

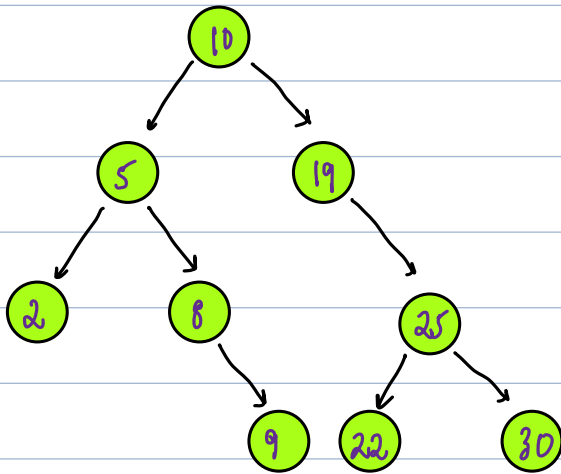
Today's Content

1. Trim BST
2. Check if given BT is BST or not

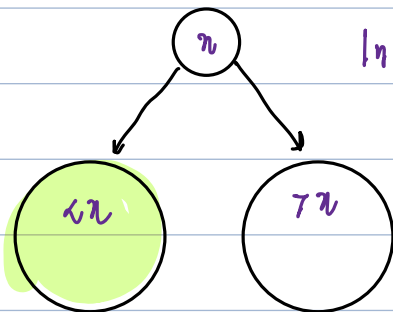
Given a BT, check if it's a BST or not.

Note: Assume all nodes are distinct

Ex 1:



Idea 1:



InOrder: L D R

$<n < n < n$

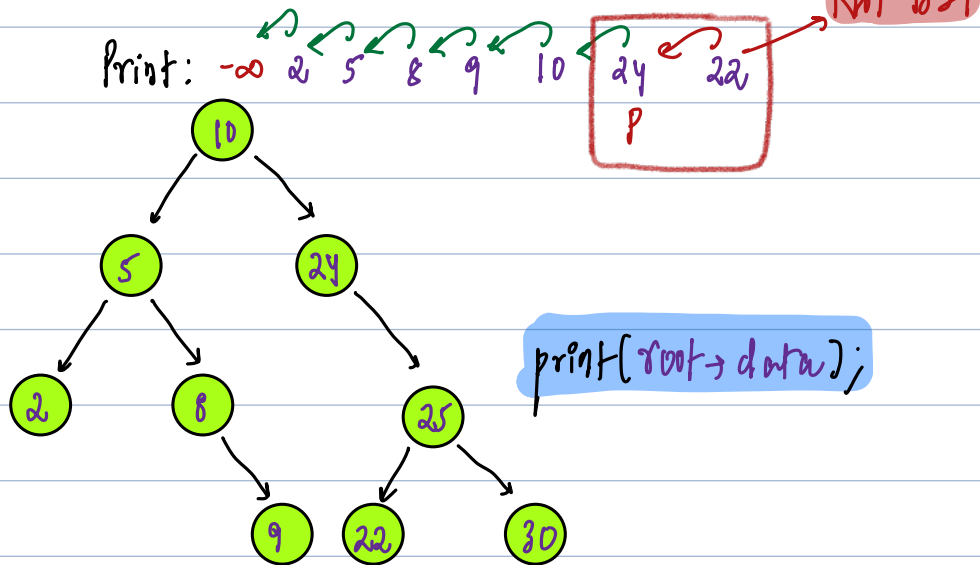
properly BST: InOrder of BST is increasing order

Idea 1: Store inOrder in an array & check if array is in increasing order.

TC: $O(N + N) = O(N)$ SC: $O(N)$

↳ #storing in an array.

Idea2:



bool isBST = true; \rightarrow or global

int p = $-\infty$;

pass by reference

void Inorder(Node* root, bool &isBST, int &p) { // TC: $O(N)$ SC: $O(H)$

if (root == nullptr) { return; }

Inorder(root->left, isBST, p);

if (p > root->data) {

isBST = false;

p = root->data;

Inorder(root->right, isBST, p);

bool isBST(Node* root) {

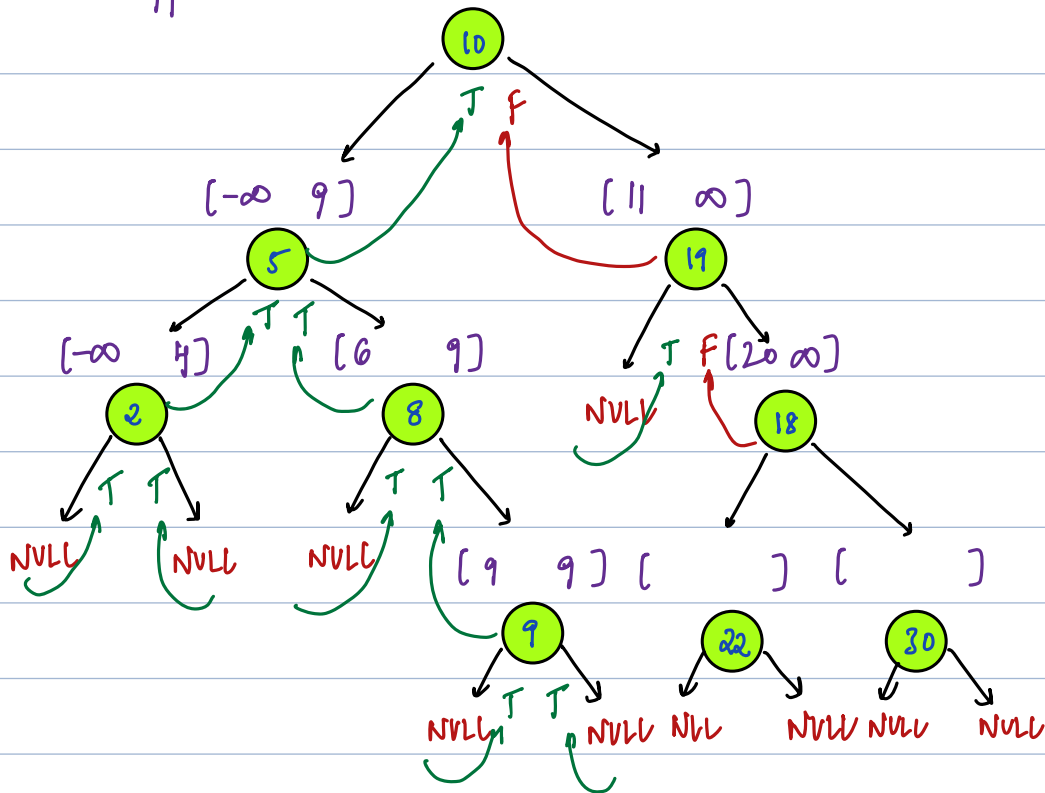
isBST = true;

p = $-\infty$;

Inorder(root, isBST, p);

return isBST;

IsBST: Approach 2 $[-\infty \infty]$



Ans: Given root node & range check if entire BST is in range or not.

bool IsBST(Node *root, int l, int h) {

if (root == NULL) {
return true;

return

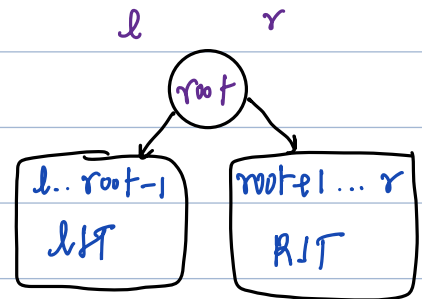
{
(l <= root->data) && (root->data <= r)
&& IsBST(root->left, l, root->data-1)
&& IsBST(root->right, root->data+1, r)
}

}

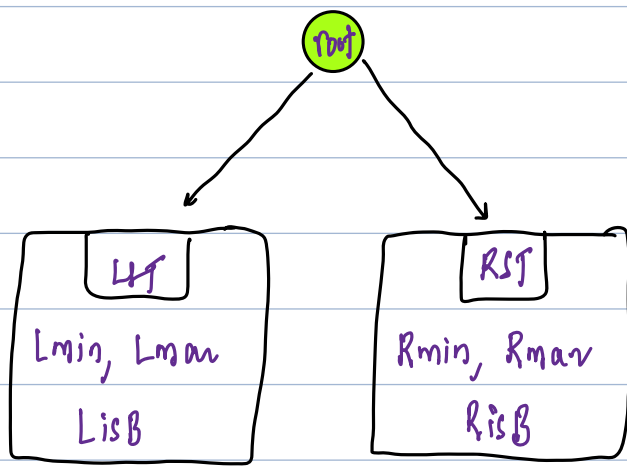
boolean solve(Node root) {

return IsBST(root, -∞, ∞);

}



Idea4:



```
vector<int> isBST(Node *root) {
```

```
    if (root == null) {
```

```
        vector<int> ans(3, 0);
```

```
        ans[0] = 1; ans[1] = -∞; # Min ans[2] = ∞; # Max
```

```
    } return ans;
```

```
    vector<int> l = isBST(root->left); # l: isB min max
```

```
    vector<int> r = isBST(root->right); # r: isB min max
```

```
    vector<int> ans(3, 0);
```

```
    if ( (l[0] == 1) && (r[0] == 1) && (root->data > l[2]) && (root->data < r[1]) ) {
```

```
        ans[0] = 1;
```

```
        ans[1] = min(l[1], r[1], root->data); # Note we compare with root->data,
```

```
        ans[2] = max(l[2], r[2], root->data); because if both left & right are
```

```
        return ans;
```

null, then data should be compared with root

```
bool solve(Node *root) {
```

```
    vector<int> ans = isBST(root);
```

```
    return ans[0] == 1;
```

```
}
```

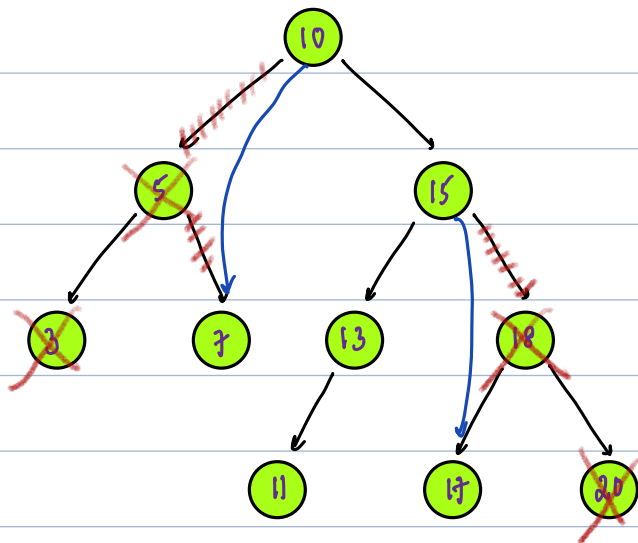
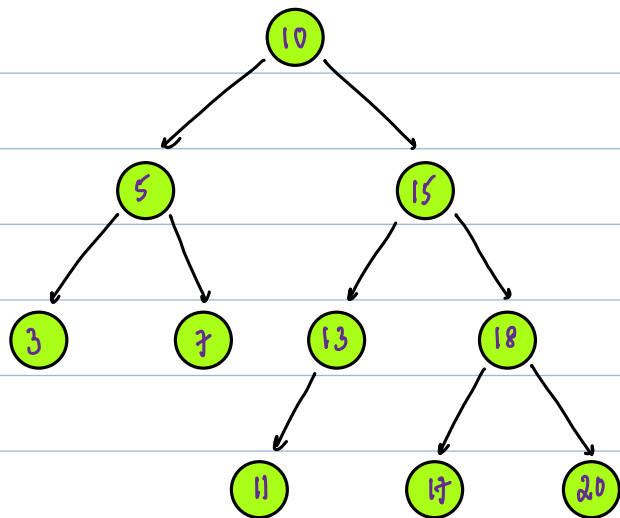
Trim BST:

Given a BST & low & high.

Delete all nodes not in range & make sure relative order maintained.

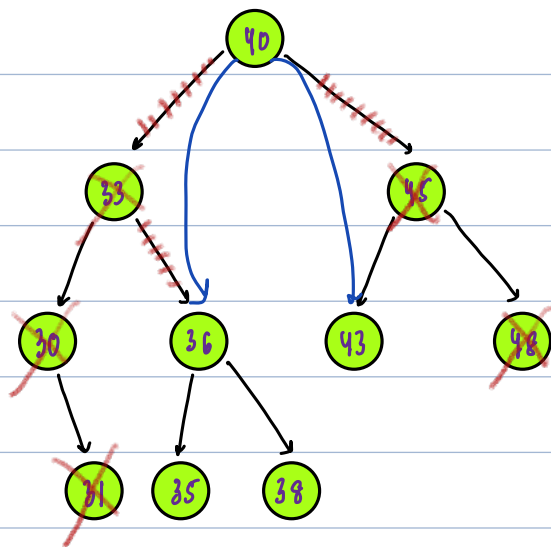
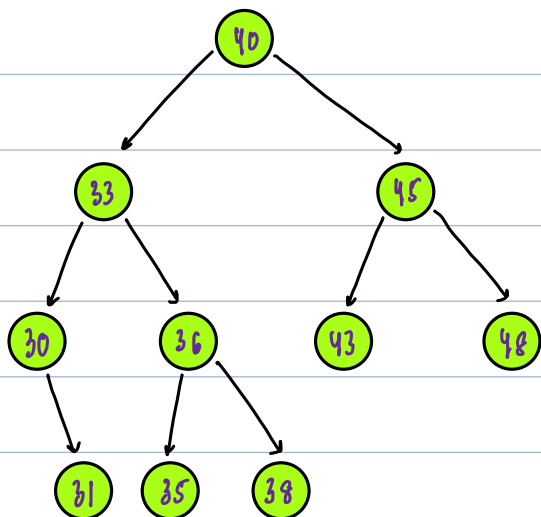
ex1

{6 - 17}

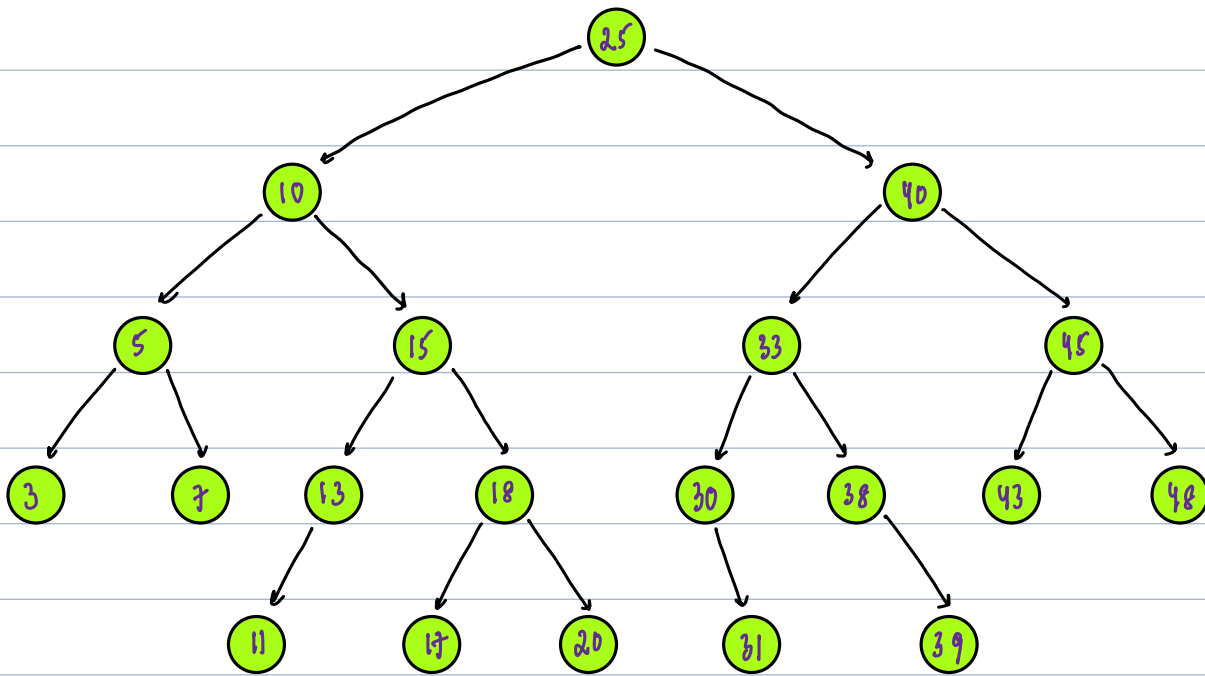


ex2

{35 - 44}



{12-37}



Ass: Given root q & q , delete all nodes not in range q return root of BST

Node Trim(Node h, int l, int r) {

if (root == null) { return null; }

root->left = Trim(root->left, l, r);

root->right = Trim(root->right, l, r);

if (l <= root->data & root->data <= r) {

return root;

else if (root->data < l) {

return root->right;

else {

return root->left;

}

}

