omega)} \quad (9.35)$$

$$\implies |H(\omega)| = \frac{100}{\sqrt{(10 - \omega^2)^2 + (0.1\omega)^2}} \quad (9.36)$$

$$\therefore |H(0)| = 10 \text{ and } |H(10)| \approx 1 \quad (9.37)$$

The phase  $\Phi(\omega)$  is given by

$$\Phi(\omega) = \tan^{-1} \frac{0.1\omega}{\omega^2 - 10} \quad (9.38)$$

$$\implies \Phi(10) = \tan^{-1} \frac{1}{90} \quad (9.39)$$

Hence the output of the system

$$y(t) = 10 + \sin\left(10t + \tan^{-1} \frac{1}{90}\right) \quad (9.40)$$

Hence  $a = 10$  and  $b = 1$

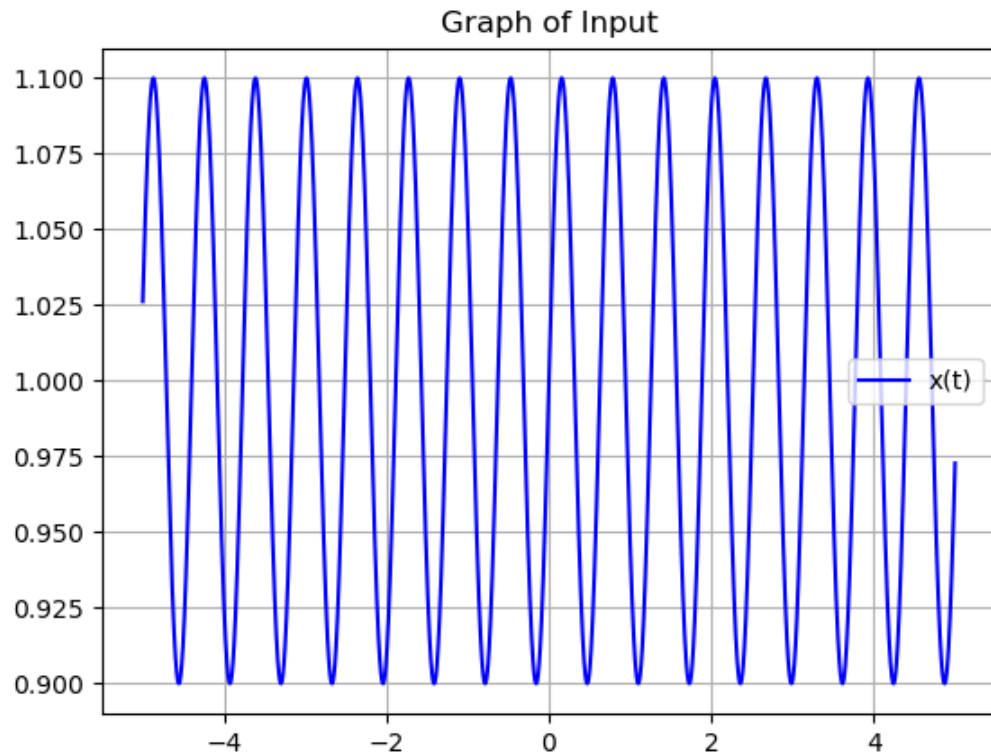


Figure 9.1: Input of the system,  $x(t)$

9.4 A periodic function  $f(x)$ , with period 2, is defined as



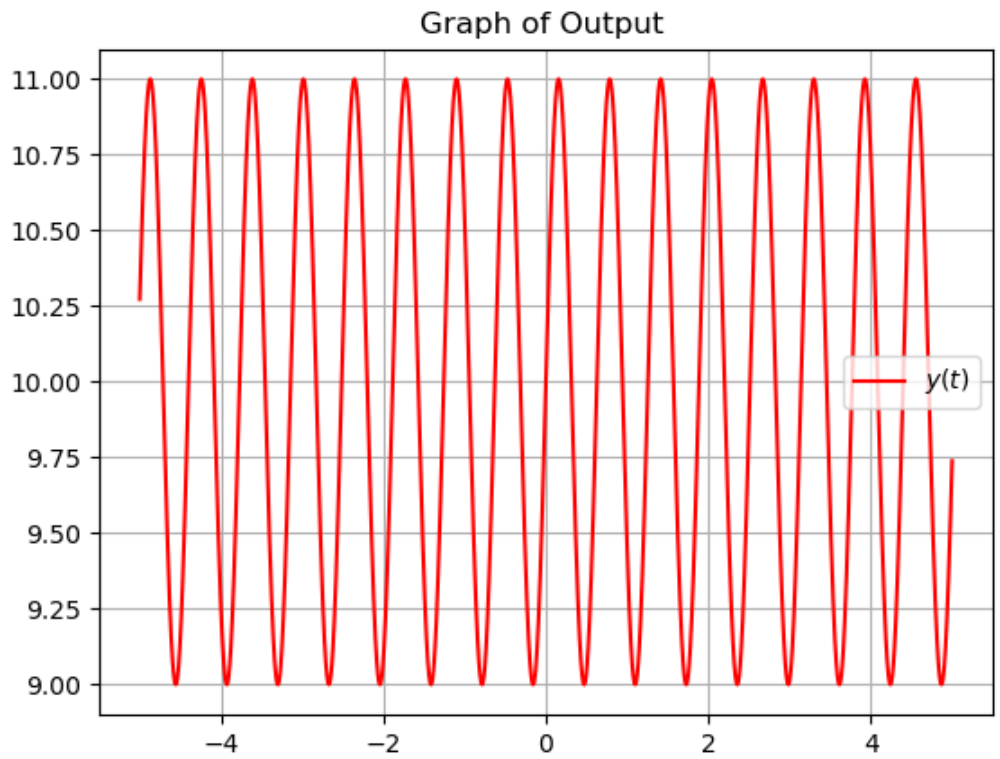


Figure 9.2: Output of the system,  $y(t)$

$$f(x) = \begin{cases} -1 - x & -1 \leq x < 0 \\ 1 - x & 0 < x \leq 1 \end{cases} \quad (9.41)$$

The Fourier series of this function contains

- A. Both  $\cos(n\pi x)$  and  $\sin(n\pi x)$  where  $n=1,2,3,\dots$
- B. Only  $\sin(n\pi x)$  where  $n=1,2,3,\dots$

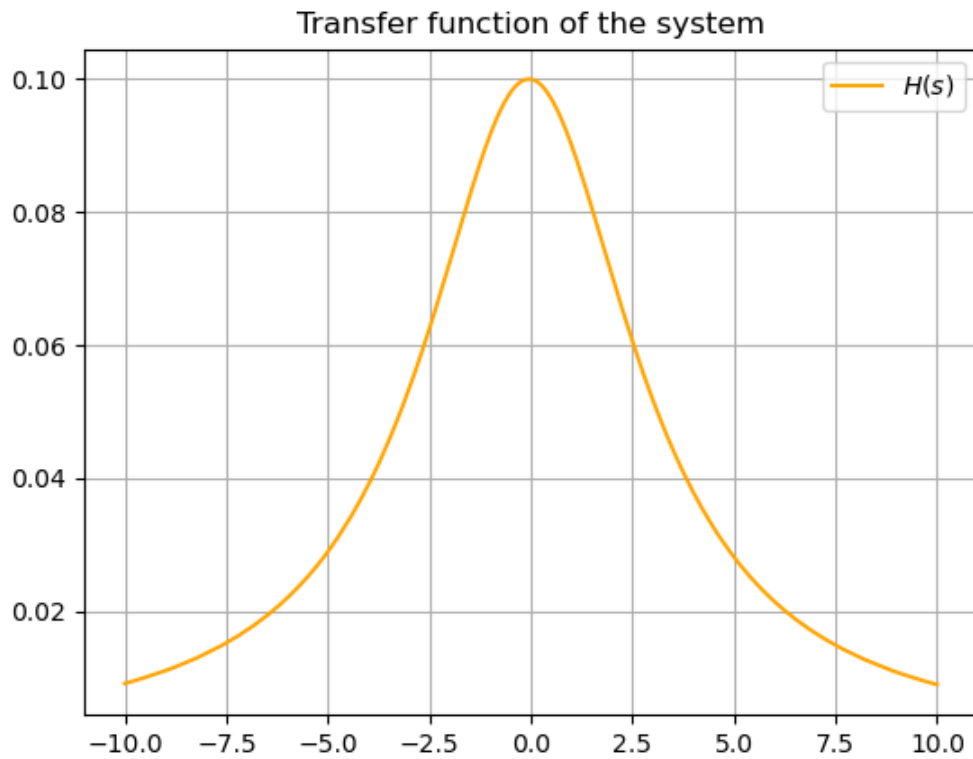


Figure 9.3: Transfer function of the system,  $H(s)$

C. Only  $\cos(n\pi x)$  where  $n=1,2,3\dots$

D. Only  $\cos(2n\pi x)$  where  $n=1,2,3\dots$

GATE IN 2022

**Solution:**

Parameter	Description
$f(x)$	Polynomial function
$2L$	Period of the Polynomial function
$c(n)$	Complex Fourier Coefficients
$a(0), a(n), b(n)$	Trigonometric Fourier Coefficients

Table 9.4: Input Parameters

The complex exponential Fourier Series of  $f(x)$  is,

$$f(x) = \sum_{n=-\infty}^{\infty} c(n) e^{jn\omega x} \quad (9.42)$$

$$\Rightarrow c(n) = \frac{1}{2L} \int_{-L}^L f(x) e^{-jn\omega x} dx \quad (9.43)$$

For  $n \neq 0$ ;

$$c(n) = \frac{1}{2} \int_{-1}^1 f(x) e^{-jn\omega x} dx \quad (9.44)$$

$$= \frac{1}{2} \left( \int_{-1}^0 (-1-x) e^{-jn\omega x} dx + \int_0^1 (+1-x) e^{-jn\omega x} dx \right) \quad (9.45)$$

$$= \frac{1}{2} \left( - \int_{-1}^0 e^{-jn\omega x} dx - \int_{-1}^1 x e^{-jn\omega x} dx + \int_0^1 e^{-jn\omega x} dx \right) \quad (9.46)$$

$$= \frac{1}{2} \left[ \frac{-1}{jn\omega} [- (1 - e^{+jn\omega}) + (e^{-jn\omega} - 1)] - \int_{-1}^1 x e^{-jn\omega x} dx \right] \quad (9.47)$$

$$= \frac{1}{2} \left[ \frac{-1}{jn\omega} [-2 + e^{+jn\omega} + e^{-jn\omega}] + \left( \frac{e^{-jn\omega x}}{jn\omega} \left[ x + \frac{1}{jn\omega} \right] \right)_{-1}^1 \right] \quad (9.48)$$

$$= \frac{-1}{jn\omega} [-1 + \cos(n\omega)] + \frac{1}{2(jn\omega)^2} [(e^{-jn\omega})(1 + jn\omega) - (e^{jn\omega})(-jn\omega + 1)] \quad (9.49)$$

$$\Rightarrow c(n) = \frac{-1}{(jn\omega)^2} [-jn\omega + j \sin(n\omega)] \quad (9.50)$$

For  $n = 0$ ;

$$c(0) = \frac{1}{2} \int_{-1}^1 f(x) dx \quad (9.51)$$

$$= \frac{1}{2} \left[ \int_{-1}^0 (-1-x) dx + \int_0^1 (1-x) dx \right] \quad (9.52)$$

$$= \frac{1}{2} \left[ \left( -x - \frac{x^2}{2} \right)_{-1}^0 + \left( x - \frac{x^2}{2} \right)_0^1 \right] \quad (9.53)$$

$$= \frac{1}{2} \left[ 0 - 1 + \frac{1}{2} + 1 - \frac{1}{2} - 0 \right] \quad (9.54)$$

$$\implies c(0) = 0 \quad (9.55)$$

The trigonometric Fourier Series of  $f(x)$  is,

$$f(x) = a(0) + \sum_{n=1}^{\infty} \{a(n) \cos(n\omega x) + b(n) \sin(n\omega x)\} \quad (9.56)$$

Finding the Fourier Coefficient  $a_0$ ,

$$a(0) = c(0) \quad (9.57)$$

$$\implies a(0) = 0 \quad (9.58)$$

Finding the Fourier Coefficients  $a(n)$ ,

$$a(n) = \frac{1}{L} \int_{-L}^L f(x) \cos(n\omega x) dx, n \geq 0 \quad (9.59)$$

$$= \frac{1}{L} \int_{-L}^L f(x) (e^{-jn\omega x} + e^{jn\omega x}) dx \quad (9.60)$$

$$\implies a(n) = c(n) + c(-n) \quad (9.61)$$

$$\implies a(n) = 0 \quad (9.62)$$

Finding the Fourier Coefficients  $b(n)$ ,

$$b_n = \frac{1}{L} \int_{-L}^L f(x) \sin(n\omega x) dx, n \geq 0 \quad (9.63)$$

$$= \frac{1}{L} \int_{-L}^L f(x) j (e^{-jn\omega x} - e^{jn\omega x}) dx \quad (9.64)$$

$$\implies b(n) = j (c(n) - c(-n)) \quad (9.65)$$

$$\implies b(n) = \frac{-2}{(n\omega)^2} [-n\omega + \sin(n\omega)] \quad (9.66)$$

$\implies$  The trigonometric Fourier Series of  $f(x)$  is,

$$f(x) = \sum_{n=1}^{\infty} \{0 + 0 + b(n) \sin(n\omega x)\} \quad (9.67)$$

$$f(x) = \sum_{n=1}^{\infty} \left\{ \frac{-2}{(n\omega)^2} [-n\omega + \sin(n\omega)] \sin(n\omega x) \right\} \quad (9.68)$$

$$f(x) = \sum_{n=1}^{\infty} \left\{ \frac{-2}{(n\pi)^2} [-n\pi + \sin(n\pi)] \sin(n\pi x) \right\} \quad (9.69)$$

$$f(x) = \sum_{n=1}^{\infty} \left\{ \frac{2}{n\pi} \sin(n\pi x) \right\} \quad (9.70)$$

$\therefore$  The Fourier series of this function contains only  $\sin(n\pi x)$  where  $n=1,2,3\dots$

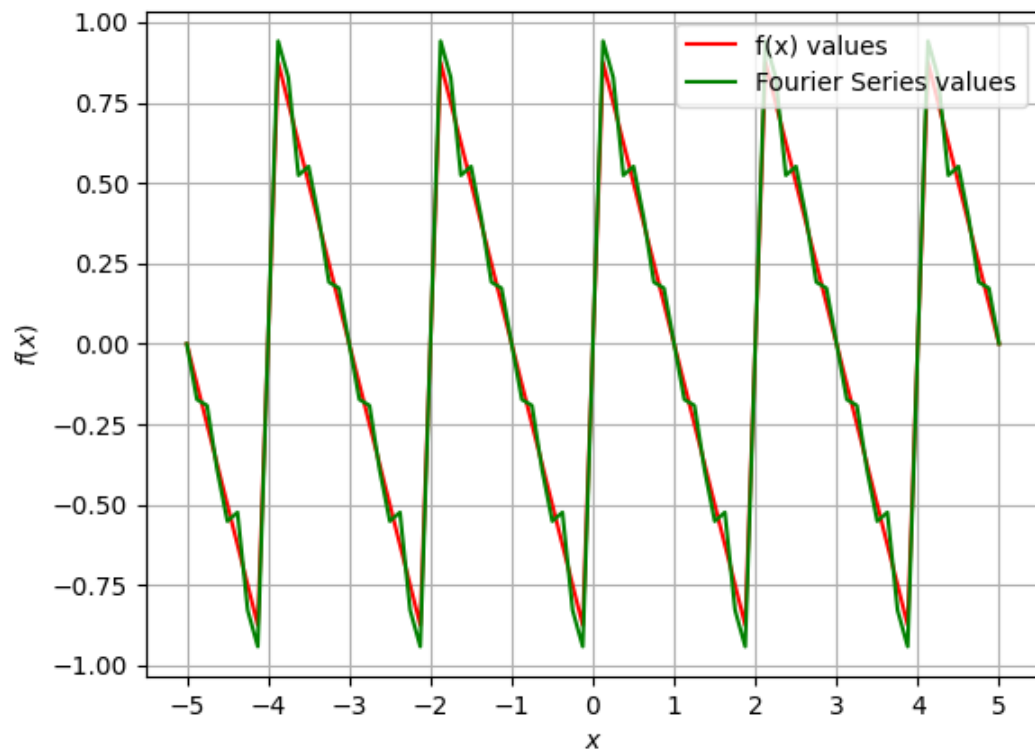


Figure 9.4:

## Appendix A

# Fourier transform

A.1 The Differentiation in frequency domain is as follows

Let  $x(t)$  be a signal such that,

$$x(t) \xleftrightarrow{\text{F.T.}} X(\omega) \quad (\text{A.1.1})$$

$$X(\omega) = \int_{t=-\infty}^{\infty} x(t) e^{-j\omega t} dt \quad (\text{A.1.2})$$

$$\frac{d}{d\omega} X(\omega) = \int_{t=-\infty}^{\infty} x(t) (-jt) e^{-j\omega t} dt \quad (\text{A.1.3})$$

$$j \frac{d}{d\omega} X(\omega) = \int_{t=-\infty}^{\infty} tx(t) e^{-j\omega t} dt \quad (\text{A.1.4})$$

$$tx(t) \xleftrightarrow{\text{F.T.}} j \frac{d}{d\omega} X(\omega) \quad (\text{A.1.5})$$

A.2 The duality property is as follows

From inverse Fourier transform we get,

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega \quad (\text{A.2.1})$$

Replacing  $t$  by  $-t$  and multiplying  $2\pi$  on both sides we get,

$$2\pi x(-t) = \int_{-\infty}^{\infty} X(\omega) e^{-j\omega t} d\omega \quad (\text{A.2.2})$$

$$X(t) \xleftrightarrow{\text{F.T.}} 2\pi x(-\omega) \quad (\text{A.2.3})$$