

# Machine, Data and Learning (CS7.301)

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## Assignment 2

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### Question 1

The five parameters of the blocks world problem are:

- States: A state would consist of a description of which blocks are on the table, and which blocks are on top of the others. For example, “A and B are on the table and C is on top of A”.
- Actions: An action consists of moving a block from one location to another (each location is either the table or the top of a block). The admissible actions are those in which the block being moved has no block on top of it.
- The initial state is specified by a certain instance of the problem. For example, all blocks might be on the table.
- The goal state is also specified by the instance of the problem.
- The cost of a path can be defined as the number of moves in it.

### Question 2

#### Breadth-First Search

In BFS, the expansions of nodes are added to the end of the open list (the open list is a queue).

**Initial state:**

```
[ C ]
A B
```

**Iteration 1:**

```
      B
[  C ; C ;      ]
A B  A  A B C
```

**Iteration 2** (expanding node 1 above, adding to end of list):

```

      B                A
[ C ;      ; C ; C ; ]
  A   A B C   A B   B   A B C

```

**Iteration 3** (expanding node 1 above, adding to end of list):

```

              A
[      ; C ; C ;      ; C ]
  A B C   A B   B   A B C   A B

```

## Depth-First Search

In DFS, the expansions of nodes are added to the beginning of the open list (the open list is a stack).

**Initial state:**

```

[ C ]
  A B

```

**Iteration 1:**

```

      B
[   C ; C ; ]
  A B   A   A B C

```

**Iteration 2** (expanding node 1 above, adding to beginning of list):

```

      A                B
[ C ; C ;      ; C ; ]
  A B   B   A B C   A   A B C

```

**Iteration 3** (expanding node 1 above, adding to the beginning of the list):

```

      B                A                B
[   C ; C ;      ; C ;      ; C ; ]
  A B   A   A B C   B   A B C   A   A B C

```

## Uniform-Cost Search

In UCS, the least-cost unexpanded node is expanded. In this case, however, we consider the path cost as the number of nodes; thus this becomes equivalent to BFS.

**Initial state:**

```

[ C ]
  A B

```

**Iteration 1:**

```

      B
[   C ; C ; ] # All have path costs 1

```

A B    A    A B C

**Iteration 2** (expanding node 1 above, adding to end of list):

$$\begin{array}{ccccccc} & B & & & & A & \\ [C & ; & & ; & C & ; & C & ; & & ] \end{array}$$
 # First two have path costs 1; next three have 2  

$$\begin{array}{ccccccc} & A & A & B & C & A & B & B & A & B & C \end{array}$$

**Iteration 3** (expanding node 1 above, adding to end of list):

$$\begin{array}{ccccccc} & & & & A & & \\ [ & ; & C & ; & C & ; & & ; & C & ] \end{array}$$
 # First has path cost 1; next four have 2  

$$\begin{array}{ccccccc} A & B & C & A & B & B & A & B & C & A & B \end{array}$$

### Question 3

Two examples of admissible heuristics that can be used for this are:

- Sum of absolute differences of heights of each block from their heights in the goal state (height of a block = number of blocks under it). For example, if we have A, C, B on a single stack (with B on the table), the distance is  $|2 - 2| + |1 - 0| + |0 - 1| = 2$ .  
This heuristic is admissible as the absolute difference is a lower bound on the number of moves needed to achieve the state.
- Absolute difference between number of stacks in current state and in goal state. For example, if we have A and B on the table, and C on top of B, then the distance is  $|2 - 1| = 1$ .  
This heuristic is also admissible as one move can change it by at most 1; thus it can only underestimate the cost.

### Question 4

We will use the first heuristic above to carry out A\* search. Thus,  $h(n)$  is defined above,  $g(n)$  is the depth of a node, and  $f(n) = h(n) + g(n)$  is what we will minimise.

**Initial State:**

$$\begin{array}{c} [C \quad (4)] \\ A \quad B \end{array}$$

**Iteration 1:**

$$\begin{array}{ccccccc} & & & & B & & \\ [ & (1+3); & C & (1+4); & C & (1+4)] \\ A & B & C & A & B & A \end{array}$$

**Iteration 2:**

```
[ A (2+2); A (2+2); B (2+2); B (2+2); # These are from node 1
  B C      B C      A C      A C
```

```

      B
      (1+3); C (1+4); # These carry over
A B C      A
```

```
C (2+4); C (2+4)] # These are also from node 1
A B      A B
```

**Iteration 3:**

```

      B
[ A (2+2); B (2+2); B (2+2); (1+3); C (1+4) # These carry over
  B C      A C      A C      A B C      A
```

```
A (3+2); # This is from node 1
B C
```

```
C (2+4); C (2+4); # These carry over
A B      A B
```

```

      C
      (3+3); A (3+4)] # These are from node 1
A B C      B
```