# Some linear algebra background

**CSE 250B** 

#### Matrix-vector notation

Vector  $x \in \mathbb{R}^p$  and matrix  $M \in \mathbb{R}^{r \times p}$ :

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_r \end{pmatrix}, \quad M = \begin{pmatrix} M_{11} & M_{12} & \cdots & M_{1p} \\ M_{21} & M_{22} & \cdots & M_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ M_{r1} & M_{r2} & \cdots & M_{rp} \end{pmatrix}.$$

#### Matrix-vector notation

Vector  $x \in \mathbb{R}^p$  and matrix  $M \in \mathbb{R}^{r \times p}$ :

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{pmatrix}, \quad M = \begin{pmatrix} M_{11} & M_{12} & \cdots & M_{1p} \\ M_{21} & M_{22} & \cdots & M_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ M_{r1} & M_{r2} & \cdots & M_{rp} \end{pmatrix}.$$

Transpose  $x^T$  and  $M^T \in \mathbb{R}^{p \times r}$ :

$$x^{T} = \begin{pmatrix} x_{1} & x_{2} & \cdots & x_{p} \end{pmatrix}, \quad M^{T} = \begin{pmatrix} M_{11} & \cdots & M_{r1} \\ M_{12} & \cdots & M_{r2} \\ M_{13} & \cdots & M_{r3} \\ \vdots & \ddots & \vdots \\ M_{1} & \cdots & M_{n} \end{pmatrix}.$$

#### **Matrix-vector notation**

Vector  $x \in \mathbb{R}^p$  and matrix  $M \in \mathbb{R}^{r \times p}$ :

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{pmatrix}, \quad M = \begin{pmatrix} M_{11} & M_{12} & \cdots & M_{1p} \\ M_{21} & M_{22} & \cdots & M_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ M_{r1} & M_{r2} & \cdots & M_{rp} \end{pmatrix}.$$

Transpose  $x^T$  and  $M^T \in \mathbb{R}^{p \times r}$ :

$$x^{T} = \begin{pmatrix} x_{1} & x_{2} & \cdots & x_{p} \end{pmatrix}, \quad M^{T} = \begin{pmatrix} M_{11} & \cdots & M_{r1} \\ M_{12} & \cdots & M_{r2} \\ M_{13} & \cdots & M_{r3} \\ \vdots & \ddots & \vdots \\ M_{1p} & \cdots & M_{rp} \end{pmatrix}.$$

Properties of transpose:  $(A^T)^T = A$  and  $(AB)^T = B^T A^T$ .

Dot product of vectors  $x, y \in \mathbb{R}^p$ :

$$x \cdot y = x^T y = x_1 y_1 + \dots + x_p y_p.$$

Dot product of vectors  $x, y \in \mathbb{R}^p$ :

$$x \cdot y = x^T y = x_1 y_1 + \dots + x_p y_p.$$

This tells us the angle between x and y:



Dot product of vectors  $x, y \in \mathbb{R}^p$ :

$$x \cdot y = x^T y = x_1 y_1 + \dots + x_p y_p.$$

This tells us the angle between x and y:



Easiest when x, y are unit vectors (length 1): then  $\cos \theta = x \cdot y$ .

Dot product of vectors  $x, y \in \mathbb{R}^p$ :

$$x \cdot y = x^T y = x_1 y_1 + \dots + x_p y_p.$$

This tells us the angle between x and y:



Easiest when x, y are *unit vectors* (length 1): then  $\cos \theta = x \cdot y$ .

x is orthogonal (at right angles) to y iff  $x \cdot y = ??$ 

Dot product of vectors  $x, y \in \mathbb{R}^p$ :

$$x \cdot y = x^T y = x_1 y_1 + \dots + x_p y_p.$$

This tells us the angle between x and y:



Easiest when x, y are unit vectors (length 1): then  $\cos \theta = x \cdot y$ .

x is orthogonal (at right angles) to y iff  $x \cdot y = ??$ What is  $x \cdot x$ ?

#### Matrix-vector products

If  $M \in \mathbb{R}^{r \times p}$  and  $x \in \mathbb{R}^p$  then

$$Mx = \begin{pmatrix} \longleftarrow & M_1 & \longrightarrow \\ \longleftarrow & M_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & M_r & \longrightarrow \end{pmatrix} \begin{pmatrix} | \\ \\ \\ | \\ \end{pmatrix} = \begin{pmatrix} M_1 \cdot x \\ M_2 \cdot x \\ \vdots \\ M_r \cdot x \end{pmatrix}$$

#### Matrix-vector products

If  $M \in \mathbb{R}^{r \times p}$  and  $x \in \mathbb{R}^p$  then

$$Mx = \begin{pmatrix} \longleftarrow & M_1 & \longrightarrow \\ \longleftarrow & M_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & M_r & \longrightarrow \end{pmatrix} \begin{pmatrix} | \\ | \\ x \\ | \end{pmatrix} = \begin{pmatrix} M_1 \cdot x \\ M_2 \cdot x \\ \vdots \\ M_r \cdot x \end{pmatrix}$$

This mapping  $x \mapsto Mx$  is a **linear function** from  $\mathbb{R}^p$  to  $\mathbb{R}^r$ :

$$M(x+x')=Mx+Mx'.$$

#### Matrix-vector products

If  $M \in \mathbb{R}^{r \times p}$  and  $x \in \mathbb{R}^p$  then

$$Mx = \begin{pmatrix} \longleftarrow & M_1 & \longrightarrow \\ \longleftarrow & M_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & M_r & \longrightarrow \end{pmatrix} \begin{pmatrix} | \\ | \\ x \\ | \\ \end{pmatrix} = \begin{pmatrix} M_1 \cdot x \\ M_2 \cdot x \\ \vdots \\ M_r \cdot x \end{pmatrix}$$

This mapping  $x \mapsto Mx$  is a **linear function** from  $\mathbb{R}^p$  to  $\mathbb{R}^r$ :

$$M(x+x')=Mx+Mx'.$$

If  $M \in \mathbb{R}^{p \times p}$  and  $x \in \mathbb{R}^p$  then  $x \mapsto x^T M x$  is a **quadratic function** from  $\mathbb{R}^p$  to  $\mathbb{R}$ :

$$x^T M x = \sum_{i,j=1}^p M_{ij} x_i x_j.$$

① Write the linear function  $f(x_1, x_2) = 3x_1 + 2x_2$  using vector notation (here,  $x_1, x_2 \in \mathbb{R}$ ).

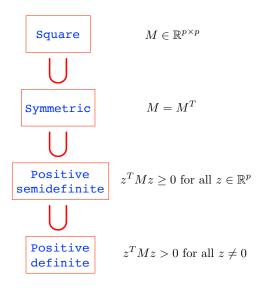
- ① Write the linear function  $f(x_1, x_2) = 3x_1 + 2x_2$  using vector notation (here,  $x_1, x_2 \in \mathbb{R}$ ).
- **2** Write the quadratic function  $f(x_1, x_2) = x_1^2 + 2x_1x_2 + 3x_2^2$  using matrices and vectors.

- ① Write the linear function  $f(x_1, x_2) = 3x_1 + 2x_2$  using vector notation (here,  $x_1, x_2 \in \mathbb{R}$ ).
- **2** Write the quadratic function  $f(x_1, x_2) = x_1^2 + 2x_1x_2 + 3x_2^2$  using matrices and vectors.
- **3** A linear function from  $\mathbb{R}^3$  to  $\mathbb{R}^3$  is given by the matrix

$$M = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{pmatrix}.$$

As x varies, does Mx fill up all of  $\mathbb{R}^3$ ?

# A hierarchy of square matrices



- 1 PSD or not?
  - $\bullet \ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

- 1 PSD or not?
  - $\bullet \ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$
  - $\bullet \ \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$

- 1 PSD or not?
  - $\bullet \ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$
  - $\bullet \ \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$
- 2 A diagonal matrix is PSD if and only if ???

- PSD or not?
  - $\bullet \ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$
  - $\bullet \ \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$
- 2 A diagonal matrix is PSD if and only if ???
- **3** Show: If M, N are of the same size and PSD and M + N is PSD.

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Quick check: say  $U \in \mathbb{R}^{r \times p}$  and  $M = UU^T$ .

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Quick check: say  $U \in \mathbb{R}^{r \times p}$  and  $M = UU^T$ .

**1** *M* is square.

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Quick check: say  $U \in \mathbb{R}^{r \times p}$  and  $M = UU^T$ .

- **1** *M* is square.
- **2** *M* is symmetric.

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Quick check: say  $U \in \mathbb{R}^{r \times p}$  and  $M = UU^T$ .

- 1 M is square.
- 2 *M* is symmetric.
- **3** Pick any  $z \in \mathbb{R}^r$ . Then

$$z^{T}Mz = z^{T}UU^{T}z = (z^{T}U)(U^{T}z)$$
  
=  $(U^{T}z)^{T}(U^{T}z) = ||U^{T}z||^{2} \ge 0.$ 

Useful fact: a matrix M is PSD iff it can be written in the form  $UU^T$  for some matrix U.

Quick check: say  $U \in \mathbb{R}^{r \times p}$  and  $M = UU^T$ .

- **1** *M* is square.
- 2 *M* is symmetric.
- **3** Pick any  $z \in \mathbb{R}^r$ . Then

$$z^{T}Mz = z^{T}UU^{T}z = (z^{T}U)(U^{T}z)$$
  
=  $(U^{T}z)^{T}(U^{T}z) = ||U^{T}z||^{2} \ge 0.$ 

Another useful fact: any covariance matrix is PSD. (Same argument, along with linearity of expectation.)

**1** Any matrix M defines a linear transformation  $x \mapsto Mx$ .

- **1** Any matrix M defines a linear transformation  $x \mapsto Mx$ .
- **2** We'd like to understand the nature of these transformations. The easiest case is when *M* is **diagonal**:

$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_{M} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{X} = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

In this case, M simply scales each coordinate separately.

- **1** Any matrix M defines a linear transformation  $x \mapsto Mx$ .
- **2** We'd like to understand the nature of these transformations. The easiest case is when *M* is **diagonal**:

$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_{M} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{X} = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

In this case, M simply scales each coordinate separately.

What about more general matrices that are symmetric but not necessarily diagonal? They also just scale coordinates separately, but in a different coordinate system.

- **1** Any matrix M defines a linear transformation  $x \mapsto Mx$ .
- **2** We'd like to understand the nature of these transformations. The easiest case is when *M* is **diagonal**:

$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_{M} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{X} = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

In this case, M simply scales each coordinate separately.

What about more general matrices that are symmetric but not necessarily diagonal? They also just scale coordinates separately, but in a different coordinate system.

Let M be a  $p \times p$  matrix.

We say  $u \in \mathbb{R}^p$  is an **eigenvector** if M maps u onto the same direction, that is,

$$Mu = \lambda u$$

for some scaling constant  $\lambda$ . This  $\lambda$  is the **eigenvalue** associated with u.

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Answer: Eigenvectors  $e_1$ ,  $e_2$ ,  $e_3$ , with corresponding eigenvalues 2, -1, 10.

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Answer: Eigenvectors  $e_1$ ,  $e_2$ ,  $e_3$ , with corresponding eigenvalues 2, -1, 10.

Question: Matrix  $M = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$  has eigenvectors

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}.$$

What are the corresponding eigenvalues?

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Answer: Eigenvectors  $e_1$ ,  $e_2$ ,  $e_3$ , with corresponding eigenvalues 2, -1, 10.

Question: Matrix  $M = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$  has eigenvectors

$$u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}.$$

What are the corresponding eigenvalues?

Answer:  $\lambda_1 = 4$  and  $\lambda_2 = 2$ .

We say u is an eigenvector of M, with eigenvalue  $\lambda$ , if  $Mu = \lambda u$ .

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Answer: Eigenvectors  $e_1$ ,  $e_2$ ,  $e_3$ , with corresponding eigenvalues 2, -1, 10.

Question: Matrix  $M = \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$  has eigenvectors

$$u_1=rac{1}{\sqrt{2}}\begin{pmatrix}1\\1\end{pmatrix},\quad u_2=rac{1}{\sqrt{2}}\begin{pmatrix}-1\\1\end{pmatrix}.$$

What are the corresponding eigenvalues?

Answer:  $\lambda_1 = 4$  and  $\lambda_2 = 2$ .

In both cases the eigenvectors form an orthonormal basis.

#### **Eigenvectors of a real symmetric matrix**

**Theorem.** Let M be any real symmetric  $p \times p$  matrix. Then M has

- p eigenvalues  $\lambda_1, \ldots, \lambda_p$
- corresponding eigenvectors  $u_1, \ldots, u_p \in \mathbb{R}^p$  that are **orthonormal**:

$$u_i \cdot u_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

#### Eigenvectors of a real symmetric matrix

**Theorem.** Let M be any real symmetric  $p \times p$  matrix. Then M has

- p eigenvalues  $\lambda_1, \ldots, \lambda_p$
- corresponding eigenvectors  $u_1, \ldots, u_p \in \mathbb{R}^p$  that are **orthonormal**:

$$u_i \cdot u_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

We can think of  $u_1, \ldots, u_p$  as being the axes of the natural coordinate system for understanding M.

#### Eigenvectors of a real symmetric matrix

**Theorem.** Let M be any real symmetric  $p \times p$  matrix. Then M has

- p eigenvalues  $\lambda_1, \ldots, \lambda_p$
- corresponding eigenvectors  $u_1, \ldots, u_p \in \mathbb{R}^p$  that are **orthonormal**:

$$u_i \cdot u_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

We can think of  $u_1, \ldots, u_p$  as being the axes of the natural coordinate system for understanding M.

**Theorem.** Let M be any real symmetric  $p \times p$  matrix, and let  $\lambda_1, \ldots, \lambda_p$  be its eigenvalues. Then:

- *M* is positive semidefinite iff every  $\lambda_i$  is  $\geq 0$ .
- M is positive definite iff every  $\lambda$  is > 0.