

# Experiments on Polar and Bipolar Line Encoding Schemes

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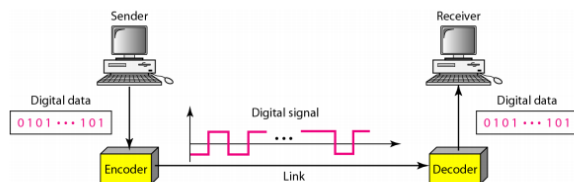
**Abstract**—The abstract goes here.

**Index Terms**—Line Encoding Schemes, Experiments, JavaScript

## 1 INTRODUCTION

Communication/transmission of data from sender to receiver takes place in a computer network. Analog/digital data traverses through communication media from source to destination in form of signals. The transmitting signals may undergo attenuation and distortion as they travel over large distances. Therefore there is a need to match the properties of transmitted signal as per the communication media for which digital data can be converted into digital signals. This conversion or encoding techniques is what will be covered in this paper.

**Line encoding:** The process of converting digital data into digital signals is referred as Line Encoding. With the help of line encoding schemes, a sequence of bits are converted into digital signal (encoding) which then get converted back into bits at the receiver end (decoding).

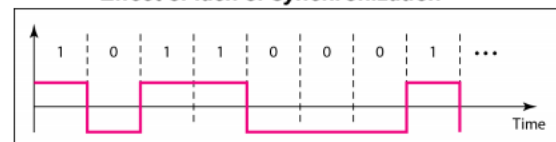


### 1.1 Signal Transmission Issues

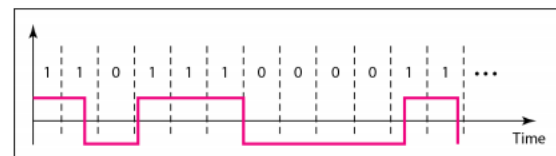
**Dc components:** After line coding has been applied onto the data to be transmitted, there is a possibility of the signal having a zero frequency component in the transmitted signal which is called DC component. This DC component in the spectrum (caused due to constant voltage level in digital signal) is unable to pass through communication medium components like transformers due to which distortion of transmitting signal takes place.

**Self Synchronization:** The bit interval of the receiver and that of the transmitter must be synchronized in order to correctly interpret the received signal. If the clock at the receiver end is faster or slower, the bit intervals will not match and misinterpretation of received signal will take place.

**Effect of lack of synchronization**



a. Sent



b. Received

The sender sends 10110001, while the receiver receives 110111000011

## 2 LITERATURE REVIEW/RELATED WORK

We worked on analysing previous techniques of signal visualisation experiments and the techniques they utilized to visualize and implement the experimentation details. This shed light towards a deeper understanding of signal encoding technologies and the related optimisations offered in these papers. A brief overview of our learnings from these are further discussed below.

### 2.1 SYNTHESIS AND SIMULATION OF AMI AND MANCHESTER CODING USING VHDL LANGUAGE

This is a research paper by Garima Saraf, Prerna Gupta and MD. Zahid Alam which is a demonstration of Encoding schemes. The techniques to be implemented are selected based on the systems performance criteria. Signal to noise ratio for longer and shorter signals has been studied in this paper based on which data coding techniques to be implemented are selected. Also various other factors like error checking have been taken into account.

### 2.2 Blind Classification of Line-Coding Schemes Based on Characteristic Features

This is a research paper published in the IEEE stating the implementation and use of line encoding techniques in modern defence systems. Signalling technologies are a key component of military operations, for which line encoding

techniques has been explored in this paper. Characteristic features of digital data to digital signals techniques have been examined in this paper based on which a blind classification algorithms has been proposed.

### 2.3 Method of Unipolar Digital to Digital Encoding Data Transmission

Method of Unipolar Digital to Digital Encoding Data Transmission This is a published paper by Nuha Abdelmageed and Jabar Alzubaidi which proposes data transmission via unipolar encoding schemes. The paper talks about various other common types of line encoding methods. The hardware implementation using latch SN74373, amplifier ULN 2003-500 mA and C++ language has been represented in the paper.

### 2.4 Design of Manchester Digital to Digital Encoding Data Transmission

A detailed analysis of Biphase encoding techniques like Manchester and their advantages over other digital data to digital signal transmission schemes have been covered in this paper. This paper mentions both software and hardware implementation of the research topic. This paper specifically concludes with three reasons why biphase techniques have an edge over other techniques which includes modulation rate, synchronization and error detection as key factors of comparison Data Resources

## 3 TECHNOLOGICAL RESOURCES USED

### 3.1 Visual Representation

Our platform uses Plotly.js. It is a high level, declarative plotting library written in JavaScript. Plotly charts are described as JSON objects which are imported in our project. All aspects of the charts like colors, lines, legends have a corresponding set of attributes which can be controlled by the developer. Graphs with Plotly are drawn as Scalar Vector Graphics offering great compatibility across browsers and platforms along with vector image exports. Plotly internally uses Stack.GI for high -performance multi-dimensional charting.

### 3.2 Project Stack

Our platform utilizes HTML as the markup language that to structure and give meaning to our web content. Cascading Style Sheets is a language of style rules that we use to apply styling to our Structured Markup content. JavaScript is a scripting language that enables us to create dynamically updating content, control graphs, animate text and images. JSON (JavaScript Object Notation) based unit

### 3.3 Deployment Strategy

We use a serverless infrastructure for the deployment of our project which is used to publish new builds of the platform directly using our Continuous Integration and Continuous Deployment (CICD) build pipeline. This eliminated the need to maintain physical infrastructure, systems and software from the developer's standpoint. Serverless architectures allows us to build highly scalable experimentation platforms, delivering high performance and seamless experienced to the developers and the users of the platform.

## 4 METHODOLOGY

Polar encoding comprises of two levels of positive and negative of amplitude. Types of Polar encoding techniques are:

Types of encoding are:

- Polar
  - Non Return to Zero (NRZ)
    - \* NRZ-L
    - \* NRZ-I
  - Return to Zero (RZ)
  - Bi Phase
    - \* Manchester
    - \* Differential Manchester
- Bipolar
  - AMI
  - Pseudoternary

### 4.1 Setup

When the user starts the application, they are presented with a central dashboard with various experiments listed that are available to perform. Here they can choose whichever encoding scheme they would like to experiment with and the application will take them to a dedicated space where the experiments for that specific encoding can be carried out.

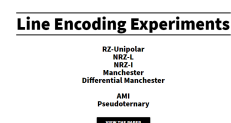


Fig. 1. Image of Dashboard

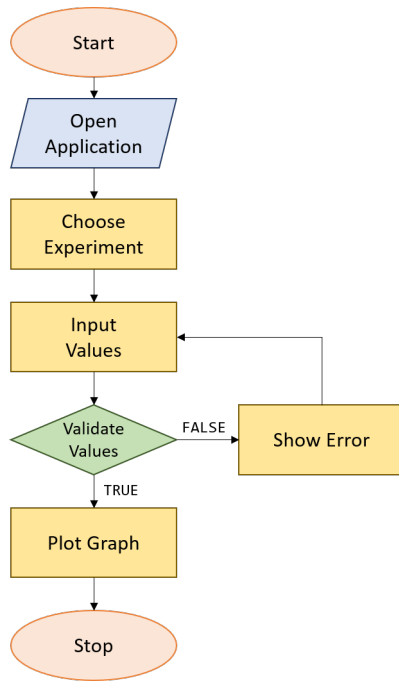


Fig. 2. Flow of Project

## 4.2 RZ

RZ uses three levels of amplitude i.e. positive, negative, zero. it returns to zero in the middle of each bit. 1 : positive-to-zero, 0 : negative-to-zero. You can refer to the figure below for a better understanding of the encoding scheme.

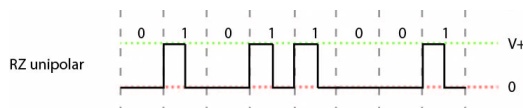


Fig. 3. RZ Encoding

## 4.3 NRZ-I

For logical 1 the signal will be inverted, but when it encounters logical 0 then signal will not undergo any transition. This is the NRZ-Invert. You can refer to the figure below for a better understanding of the encoding scheme.

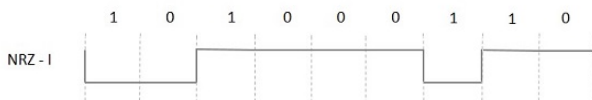


Fig. 4. NRZ-I Encoding

## 4.4 NRZ-L

In NRZ-L type of encoding, high volt is assigned for logical 0 bit and low volt is assigned for logical 1. Level of voltage determines bit value. This is NRZ-Level. You can refer to the figure below for a better understanding of the encoding scheme.

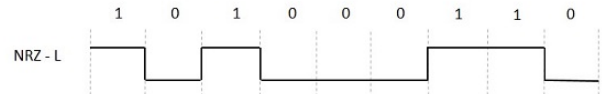


Fig. 5. NRZ-I Encoding

## 4.5 Manchester

It is a combination of NRZ-L and RZ. The duration of each bit is divided into two halves. 0 is and 1 is . You can refer to the figure below for a better understanding of the encoding scheme.

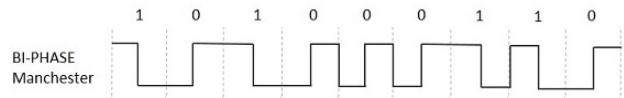


Fig. 6. Manchester Encoding

## 4.6 Differential Manchester

It combines the idea of RZ and NRZ-I. If the next bit is 0, transition will occur but if the next bit is 1, no transition will occur. You can refer to the figure below for a better understanding of the encoding scheme.

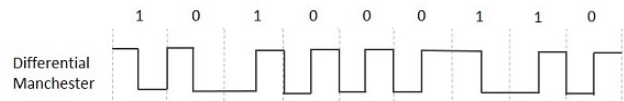


Fig. 7. Differential Manchester Encoding

## 4.7 AMI

In Alternate Mark Inversion or AMI, 0 bit is represented by Zero level and binary 1 is represented by alternating positive and negative voltages. You can refer to the figure below for a better understanding of the encoding scheme.

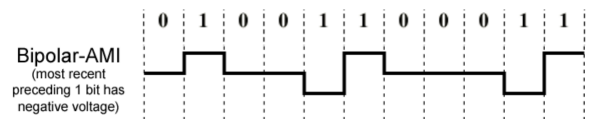


Fig. 8. AMI Encoding

## 4.8 Pseudoternary

Pseudoternary is similar to AMI with slight difference that alternating positive and negative is used for binary 0 instead of binary 1. You can refer to the figure below for a better understanding of the encoding scheme.

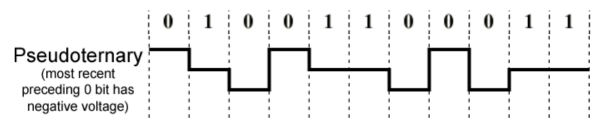


Fig. 9. Pseudoternary Encoding

## 5 RESULTS

### 5.1 RZ

#### Explanation

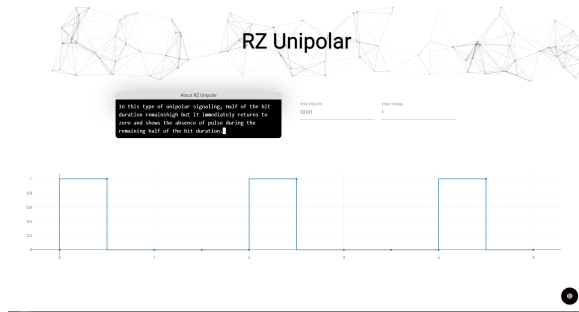


Fig. 10. RZ Experiment Dashboard

### 5.2 NRZ-I

#### Explanation

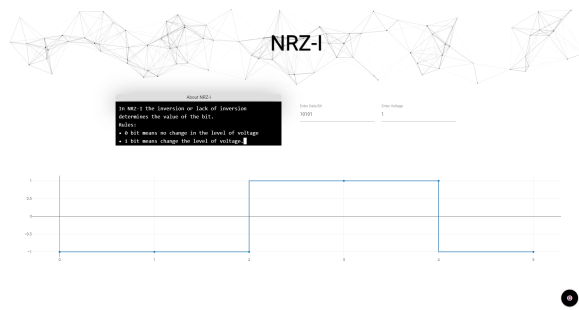


Fig. 11. NRZI Experiment Dashboard

### 5.3 NRZ-L

#### Explanation

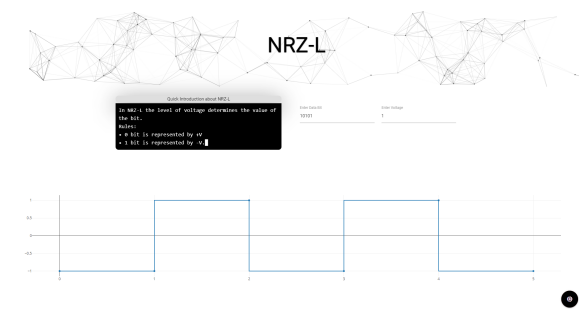


Fig. 12. NRZL Experiment Dashboard

### 5.4 Manchester

#### Explanation



Fig. 13. Manchester Experiment Dashboard

### 5.5 Differential Manchester

#### Explanation

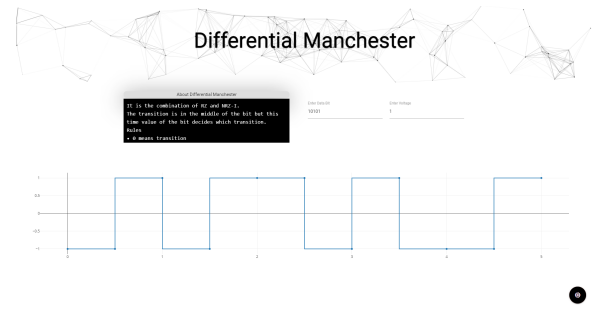


Fig. 14. Differential Manchester Experiment Dashboard

### 5.6 AMI

#### Explanation

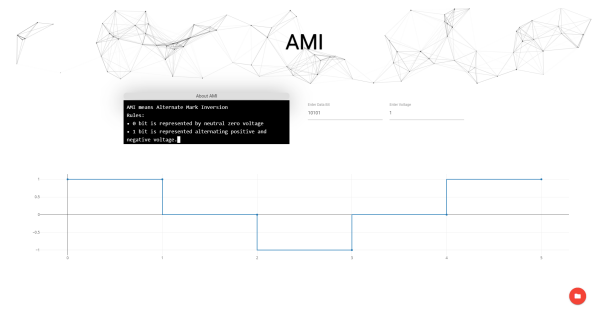


Fig. 15. AMI Experiment Dashboard

### 5.7 PSEUDOTERNARY

#### Explanation

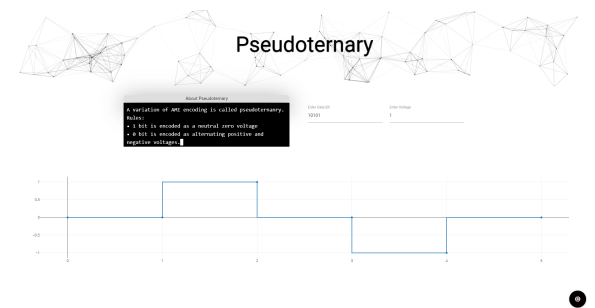


Fig. 16. PSEUDOTERNARY Experiment Dashboard

Our experimentation platform shows massive performance improvements and cross platform compatibility allowing anyone with an internet connection to perform experiments online using a virtual lab experience. It removes the hassle of installing dependencies and configuring a development environment making the platform accessible to everyone. It offers advanced features like live updates and in-browser voltage control while keeping the interface simple and optimized so that it can be used by people who are just starting to venture out in the field of signal encoding.

## 6 CONCLUSION

This project showcase an advanced mechanism for line encoding experimentation. It brings features like cross-platform compatibility, live-updates, dynamic voltage control, modern plotting libraries with granular control of generated graphs and the ability to save results for future use. These advanced features are presented in a simplistic manner to make them simple and accessible by everyone. The platform takes the leanings from various previous works and creates a culmination of these to offer a modern experimentation platform that is available virtually.

## ACKNOWLEDGMENTS

The authors would like to thank...

## REFERENCES

- [1] H. Kopka and P. W. Daly, *A Guide to L<sup>A</sup>T<sub>E</sub>X*, 3rd ed. Harlow, England: Addison-Wesley, 1999.