


RoadVision

A computer vision based solution for pothole severity estimation

BY TEAM
APEXCODERS



INTRODUCTION

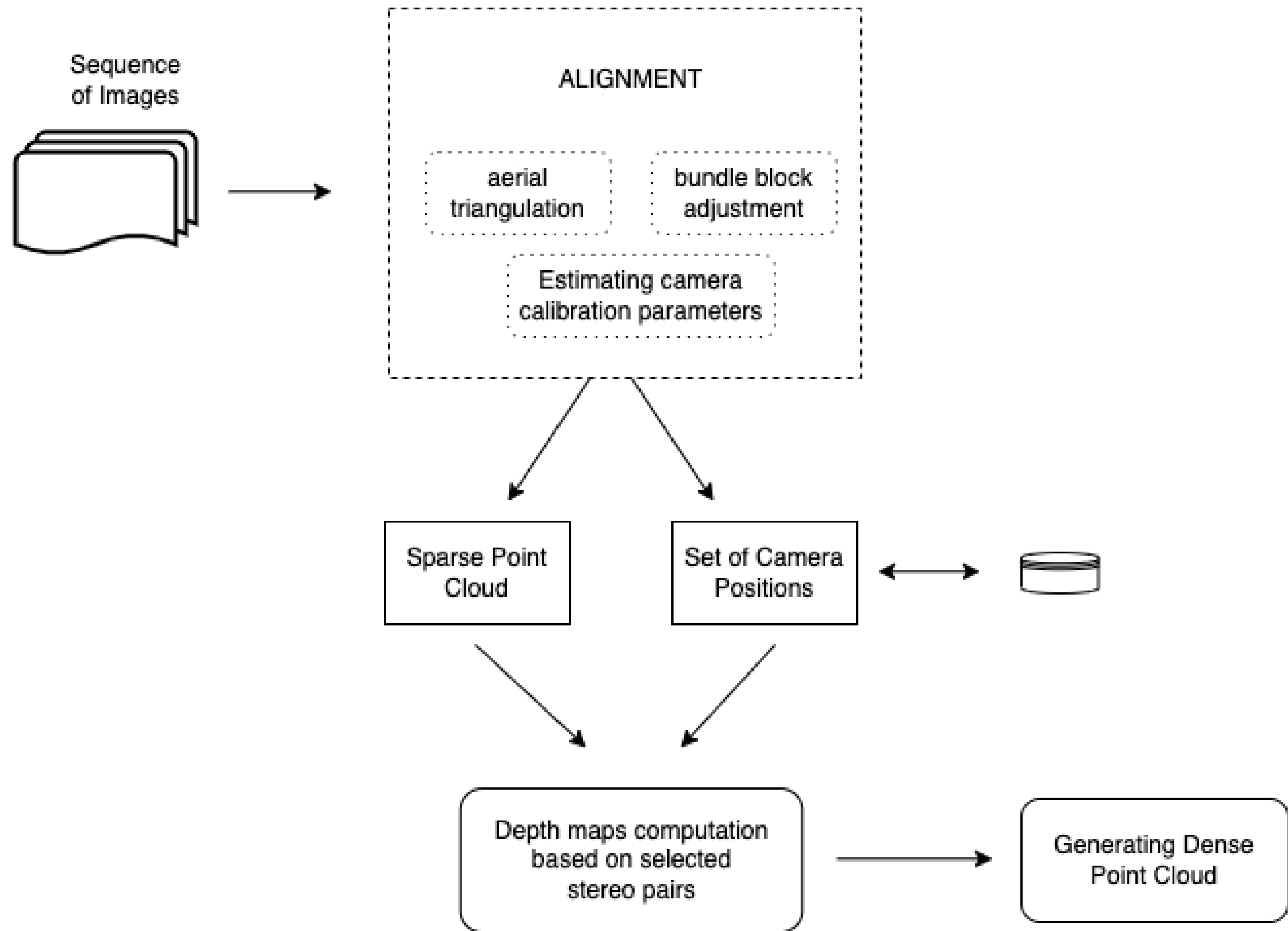
- The current pothole inspection techniques are highly labor-intensive and manual.
 - Our solution is two-fold -
 - a. Assessing the road quality using pothole detection and segmentation.
 - b. Extracting the physical properties of identified potential potholes by performing 3D Reconstruction to estimate their severity.
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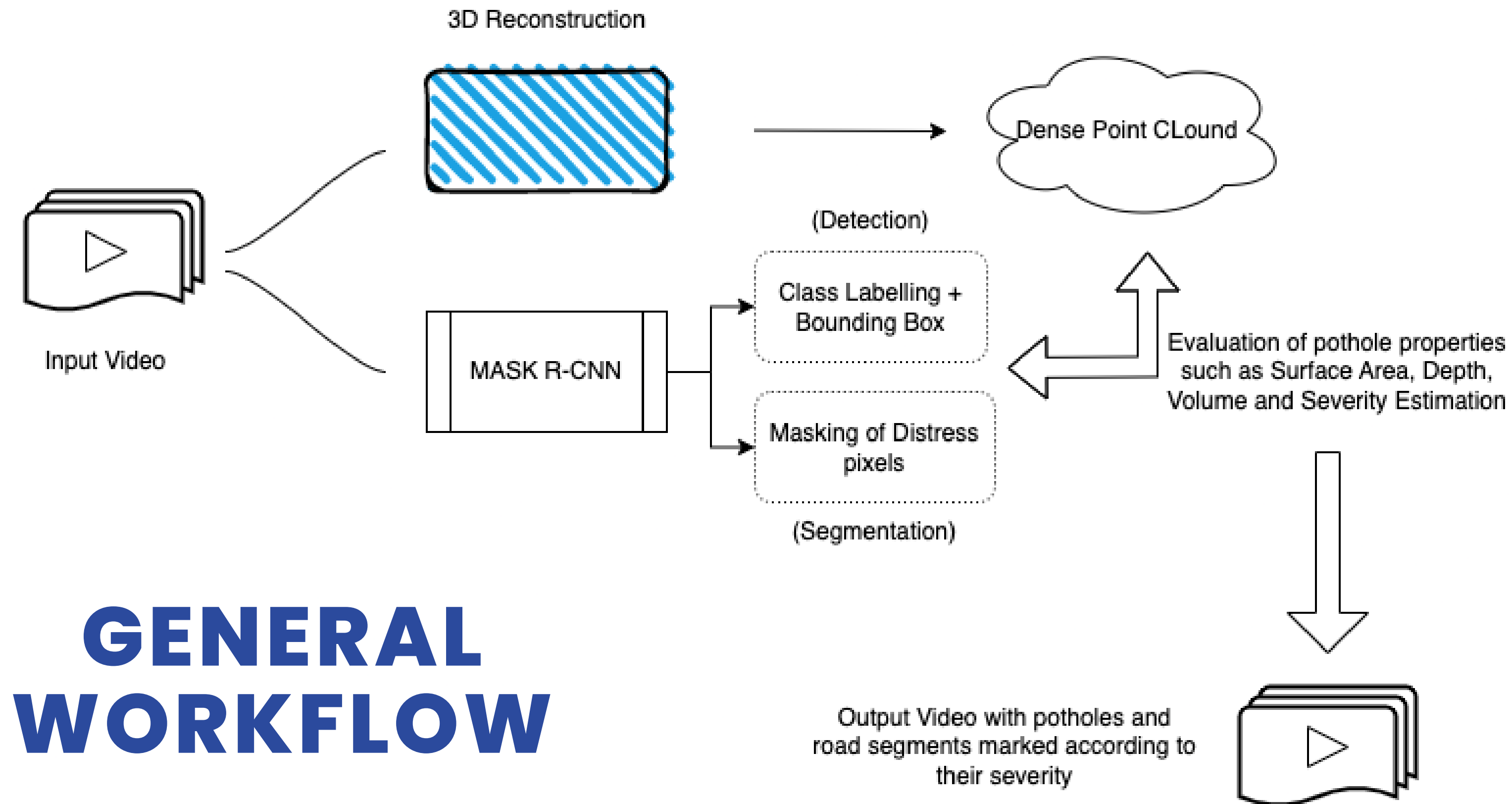
POTHOLE SEGMENTATION

- Mask R-CNN architecture is used which works on top of Faster R-CNN
- The Model was trained on an aggregation of 5 datasets.
- We are able to gain the region and shape of the potholes with an accuracy of 82% which outperforms the YOLO (v5 and v7) models.

3D RECONSTRUCTION


- We have used the Agisoft Metashape software for creating 3D point clouds which executes the following steps: -
 - Alignment
 - Sparse point cloud construction.
 - Dense data point cloud construction.
 - 3D Mesh construction
- We have used python scripts to interact with the tool to automate the process of getting 3D spatial data.







RELEVANCE AND FUTURE SCOPE

- Our solution is capable to be deployed on an edge(eg. NVIDIA Jetson Nano) and thus acts as a stand-alone automated project. In addition, it is highly cost-effective and computationally optimized, and is, therefore, a great alternative to LIDAR-related technologies.
 - This project can easily be scaled to be used with thermal and satellite imagery which is seldom used by city planners.
 - It can also be integrated with Navigation apps (eg. Google maps, Waze, etc.) for better pathfinding, and also help in accident prevention.
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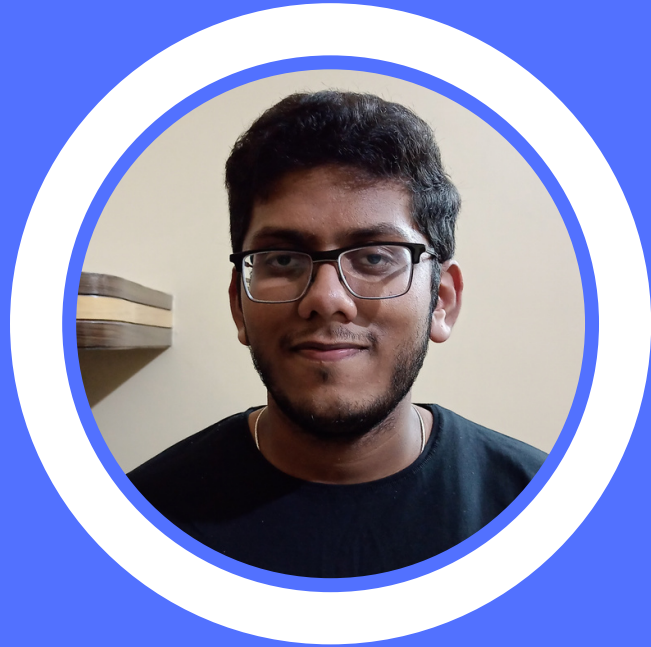
LINKS

1 [Report Link](#)

2 [Colab Notebook Link](#)

3 [GitHub Repo Link](#)

TEAM APEXCODERS



SHIVANKAR PILLIGUNDLA



SRINIVAS MANDA



HARDIK KHANDELWAL



KARANJIT SAHA



NETRADEEPAK CHICHWADKAR



ABHINAV MAHAJAN

THANK YOU

