

Engineering Mathematics-I

KAS-103

Lecture: 5th

Module-II
Vector Calculus

Content: Introduction of vectors and important properties.

Vector calculus is important concept for all Engineering branches. It is used in all Engineering applications.

Vector: - A vector is a quantity which has magnitude and direction. Consider (x, y, z) in a Cartesian co-ordinate system in a space.

$\vec{a} = a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k}$ is a given vector.

with initial point $P(x_1, y_1, z_1)$

and terminal point $Q(x_2, y_2, z_2)$.

then difference $a_1 = x_2 - x_1, a_2 = y_2 - y_1, a_3 = z_2 - z_1$, are called Components of a vector with respect to co-ordinate system.

$|\vec{PQ}| = |\vec{a}|$ = Magnitude of vector.

$$= \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} \quad \text{[distance formula]}$$

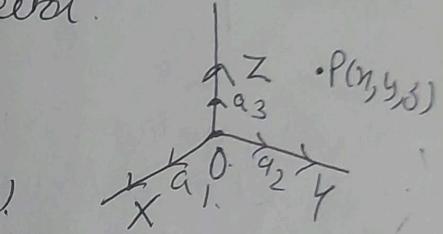
$$= \sqrt{a_1^2 + a_2^2 + a_3^2}.$$

Position Vector: - Let $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$, the

vector with initial point $O(0, 0, 0)$ & terminal point (x, y, z) . denoted as $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$

is called position vector.

\vec{r} has components x, y, z .



Remark:

If \vec{a} is given to a function u

if $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$ is a vector, then $\vec{a} = \nabla u$

if $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$ is a vector, then $\vec{a} = \nabla u$

Properties of Vectors -

1) Dot Product - Dot product of two vectors is a scalar quantity. Consider two vectors $\vec{a} = a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}$ and $\vec{b} = b_1 \vec{i} + b_2 \vec{j} + b_3 \vec{k}$.

$$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$$

as. $[\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = 1, \vec{i} \cdot \vec{j} = \vec{j} \cdot \vec{k} = \vec{k} \cdot \vec{i} = 0]$

2) Cross Product - Cross product of two vectors is always a vector quantity. Consider two vectors $\vec{a} = a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}$ and $\vec{b} = b_1 \vec{i} + b_2 \vec{j} + b_3 \vec{k}$

$$\vec{a} \times \vec{b} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

Scalar function: Scalar function $f(x, y, z)$ is a function defined at each point in certain domain D in space. Its value is real and depends only on the point $P(x, y, z)$ eg.

$$f = xyz, x+y+z=1, x^2+y^2+z^2=1.$$

Vector function: If to each value of variable t , there corresponds a value of vector \vec{r} , \vec{r} is called vector function of variable t denoted by $\vec{r} = \vec{r}(t)$ or $\vec{r} = \vec{f}(t)$.

eg. position vector(\vec{r}) of moving particle is a vector function of time t .

Any vector function can be represented in its components as $\vec{r}(t) = f_1(t) \vec{i} + f_2(t) \vec{j} + f_3(t) \vec{k}$, where $\vec{i}, \vec{j}, \vec{k}$ denotes unit vectors along axis of x, y, z respectively.

gradient of scalar field. - Let $\phi(x, y, z)$ be a scalar point-function and differential operator be $\nabla = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right)$ then gradient of function $\phi(x, y, z)$ is denoted as $\nabla \phi$

$$= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \phi(x, y, z) = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

Thus, ∇ converts scalar point function to a vector point function. grad ϕ is normal to surface.

Remark #. $\nabla \phi = \text{grad } \phi$

$|\text{grad } \phi|$ is rate of change of $\phi(x, y, z)$ in direction of normal.

Properties:-

$$1. \nabla(f \pm g) = \nabla f \pm \nabla g$$

$$2. \nabla(f \cdot g) = g \nabla f + f \nabla g$$

$$3. \nabla(f/g) = \frac{g \nabla f - f \nabla g}{g^2}, g \neq 0$$

4. Gradient of a constant function is always 0
i.e. $\nabla C = 0$, if C is a constant function

Q1 find grad ϕ if $\phi(x, y, z) = 3x^2y - y^3z^2$. Also find grad ϕ at $(1, -2, 1)$

Q2. Let $\phi(x, y, z) = 3x^2y - y^3z^2$.

$$\nabla \phi = \hat{i} \frac{\partial \phi}{\partial x} + \hat{j} \frac{\partial \phi}{\partial y} + \hat{k} \frac{\partial \phi}{\partial z}$$

$$\nabla \phi = 6xy \hat{i} + (3x^2 - 3y^2z^2) \hat{j} - 2y^3z \hat{k}$$

$$[\nabla \phi]_{(1, -2, 1)} = -12 \hat{i} + [3 - 12] \hat{j} - (-8) \hat{k} = -12 \hat{i} - 9 \hat{j} + 8 \hat{k}$$

$$= \hat{i}(0-0) - \hat{j}(9) + \hat{k}(8)$$

2015, BQ: If $u = x + y + 3$, $v = x^2 + y^2 + z^2$, $w = yz + 3x + 2y$, prove that $\text{grad } u$, $\text{grad } v$ and $\text{grad } w$ are

sol. To prove vectors are co-planar we have to prove $\vec{a} \cdot (\vec{b} \times \vec{c}) = 0$.

$$\vec{a} = \text{grad } u = \hat{i} + \hat{j} + \hat{k}$$

$$\vec{b} = \text{grad } v = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\vec{c} = \text{grad } w = (yz)\hat{i} + (z+x)\hat{j} + (x+y)\hat{k}$$

$$\vec{a} \cdot \vec{b} \times \vec{c} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 2x & 2y & 2z \\ x+y & x+2y & x+2y \end{vmatrix}$$

$$\begin{matrix} R_1 + R_2 + R_3 & \Rightarrow \\ (x+y) & \begin{vmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ x+y & x+2y & x+2y \end{vmatrix} = 0 & \end{matrix} \quad [\because R_1 = R_2]$$

∴ Vectors are co-planar.

Hence $\text{grad } u$, $\text{grad } v$, $\text{grad } w$ are co-planar.

2014 Q. find a unit vector normal to surface $x^3 + y^3 + 3xyz = 3$ at the point $(1, 2, -1)$

sol. Normal vector to surface $= \nabla \varphi$

$$\text{Here } \varphi = x^3 + y^3 + 3xyz - 3$$

$$\nabla \varphi = (3x^2 + 3yz)\hat{i} + (3y^2 + 3xz)\hat{j} + 3xy\hat{k}$$

$$\begin{aligned} [\nabla \varphi]_{(1, 2, -1)} &= (3-6)\hat{i} + [12-3]\hat{j} + 6\hat{k} \\ &= -3\hat{i} + 9\hat{j} + 6\hat{k} \end{aligned}$$

$$\begin{aligned} \text{unit normal vector} &= \frac{\nabla \varphi}{|\nabla \varphi|} = \frac{-3\hat{i} + 9\hat{j} + 6\hat{k}}{\sqrt{9+81+36}} \\ &= \frac{-3\hat{i} + 9\hat{j} + 6\hat{k}}{3\sqrt{14}} = \frac{-1+3\hat{j}+2\hat{k}}{\sqrt{14}} \end{aligned}$$

~~Now~~ $\nabla \varphi$ is \vec{u}

given to de
relation $d\varphi =$

2014 Q. If $\vec{r} = \vec{x}$
curl $\vec{r} =$

Content: Gradient, Normal unit vector, Tangent, Tangent and Normal, Directional derivative.

Gradient -

1) Prove that $\nabla\left(\frac{f}{g}\right) = \frac{g\nabla f - f\nabla g}{g^2}$, $g \neq 0$.

$$\nabla\left(\frac{f}{g}\right) = \nabla\left(fg^{-1}\right)$$

$$= \left[\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right] (fg^{-1})$$

$$= \hat{i} \frac{\partial}{\partial x} (fg^{-1}) + \hat{j} \frac{\partial}{\partial y} (fg^{-1}) + \hat{k} \left(\frac{\partial}{\partial z} \right) (fg^{-1})$$

$$= \hat{i} \left[f \left(-1g^{-2} \frac{\partial g}{\partial x} \right) + g^{-1} \frac{\partial f}{\partial x} \right] + \hat{j} \left[f \left(-1g^{-2} \frac{\partial g}{\partial y} \right) + g^{-1} \frac{\partial f}{\partial y} \right] + \hat{k} \left[f \left(-1g^{-2} \frac{\partial g}{\partial z} \right) + g^{-1} \frac{\partial f}{\partial z} \right]$$

$$= \frac{g\nabla f - f\nabla g}{g^2}, g \neq 0$$

Normal Unit vector - Let $\varphi(x, y, z)$ be scalar point function, then unit vector denotes as $\hat{n} = \frac{\nabla\varphi}{|\nabla\varphi|}$.
is called normal unit vector $\because |\hat{n}| = 1$.

Remark If φ is a scalar point function $\nabla\varphi$ is a vector point function. If $\nabla\varphi$ is given to determine φ we have to use relation $d\varphi = \vec{F} \cdot d\vec{r}$.
where $\vec{F} = \nabla\varphi$.

$$\sqrt{16+4+16} = \sqrt{36} = 6$$

Rotational
point fu

Q. If $\nabla \phi = (y^2 - 2xyz^3) \mathbf{i} + (3 + 2xy - x^2z^3) \mathbf{j} + 16z \mathbf{k}$ find ϕ .

Sol. Let $\vec{F} = \nabla \phi$.

$$\vec{F} \cdot d\vec{r} = \left(\frac{\partial \phi}{\partial x} \mathbf{i} + \frac{\partial \phi}{\partial y} \mathbf{j} + \frac{\partial \phi}{\partial z} \mathbf{k} \right) \cdot (dx \mathbf{i} + dy \mathbf{j} + dz \mathbf{k})$$

$$\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz = d\phi. \quad [\text{Total derivative}]$$

$$d\phi = (y^2 - 2xyz^3) dx + (3 + 2xy - x^2z^3) dy + (6z^3 - 3x^2y) dz$$

Integrating with respect to 'x', treating y, z as c.

$$\phi = xy^2 - x^2yz^3 + C_1$$

$$\phi = 3y + 2xy^2 - x^2z^3y + C_2 \quad [\text{Term 'y'}]$$

$$\phi = \frac{6z^4}{4} - x^2yz^3 + C_3 \quad [\text{Term 'z'}]$$

$$\therefore \phi = xy^2 - x^2yz^3 + 3y + \frac{3}{2}z^4 + C, \text{ c is constant.}$$

Q. If $\vec{r} = x \mathbf{i} + y \mathbf{j} + z \mathbf{k}$. show that $\text{grad} \vec{r} = \frac{\vec{r}}{r}$.

$$\text{Sol. grad} \vec{r} = i \frac{\partial r}{\partial x} + j \frac{\partial r}{\partial y} + k \frac{\partial r}{\partial z}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

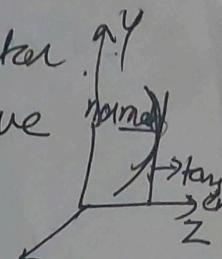
$$r^2 = x^2 + y^2 + z^2.$$

$$\frac{\partial r}{\partial x} = \frac{x}{r}$$

$$\frac{\partial r}{\partial y} = \frac{y}{r}, \quad \frac{\partial r}{\partial z} = \frac{z}{r}$$

$$\text{Hence grad} \vec{r} = \frac{x}{r} \mathbf{i} + \frac{y}{r} \mathbf{j} + \frac{z}{r} \mathbf{k} = \frac{\vec{r}}{r} \quad \text{Hence proved.}$$

163. Tangent and Normal plane The gradient vector ∇f if (x_0, y_0, z_0) is orthogonal to the level curve $f(x, y, z) = k$ at the point (x_0, y_0, z_0) .



Eqn of tangent plane to the surface $f(x, y, z) = k$ at point (x_0, y_0, z_0) is.

$$(x - x_0) \left(\frac{\partial f}{\partial x} \right)_{(x_0, y_0, z_0)} + (y - y_0) \left(\frac{\partial f}{\partial y} \right)_{(x_0, y_0, z_0)} + (z - z_0) \left(\frac{\partial f}{\partial z} \right)_{(x_0, y_0, z_0)} = 0$$

Eqn of Normal plane to the surface is.

$$\frac{\left(\frac{\partial f}{\partial x} \right)_{(x_0, y_0, z_0)}}{x - x_0} = \frac{\left(\frac{\partial f}{\partial y} \right)_{(x_0, y_0, z_0)}}{y - y_0} = \frac{\left(\frac{\partial f}{\partial z} \right)_{(x_0, y_0, z_0)}}{z - z_0}$$

a. $\vec{x}(t) = (x_0, y_0, z_0) + t \nabla f(x_0, y_0, z_0)$

Q. find the tangent plane and normal line to

$$x^2 + y^2 + z^2 = 30 \text{ at } (1, -2, 5)$$

Ans. eqn of tangent plane is

$$(x - 1) \left(\frac{\partial f}{\partial x} \right)_{(1, -2, 5)} + (y + 2) \left(\frac{\partial f}{\partial y} \right)_{(1, -2, 5)} + (z - 5) \left(\frac{\partial f}{\partial z} \right)_{(1, -2, 5)} = 0$$

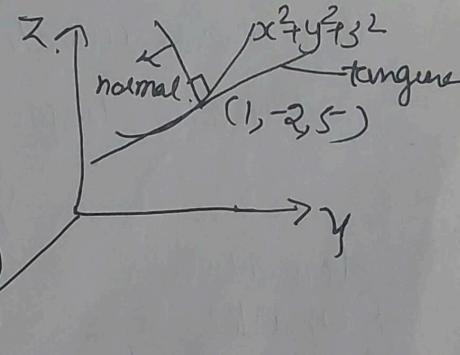
$$= (x - 1) \left(\frac{\partial f}{\partial x} \right)_{(1, -2, 5)} + (y + 2) \left(\frac{\partial f}{\partial y} \right)_{(1, -2, 5)} + (z - 5) \left(\frac{\partial f}{\partial z} \right)_{(1, -2, 5)} = 0$$

$$\Rightarrow +2(x-1) - 4(y+2) + 10(z-5) = 0 \text{ Ans.}$$

$$= 2x - 4y + 10z - 2 - 8 - 50 = 0$$

$$2x - 4y + 10z - 60 = 0$$

$$x - 2y + 5z - 30 = 0.$$



Quantifying
point-
plane
function into scalar function

$$= \frac{\partial V}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial V}{\partial z}$$

$$2x + 2y + 2z$$

gen
reg
unit

$x^2 + y^2 + z^2$

Content: Divergence and solenoidal vector

Divergence: - Divergence is a vector operator that measures the magnitude of a vector field's source at a given point.

Divergence represents the volume density of the outward flux of a vector field.

If $\vec{V} = V_1 \hat{i} + V_2 \hat{j} + V_3 \hat{k}$ be a vector point function then $\operatorname{div} \vec{V} = \nabla \cdot \vec{V} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot \vec{V}$
 $= \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z}$.

Remark:

1. $\operatorname{div} \vec{V}$ is a scalar quantity.
2. div converts a vector point function into scalar function.
3. $\vec{V} \cdot \nabla \neq \nabla \cdot \vec{V}$
4. If \vec{V} is constant vector, then $\nabla \cdot \vec{V} = 0$
5. If c is constant $\operatorname{div}(c\vec{V}) = c\operatorname{div}\vec{V}$

Solenoidal vector: - If $\operatorname{div} \vec{V} = 0$, then \vec{V} is called solenoidal [incompressible] vector function.

Q.1 If $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$ show that $\operatorname{div} \vec{r} = 3$.

Sol. $\operatorname{div} \vec{r} = \nabla \cdot \vec{r} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (x \hat{i} + y \hat{j} + z \hat{k})$
 $= \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z)$
 $= 1 + 1 + 1$
 $= 3$ Ans.

If \vec{f} is a constant vector then $\nabla \times \vec{f} = 0$

2016. find divergence of vector function $\vec{F}(x, y, z) = e^{xyz}(xy^2\vec{i} + yz^2\vec{j} + zx^2\vec{k})$ at the point $(1, 2, 3)$

Sol. $\text{div } \vec{F} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$

where $F_1 = e^{xyz}(xy^2)$, $F_2 = e^{xyz}(yz^2)$, $F_3 = e^{xyz}(zx^2)$

$$\begin{aligned} \therefore \text{div } \vec{F} &= y^2[e^{xyz} + xyz e^{xyz}] + z^2[e^{xyz} + yz^2 e^{xyz}] + x^2[e^{xyz} + xyz^2 e^{xyz}] \\ &= (1+xyz)(x^2+y^2+z^2) e^{xyz} = 98e^6 \text{ at } (1, 2, 3) \end{aligned}$$

Q. Prove that $\text{div}(\text{grad } x^n) = n(n+1)x^{n-2}$ where

Sol. $\text{grad } x^n = \nabla x^n$
 $= \left[\frac{\partial}{\partial x} x^n + \frac{\partial}{\partial y} x^n + \frac{\partial}{\partial z} x^n \right]$
 $= \left[n x^{n-1} \frac{\partial x}{\partial x} + n x^{n-1} \frac{\partial x}{\partial y} + n x^{n-1} \frac{\partial x}{\partial z} \right]$
 $\therefore n x^{n-1} \left[\frac{x}{x} + \frac{y}{x} + \frac{z}{x} \right] = n x^{n-2} \vec{x}$

$$\therefore \text{div}(\text{grad } x^n) = \text{div}(n x^{n-2} \vec{x})$$

$$\exists n x^{n-2} \cdot \nabla \cdot \vec{x}$$

$$= \frac{\partial}{\partial x}(n x^{n-2} x) + \frac{\partial}{\partial y}(n x^{n-2} y) + \frac{\partial}{\partial z}(n x^{n-2} z)$$

$$= \sum n x^{n-2} + n(n-2) x^{n-3} \cdot \frac{\partial x}{\partial x}$$

$$= \sum n x^{n-2} + n(n-2) x^{n-3} \frac{x^2}{x}$$

$$= 3n x^{n-2} + n(n-2) \frac{x^{n-3}}{x} (x^2 + y^2 + z^2) = [3n + n^2 - 2n] x^{n-2}$$

$$= n(n+1) x^{n-2}$$

2007 Q2 of $\vec{F}(x, y, z)$ of vector

Prove that $(y^2 - z^2 + 3yz - 2x) \hat{i} + (3yz + 2xy) \hat{j} + (3xy - 2xz + 2z) \hat{k}$ is solenoidal.

To prove vector is solenoidal we have to

Show $\operatorname{div} \vec{F} = 0$

Here $\vec{F} = (y^2 - z^2 + 3yz - 2x) \hat{i} + (3yz + 2xy) \hat{j} + (3xy - 2xz + 2z) \hat{k}$

$$\nabla \cdot \vec{F} = - \cancel{\frac{\partial}{\partial x}} (y^2 - z^2 + 3yz - 2x) + \frac{\partial}{\partial y} (3yz + 2xy) + \frac{\partial}{\partial z} (3xy - 2xz + 2z)$$

$$= -2 + 2x - 2x + 2 = 0. \text{ Hence proved.}$$

Q. find the value of p such that $\vec{V} = (x+py) \hat{i} + (py - 3z) \hat{j} + (z - 2y) \hat{k}$ is solenoidal.

Sol. Given \vec{V} is solenoidal $\Rightarrow \nabla \cdot \vec{V} = 0$.

$$\frac{\partial}{\partial x} (x+py) + \frac{\partial}{\partial y} (py - 3z) + \frac{\partial}{\partial z} (z - 2y) = 0$$

$$1 + p - 2 = 0 \quad p = 1. \text{ Ans.}$$

Q. Show that $\nabla^2 \left(\frac{x}{r^3} \right) = 0$ where r is magnitude of position vector $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$.

Sol. We have $r^2 = x^2 + y^2 + z^2$

$$\frac{\partial x}{\partial x} \frac{\partial x}{\partial x} = 2x \Rightarrow \frac{\partial x}{\partial x} = \frac{x}{r} \quad , \frac{\partial x}{\partial y} = \frac{y}{r} \quad , \frac{\partial x}{\partial z} = \frac{z}{r}$$

$$\therefore \frac{\partial}{\partial x} \left(\frac{x}{r^3} \right) = \frac{1}{r^3} - \frac{3x}{r^4} \frac{\partial x}{\partial x} = \frac{1}{r^3} - \frac{3x^2}{r^5}$$

$$\frac{\partial^2}{\partial x^2} \left(\frac{x}{r^3} \right) = \frac{\partial}{\partial x} \left(\frac{1}{r^3} - \frac{3x^2}{r^5} \right) = -\frac{3}{r^4} \frac{\partial x}{\partial x} - \frac{6x}{r^5} + \frac{15x^2}{r^6} \frac{\partial x}{\partial x}$$

$$= -\frac{3x}{r^5} - \frac{6x}{r^5} + \frac{15x^3}{r^7} = -\frac{9x}{r^5} + \frac{15x^3}{r^7}$$

Similarly $\frac{\partial^2}{\partial y^2} = \frac{\partial^2}{\partial z^2} = -3x \frac{\partial}{\partial y} \left(\frac{y}{r^3} \right) = -\frac{3x}{r^5} + \frac{15x^2 y^2}{r^7}$

$$\frac{\partial^2}{\partial z^2} \left(\frac{x}{z^3} \right) = \frac{-3x}{z^5} + \frac{15xz^2}{z^7}$$

$$\therefore \nabla^2 \left(\frac{x}{z^3} \right) = -\frac{15x}{z^5} + \frac{15x}{z^7} (x^2 y^2 z^2) \\ = -\frac{15x}{z^5} + \frac{15x}{z^5} = 0.$$

Important results

$$\textcircled{1} \quad \text{div}(\text{grad } \phi) = \nabla^2 \phi = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \quad \text{proof}$$

$$\textcircled{2} \quad \text{div}(\text{curl } \vec{V}) = 0$$

$$\textcircled{3} \quad \text{curl}(\text{grad } \phi) = 0$$

$$\vec{V} + \vec{V}_3 \hat{k}$$

$$\frac{\partial V_3}{\partial x} + \frac{\partial V_1}{\partial z}$$

\vec{V} is of

n.
rotation
ten

curl \vec{V}
said

then

10

Lecture 55
content: curl, Irrotational Vector

Vector Calculus
Part IV

Curl: Let \vec{V} be a vector point function then
curl \vec{V} is defined as.

$$\text{curl } \vec{V} = \nabla \times \vec{V} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \times (v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} = \hat{i} \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) + \hat{j} \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) + \hat{k} \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right)$$

curl \vec{V} the vector point function \vec{V} is again a vector point function.

curl \vec{V} is vector point function.

curl \vec{V} is used to represent rotation of a field.

If \vec{f} is a constant vector then $\nabla \times \vec{f} = 0$.

Q) **Irrotational vector:** If $\text{curl } \vec{V} = 0$ then \vec{V} , vector point function is said to be irrotational.

Q1) If $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$, then prove $\text{curl } \vec{r} = 0$

Sol. $\text{curl } \vec{r} = \nabla \times \vec{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$

$$= \hat{i} (0-0) - \hat{j} (0-0) + \hat{k} (0-0)$$

$$\boxed{\nabla \times \vec{r} = 0.} \quad \text{Hence proved.}$$

Q2) If $\vec{F}(x, y, z) = x^2 y^2 \hat{i} + x^2 y \hat{j} + (y^2 - xy) \hat{k}$ find curl of vector.

Ques. $\text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2y^2 & 2xy & (y^2 - x^2) \end{vmatrix}$

$$= \hat{i} [2y - x - 0] - \hat{j} [-y + 0] + \hat{k} [0 - 0]$$

$$\nabla \times \vec{F} = (2y - x) \hat{i} + y \hat{j} + 2y(1 - x^2) \hat{k}$$

Q Prove that $\vec{a} \times (\nabla \times \vec{F}) = \nabla(\vec{a} \cdot \vec{F}) - (\vec{a} \cdot \nabla) \vec{F}$ Ans
 \vec{a} is a constant vector.

Ques. LHS $\vec{a} \times (\nabla \times \vec{F}) = \vec{a} \times \vec{0} = \vec{0}$.

RHS $\nabla(\vec{a} \cdot \vec{F}) - (\vec{a} \cdot \nabla) \vec{F}$

$$= \nabla(a_1 x + a_2 y + a_3 z) - (a_1 \frac{\partial}{\partial x} + a_2 \frac{\partial}{\partial y} + a_3 \frac{\partial}{\partial z})(x \hat{i} + y \hat{j} + z \hat{k})$$

$$\Rightarrow a_1 \hat{i} + a_2 \hat{j} + a_3 \hat{k} - a_1 \hat{i} - a_2 \hat{j} - a_3 \hat{k} = 0 \text{ hence proved.}$$

Ques. Prove that

Q Prove that $\vec{F} = 2xy \hat{i} + (x^2 + a_3 z) \hat{j} + (y^2 + 1) \hat{k}$ is irrotational.

Ques. A vector is irrotational if $\nabla \times \vec{F} = \vec{0}$

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xy & (x^2 + a_3 z) & (y^2 + 1) \end{vmatrix}$$

$$= \hat{i} (2y - 2y) - \hat{j} (0 - 0) + \hat{k} (2x - 2x) = \vec{0}.$$

Hence proved.

Scalar Potential: $d\phi = \nabla \phi \cdot d\vec{r}$ is called total derivative of ϕ .

$$\text{as } d\phi = \left(\frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \right) - \nabla \phi$$

where ϕ is a scalar function $\vec{r} = x \hat{i} + y \hat{j} + z \hat{k}$
 $d\vec{r} = dx \hat{i} + dy \hat{j} + dz \hat{k}$
 $\vec{F} = \vec{a} \times \vec{r}$
 $\vec{F} = \vec{a} \cdot \nabla \phi$
 \vec{a} shows that $\vec{F} = \nabla \phi$ is irrotational

one's

where ϕ is a scalar point function

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k} \quad (\text{position vector})$$

$$d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

function ϕ is called potential field or scalar potential.

evaluating ϕ from relation ①. gives scalar potential ϕ .

2014) ② Show that $\vec{v} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$ is irrotational. find velocity potential ϕ such that

$$\vec{A} = \nabla\phi$$

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6xy + z^3 & 3x^2 - z & 3xz^2 - y \end{vmatrix}$$

$$= \hat{i}(-1+1) - \hat{j}(3z^2 - 3z^2) + \hat{k}(6x - 6x)$$

$$\Rightarrow \vec{A} \text{ is irrotational.}$$

Given $\vec{A} = \nabla\phi$.

to determine scalar potential ϕ .

$$\text{Consider } d\phi = \nabla\phi \cdot d\vec{r}$$

$$d\phi = (6xy + z^3)dx + (3x^2 - z)dy + (3xz^2 - y)dz$$

to determine ϕ integrate w.r.t (x, y, z) resp

$$\phi = 3x^2y + nz^3 + C_1$$

$$\phi = 3x^2y - yz + C_2$$

$$\phi = nz^3 - yz + C_3$$

$$\boxed{\text{Hence } \phi = 3x^2y - yz + nz^3 + C \quad \text{Ans.}}$$

Find constants a, b, c such that $\vec{F} = (x+ay+yz)\vec{i} + (2x-3y-3z)\vec{j} + (4x-y+2z)\vec{k}$ is irrotational

904. Find φ , if $\vec{F} = \nabla\varphi$.

$$\nabla \times \vec{F} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+ay+yz & 2x-3y-3z & 4x-y+2z \end{vmatrix} = ?[c+1] - ?[4-a] = \vec{0}$$

$$\Rightarrow c = -1, a-4 = 0 \Rightarrow a = 4, b = 2$$

Hence $a = 4, b = 2, c = -1$

$$\vec{F} = (x+2y+4z)\vec{i} + (2x-3y-3)\vec{j} + (4x-y+2z)\vec{k}$$

φ is scalar potential

$$\begin{aligned} d\varphi &= \nabla\varphi \cdot d\vec{r} = (x+2y+4z)dx + (2x-3y-3)dy + (4x-y+2z)dz \\ &= \frac{x^2}{2} - 3y^2 + z^2 + 2xy + 4xz - yz + C. \end{aligned}$$

$[\nabla f, \vec{a}]$
 $[\vec{a}, \vec{b}] = \frac{1}{3} \text{ for}$
 between the points
 be point (x_1, y_1, z_1)
 $x_1 = 0$ and $y_1 = 0$