

Dimension Reduction

CS 760@UW-Madison



Goals for the lecture



you should understand the following concepts

- dimension reduction
- principal component analysis: definition and formulation
- two interpretations
- strength and weakness

Big & High-Dimensional Data



- High-Dimensions = Lot of Features

Document classification

Features per document =
thousands of words/unigrams
millions of bigrams, contextual
information



Surveys - Netflix

480189 users x 17770 movies

	movie 1	movie 2	movie 3	movie 4	movie 5	movie 6
Tom	5	?	?	1	3	?
George	?	?	3	1	2	5
Susan	4	3	1	?	5	1
Beth	4	3	?	2	4	2

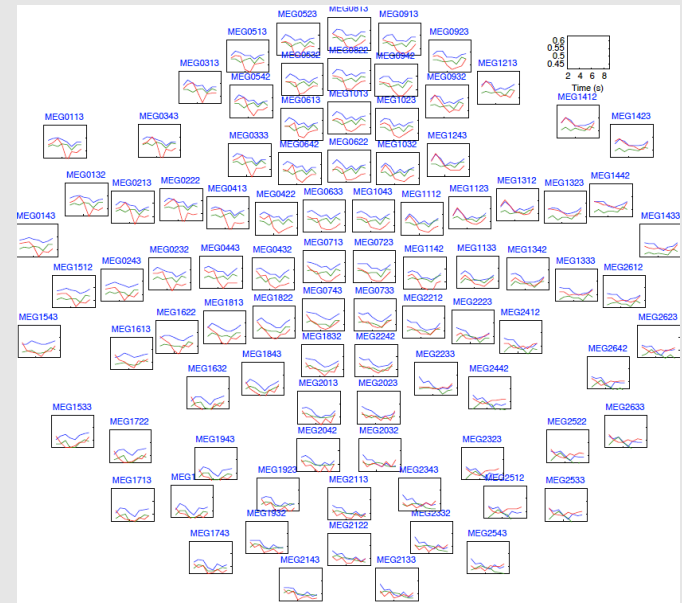
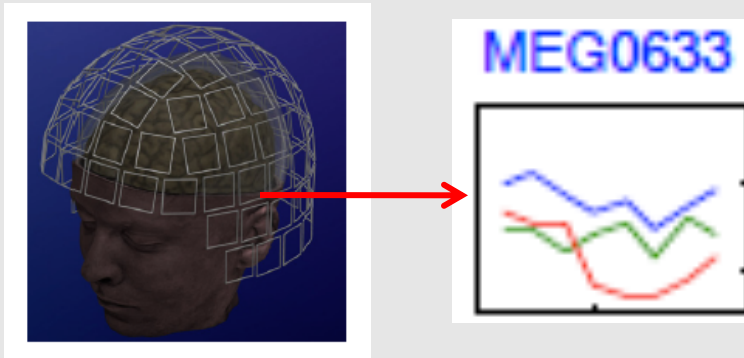
Big & High-Dimensional Data



- High-Dimensions = Lot of Features

MEG Brain Imaging

120 locations x 500 time points
x 20 objects



Or any high-dimensional image data



- Big & High-Dimensional Data.
- Useful to learn lower dimensional representations of the data.

Learning Representations

PCA, Kernel PCA, ICA: Powerful unsupervised learning techniques for extracting hidden (potentially lower dimensional) structure from high dimensional datasets.

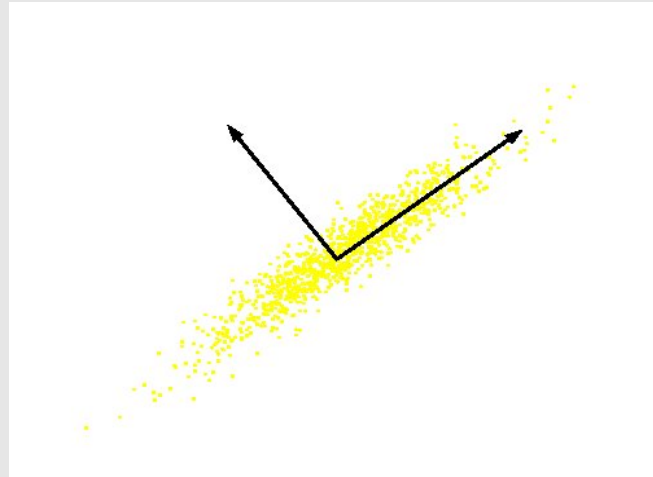
Useful for:

- Visualization
- More efficient use of resources (e.g., time, memory, communication)
- Statistical: fewer dimensions → better generalization
- Noise removal (improving data quality; but: see later)
- Further processing by machine learning algorithms

Principal Component Analysis (PCA)



What is PCA: Unsupervised technique for extracting variance structure from high dimensional datasets.

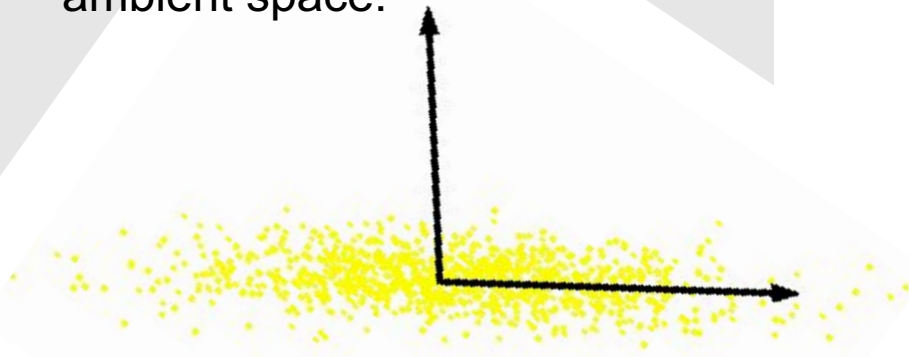


- PCA is an orthogonal projection or transformation of the data into a (possibly lower dimensional) subspace so that the variance of the projected data is maximally retained.

Principal Component Analysis (PCA)

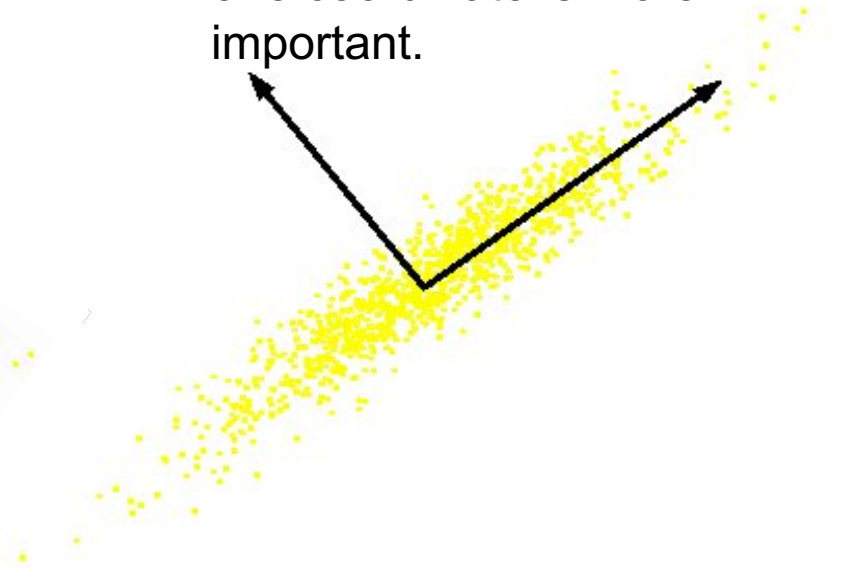


Intrinsically lower dimensional
than the dimension of the
ambient space.



Only one relevant feature

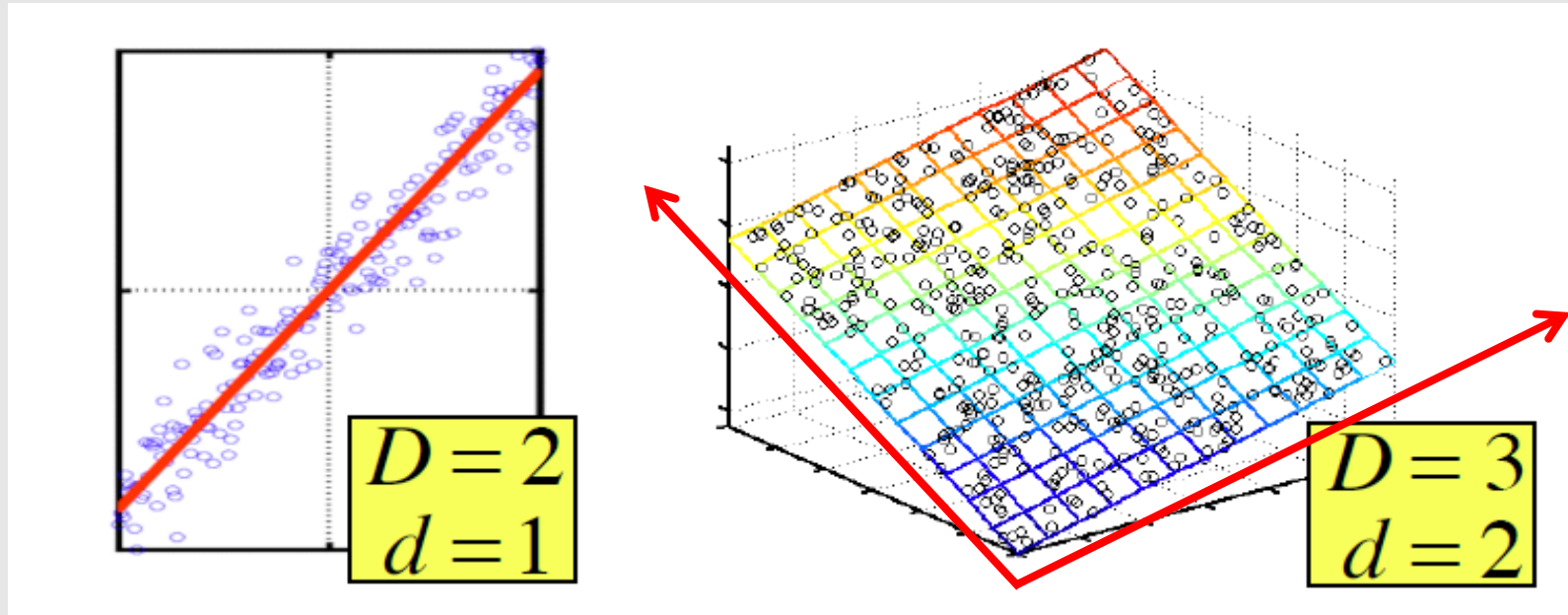
If we rotate data, again only
one coordinate is more
important.



Both features are relevant

Question: Can we transform the features so that we only need to
preserve one latent feature?

Principal Component Analysis (PCA)



In case where data lies on or near a low d -dimensional linear subspace, axes of this subspace are an effective representation of the data.

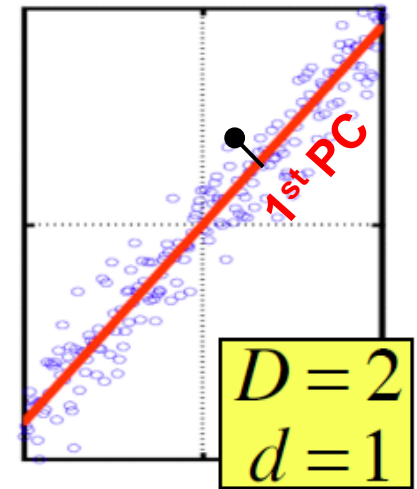
Identifying the axes is known as [Principal Components Analysis](#), and can be obtained by using classic matrix computation tools (Eigen or Singular Value Decomposition).

Principal Component Analysis (PCA)



Principal Components (PC) are orthogonal directions that capture most of the variance in the data.

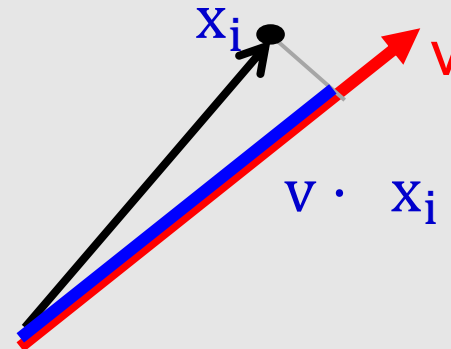
- First PC – direction of greatest variability in data.
- Projection of data points along first PC discriminates data most along any one direction (pts are the most spread out when we project the data on that direction compared to any other directions).



Quick reminder:

$\|v\|=1$, Point x_i (D-dimensional vector)

Projection of x_i onto v is $v \cdot x_i$

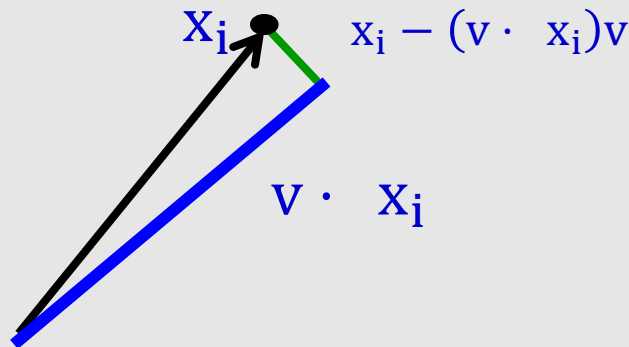


Principal Component Analysis (PCA)



Principal Components (PC) are orthogonal directions that capture most of the variance in the data.

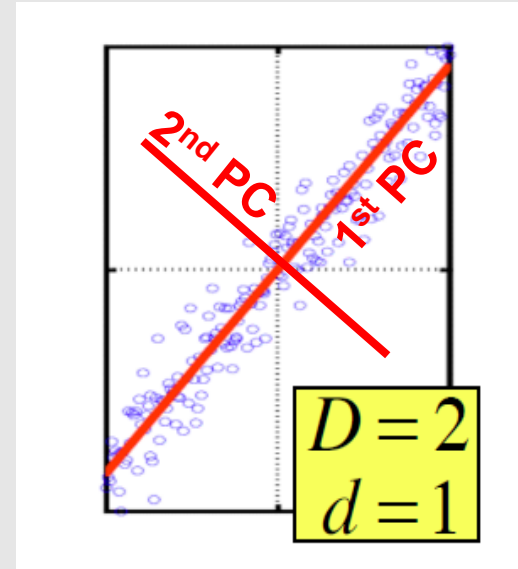
- 1st PC – direction of greatest variability in data.



- 2nd PC – Next orthogonal direction of greatest variability

(remove all variability in first direction, then find next direction of greatest variability)

- And so on ...



Principal Component Analysis (PCA)



Let $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_d$ denote the d principal components.

$$\mathbf{v}_i \cdot \mathbf{v}_j = 0, i \neq j \quad \text{and} \quad \mathbf{v}_i \cdot \mathbf{v}_i = 1, i = j$$

Assume data is centered (we subtracted the sample mean).

Let $\mathbf{X} = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n]$ (columns are the datapoints)

Find vector that maximizes sample variance of projected data

$$\sum_{i=1}^n (\mathbf{v}^T \mathbf{x}_i)^2 = \mathbf{v}^T \mathbf{X} \mathbf{X}^T \mathbf{v}$$

$$\max_{\mathbf{v}} \mathbf{v}^T \mathbf{X} \mathbf{X}^T \mathbf{v} \quad \text{s.t.} \quad \mathbf{v}^T \mathbf{v} = 1$$

$$\text{Lagrangian: } \max_{\mathbf{v}} \mathbf{v}^T \mathbf{X} \mathbf{X}^T \mathbf{v} - \lambda \mathbf{v}^T \mathbf{v}$$

Wrap constraints into the objective function

$$\partial / \partial \mathbf{v} = 0$$

$$(\mathbf{X} \mathbf{X}^T - \lambda \mathbf{I}) \mathbf{v} = 0$$

$$\Rightarrow (\mathbf{X} \mathbf{X}^T) \mathbf{v} = \lambda \mathbf{v}$$

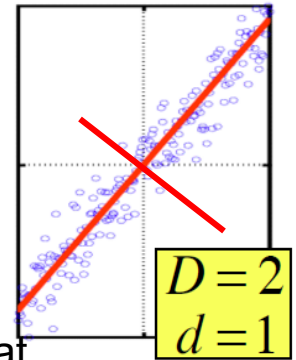
Principal Component Analysis (PCA)



$(X X^T) \mathbf{v} = \lambda \mathbf{v}$, so \mathbf{v} (the first PC) is the eigenvector of sample correlation/covariance matrix $X X^T$

Sample variance of projection $\mathbf{v}^T X X^T \mathbf{v} = \lambda \mathbf{v}^T \mathbf{v} = \lambda$

Thus, the eigenvalue λ denotes the amount of variability captured along that dimension (aka amount of energy along that dimension).



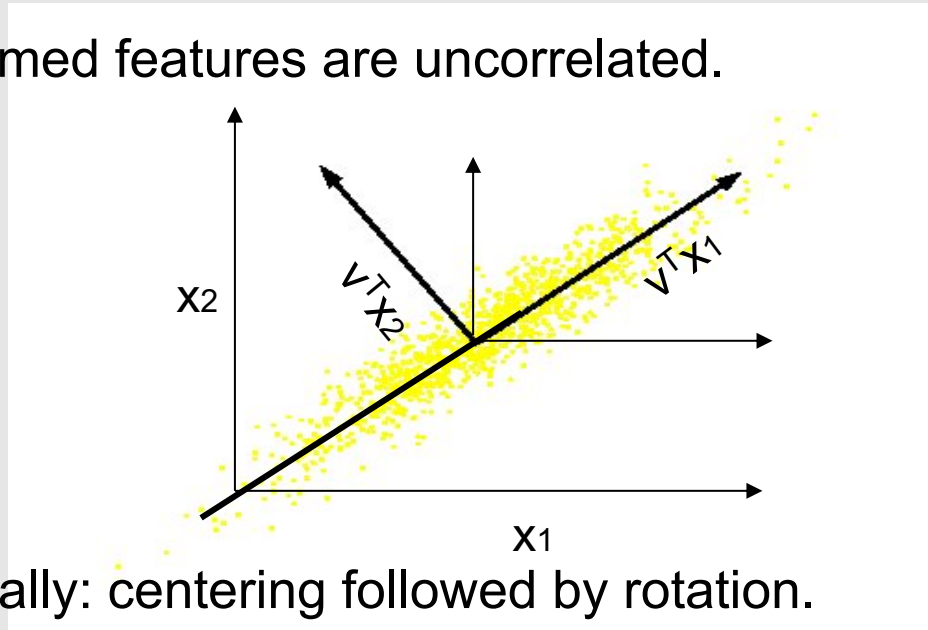
Eigenvalues $\lambda_1 \geq \lambda_2 \geq \lambda_3 \geq \dots$

- The 1st PC \mathbf{v}_1 is the eigenvector of the sample covariance matrix $X X^T$ associated with the largest eigenvalue
- The 2nd PC \mathbf{v}_2 is the eigenvector of the sample covariance matrix $X X^T$ associated with the second largest eigenvalue
- And so on ...

Principal Component Analysis (PCA)



- So, the new axes are the eigenvectors of the matrix of sample correlations $X X^T$ of the data.
- Transformed features are uncorrelated.



- Geometrically: centering followed by rotation.
 - Linear transformation

Key computation: eigendecomposition of XX^T : $XX^T = \sum_{i=1}^D \lambda_i v_i v_i^T$ (closely related to SVD of X : $X = U \Sigma W^T$).



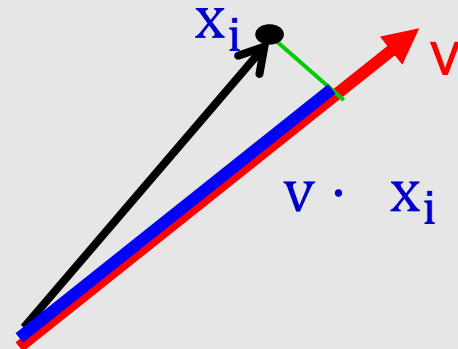
Two Interpretations

So far: **Maximum Variance Subspace**. PCA finds vectors \mathbf{v} such that projections on to the vectors retains maximum variance in the data

$$\sum_{i=1}^n (\mathbf{v}^T \mathbf{x}_i)^2 = \mathbf{v}^T \mathbf{X} \mathbf{X}^T \mathbf{v}$$

Alternative viewpoint: **Minimum Reconstruction Error**. PCA finds vectors \mathbf{v} such that projection on to the vectors yields minimum MSE reconstruction

$$\sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{v}^T \mathbf{x}_i) \mathbf{v}\|^2$$



Two Interpretations



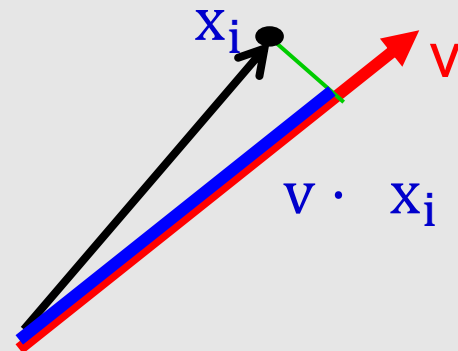
E.g., for the first component.

Maximum Variance Direction: 1st PC a vector \mathbf{v} such that projection on to this vector capture maximum variance in the data (out of all possible one dimensional projections)

$$\sum_{i=1}^n (\mathbf{v}^T \mathbf{x}_i)^2 = \mathbf{v}^T \mathbf{X} \mathbf{X}^T \mathbf{v}$$

Minimum Reconstruction Error: 1st PC a vector \mathbf{v} such that projection on to this vector yields minimum MSE reconstruction

$$\sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{v}^T \mathbf{x}_i) \mathbf{v}\|^2$$





Why? Pythagorean Theorem

E.g., for the first component.

Maximum Variance Direction: 1st PC a vector \mathbf{v} such that projection on to this vector capture maximum variance in the data (out of all possible one dimensional projections)

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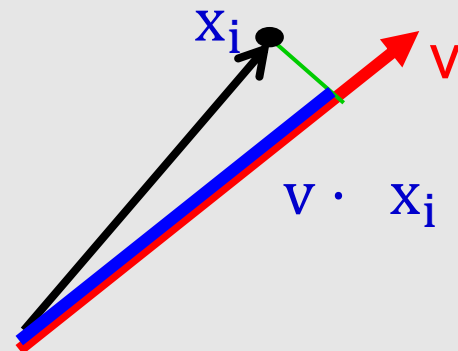
$$\sum_{i=1}^n \|\mathbf{x}_i - (\mathbf{v}^T \mathbf{x}_i) \mathbf{v}\|^2$$

Minimum Reconstruction Error: 1st PC a vector \mathbf{v} such that projection on to this vector yields minimum MSE reconstruction

$$\text{blue}^2 + \text{green}^2 = \text{black}^2$$

black² is fixed (it's just the data)

So, maximizing blue² is equivalent to minimizing green²



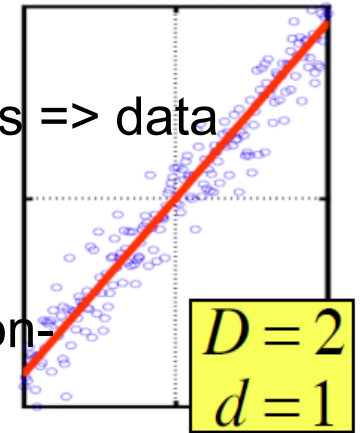
Dimensionality Reduction using PCA



The eigenvalue λ denotes the amount of variability captured along that dimension (aka amount of energy along that dimension).

Zero eigenvalues indicate no variability along those directions => data lies exactly on a linear subspace

Only keep data projections onto principal components with non-zero eigenvalues, say v_1, \dots, v_k , where $k = \text{rank}(X X^T)$



Original representation

Data point

$$x_i = (x_i^1, \dots, x_i^D)$$

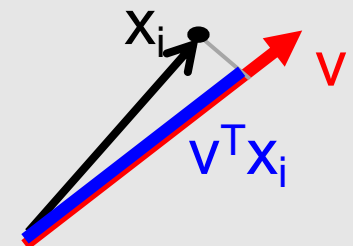
D-dimensional vector

Transformed representation

projection

$$(v_1 \cdot x_i, \dots, v_d \cdot x_i)$$

d-dimensional vector



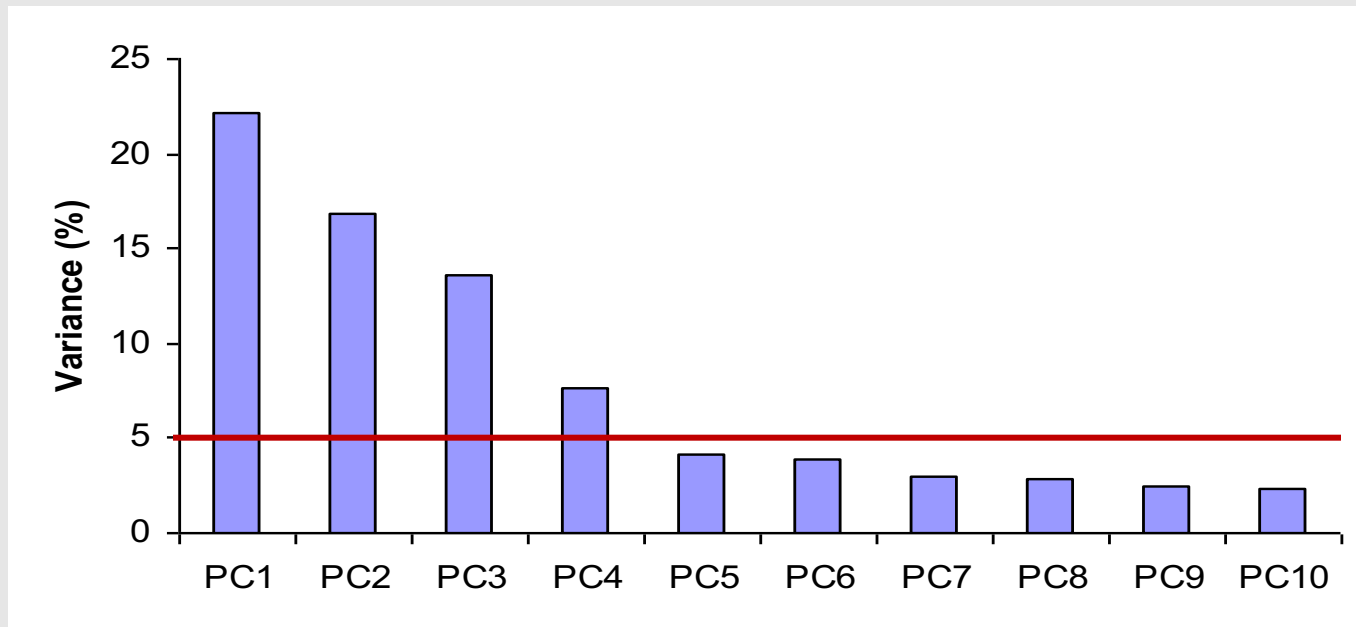
Dimensionality Reduction using PCA



In high-dimensional problems, data sometimes lies near a linear subspace, as noise introduces small variability

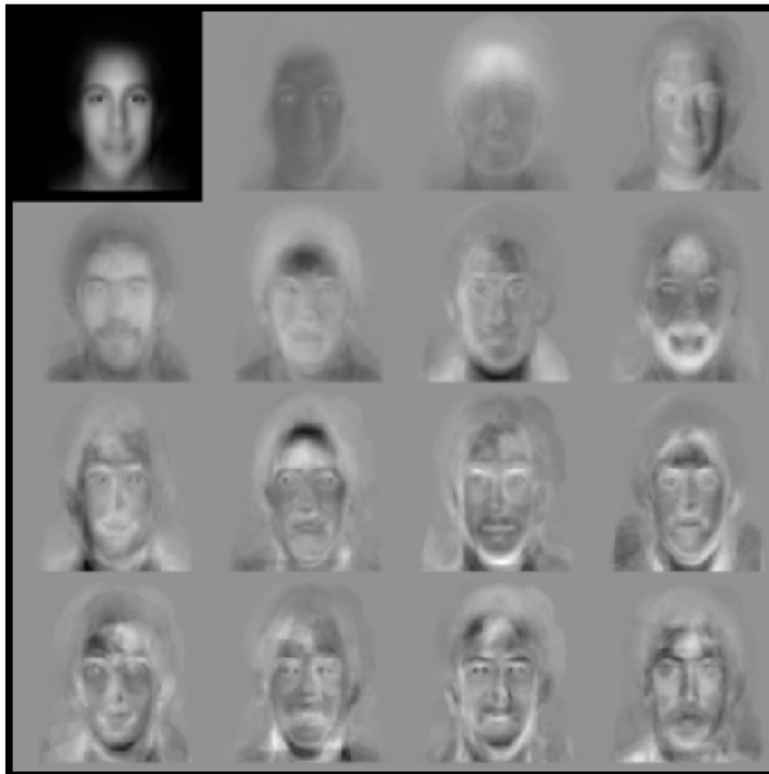
Only keep data projections onto principal components with **large** eigenvalues

Can *ignore* the components of smaller significance.



Might **lose some info**, but if eigenvalues are small, do not lose much

Example: faces



Eigenfaces
from 7562
images:

**top left image
is linear
combination
of rest.**

Sirovich & Kirby (1987)
Turk & Pentland (1991)

Can represent a face image using just 15 numbers!



Strengths

Eigenvector method

No tuning of the parameters

No local optima

Weaknesses

Limited to second order statistics

Limited to linear projections

May not be the correct directions for supervised learning

An aerial photograph of a city harbor at sunset. The sun is low on the horizon, casting a warm, golden glow over the water and the city. Numerous sailboats are scattered across the harbor. The city buildings are visible along the shoreline, and a large hill is in the background.

THANK YOU

Some of the slides in these lectures have been adapted/borrowed from materials developed by Yingyu Liang, Mark Craven, David Page, Jude Shavlik, Tom Mitchell, Nina Balcan, Elad Hazan, Tom Dietterich, and Pedro Domingos.

