

# 9.3.11

EE24BTECH11024 - G. Abhimanyu Koushik

## Question:

Solve the differential equation  $\frac{d^2y}{dx^2} + 1 = 0$  with initial conditions  $y(0) = 0$  and  $y'(0) = 0$

## Solution:

Variable	Description
$c_1$	First Integration constant
$c_2$	Second Integration constant
$n$	Order of given differential equation
$a_i$	Coefficient of $i$ th derivative of the function in the equation
$c$	constant in the equation
$y^i$	$i$ th derivative of given function
$\mathbf{y}(t)$	$\begin{pmatrix} c \\ y(t) \\ y'(t) \\ \vdots \\ y^{n-1}(t) \end{pmatrix}$
$h$	stepsize, taken to be 0.001

TABLE 0: Variables Used

## Theoretical Solution:

Laplace Transform definition

$$\mathcal{L}(f(t)) = \int_0^{\infty} e^{-st} f(t) dt \quad (0.1)$$

Properties of Laplace tranform

$$\mathcal{L}(y'') = s^2 \mathcal{L}(y) - sy(0) - y'(0) \quad (0.2)$$

$$\mathcal{L}(1) = \frac{1}{s} \quad (0.3)$$

$$\mathcal{L}^{-1}\left(\frac{2}{s^3}\right) = x^2 \quad (0.4)$$

$$\mathcal{L}(cf(t)) = c\mathcal{L}(f(t)) \quad (0.5)$$

Applying the properties to the given equation

$$y'' + 1 = 0 \quad (0.6)$$

$$\mathcal{L}(y'') + \mathcal{L}(1) = 0 \quad (0.7)$$

$$s^2 \mathcal{L}(y) - sy'(0) - y'(0) + \frac{1}{s} = 0 \quad (0.8)$$

$$(0.9)$$

Substituting the initial conditions gives

$$s^3 \mathcal{L}(y) + 1 = 0 \quad (0.10)$$

$$\mathcal{L}(y) = \frac{-1}{s^3} \quad (0.11)$$

$$y = \mathcal{L}^{-1}\left(\frac{-1}{s^3}\right) \quad (0.12)$$

$$y = \frac{-1}{2} \mathcal{L}^{-1}\left(\frac{2}{s^3}\right) \quad (0.13)$$

$$y = \frac{-1}{2} s^2 \quad (0.14)$$

The theoretical solution is

$$f(x) = \frac{-x^2}{2} \quad (0.15)$$

Computational Solution:

Consider the given linear differential equation

$$a_n y^n + a_{n-1} y^{n-1} + \dots + a_1 y' + a_0 y + c = 0 \quad (0.16)$$

Then

$$y'(t) = \lim_{h \rightarrow 0} \frac{y(t+h) - y(t)}{h} \quad (0.17)$$

$$y(t+h) = y(t) + hy'(t) \quad (0.18)$$

Similarly

$$y^i(t+h) = y^i(t) + hy^{i+1}(t) \quad (0.19)$$

$$y^{n-1}(t+h) = y^{n-1}(t) + hy^n(t) \quad (0.20)$$

$$y^{n-1}(t+h) = y^{n-1}(t) + h \left( -\frac{a_{n-1}}{a_n} y^{n-1} - \frac{a_{n-2}}{a_n} y^{n-2} - \dots - \frac{a_0}{a_n} y - \frac{c}{a_n} \right) \quad (0.21)$$

Where i ranges from 0 to  $n-1$

$$\mathbf{y}(t+h) = \mathbf{y}(t) + \begin{pmatrix} 0 & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 \\ -\frac{1}{a_n} & -\frac{a_0}{a_n} & -\frac{a_1}{a_n} & -\frac{a_2}{a_n} & \dots & -\frac{a_{n-2}}{a_n} & -\frac{a_{n-1}}{a_n} \end{pmatrix} (h\mathbf{y}(t)) \quad (0.22)$$

$$\mathbf{y}(t+h) = \begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & h & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & h & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 & h \\ -\frac{h}{a_n} & -\frac{a_0h}{a_n} & -\frac{a_1h}{a_n} & -\frac{a_2h}{a_n} & \dots & -\frac{a_{n-2}h}{a_n} & 1 - \frac{a_{n-1}h}{a_n} \end{pmatrix} (\mathbf{y}(t)) \quad (0.23)$$

Discretizing the steps gives us

$$\mathbf{y}_{k+1} = \begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & h & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & h & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 & h \\ -\frac{h}{a_n} & -\frac{a_0h}{a_n} & -\frac{a_1h}{a_n} & -\frac{a_2h}{a_n} & \dots & -\frac{a_{n-2}h}{a_n} & 1 - \frac{a_{n-1}h}{a_n} \end{pmatrix} (\mathbf{y}_k) \quad (0.24)$$

where  $k$  ranges from 0 to number of data points with  $y_0^i$  being the given initial condition

and vector  $\mathbf{y}_0 = \begin{pmatrix} c \\ y(0) \\ y'(0) \\ \vdots \\ y^{n-1}(0) \end{pmatrix}$

For the given question

$$\mathbf{y}_{k+1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & h \\ -h & 0 & 1 \end{pmatrix} \mathbf{y}_k \quad (0.25)$$

Record the  $y_k$  for

$$x_k = \text{lowerbound} + kh \quad (0.26)$$

and then plot the graph. The result will be as given below.

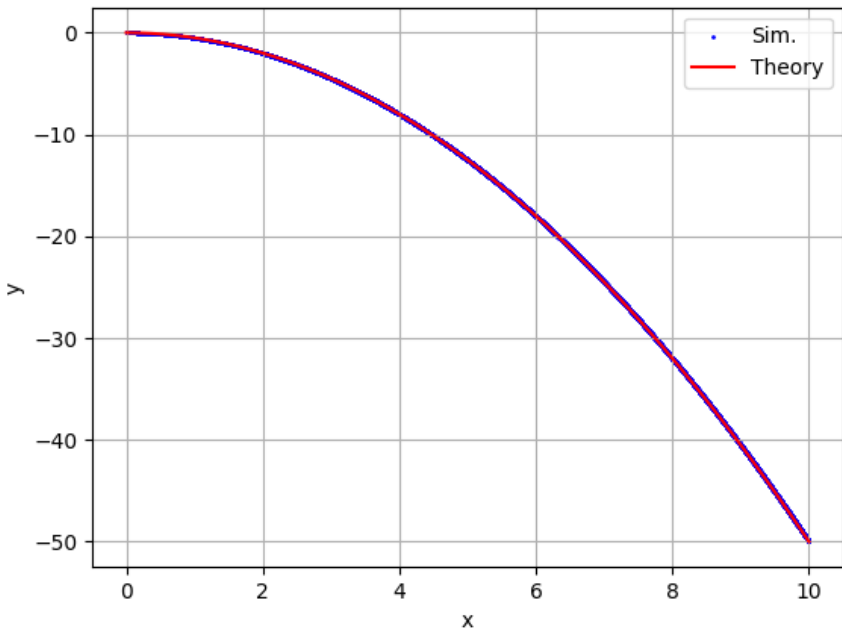


Fig. 0.1: Comparison between the Theoretical solution and Computational solution