

9.3.11.1

EE24BTECH11042 - M.SRUJANA

Question:

Solve the differential equation $\frac{d^2y}{dx^2} = -y$ with initial conditions $y(0) = 1$ and $y'(0) = 0$

Solution:

Theoretical Solution:

Laplace Transform definition

$$\mathcal{L}(f(t)) = \int_0^{\infty} e^{-st} f(t) dt \quad (0.1)$$

Properties of Laplace Transform:

$$\mathcal{L}(y'') = s^2 \mathcal{L}(y) - sy(0) - y'(0) \quad (0.2)$$

$$\mathcal{L}(1) = \frac{1}{s} \quad (0.3)$$

$$\mathcal{L}(cf(t)) = c\mathcal{L}(f(t)) \quad (0.4)$$

$$\mathcal{L}(e^{at} f(t)) = F(s - a) \quad (0.5)$$

Applying the Laplace Transform to the differential equation:

$$y'' + y = 0 \quad (0.6)$$

$$\mathcal{L}(y'') + \mathcal{L}(y) = 0 \quad (0.7)$$

$$s^2 \mathcal{L}(y) - sy(0) - y'(0) + \mathcal{L}(y) = 0 \quad (0.8)$$

Substitute the initial conditions:

$$(s^2 + 1)\mathcal{L}(y) = s \quad (0.9)$$

$$\mathcal{L}(y) = \frac{s}{s^2 + 1} \quad (0.10)$$

$$\mathcal{L}(y) = \frac{1}{2} \left(\frac{1}{s+i} + \frac{1}{s-i} \right) \quad (0.11)$$

Taking the inverse Laplace transform:

$$y = \frac{1}{2} (e^{ix} + e^{-ix}) \quad (0.12)$$

$$y = \cos(x) \quad (0.13)$$

So, the theoretical solution is:

$$y(x) = \cos(x) \quad (0.14)$$

Now, we will find the difference equation using the Bilinear Z-transform.

Using the substitution for s :

$$s = \frac{2}{T} \left(\frac{1 - z^{-1}}{1 + z^{-1}} \right) \quad (0.15)$$

Applying this substitution to the Laplace transform expression:

$$Y(z) = \frac{1}{2} \left(\frac{T(1 + z^{-1})}{2(1 - z^{-1}) + T(1 + z^{-1})} + \frac{T(1 + z^{-1})}{2(1 - z^{-1}) - T(1 + z^{-1})} \right) \quad (0.16)$$

Simplify the expression:

$$Y(z) = \frac{T(1 + z^{-1})}{2(1 - z^{-1}) + T(1 + z^{-1})} - \frac{T(1 + z^{-1})}{2(1 - z^{-1}) - T(1 + z^{-1})} \quad (0.17)$$

Define the constants:

$$\alpha_1 = -\frac{T - 2}{T + 2} \quad (0.18)$$

$$\alpha_2 = -\frac{T + 2}{T - 2} \quad (0.19)$$

Thus, we have:

$$Y(z) = \frac{T}{2(T + 2)} \left(\frac{1}{1 - \alpha_1 z^{-1}} + \frac{z^{-1}}{1 - \alpha_1 z^{-1}} \right) - \frac{T}{2(T - 2)} \left(\frac{1}{1 - \alpha_2 z^{-1}} + \frac{z^{-1}}{1 - \alpha_2 z^{-1}} \right) \quad (0.20)$$

The radius of convergence is given by:

$$\text{Radius of convergence} = \max(|\alpha_1|, |\alpha_2|) \quad (0.21)$$

Finally, apply the inverse Z-transform:

$$(1 - \alpha_1 z^{-1})(1 - \alpha_2 z^{-1})Y(z) = \frac{T}{2} \left(\frac{1 - (\alpha_2 - 1)z^{-1} - \alpha_2 z^{-2}}{T + 2} - \frac{1 - (\alpha_1 - 1)z^{-1} - \alpha_1 z^{-2}}{T - 2} \right) \quad (0.22)$$

Rearrange to get the difference equation:

$$y_{n+2} - (\alpha_1 + \alpha_2)y_{n+1} + y_n = \frac{T}{2} \left(\frac{\alpha_1}{T - 2} - \frac{\alpha_2}{T + 2} \right) \delta(n) \quad (0.23)$$

Now, moving to the computational solution, discretize the equation using the trapezoidal rule:

$$y_{k+1} - y_k = \frac{h}{2} (y'_k + y'_{k+1}) \quad (0.24)$$

$$y'_{k+1} - y'_k = \frac{h}{2} (y_k + y_{k+1}) \quad (0.25)$$

Solve for y_{k+1} and y'_{k+1} :

$$y_{k+1} = \frac{(y_k)(4 + h^2) + 4hy'_k}{4 - h^2} \quad (0.26)$$

$$y'_{k+1} = \frac{(y'_k)(4 + h^2) + 4hy_k}{4 - h^2} \quad (0.27)$$

Use these difference equations to compute the values of y and y' at each step and plot the results. The figure below compares the theoretical and computational solutions. Comparison between the theoretical solution and computational solutions.

