

Introduction to Matlab

MA 573

Lab Component

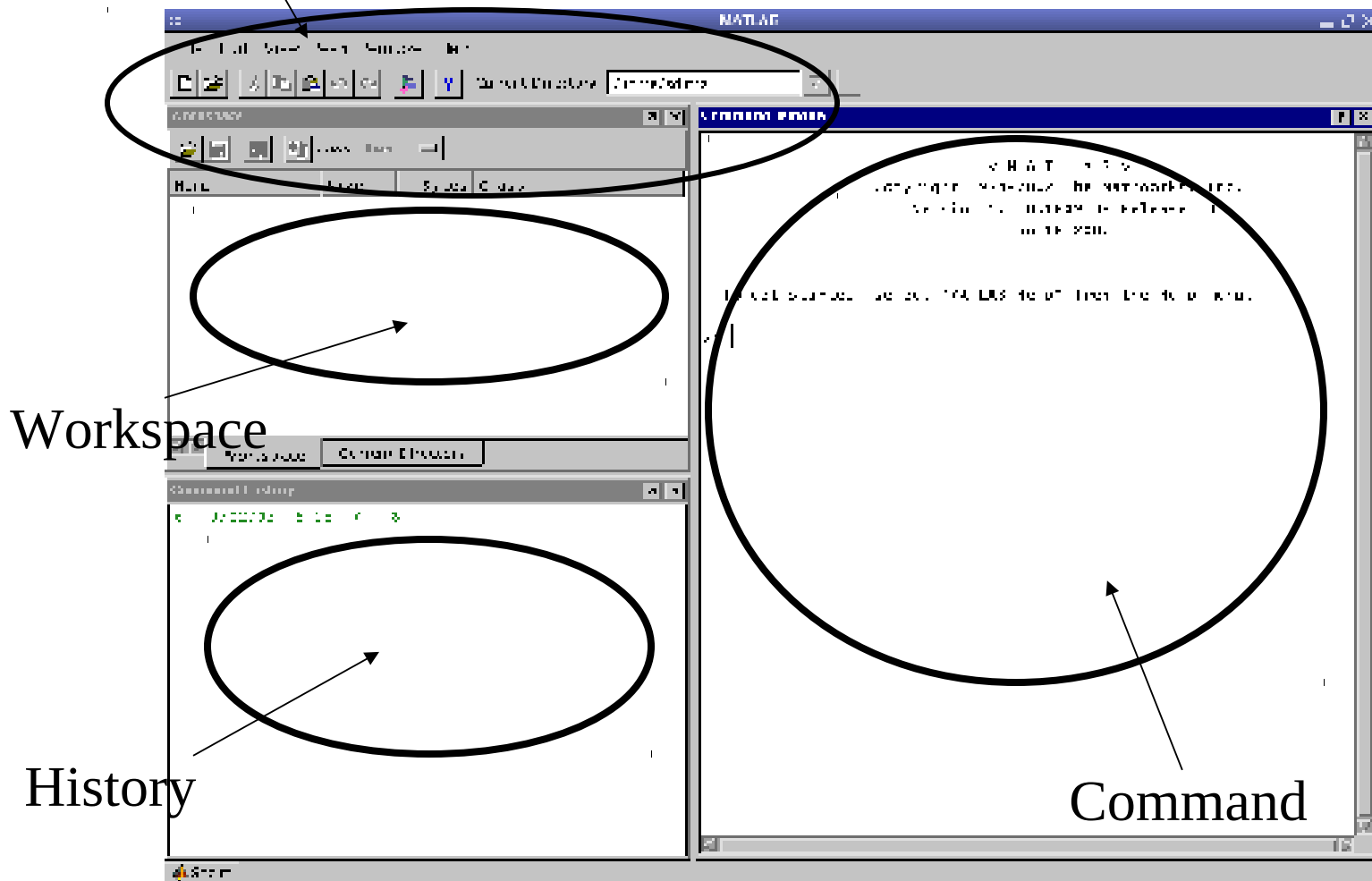
Date : 08.01.2020

History

Cleve Moler, the chairman of the computer science department at the [University of New Mexico](#), started developing Matlab in the late [1970s](#). Later In 1984, [MathWorks](#) started to continue its development. Matlab stands for [Matrix Laboratory](#).

MATLAB Desktop

Menu and toolbar



Matlab Assignment & Operators

Assignment = $a = b$ (assign b to a)

Addition + $a + b$

Subtraction - $a - b$

Multiplication * or .* $a*b$ or $a.*b$

Division / or ./ a/b or $a./b$

Power ^ or .^ a^b or $a.^b$

```
a= input('enter the number a= ');
```

```
b= input('enter the number b= ');
```

```
s= a+b;
```

```
fprintf('the final sum is= %d\n', s);
```

Matrices & Vectors

» rowvec = [12 , 14 , 63] or [12 14 63]

rowvec = 12 14 63

» colvec = [13 ; 45 ; -2]

colvec =

13

45

-2

Matrices & Vectors

Matrices Easy to define:

```
>> A = [16 3; 5 10]
A =
    16     3
     5    10
```

- Use ‘,’ or ‘ ’ to separate row elements -- use ‘;’ to separate rows

Creating Vectors and Matrices

- Define

```
>> A = [16 3; 5 10]
A =
    16     3
     5    10

>> B = [3 4 5
        6 7 8]
B =
     3     4     5
     6     7     8
```

- Transpose

Vector :

```
>> a=[1 2 3];
>> a'
```

1
2
3

Matrix:

```
>> A=[1 2; 3 4];
>> A'
```

ans =

1 3
2 4

Matrices

```
>>A = [1 2 3; 4 5 6; 7 8 9]
```

A =

1 2 3

4 5 6

7 8 9

```
>> A'
```

A' =

1 4 7

2 5 8

3 6 9

>> $A(:,2)$ - For getting second column
>> $A(2,:)$ - For getting second row
>> $\det(A)$ - getting determinant
>> $\text{inv}(A)$ – getting inverse
>> $A*B$ – matrix multiplication
>> $A+B$ – matrix addition
>> $\text{diag}(A)$ – diagonal element of A
>> $\text{zeros}(n)$ – $(n \times n)$ zero matrix
>> $\text{eye}(n)$ – $(n \times n)$ identity matrix

Creating Vectors

Create vector with equally spaced intervals

```
>> x=0:0.5:pi
```

```
x =
```

```
0 0.5000 1.0000 1.5000 2.0000 2.5000 3.0000
```

Create vector with n equally spaced intervals

```
>> x=linspace(0, pi, 7)
```

```
x =
```

```
0 0.5236 1.0472 1.5708 2.0944 2.6180 3.1416
```

Note: MATLAB uses pi to represent π , uses i or j to represent imaginary unit

```
>> sqrt(-1)
```

Creating Matrices

- `zeros(m, n)`: matrix with all zeros
- `ones(m, n)`: matrix with all ones.
- `eye(m, n)`: the identity matrix
- `rand(m, n)`: uniformly distributed random
- `randn(m, n)`: normally distributed random
- `magic(m)`: square matrix whose elements have the same sum, along the row, column and diagonal.
- `pascal(m)` : Pascal matrix.
 $s_{ij} = (i+j)! / i! j!$

Matrix operations

- \wedge : exponentiation
- $*$: multiplication
- $/$: division
- \backslash : left division. The operation $A \backslash B$ is effectively the same as $\text{INV}(A) * B$, although left division is calculated differently and is much quicker.
- $+$: addition
- $-$: subtraction

Array Operations

- Evaluated element by element
 - . ' : array transpose (non-conjugated transpose)
 - . ^ : array power
 - . * : array multiplication
 - . / : array division
- Very different from Matrix operations

```
>> A=[1 2;3 4];  
>> B=[5 6;7 8];  
>> A*B  
    19    22  
    43    50
```

But:

```
>> A.*B  
     5     12  
    21     32
```

Some Built-in functions

- `mean(A)` : mean value of a vector
- `max(A)`, `min (A)` : maximum and minimum.
- `sum(A)` : summation.
- `sort(A)` : sorted vector
- `median(A)` : median value
- `std(A)` : standard deviation.
- `det(A)` : determinant of a square matrix
- `dot(a, b)` : dot product of two vectors
- `Cross(a, b)` : cross product of two vectors
- `Inv(A)` : Inverse of a matrix A

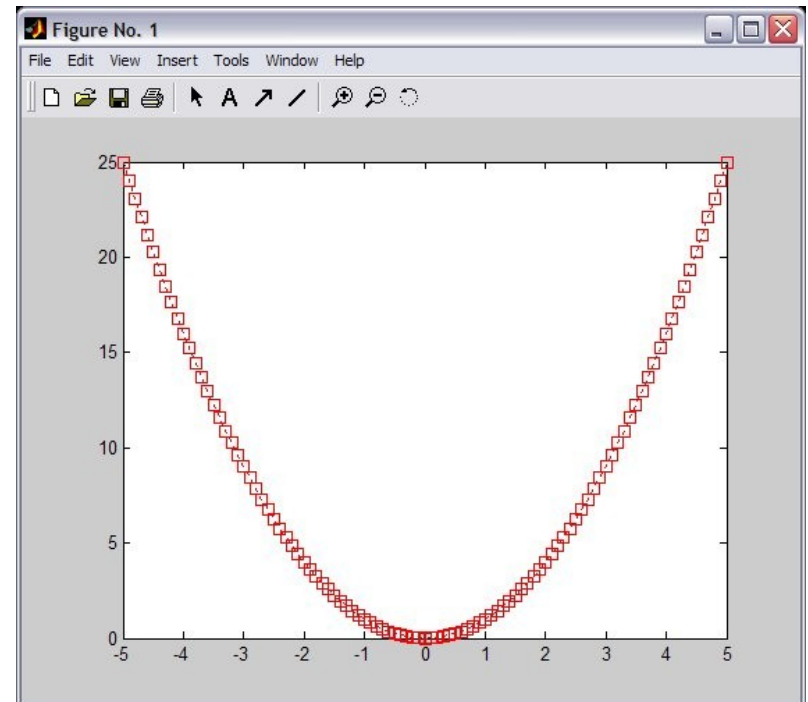
Graphics - 2D Plots

`plot(xdata, ydata, 'marker_style');`

For example:

```
>> x=-5:0.1:5;  
>> sqr=x.^2;  
>> p11=plot(x, sqr, 'r:s');
```

Gives:

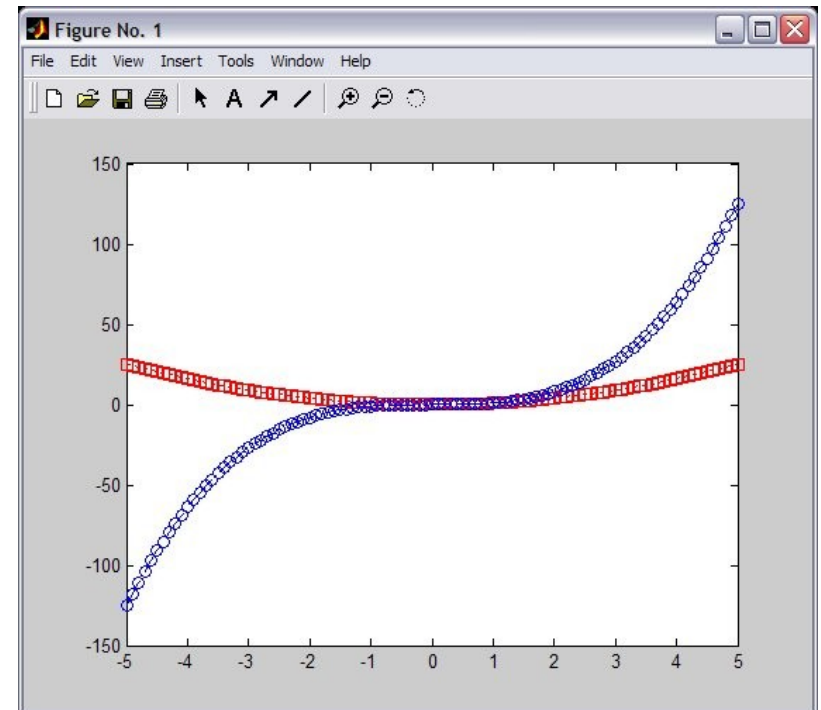


Graphics - Overlay Plots

Use `hold on` for overlaying graphs

So the following: Gives:

```
>> hold on;  
>> cub=x.^3;  
>> pl2=plot(x, cub, 'b-o');
```

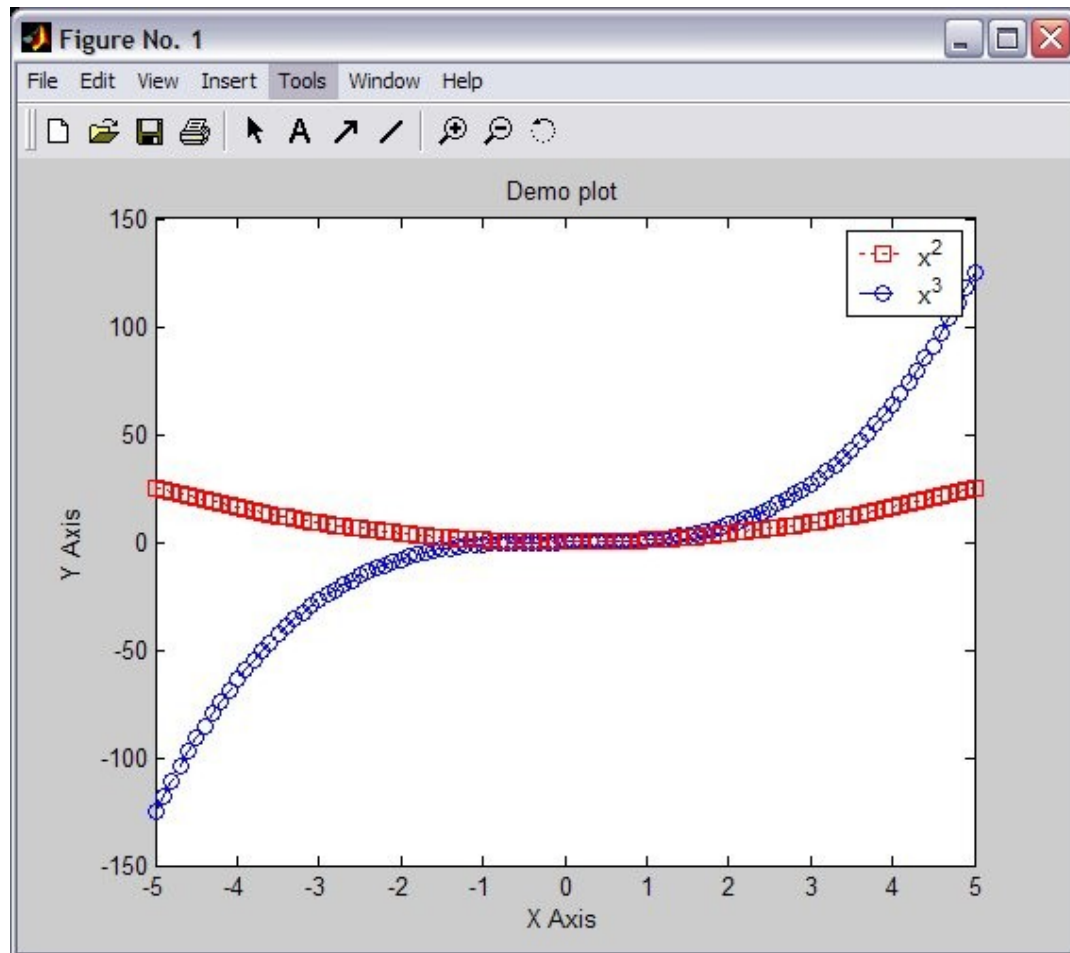


Graphics - Annotation

Use `title`, `xlabel`, `ylabel` and `legend` for annotation

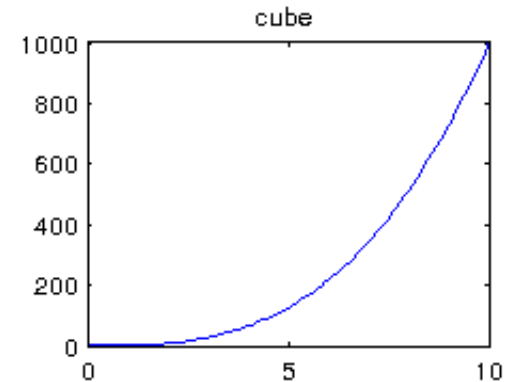
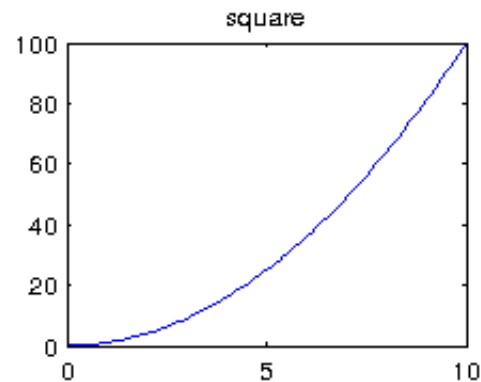
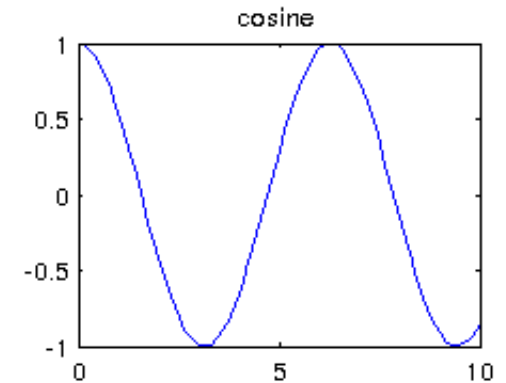
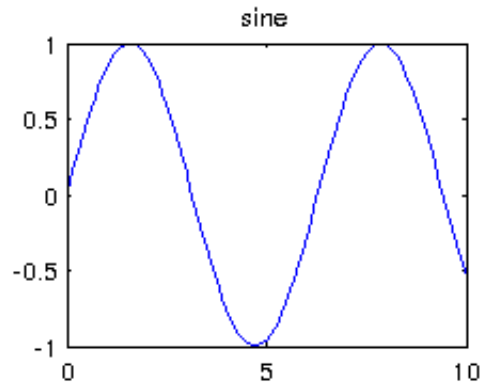
```
>> title('Demo plot');  
>> xlabel('X Axis');  
>> ylabel('Y Axis');  
>> legend([p11, p12], 'x^2', 'x^3');
```

Graphics - Annotation



```
x=0:0.1:10;  
f1=sin(x);  
f2=cos(x);  
f3=x.^2;  
f4=x.^3;  
subplot(2,2,1);  
plot(x,f1);  
title('sine');  
subplot(2,2,2);  
plot(x,f2);  
title('cosine');  
subplot(2,2,3);  
plot(x,f3);  
title('square');  
subplot(2,2,4);  
plot(x,f4);  
title('cube');
```

Subplot



Functions

```
function f= myfunc(x)
    f=x.^3;
end
```

Save it in another file and give the file name myfunc.m . then in main file declare the function as :

```
x=linspace(2,3,10);
final= myfunc(x);
plot(x,final,'r:o');
```

Practice Problems

- Plot the following signals in linear scale

$$x(t) = \sin(3t) \quad -5 < t < 5$$

$$y(t) = e^{2t+3} \quad 0 < t < 5$$

- Plot the following signals, use log scale for y-axis

$$x(t) = e^{t+2}(2t+1) \quad 0 < t < 10$$

- Plot the real part and imaginary part of the following signal

$$x(t) = e^{0.5t+j(t+\pi/3)} \quad 0 < t < 10$$

- For the signal in previous question, plot its phase and magnitude