```
# import keras
# from keras.datasets import cifar10
# from keras.models import Model, Sequential
# from keras.layers import Dense, Dropout, Flatten, Input, AveragePooling2D, merge, Activa
# from keras.layers import Conv2D, MaxPooling2D, BatchNormalization
# from keras.layers import Concatenate
# from keras.optimizers import Adam
# Load necessary libraries
from tensorflow.keras import models, layers
from tensorflow.keras.models import Model
from tensorflow.keras.layers import BatchNormalization, Activation, Flatten
from tensorflow.keras.optimizers import Adam
from numpy import expand_dims
from keras.preprocessing.image import load_img
from keras.preprocessing.image import img_to_array
from keras.preprocessing.image import ImageDataGenerator
from keras import regularizers
from matplotlib import pyplot
# this part will prevent tensorflow to allocate all the avaliable GPU Memory
# backend
import tensorflow as tf
# Hyperparameters
batch_size = 128
num_classes = 10
epochs = 10
1 = 40
num filter = 12
compression = 0.5
dropout_rate = 0.2
# Load CIFAR10 Data
(X_train, y_train), (X_test, y_test) = tf.keras.datasets.cifar10.load_data()
img_height, img_width, channel = X_train.shape[1],X_train.shape[2],X_train.shape[3]
# convert to one hot encoing
y_train = tf.keras.utils.to_categorical(y_train, num_classes)
y test = tf.keras.utils.to categorical(y test, num classes)
    Downloading data from <a href="https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz">https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz</a>
     X_train.shape
     (50000, 32, 32, 3)
X test.shape
```

```
(10000, 32, 32, 3)
```

```
# Dense Block
def denseblock(input, num_filter = 12, dropout_rate = 0.2):
    global compression
    temp = input
    for _ in range(1):
        BatchNorm = layers.BatchNormalization()(temp)
        relu = layers.Activation('relu')(BatchNorm)
        Conv2D_3_3 = layers.Conv2D(int(num_filter*compression), (3,3), use_bias=False ,pad
        if dropout_rate>0:
            Conv2D 3 3 = layers.Dropout(dropout rate)(Conv2D 3 3)
        concat = layers.Concatenate(axis=-1)([temp,Conv2D_3_3])
        temp = concat
    return temp
## transition Blosck
def transition(input, num_filter = 12, dropout_rate = 0.2):
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
    Conv2D_BottleNeck = layers.Conv2D(int(num_filter*compression), (1,1), use_bias=False ,
    if dropout_rate>0:
         Conv2D_BottleNeck = layers.Dropout(dropout_rate)(Conv2D_BottleNeck)
    avg = layers.AveragePooling2D(pool_size=(2,2))(Conv2D_BottleNeck)
    return avg
#output layer
def output_layer(input):
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
    AvgPooling = layers.AveragePooling2D(pool size=(2,2))(relu)
    flat = layers.Flatten()(AvgPooling)
    output = layers.Dense(num_classes, activation='softmax')(flat)
    return output
num filter = 12
dropout rate = 0.2
1 = 12
input = layers.Input(shape=(img_height, img_width, channel,))
First_Conv2D = layers.Conv2D(num_filter, (3,3), use_bias=False ,padding='same')(input)
First Block = denseblock(First Conv2D, num filter, dropout rate)
First_Transition = transition(First_Block, num_filter, dropout_rate)
Second Block = denseblock(First Transition, num filter, dropout rate)
Second Transition = transition(Second Block, num filter, dropout rate)
Third Block = denseblock(Second Transition, num filter, dropout rate)
Third Transition = transition(Third Block, num filter, dropout rate)
```

Last_Block = denseblock(Third_Transition, num_filter, dropout_rate)
output = output_layer(Last_Block)

#https://arxiv.org/pdf/1608.06993.pdf
from IPython.display import IFrame, YouTubeVideo
YouTubeVideo(id='-W6y8xnd--U', width=600)

Densely Connected Convolutional Networks



model = Model(inputs=[input], outputs=[output])
model.summary()

conv2d_48 (Conv2D)	(None, 4, 4, 6)	2916	['activation_47[0 ^
dropout_47 (Dropout)	(None, 4, 4, 6)	0	['conv2d_48[0][0]
concatenate_44 (Concatenate)	(None, 4, 4, 60)	0	['concatenate_43[0 'dropout_47[0][0
<pre>batch_normalization_48 (BatchN ormalization)</pre>	(None, 4, 4, 60)	240	['concatenate_44[(
activation_48 (Activation)	(None, 4, 4, 60)	0	['batch_normaliza [.]
conv2d_49 (Conv2D)	(None, 4, 4, 6)	3240	['activation_48[0
dropout_48 (Dropout)	(None, 4, 4, 6)	0	['conv2d_49[0][0]
concatenate_45 (Concatenate)	(None, 4, 4, 66)	0	['concatenate_44[0 'dropout_48[0][0
<pre>batch_normalization_49 (BatchN ormalization)</pre>	(None, 4, 4, 66)	264	['concatenate_45[(
activation_49 (Activation)	(None, 4, 4, 66)	0	['batch_normaliza
conv2d_50 (Conv2D)	(None, 4, 4, 6)	3564	['activation_49[0
dropout_49 (Dropout)	(None, 4, 4, 6)	0	['conv2d_50[0][0]

```
concatenate 46 (Concatenate)
                              (None, 4, 4, 72)
                                                             ['concatenate 45[(
                                                              'dropout 49[0][0
 batch normalization 50 (BatchN (None, 4, 4, 72)
                                                 288
                                                             ['concatenate 46[(
ormalization)
activation_50 (Activation)
                              (None, 4, 4, 72)
                                                             ['batch_normaliza
conv2d 51 (Conv2D)
                              (None, 4, 4, 6)
                                                 3888
                                                             ['activation 50[0
dropout_50 (Dropout)
                              (None, 4, 4, 6)
                                                             ['conv2d_51[0][0]
 concatenate_47 (Concatenate)
                              (None, 4, 4, 78)
                                                 0
                                                             ['concatenate 46[(
                                                              'dropout_50[0][0
 batch_normalization_51 (BatchN (None, 4, 4, 78)
                                                 312
                                                             ['concatenate_47[(
ormalization)
activation 51 (Activation)
                              (None, 4, 4, 78)
                                                 0
                                                             ['batch normaliza
average_pooling2d_3 (AveragePo (None, 2, 2, 78)
                                                             ['activation 51[0
oling2D)
flatten (Flatten)
                              (None, 312)
                                                             ['average_pooling
dense (Dense)
                              (None, 10)
                                                             ['flatten[0][0]']
                                                 3130
______
Total params: 118,918
```

```
model.compile(loss='categorical_crossentropy',
      optimizer=Adam(),
      metrics=['accuracy'])
model.fit(X_train, y_train,
        batch_size=batch_size,
        epochs=epochs,
        verbose=1,
        validation_data=(X_test, y_test))
  Epoch 1/10
  Epoch 2/10
  Epoch 3/10
  Epoch 4/10
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  391/391 [============== ] - 24s 61ms/step - loss: 0.9513 - accuracy: (
  Epoch 8/10
  391/391 [============== ] - 24s 61ms/step - loss: 0.9180 - accuracy: (
```

determine Loss function and Optimizer

```
Epoch 9/10
   Epoch 10/10
   <tensorflow.python.keras.callbacks.History at 0x7efc85359240>
# Test the model
score = model.evaluate(X_test, y_test, verbose=1)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
   Test loss: 1.7172198295593262
   Test accuracy: 0.5551999807357788
# Save the trained weights in to .h5 format
model.save_weights("DNST_model.h5")
print("Saved model to disk")
   Saved model to disk
# free model variable
del model
```

Assignment

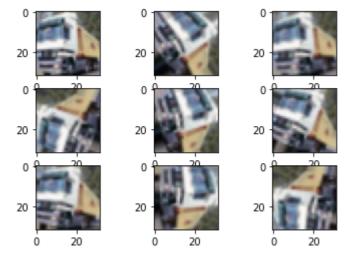
- Please visit this link to access the state-of-art DenseNet code for reference DenseNet cifar10 notebook link
- 2. You need to create a copy of this and "retrain" this model to achieve 90+ test accuracy.
- 3. You cannot use Dense Layers (also called fully connected layers), or DropOut.
- 4. You MUST use Image Augmentation Techniques.
- 5. You cannot use an already trained model as a beginning points, you have to initilize as your own
- 6. You cannot run the program for more than 300 Epochs, and it should be clear from your log, that you have only used 300 Epochs
- 7. You cannot use test images for training the model.
- 8. You cannot change the general architecture of DenseNet (which means you must use Dense Block, Transition and Output blocks as mentioned in the code)
- 9. You are free to change Convolution types (e.g. from 3x3 normal convolution to Depthwise Separable, etc)
- 10. You cannot have more than 1 Million parameters in total
- 11. You are free to move the code from Keras to Tensorflow, Pytorch, MXNET etc.
- 12. You can use any optimization algorithm you need.

13. You can checkpoint your model and retrain the model from that checkpoint so that no need of training the model from first if you lost at any epoch while training. You can directly load that model and Train from that epoch.

```
# Hyperparameters
batch_size = 128
num_classes = 10
epochs = 10
1 = 40
num_filter = 12
compression = 0.5
dropout_rate = 0.2
# Load CIFAR10 Data
(X_train, y_train), (X_test, y_test) = tf.keras.datasets.cifar10.load_data()
img_height, img_width, channel = X_train.shape[1],X_train.shape[2],X_train.shape[3]
# Apply one hot encoding
y_train = tf.keras.utils.to_categorical(y_train, num_classes)
y_test = tf.keras.utils.to_categorical(y_test, num_classes)
X_train.shape
     (50000, 32, 32, 3)
X_test.shape
     (10000, 32, 32, 3)
y_train.shape
     (50000, 10)
y_test.shape
     (10000, 10)
def normalize_pixels(train, test):
    Normalize data into range of 0 to 1
    train norm = train.astype('float32')
    test_norm = test.astype('float32')
    train_norm /= 255
    test norm /= 255
    return (train_norm, test_norm)
```

```
X_train, X_test=normalize_pixels(X_train, X_test)
#Reference: https://machinelearningmastery.com/how-to-configure-image-data-augmentation-wh
sample_image=X_train[1]
sample_image.shape
     (32, 32, 3)
sample_images = expand_dims(sample_image, 0)
# create image data augmentation generator
datagen = ImageDataGenerator(rotation_range=90)
# prepare iterator
it = datagen.flow(sample_images, batch_size=1)
# generate sample images and plot
for i in range(9):
    pyplot.subplot(330 + 1 + i)
    # generate batch of images
    batch = it.next()
    image = batch[0];
    # plot raw pixel data
    pyplot.imshow(image)
```

pyplot.show()



1.1 Model using Dense Layer

```
pyplot.title('Cross Entropy Loss')
    pyplot.plot(history.history['loss'], color='blue', label='train')
    pyplot.plot(history.history['val loss'], color='orange', label='test')
    pyplot.show()
def model_harness(X_train, y_train, X_test, y_test, given_batch_size, given_step_size, giv
    define model using data augmentation technique and extend it to it's vertical limit
    # model = pickle.load('densenet.pkl')
    # create data generator
    datagen = ImageDataGenerator(width_shift_range=0.1, height_shift_range=0.1, horizontal
    # prepare iterator
    iterator_train = datagen.flow(X_train, y_train, batch_size=given_batch_size)
    # fit model
    steps = int(X_train.shape[0] / given_step_size)
    history = model.fit_generator(iterator_train, steps_per_epoch=steps, epochs=given_epoc
    # evaluate model
    _, acc = model.evaluate(X_test, y_test, verbose=1)
    print('> %.3f' % (acc * 100.0))
    # file = open('/densenet.pkl', 'wb')
    # pickle.dumps(model)#, file
    # learning curves
    model_summarize(history)
def denseblock(input, num_filter = 64, dropout_rate = 0):
    #code for dense block
    global compression
    temp = input
    for in range(1):
        BatchNorm = layers.BatchNormalization()(temp)
        relu = layers.Activation('relu')(BatchNorm)
        Conv2D 5 5 = layers.Conv2D(int(num filter*compression), (5,5),kernel initializer="
        if dropout rate>0:
            Conv2D_5_5 = layers.Dropout(dropout_rate)(Conv2D_5_5)
        concat = layers.Concatenate(axis=-1)([temp,Conv2D_5_5])
        temp = concat
    return temp
def transition(input, num filter = 32, dropout rate = 0):
    #code for transition block
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
```

```
Final CNN on CIFR Assignment.ipynb - Colaboratory
    Conv2D_BottleNeck = layers.Conv2D(int(num_filter*compression), (5,5), kernel_initializ
    if dropout rate>0:
         Conv2D BottleNeck = layers.Dropout(dropout rate)(Conv2D BottleNeck)
    avg = layers.AveragePooling2D(pool size=(2,2))(Conv2D BottleNeck)
    return avg
def output_layer(input):
    #Code for output layer
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
    AvgPooling = layers.AveragePooling2D(pool_size=(2,2))(relu)
    flat = layers.Flatten()(AvgPooling)
    output = layers.Dense(num_classes, activation='softmax')(flat)
    return output
num filter = 10
dropout_rate = 0
1 = 12
input = layers.Input(shape=(img height, img width, channel))
First_Conv2D = layers.Conv2D(num_filter, (5,5), use_bias=False ,padding='same')(input)
BatchNorm = layers.BatchNormalization()(First_Conv2D)
First_Block = denseblock(BatchNorm, 32, dropout_rate)
First_Transition = transition(First_Block, num_filter, dropout_rate)
Second_Block = denseblock(First_Transition, 16, dropout_rate)
Second_Transition = transition(Second_Block, num_filter, dropout_rate)
Third_Block = denseblock(Second_Transition, num_filter, dropout_rate)
Third Transition = transition(Third Block, num filter, dropout rate)
Last Block = denseblock(Third Transition, num filter, dropout rate)
output = output layer(Last Block)
```

model = Model(inputs=[input], outputs=[output]) model.summary()

conv2d_97 (Conv2D)	(None,	4,	4,	5)	3755	activation_96[0][(^
concatenate_89 (Concatenate)	(None,	4,	4,	35)	0	concatenate_88[0] conv2d_97[0][0]
batch_normalization_98 (BatchNo	(None,	4,	4,	35)	140	concatenate_89[0]
activation_97 (Activation)	(None,	4,	4,	35)	0	batch_normalizati
conv2d_98 (Conv2D)	(None,	4,	4,	5)	4380	activation_97[0][
concatenate_90 (Concatenate)	(None,	4,	4,	40)	0	concatenate_89[0] conv2d_98[0][0]

batch_normalization_99 (BatchNo	(None,	4,	4,	40)	160	concatenate_90[0]
activation_98 (Activation)	(None,	4,	4,	40)	0	batch_normalization
conv2d_99 (Conv2D)	(None,	4,	4,	5)	5005	activation_98[0][
concatenate_91 (Concatenate)	(None,	4,	4,	45)	0	concatenate_90[0] conv2d_99[0][0]
batch_normalization_100 (BatchN	(None,	4,	4,	45)	180	concatenate_91[0]
activation_99 (Activation)	(None,	4,	4,	45)	0	batch_normalization
conv2d_100 (Conv2D)	(None,	4,	4,	5)	5630	activation_99[0][0
concatenate_92 (Concatenate)	(None,	4,	4,	50)	0	concatenate_91[0] conv2d_100[0][0]
batch_normalization_101 (BatchN	(None,	4,	4,	50)	200	concatenate_92[0]
activation_100 (Activation)	(None,	4,	4,	50)	0	batch_normalization
conv2d_101 (Conv2D)	(None,	4,	4,	5)	6255	activation_100[0]
concatenate_93 (Concatenate)	(None,	4,	4,	55)	0	concatenate_92[0] conv2d_101[0][0]
batch_normalization_102 (BatchN	(None,	4,	4,	55)	220	concatenate_93[0]
activation_101 (Activation)	(None,	4,	4,	55)	0	batch_normalization
conv2d_102 (Conv2D)	(None,	4,	4,	5)	6880	activation_101[0]
concatenate_94 (Concatenate)	(None,	4,	4,	60)	0	concatenate_93[0] conv2d_102[0][0]
batch_normalization_103 (BatchN	(None,	4,	4,	60)	240	concatenate_94[0]
activation_102 (Activation)	(None,	4,	4,	60)	0	batch_normalization
conv2d_103 (Conv2D)	(None,	4,	4,	5)	7505	activation_102[0]
concatenate_95 (Concatenate)	(None,	4,	4,	65)	0	concatenate_94[0]
4						>

```
# entry point, run the test harness
model_harness(X_train, y_train, X_test, y_test, 64, 64, 75)
```

```
Epoch 28/75
781/781 [============= ] - 83s 106ms/step - loss: 0.3571 - accuracy:
Epoch 29/75
781/781 [============== ] - 82s 106ms/step - loss: 0.3428 - accuracy:
Epoch 30/75
781/781 [============= ] - 81s 104ms/step - loss: 0.3372 - accuracy:
Epoch 31/75
781/781 [============= ] - 81s 104ms/step - loss: 0.3238 - accuracy:
Epoch 32/75
781/781 [============= ] - 81s 104ms/step - loss: 0.3243 - accuracy:
Epoch 33/75
781/781 [============= ] - 81s 104ms/step - loss: 0.3156 - accuracy:
Epoch 34/75
781/781 [============= ] - 81s 104ms/step - loss: 0.3077 - accuracy:
Epoch 35/75
781/781 [============== ] - 81s 104ms/step - loss: 0.3012 - accuracy:
Epoch 36/75
781/781 [============= ] - 81s 104ms/step - loss: 0.2919 - accuracy:
Epoch 37/75
781/781 [============= ] - 81s 104ms/step - loss: 0.2878 - accuracy:
Epoch 38/75
781/781 [============= ] - 81s 104ms/step - loss: 0.2846 - accuracy:
Epoch 39/75
781/781 [============= ] - 80s 103ms/step - loss: 0.2762 - accuracy:
Epoch 40/75
781/781 [============== ] - 81s 103ms/step - loss: 0.2674 - accuracy:
Epoch 41/75
781/781 [============= ] - 81s 103ms/step - loss: 0.2639 - accuracy:
Epoch 42/75
781/781 [============= ] - 81s 103ms/step - loss: 0.2562 - accuracy:
Epoch 43/75
Epoch 44/75
781/781 [============= ] - 81s 103ms/step - loss: 0.2468 - accuracy:
Epoch 45/75
Epoch 46/75
Epoch 47/75
781/781 [============= ] - 81s 104ms/step - loss: 0.2392 - accuracy:
Epoch 48/75
Epoch 49/75
781/781 [============== ] - 83s 107ms/step - loss: 0.2287 - accuracy:
Epoch 50/75
Epoch 51/75
Epoch 52/75
781/781 [============== ] - 82s 105ms/step - loss: 0.2116 - accuracy:
Epoch 53/75
Epoch 54/75
781/781 [============= ] - 82s 104ms/step - loss: 0.2055 - accuracy:
Epoch 55/75
781/781 [============== ] - 81s 104ms/step - loss: 0.1993 - accuracy:
Epoch 56/75
701/701 [______1
                           01c 10/mc/c+on locc. 0 1006
```

```
# Save the trained weights in to .h5 format
model.save_weights("DNST_model_with_dense_layer.h5")
print("Saved model to disk")

Saved model to disk
```

free model variable

del model

2 Model without applying Dense layer and implemented all instructions suggested in the assignment

```
def denseblock(input, num_filter = 12, dropout_rate = 0.2):
····Create · Dense · Block
....
····global·compression
····temp·=·input
    for _ in range(1):
        BatchNorm = layers.BatchNormalization()(temp)
        relu = layers.Activation('relu')(BatchNorm)
        Conv2D_5_5 = layers.Conv2D(int(num_filter*compression), (5,5), use_bias=False ,pad
        if dropout rate>0:
            Conv2D_5_5 = layers.Dropout(dropout_rate)(Conv2D_5_5)
        concat = layers.Concatenate(axis=-1)([temp,Conv2D_5_5])
        temp = concat
    return temp
def transition(input, num_filter = 12, dropout_rate = 0.2):
    Create transition block
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
    Conv2D_BottleNeck = layers.Conv2D(int(num_filter*compression), (5,5), use_bias=False ,
    if dropout rate>0:
         Conv2D_BottleNeck = layers.Dropout(dropout_rate)(Conv2D_BottleNeck)
    avg = layers.AveragePooling2D(pool size=(2,2))(Conv2D BottleNeck)
    return avg
def output_layer(input):
    Define output layer
    global compression
    BatchNorm = layers.BatchNormalization()(input)
    relu = layers.Activation('relu')(BatchNorm)
    AvgPooling = lavers MayPooling?D(nool size=(2 2))(relu)
```

```
AVBI DOTTILE - TAYCI 3. MANI DOTTILED ( POOT 3120- (2,2/) (1 CTA)
```

output = layers.Conv2D(filters=10,kernel_size=(2,2),activation='softmax')(AvgPooling)

flat = layers.Flatten()(output)

return flat

num_filter = 12
dropout_rate = 0

1 = 12

input = layers.Input(shape=(img_height, img_width, channel,))

First_Conv2D = layers.Conv2D(32, (3,3), use_bias=False ,padding='same')(input)

First_Block = denseblock(First_Conv2D,10, dropout_rate)
First_Transition = transition(First_Block, 64, dropout_rate)

Second_Block = denseblock(First_Transition, 10, dropout_rate)
Second_Transition = transition(Second_Block, 32, dropout_rate)

Third_Block = denseblock(Second_Transition, num_filter, dropout_rate)
Third_Transition = transition(Third_Block, 32, dropout_rate)

Last_Block = denseblock(Third_Transition, num_filter, dropout_rate)
output = output_layer(Last_Block)

model = Model(inputs=[input], outputs=[output])
model.summary()

batch_normalization_62 (BatchNo	(None,	32,	32,	77)	308	concatenate_56[0] ^
activation_61 (Activation)	(None,	32,	32,	77)	0	batch_normalization
conv2d_62 (Conv2D)	(None,	32,	32,	5)	9625	activation_61[0][
concatenate_57 (Concatenate)	(None,	32,	32,	82)	0	concatenate_56[0] conv2d_62[0][0]
batch_normalization_63 (BatchNo	(None,	32,	32,	82)	328	concatenate_57[0]
activation_62 (Activation)	(None,	32,	32,	82)	0	batch_normalization
conv2d_63 (Conv2D)	(None,	32,	32,	5)	10250	activation_62[0][
concatenate_58 (Concatenate)	(None,	32,	32,	87)	0	concatenate_57[0] conv2d_63[0][0]
batch_normalization_64 (BatchNo	(None,	32,	32,	87)	348	concatenate_58[0]
activation_63 (Activation)	(None,	32,	32,	87)	0	batch_normalization
conv2d_64 (Conv2D)	(None,	32,	32,	5)	10875	activation_63[0][
concatenate_59 (Concatenate)	(None,	32,	32,	92)	0	concatenate_58[0] conv2d_64[0][0]
batch_normalization_65 (BatchNo	-	-	-	-	368	concatenate_59[0]

activation_64 (Activation)	(None,	32,	32,	92)	0	batch_normalization
conv2d_65 (Conv2D)	(None,	32,	32,	32)	73600	activation_64[0][
average_pooling2d_4 (AveragePoo	(None,	16,	16,	32)	0	conv2d_65[0][0]
batch_normalization_66 (BatchNo	(None,	16,	16,	32)	128	average_pooling2d
activation_65 (Activation)	(None,	16,	16,	32)	0	batch_normalization
conv2d_66 (Conv2D)	(None,	16,	16,	5)	4000	activation_65[0][
concatenate_60 (Concatenate)	(None,	16,	16,	37)	0	average_pooling2d conv2d_66[0][0]
batch_normalization_67 (BatchNo	(None,	16,	16,	37)	148	concatenate_60[0]
activation_66 (Activation)	(None,	16,	16,	37)	0	batch_normalization
conv2d_67 (Conv2D)	(None,	16,	16,	5)	4625	activation_66[0][
concatenate_61 (Concatenate)	(None,	16,	16,	42)	0	concatenate_60[0] conv2d_67[0][0]
batch_normalization_68 (BatchNo	(None,	16,	16,	42)	168	concatenate_61[0]
activation_67 (Activation)	(None,	16,	16,	42)	0	batch_normalization
1 (0 (0 30)	/NI	1.0	1.0	۲\	F3F0	+: +: C3[0][.

```
# sample run
model_harness(X_train, y_train, X_test, y_test, 60, 39, 1)
```

WARNING:tensorflow:From <ipython-input-22-9641928ef676>:12: Model.fit_generator (from Instructions for updating:

Please use Model.fit, which supports generators.

entry point, run the test harness for 50 * 5 iterations, 1st slot will be: model_harness(X_train, y_train, X_test, y_test, 60, 39, 50)

```
Epoch 1/50
Epoch 2/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.6867 - accur
Epoch 3/50
1282/1282 [============== ] - 122s 95ms/step - loss: 0.5855 - accur
Epoch 4/50
1282/1282 [=============== ] - 122s 95ms/step - loss: 0.5207 - accur
Epoch 5/50
1282/1282 [============== ] - 122s 95ms/step - loss: 0.4703 - accur
Epoch 6/50
Epoch 7/50
1282/1282 [============= ] - 122s 95ms/step - loss: 0.3976 - accur
Epoch 8/50
1282/1282 [=============== ] - 122s 96ms/step - loss: 0.3685 - accur
Epoch 9/50
Epoch 10/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.3253 - accur
Epoch 11/50
Epoch 12/50
Epoch 13/50
Epoch 14/50
Epoch 15/50
Epoch 16/50
1282/1282 [============= ] - 123s 96ms/step - loss: 0.2365 - accur
Epoch 17/50
1282/1282 [============= ] - 123s 96ms/step - loss: 0.2280 - accur
Epoch 18/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.2166 - accur
Epoch 19/50
1282/1282 [============= ] - 124s 96ms/step - loss: 0.2117 - accur
Epoch 20/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.2027 - accur
Epoch 21/50
1282/1282 [============= ] - 123s 96ms/step - loss: 0.1952 - accur
Epoch 22/50
1282/1282 [============= ] - 123s 96ms/step - loss: 0.1877 - accur
Epoch 23/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.1831 - accur
Epoch 24/50
1282/1282 [============== ] - 123s 96ms/step - loss: 0.1742 - accur
Epoch 25/50
Epoch 26/50
```

entry point, run the test harness for 25 * 8 iterations, 2nd slot will be: $model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)$

```
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
```

entry point, run the test harness for 25 * 8 iterations, 3rd slot will be: $model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)$

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Fnoch 16/25
```

entry point, run the test harness for 25 * 8 iterations, 4th slot will be: $model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)$

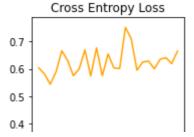
```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
Fnoch 22/25
```

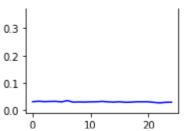
entry point, run the test harness for 25 * 8 iterations, 5th slot will be:
model harness(X train, y train, X test, y test, 60, 39, 25)

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
Epoch 22/25
Epoch 23/25
Epoch 24/25
Epoch 25/25
> 89.190
Cross Entropy Loss
```

entry point, run the test harness for 25 * 8 iterations, 6th slot will be: model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
Epoch 22/25
Epoch 23/25
Epoch 24/25
Epoch 25/25
> 88.550
```





entry point, run the test harness for 25 * 8 iterations, 7th slot will be: model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)

```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Enach 10/25
```

entry point, run the test harness for 25 * 8 iterations, 8th slot will be: $model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)$

```
Epoch 6/25
 Epoch 7/25
 Epoch 8/25
 Epoch 9/25
 Epoch 10/25
 Epoch 11/25
 Epoch 12/25
 Epoch 13/25
 Epoch 14/25
 Epoch 15/25
 Epoch 16/25
 Epoch 17/25
 Epoch 18/25
 Epoch 19/25
 Epoch 20/25
 Epoch 21/25
# Save the trained weights in to .h5 format
model.save_weights("DNST_model_without_dense_layer.h5")
print("Saved model to disk")
 Saved model to disk
```

You can checkpoint your model and retrain the model from that checkpoint

##so that no need of training the model from first if you lost at any epoch while training ##You can directly load that model and Train from that epoch, ##it really saves the computing time as well.

entry point, run the test harness
model_harness(X_train, y_train, X_test, y_test, 60, 39, 25)