In [2]:

```
import numpy as np
np.random.seed(0)
class OneHiddenLayerNetwork:
    @staticmethod
    def tang(y):
        return np.tanh(y)
    @staticmethod
    def derivative_tang(y):
        return 1.0 - y ** 2
    @staticmethod
    def sigmoid(y):
        return 1 / (1 + np.exp(-y))
    @staticmethod
    def derivative_sigmoid(y):
        return y * (1 - y)
    def __init__(self, learning_rate = 0.1):
        self.learning_rate = learning_rate
        self.output = None
        self.weights = [
             np.random.uniform(low = -0.2, high = 0.2, size = (2,2)),
             np.random.uniform(low = -2, high = 2, size = (2,1))
        ]
    def activation(self, activation_type, y):
        if activation_type == 'sigmoid':
            return self.sigmoid(y)
        if activation_type == 'tang':
            return self.tang(y)
        raise ValueError('Undefined derivative activation function : {}'.format(activation_type))
    def derivative_activation(self, activation_type, y):
        if activation_type == 'sigmoid':
            return self.derivative_sigmoid(y)
        if activation_type == 'tang':
            return self.derivative_tang(y)
        raise ValueError('Undefined derivative activation function : {}'.format(activation_type))
    def feed_forward_pass(self, x_values):
        input_layer = x_values
        hidden_layer = self.activation('tang', np.dot(input_layer, self.weights[0]))
        output_layer = self.activation('tang', np.dot(hidden_layer, self.weights[1]))
        self.layers = [
            input_layer,
            hidden_layer,
            output_layer
        ]
        return self.layers[2]
    def backward_pass(self, target_output, actual_output):
        err = (target_output - actual_output)
        for backward in range(2, 0, -1):
            err_delta = err * self.derivative_activation('tang', self.layers[backward])
            self.weights[backward - 1] += self.learning_rate * np.dot(self.layers[backward - 1].T, err_delta)
            err = np.dot(err_delta, self.weights[backward - 1].T)
    def train(self, x_values, target):
        self.output = self.feed_forward_pass(x_values)
        self.backward_pass(target, self.output)
    def predict(self, x_values):
        return self.feed_forward_pass(x_values)
X = np.array(([0,0],[0,1],[1,0],[1,1]), dtype = float)
y = np.array(([0],[1],[1],[0]), dtype = float)
network = OneHiddenLayerNetwork(learning_rate = 0.1)
iterations = 5000
for i in range (iterations):
    network.train(X,y)
    ten = iterations // 10
    if i % ten == 0:
        print('-' * 10)
        print("Iteration number: " + str(i) + '/' + "Squared loss: " + str(np.mean(np.square(y-network.output))
for i in range (len(X)):
    print('-' * 10)
    print('Input value: ' + str(X[i]))
    print('Predicted target: ' + str(network.predict(X[i])))
    print('Actual target: ' + str(y[i]))
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Iteration number: 0/Squared loss: 0.4799042135840691
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Iteration number: 500/Squared loss: 0.042950494381573334
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Iteration number: 1000/Squared loss: 0.013212838667124902
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Iteration number: 1500/Squared loss: 0.007013232507805753
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Iteration number: 2000/Squared loss: 0.004629345031713994
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Iteration number: 2500/Squared loss: 0.0034124014973550645
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Iteration number: 3000/Squared loss: 0.002685484896745162
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Iteration number: 3500/Squared loss: 0.00220614325698692
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Iteration number: 4000/Squared loss: 0.0018679274404917088
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Iteration number: 4500/Squared loss: 0.0016172802953130275
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Input value: [0. 0.]
Predicted target: [0.]
Actual target: [0.]
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Input value: [0. 1.]
Predicted target: [0.9470363]
Actual target: [1.]
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Input value: [1. 0.]
Predicted target: [0.94703627]
Actual target: [1.]
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Input value: [1. 1.]
Predicted target: [0.00936281]
Actual target: [0.]
```