Substitution in Arrays

• We haven't discussed how to understand array assignments yet. If we assign an expression to b[e], the index e can only be evaluated at runtime; which can lead to the following problem.

Assuming b[j] and b[k] are safe and $j \not\equiv k$, then what is wp(b[j] := b[j] + 1, b[k] < b[j])?

- Some might say it is b[k] < b[j] + 1 but what if k and j evaluated to the same integer at runtime? Will we only substitute b[j] with b[j] + 1? Or will we substitute both b[j] and b[k] with b[j] + 1 (and if so, we will get the weakest precondition being $b[j] + 1 < b[j] + 1 \Leftrightarrow F$)?
- We need to figure out how to understand substitutions in arrays $(e)[e_1/b[e_0]]$ first.
- 1. How to understand (b[m])[6 / d[2]] where m is a variable or named constant?
 - o If b and d are different arrays ($b \not\equiv d$), then this is simple: there will be no expression d[2] in array b[m] then $(b[m])[6/d[2]] \equiv b[m]$.
 - If b and d are the same array ($b \equiv d$), then we need to consider whether m = 2: if m = 2 then $(b[m])[6 / d[2]] \equiv 6$ or else it b[m].
- 2. How to understand (b[e])[6 / d[2]] where e is an expression?
 - o If b and d are different arrays, then $b[e] \not\equiv d[2]$ and we need to look recursively into e since expression d[2] might appear in e; then, $(b[e])[6 / d[2]] \equiv b [e[6 / d[2]]]$.
 - o If b and d are the same array, we need to evaluate e. If e is evaluated to 2 at run time, then $(b[e])[6/d[2]] \equiv 6$, or else we will look recursively into e like in the above case).
- Here we give the definition of syntactic substitution in arrays:

$$(b[e_2])[e_1/b[e_0]] \equiv \text{if } e_2' = e_0 \text{ then } e_1 \text{ else } b[e_2'] \text{ fi, where } e_2' \equiv (e_2)[e_1/b[e_0]].$$

- o This definition covers all cases in Example 1 and 2 while the substitution happens in the same array:
 - When e_2 is a named constant, aka $e_2 \equiv k$, then we get $e_2' \equiv k[e_1/b[e_0]] \equiv k$, and then $(b[k])[e_1/b[e_0]] \equiv if k = e_0$ then e_1 else b[k] fi.
- 3. Finish the following syntactic substitutions.
 - a) $(b[k])[5/b[0]] \equiv \text{if } k = 0 \text{ then } 5 \text{ else } b[k] \text{ fi}$
 - b) $(b[k])[e_0 / b[j]] \equiv \text{if } k = j \text{ then } e_0 \text{ else } b[k] \text{ fi}$
 - c) $(b[k])[b[j] + 1 / b[j]] \equiv \mathbf{if} \ k = j \ \mathbf{then} \ b[j] + 1 \ \mathbf{else} \ b[k] \ \mathbf{fi}$ Note that, we will keep e_1 (in this case b[j] + 1) as it is, even if it involves b.
 - d) $(b[k])[b[j]/b[b[k]] \equiv if k = b[k] then b[j] else b[k] fi$
 - e) (b[b[k]])[5/b[0]]

```
The inner b[k] need to be taken care first, and (b[k])[5/b[0]] \equiv \mathbf{if} \ k = 0 \ \mathbf{then} \ 5 \ \mathbf{else} \ b[k] \ \mathbf{fi}. Then, (b[b[k]])[5/b[0]]
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\equiv if (if k = 0 then 5 else b[k]fi) = 0 then 5 else b[if k = 0 then 5 else b[k]fi] fi
```





- In Example 3.e) we "logically simplified" a complicated expression to a "shorter" expression. Formally, we call this operation **optimization**, it means we replace an expression/predicate with a "shorter" expression/predicate that is semantically equal. It is written as $e_1 \mapsto e_2$ (" e_1 optimizes to e_2 ").
 - We introduce this definition here because syntactic substitutions in arrays usually end up with a long and complicated text (either expression or predicate). It can be useful to shorten it first before execution, similarly to how compilers can optimize code.
 - o The optimization is done in a static way: the optimization is done before the code runs.
 - \circ Since to $e_1\mapsto e_2$ we need $e_1\Leftrightarrow e_2$, it is okay to just use " \Leftrightarrow " to represent optimization. But " $e_1\Leftrightarrow e_2$ " emphasizes that e_1 and e_2 are semantically equal, and " $e_1\mapsto e_2$ " emphasizes that e_1 is (or can be) optimized to e_2 .
- 4. Let's look at a simple example before we introduce the rules. Optimize the following expressions.

```
a) (b[0])[e_1 / b[2]] \equiv \text{if } 0 = 2 \text{ then } e_1 \text{ else } b[0] \text{ fi} \mapsto b[0]
```

b) $(b[1])[e_1/b[1]] \equiv \text{if } 1 = 1 \text{ then } e_1 \text{ else } b[1] \text{ fi } \mapsto e_1$

Rules for Optimizing Condition Expressions

Let's identify some general rules for optimizing conditional expressions and predicates involving them. This will let us simplify calculation of wlp or wp for array assignments.

```
• (if T then e_1 else e_2 fi) \mapsto e_1
```

- (if F then e_1 else e_2 fi) $\mapsto e_2$
- (if B then e else e fi) \mapsto e
- If we know that $B \Rightarrow e_1 = e_2$, then (if B then e_1 else e_2 fi) $\mapsto e_2$.
 - o Since B can imply that $e_1=e_2$, then no matter whether B is true or not, we always have e_2 .
- If we know that $\neg B \Rightarrow e_1 = e_2$, then (if B then e_1 else e_2 fi) $\mapsto e_1$.

Let op_1 be a unary operator, such as "¬"...; and op_2 be a binary operator such as "+", "<"...

```
• op_1 (if B then e_1 else e_2 fi) \mapsto if B then op_1(e_1) else op_1(e_2) fi
```

- (if B then e_1 else e_2 fi) $op_2 e_3 \mapsto if B$ then $e_1 op_2 e_3$ else $e_2 op_2 e_3$ fi
- $b[\text{ if } B \text{ then } e_1 \text{ else } e_2 \text{ fi }] \mapsto \text{ if } B \text{ then } b[e_1] \text{ else } b[e_2] \text{ fi }$
- $f(\text{if } B \text{ then } e_1 \text{ else } e_2 \text{ fi}) \mapsto \text{if } B \text{ then } f(e_1) \text{ else } f(e_2) \text{ fi}$

Let B_1, B_2, B_3 be Boolean expression.

```
• (if B then B_1 else B_2 fi) \mapsto (B \land B_1) \lor (\negB \land B_2)
```

- (if B then B_1 else B_2 fi) \mapsto $(B \to B_1) \land (\neg B \to B_2)$
- (if B then B_1 else F fi) \mapsto (B \land B_1)

```
\circ \quad (if B then B_1 else F fi) \Leftrightarrow (B \land B_1) \lor (\neg B \land F) \Leftrightarrow (B \land B_1)
```

- (if B then F else B_2 fi) $\mapsto (\neg B \land B_2)$
- (if B then B_1 else T fi) \mapsto ($B \to B_1$)
- (if B then B_1 else T fi) $\mapsto (\neg B \lor B_1)$
 - (if B then B_1 else T fi) \Leftrightarrow (B \rightarrow B_1) \land (\neg B \rightarrow T) \Leftrightarrow (B \rightarrow B_1)
- (if B then T else B_2 fi) $\mapsto (\neg B \to B_2)$
- (if B then T else B_2 fi) \mapsto (B \vee B_2)

Now, let's go back to the first question of the class.

5. Let j and k be two named constants that are at least 0 and less than size(b). Calculate wp(b[j] := b[j] + 1, b[k] < b[j], assuming b[j] and b[k] are safe.

```
wp(b[j] := b[j] + 1, b[k] < b[j])
\equiv (b[k] < b[j]) [b[j] + 1 / b[j]]
\equiv (b[k]) [b[j] + 1 / b[j]] < (b[j]) [b[j] + 1 / b[j]]
\equiv (if k = j then b[j] + 1 else b[k] fi) < (b[j] + 1)
\mapsto if k = j then (b[j] + 1) < (b[j] + 1) else b[k] < (b[j] + 1) fi
\mapsto if k = j then F else b[k] < (b[j] + 1) fi
\mapsto k \neq j \land b[k] < (b[j] + 1)
```

- This gives us a valid triple $\{k \neq j \land b[k] < (b[j] + 1)\} b[j] := b[j] + 1\{b[k] < b[j]\}$
- 6. Correct a full proof outline of a program that swaps the values of primitive-type variables x and y.
 - \circ To swaps the values of x and y, we need the help of a temporary variable u, then we can create the following minimal proof outline:

$$\{x = x_0 \land y = y_0\} u := x; x := y; y := u \{x = y_0 \land y = x_0\}$$

- We can keep using backward assignments to create the following full proof outline: $\{x = x_0 \land y = y_0\} u \coloneqq x; \{y = y_0 \land u = x_0\} x \coloneqq y; \{x = y_0 \land u = x_0\} y \coloneqq u \{x = y_0 \land y = x_0\}$
- 7. Create a full proof outline of a program that swaps b[m] and b[n], assuming that m and n are natural numbers less than size(b).
 - o Like question 6, we need to prove the following minimal proof outline:

```
{b[m] = c \land b[n] = d} u := b[m]; b[m] := b[n]; b[n] := u {b[m] = d \land b[n] = c}
```

o If we keep using backward assignments, then we can come up with the following full proof outline:

```
\{b[m] = c \land b[n] = d\} \{q_0\} u := b[m]; \{q_1\} b[m] := b[n]; \{q_2\} b[n] := u \{b[m] = d \land b[n] = c\}
```

Let's calculate q_2 , q_1 and q_0 . Note that, we also need to prove $b[m] = c \land b[n] = d \Rightarrow q_0$.

```
q_2 \equiv (b[m] = d \land b[n] = c) \left[ u / b[n] \right]
\equiv (b[m] = d) \left[ u / b[n] \right] \land (b[n] = c) \left[ u / b[n] \right]
\equiv (b[m]) \left[ u / b[n] \right] = d \land (u = c)
\equiv (\mathbf{if } m = n \mathbf{ then } u \mathbf{ else } b[m] \mathbf{ fi}) = d \land (u = c)  # Stop here if pure syntactic result is needed
```

$$q_1 \equiv \left((\mathbf{if} \ m = n \ \mathbf{then} \ u \ \mathbf{else} \ b[m] \ \mathbf{fi}) = d \land (u = c) \right) \left[b[n] \ / \ b[m] \right]$$

$$\equiv \left(\mathbf{if} \ m = n \ \mathbf{then} \ u \ \mathbf{else} \ b[m] \ \mathbf{fi} \right) \left[b[n] \ / \ b[m] \right] = d \land (u = c)$$

$$\equiv \left(\mathbf{if} \ m = n \ \mathbf{then} \ u \ \mathbf{else} \ b[n] \ \mathbf{fi} \right) = d \land (u = c)$$

```
q_0 \equiv \left( (\mathbf{if} \ m = n \ \mathbf{then} \ u \ \mathbf{else} \ b[n] \ \mathbf{fi}) = d \land (u = c) \right) [b[m] \ / \ u]
\equiv \left( \mathbf{if} \ m = n \ \mathbf{then} \ b[m] \ \mathbf{else} \ b[n] \ \mathbf{fi} \right) = d \land (b[m] = c)
\# \ \mathsf{Let's} \ \mathsf{try} \ \mathsf{to} \ \mathsf{optimize} \ q_0.
\# \ m = n \ \mathsf{implies} \ b[m] = b[n]
\mapsto b[n] = d \land (b[m] = c)
```

It is obvious that the precondition $b[m] = c \wedge b[n] = d \Leftrightarrow q_0$ so the proof is done (and we can remove the condition q_0).

Parallel Program Basics

- A parallel program is trying to run all different threads "at the same time". In our language, the syntax of a parallel statement/program with n threads is $S \equiv [S_1 \parallel S_2 \parallel \cdots \parallel S_n]$. We say $[S_1 \parallel S_2 \parallel \cdots \parallel S_n]$ is the **parallel** composition of threads S_1, S_2, \ldots, S_n .
 - Each thread S_i in the composition should be non-parallel and deterministic: it is not legal to wright $S \equiv [S_1 \parallel [S_2 \parallel S_3]]$.
- Before we formally define the semantics of parallel programs, let's use a simple example to see the difference between sequential, parallel, and nondeterministic conditional programs.
- 8. Find a postcondition for each of the following valid triples.
 - a) $\{x=5\} x \coloneqq x+1; x \coloneqq x*2 \{q\}$ It is quite easy to see that x=12 is a valid postcondition: we will finish two assignments in the given order. It is almost the strongest postcondition, we only omitted the initial value of x compared to $x_0=5 \land x_1=x_0+1 \land x=x_1*2$.
 - b) $\{x=5\}$ if $T \to x := x+1 \square T \to x := x*2$ fi $\{q\}$ Both arms have true guard, so we will execute two branches at the same time with equal probability. Thus, the postcondition is x=6 V x=10. As an aside, the strongest postcondition is $x_0=5$ $\land x=x_0+1$ V $x_0=5$ $\land x=x_0*2$.
 - c) $\{x=5\}$ $[x \coloneqq x+1 \parallel x \coloneqq x*2] \{q\}$ Both threads will be executed "at the same time"; but some thread must be executed faster than the other in real life, and threads will be executed in any possible order. Thus, we might have x=12 if we execute $x \coloneqq x+1$ first, or we might have x=11 if we execute $x \coloneqq x*2$ first. Thus, $x=11 \lor x=12$ is a valid postcondition here.
- The above example shows the difference between sequential, parallel, and nondeterministic programs.
 - o For a sequential statement, we execute each unit statement in the given order.
 - \circ For a nondeterministic **if fi** statement, we execute each arm at the same time with the same probability.
 - o For a parallel statement, all unit statements in the composition will be executed in any possible order. So, parallel statements can be considered as a simulation of nondeterminism: $[x \coloneqq x + 1 \parallel x \coloneqq x * 2]$ can simulate **if** $T \to x \coloneqq x + 1$; $x \coloneqq x * 2 \square T \to x \coloneqq x * 2$; $x \coloneqq x + 1$ **fi.**