Microprocessor Lab Report

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1.1 Objective

Find out the sum of the first 30 natural numbers.

1.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

1.3 Procedure

We know that

$$1+2+3+\ldots+29+30=\frac{30\times 29}{2}=435=01D1H$$

This result is not possible to store in a single register, so we need to use register pair to store the result.

1.4 Program

```
; end result is 465, more than 255 hence we need to do extended additions

MVI D,1E; setup D, the counter as 30

MVI C,01; setup BC as 1

L1: DAD B; Double add BC to HL

INX B; extended increment BC

DCR D; decrement D

JNZ L1; if D becomes 0, Z flag becomes 0 and we break

HLT

Ans will be in HL
```

Listing 1: assembly program to find sum of the first 30 natural numbers

1.5 Experimentation

Register	Value	7	6	5	4	3	2	1	0
Accumulator	00	0	0	0	0	0	0	0	0
Register B	00	0	0	0	0	0	0	0	0
Register C	1F	0	0	0	1	1	1	1	1
Register D	00	0	0	0	0	0	0	0	0
Register E	00	0	0	0	0	0	0	0	0
Register H	01	0	0	0	0	0	0	0	1
Register L	D1	1	1	0	1	0	0	0	1
Memory(M)	00	0	0	0	0	0	0	0	0

Figure 1: Register configuration after execution (observe HL)

1.6 Conclusion

We see that after the execution of program, the data stored in HL register pair is 01D1H, which is the hexadecimal value of 435.

2.1 Objective

From an array of 10-byte size integers (unsigned) find out the maximum and minimum.

2.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

2.3 Procedure

The idea is to linearly iterate through all the values of the arr, and update the register for minimum(C) and maximum(B) values.

2.4 Program

```
;Actual Program
   # ORG 5000H
   # ARR: DB 5,2,3,4,F,C,7,A,B,1
   # ORG 0000
          LXI H, ARR
          {\tt MOV} B,M \, ;B is maximum val
          MOV C,M ;C is minimum val
          MVI D,OA
   ;CMP R does (A - R) in background
10
   ; If A - R > 0 then Cy = 0, Z = 0
   ; If A - R = 0 then Cy = 0, Z = 1
11
   ;If A - R < 0 then Cy = 1, Z = 1
          MOV A,M
14
   LP:
          CMP B
           JC MIN
                    ; will Jump when Cy = 1, A - B < 0, A < B
16
          MOV B,A ;will only happen if A > B
17
18
   MIN:
          CMP C
19
          JNC SKIP ;will Jump when Cy = 0, A - C > 0, A > C
20
          MOV C,A ; will only happen if A < C
21
22
   SKIP:
          INX H
          DCR D
24
          JNZ LP
25
```

Listing 2: assembly program to find minimum and maximum number in 10-byte unsigned array

2.5 Experimentation

Register	Value	7	6	5	4	3	2	1	0	Desistes	Malica	7	-	-		3	2	-	0
Accumulator	01	0	0	0	0	0	0	0	1	Register	Value	-	6	5	4	_	2	1	_
Register B	0F	0	0	0	0	1	1	1	1	Accumulator	06	0	0	0	0	0	1	1	0
				_	-	-	1	1	-	Register B	0F	0	0	0	0	1	1	1	1
Register C	01	0	0	0	0	0	0	0	1	Register C	06	0	0	0	0	0	1	1	0
Register D	00	0	0	0	0	0	0	0	0	Register D	00	0	0	0	0	0	0	0	0
Register E	00	0	0	0	0	0	0	0	0			_	_	_	_	_	_	_	_
Register H	50	0	1	0	1	0	0	0	0	Register E	00	0	0	0	0	0	0	0	0
-		0	_		_	-		1		Register H	50	0	1	0	1	0	0	0	0
Register L	0A	-	0	0	0	1	0	1	0	Register L	0A	0	0	0	0	1	0	1	0
Memory(M)	00	0	0	0	0	0	0	0	0	Memory(M)	00	0	0	0	0	0	0	0	0
(a) result	for {5,2,	,3,4	ŀ,F	,C,	,7,	A,I	3,1	}		(b) result	for {F,E	,D,	С,	В,	4,9),8,	,7,6	3}	

Figure 2: Result for different inputs

2.6 Conclusion

We see that that after program execution, B has the maximum value of array, and C has the minimum value of the array.

3.1 Objective

Write a routine that produces a delay. The delay value must be passed to register pair DE.

3.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

3.3 Procedure

Idea is to assign DE a very big value (say FFFF), and decrement it in a loop till DE becomes 0 to produce delay in execution.

3.4 Program

```
LXI D,FFFF
          CALL DELAY
          HLT
   ;delay: this subroutine produces delay
   ;in: value in DE pair
   ;out: none
   ;destroys: A
   DELAY: DCX D
                   ;doesn't affect any flags, that's why doing OR
9
          MOV A,E
                   ; will give 0 only when both D and E 00
          ORA D
11
          JNZ DELAY
12
          RET
```

Listing 3: assembly program to produce delay

3.5 Conclusion

We see that the code runs for sometime, then completes it's execution, signifying that the delay function worked and delayed execution of CPU for some time.

4.1 Objective

Write a subroutine to move a block of bytes from location X to location Y. Note that the caller would specify

- X, the source address
- Y, the destination address
- Z, the block size

Note that X, Y and Z are 16-bit quantities.

4.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

4.3 Procedure

Start reading numbers from location X and save them to location Y, after each iteration, update address of X and Y to next byte. Do this Z times and the whole block is copied.

```
;setup of data
   #ORG 2500
   #ARR: DB 4,2,6,7,8
3
   # DESTLOC EQU 4500
   #ORG 0000
6
   ;let BC = 5, X = 2500, Y = 4500
   ;hence add data from 2500 to 2504
          LXI B,0005
9
          LXI D, ARR
10
11
          LXI H, DESTLOC
          CALL MOVE
          HLT
13
   ;MOVE: move Z number of bytes from loc (X to X+Z) to loc (Y to Y+Z)
14
   ;Z store in BC
15
   ;X store in DE
   ;Y store in HL
17
18
19
          LDAX D
                    ;A = Mem[DE]
          MOV M, A ; Mem[HL] = A
20
                    ;HL++
          INX H
21
          INX D
                    ;DE++
22
          DCX B
                   ;BC--
23
   ;DCX doesn't set flags so do manual check by OR
          MOV A,B
25
26
          ORA C
          JNZ MOVE
27
```

Listing 4: assembly program to move block

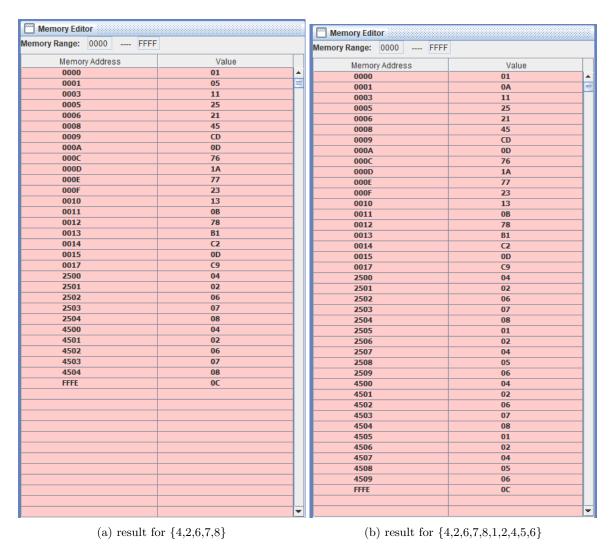


Figure 3: Result for different inputs

4.6 Conclusion

We see that all the data from location 2500(X) to (2500 + Z) has been copied to location 4500(Y) to (4500 + Z) [Z is 5 in 3a and 10 in 3b].

5.1 Objective

Write a function isODD(unsigned n) in assembly that takes an unsigned integer (a byte) and determines if it is odd (returns 1) or 0 if it is even.

5.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

5.3 Procedure

Odd numbers will always be in the form of 2x + 1, which means that they will have 1 as their LSB. So we just check if $number \wedge 01$ is 1 or not. If the result is 1, then the number is odd, else it is even.

5.4 Program

```
# NUM EQU 49 ;73 in hex
          MVI B, NUM
          CALL ISODD
   ; isODD(n): function which tell if n is odd or even
   ; in: n = B
   ;out: ans in C, if n even C = 0,else 1
   ;destroys: A
   ;idea: X AND 01 = 0 if X is even, 1 is X is Odd
   ISODD: MOV A,B
11
12
           ANI 01
                    ;A = A \text{ and } 01
                    ;store result in C
          MOV C,A
          RET
```

Listing 5: assembly program to check if given number isOdd or not

5.5 Experimentation

Register	Value	7	6	5	4	3	2	1	0	Register	Value	7	6	5	4	3	2	1	0
Accumulator	01	0	0	0	0	0	0	0	1	Accumulator	00	0	0	0	0	0	0	0	0
Register B	49	0	1	0	0	1	0	0	1	Register B	4A	0	1	0	0	1	0	1	0
Register C	01	0	0	0	0	0	0	0	1	Register C	00	0	0	0	0	0	0	0	0
Register D	00	0	0	0	0	0	0	0	0	Register D	00	0	0	0	0	0	0	0	0
Register E	00	0	0	0	0	0	0	0	0	Register E	00	0	0	0	0	0	0	0	0
Register H	00	0	0	0	0	0	0	0	0	Register H	00	0	0	0	0	0	0	0	0
Register L	00	0	0	0	0	0	0	0	0	Register L	00	0	0	0	0	0	0	0	0
Memory(M)	06	0	0	0	0	0	1	1	0	Memory(M)	06	0	0	0	0	0	1	1	0

(a) result for odd number(73)

(b) result for even number (73)

Figure 4: Result for both even and odd numbers

5.6 Conclusion

We see that in case of odd number, C is 1 after execution and in case of even number, C is 0 after execution.

6.1 Objective

Write a function to add two multi-byte numbers stored in location X and Y. The result is stored in X. Pass a parameter Z indicating the no. of bytes to be added.

6.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

6.3 Procedure

We simulate the default way of adding numbers, we go from right to left, adding (with carry) the numbers and adding it to stack, then we keep popping the elements and save it in X.

```
# ORG 8500
   # NUM1: DB FF,FF,FF
   # ORG 9000
3
  # NUM2: DB FF,FF,FF
   # NUMBYTE EQU 3
   # ORG 0000
6
          MVI C, NUMBYTE
                            ;C <- 03
          LXI H, NUM1
                            ;HL <- 8500
                            ;DE <- 9000
          LXI D, NUM2
          CALL ADDB
11
12
   ; add Z bytes, first number starts from X, other number starts from Y
   ; Z->C
13
   ;X->HL
14
15
   ; Y->DE
16
   ;destroys -> B
   # SAVELOC EQU 1500
17
   ADDB: SHLD SAVELOC ; save start of X to 1500 addr to be read later
          MVI B,00
                       ;set B as 0, will act as counter afterward
19
20
   ;now we need to put HL and DE pair to back of array
          XCHG
                        ;swap HL and DE
21
          DAD B
                        ;HL = HL + BC [with B = 0] [HL now is DE]
22
23
          DCX H
          XCHG
                        ;swap HL and DE again
24
                        ; HL = HL + BC
          DAD B
25
26
          DCX H
   ; now both DE and HL are in the end of their array
27
   LOOP: LDAX D ; A -> Mem[DE]
28
          ADC M
                    ;A -> A+ Mem[HL] + carry
          PUSH PSW ; push AF data to SP, first A, then F
30
31
          INR B
          DCX H
          DCX D
33
34
          DCR C
          JNZ LOOP ; jump to Loop till C!=0
35
36
   ; now addition done and saved to Stack, need to check if carry exist
          JNC SKIP
37
   ; these will execute only when there is a carry
38
39
          MVI A.01
          PUSH PSW
40
          INR B
41
43
   SKIP: LHLD SAVELOC
                          ;read saved LH data to go to start of X
44
   L1:
          POP PSW
                    ;pop SP to AF, first F then A
          MOV M,A
46
          TNX H
47
          DCR B
48
           JNZ L1
49
          RET
```

Listing 6: assembly program to add multi-byte numbers



Figure 5: Result of multi-byte addition (start looking from address 8500)

6.6 Conclusion

We see that the result of multi-byte addition is correct. Hence the program is working as expected.

7.1 Objective

Write a fast sub-routine to multiply 9 by 15.

7.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

7.3 Procedure

We use the Shift-and-Add Multiplication to fast multiply 15 and 9, as register size is 8 bits, we can do this multiplication by using a loop which runs 8 times, i.e O(1)

This method is faster than default loop method, which run in $O(\min(m, n))$, where m and n are the numbers that will be multiplied.

7.4 Program

```
LXI D,000F
                       ;15 in hex
          MVI A,09
          LXI H,0000
                       ;result will be in HL
          MVI B,08
                       ;8 bit data, 8 rotations to iterate through all the bits of A
   LP:
                    ;HL = HL + HL (multiply by 2)(assume left shift)
          RAL
                   ;rotate A left(<-), leftmost value in C flag
          JNC SKIP
          DAD D
                   ;if 1 in A's bit, we add D also
9
   SKIP:
          DCR B
10
          JNZ LP
          SHLD 2500
          HLT
13
   ;ans in HL register
```

Listing 7: assembly program to fast multiply 15 times 9

7.5 Experimentation

Register	Value	7	6	5	4	3	2	1	0
Accumulator	04	0	0	0	0	0	1	0	0
Register B	00	0	0	0	0	0	0	0	0
Register C	00	0	0	0	0	0	0	0	0
Register D	00	0	0	0	0	0	0	0	0
Register E	0F	0	0	0	0	1	1	1	1
Register H	00	0	0	0	0	0	0	0	0
Register L	87	1	0	0	0	0	1	1	1
Memory(M)	00	0	0	0	0	0	0	0	0

Figure 6: Register configuration after execution (look at HL)

7.6 Conclusion

```
9 \times 15 = 135 = 0087H
```

We see that the result in HL register is same as what we expected.

8.1 Objective

Write a subroutine to sort a 5-element byte array (Any algorithm will do)

8.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

8.3 Procedure

We use bubble sort algorithm to sort the array.

```
# ORG 2500
   # ARR: DB 4,2,5,6,7
   # LEN EQU 5
   # ORG 0000
   START:
                  LXI H, ARR
                               ;start of array
                 MVI C,LEN
                  DCR C
                                ;c-- as we will only go through first 4
                 MVI D,00
                               ;d acts a bool, if any swap happend, d = 1
    CHECK:
                 MOV A,M
11
                 INX H
12
                 CMP M ; compare a[i] with a[i+1]
   ;if a[i] - a[i+1] > 0 \rightarrow Cy = 0, Z = 0 (we swap)
;if a[i] - a[i+1] = 0 \rightarrow Cy = 0, Z = 1 (we don't swap)
14
15
   ;if a[i] - a[i+1] < 0 -> Cy = 1, Z = 0 (we don't swap)
                  JC NEXTBYTE
17
                 JZ NEXTBYTE
    ;here swap occurs
19
                 MOV B,M ;a[i] = A, a[i+1] = B
20
21
                  MOV M,A ;a[i+1] = A
                  DCX H
22
                 MOV M,B ;a[i] = B
23
24
                  INX H
                 MVI D,01
                               ;set flag that swap occured
25
26
   NEXTBYTE:
27
                  JNZ CHECK
28
                  MOV A,D
30
                 \ensuremath{\mathtt{CPI}} 01 ;comapare immediate A and 01
    ;if A - 01 > 0 -> Cy = 0, Z = 0 -> A(D) is zero, no swap taken place, exit
31
   ;if A - 01 = 0 \rightarrow Cy = 0, Z = 1 \rightarrow A or D is 1, swap taken place redo
32
                  JZ START
33
                 HLT
```

Listing 8: assembly program to bubble sort array

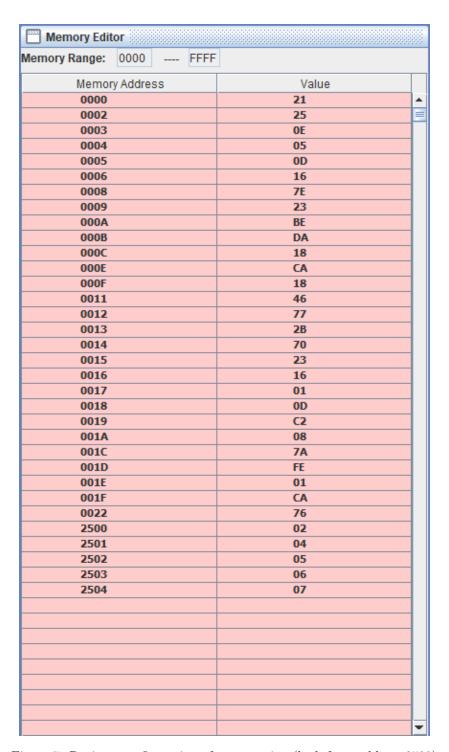


Figure 7: Register configuration after execution (look from address 2500)

8.6 Conclusion

We see that after program execution, values of address 2500 - 2504 is sorted in ascending order. Hence the program is working as expected.

9.1 Objective

Write a sub-routine to store all the registers (A, F, B, C, D, E, H, L, I, SPL, SPH, PCL, PC, in that order) starting from location MYREGISTERS.

9.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

9.3 Program

```
MVI A,10
                        ;set A
          LXI B,5092
                        ;set BC
          LXI D,2794
                        ;set DE
          LXI H,3792
                        ;set HL
          SIM
                        ;set inturrept mask as value of {\tt A}
          LXI SP,F001
          CALL DEBUG
          HLT
   # MYREGISTERS EQU 2000H
11
   DEBUG: PUSH H
          PUSH D
12
          PUSH B
14
          PUSH PSW
          LXI H, MYREGISTERS
16
          POP D
17
          CALL STORE
                        ;store AF
          POP D
18
          CALL STORE
                        ;store BC
          POP D
20
          CALL STORE
                        ;store DE
21
          POP D
22
          CALL STORE
                        ;store HL
23
24
          RIM
          MOV M,A
                        ;store I
          INX H
26
          XCHG
                        ;swap HL and DE
          LXI H,0000
28
                        ;now HL <- SP
          DAD SP
29
30
          XCHG
                        ;now HL-> save addr, DE<- SP
   ;problem, SP also has this function call stuff, so we need to remove it's info from DE
31
   ;(DE = DE + 2 [remember SP stack works reverse that's why +])
          INX D
33
          INX D
34
   ;now store DE
          CALL STORE
36
   ; now we need to store PC, which will be in Stack due to function call
37
          XCHG
                        ;swap HL and DE to store HL stuff in DE
38
                        ;get PC data from SP (stack mem has garbage now)
          XTHL
39
          XCHG
40
                        ;now HL has save addr, DE has data
          CALL STORE
          XCHG
                        :PC data back in HL
42
          XTHL
                        ;PC data back in stack
          XCHG
                        ; save addr back in HL
44
          RET
45
   ;Procedure STORE
47
   ;stores data in DE to memory whose address is in HL
   STORE: MOV M,D
49
          INX H
50
51
          MOV M,E
          INX H
          RET
```

Listing 9: assembly program to store register configuration

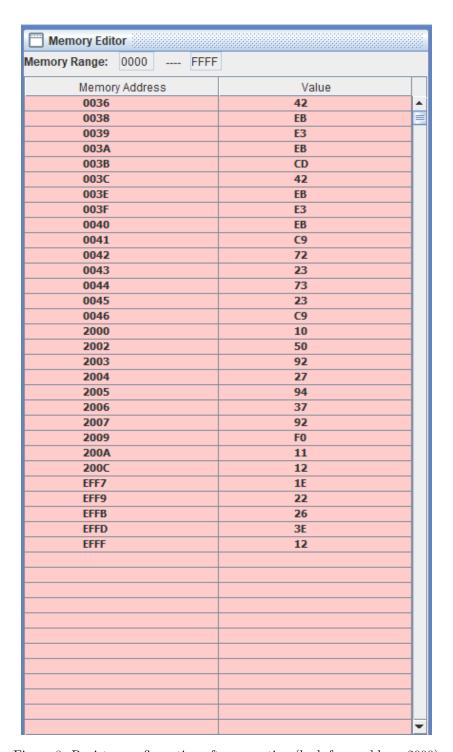


Figure 8: Register configuration after execution (look from address 2000)

9.5 Conclusion

We see that after program execution, all the predefined value of registers are stored in memory starting from address 2000.

10.1 Objective

Implement a POST or power-on-self-test where each RAM location is tested for stuck-at-zero or stuck-at-one fault. In your case the function takes the start address of the RAM block and the block size in bytes. The function sets CY in case of any error (else it is set to 0); HL contains the faulty location and Acc contains 0 for stuck at zero fault and 1 for stuck at one fault. [Note: usually there wont be any error as your RAM is not faulty, so direct checking may not set CY flag]

10.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

10.3 Procedure

We iteratively go through STARTLOC to (STARTLOC + LEN) and check if any value is 1 or not, if it is, we exit from there setting the C flag.

```
#STARTLOC EQU 6400
   #LEN EQU 05
   ;let position 6403 have stuck at one fault
            LXI H,6403
            MVI M,01
   ;let we start out search from 6400 an search 05 addresses
            LXI H, STARTLOC
            MVI B, LEN
            CALL POST
            HLT
10
11
12
   POST:
           MOV A,M
            CPI 01
   ;A will be 0 or 1, if 1 we need to exit
14
   ;A zero \rightarrow A - 1 < 0, Cy =1
   ; A one \rightarrow A - 1 = 0, Z = 1, we exit here
16
            JZ ERR ;if 1 found, we exit are set Cy 1 directly
17
18
            DCR B
19
20
            JNZ POST
   ; we will reach here only if there is no 1 found, so we need to set Cy 0
21
            JC REVERT ; if Cy 1 , we revert, else we direct return
   ;we reach here when 1 found
24
25
            STC ;set Cy 1
26
   ERR:
           RET
27
   ;we reach here if no 1 found but Cy 1 due to previous CMP stuff
29
   REVERT: CMC ; complements Cy, if Cy 1, Cy becomes 0
30
            RET
```

Listing 10: assembly program for POST for stuck at 1 fault

Register	Value	7	6	5	4	3	2	1	0	Register	Value	7	6	5	4	3	2	1	0				
Accumulator	01	0	0	0	0	0	0	0	1	Accumulator	00	0	0	0	0	0	0	0	0				
Register B	02	0	0	0	0	0	0	1	0	Register B	00	0	0	0	0	0	0	0	0				
Register C	00	0	0	0	0	0	0	0	0	Register C	00	0	0	0	0	0	0	0	0				
Register D	00	0	0	0	0	0	0	0	0	Register D	00	0	0	0	0	0	0	0	0				
Register E	00	0	0	0	0	0	0	0	0	Register E	00	0	0	0	0	0	0	0	0				
Register H	64	0	1	1	0	0	1	0	0	Register H	64	0	1	1	0	0	1	0	0				
Register L	03	0	0	0	0	0	0	1	1	Register L	05	0	0	0	0	0	1	0	1				
Memory(M)	01	0	0	0	0	0	0	0	1	Memory(M)	00	0	0	0	0	0	0	0	0				
Resister	Value	S	Z	*	AC	*	Р	*	CY	Resister	Value	S	Z	*	AC	*	Р	*	CY				
Flag Resister	55	0	1	0	1	0	1	0	1	Flag Resister	54	0	1	0	1	0	1	0	0				
Torre						/-1				Tues						\/=l	_						
Type Value											Type					Value							
Stack Pointer(SP)				000					Stack Pointer(SP)		_	0000											
Memory Pointer (HL)				640					Memory Pointer (HL)			6405											
Program Status Word(015	55				Program Status Word(Program Status Word(PSW)					0054									
Program Counter(PC)			000	D				Program Counter(PC)	gram Counter(PC) 0008														
Clock Cycle Counter 221										Clock Cycle Counter	Clock Cycle Counter 266												
Instruction Counter 29									Instruction Counter					37									

(a) result of the program

(b) result of the program if we comment line 4 and 5 $\,$

Figure 9: Result of Program Execution

10.6 Conclusion

We see that if there exist a 1 in some memory location, the program sets Cy flag and HL register to stuck address; when there is no 1 in whole array, C is unset Hence the program is working as expected.

11.1 Objective

Implement a binary search — the function would take the start address and no. of elements in the array. If successful the function resets CY flag and the HL pair points to the element found else CY is set and the value in HL pair is irrelevant.

11.2 Tool/Experimental setup considered

• Jubin's 8085 Simulator

11.3 Program

```
# ORG 2000H
2
   # ARR : DB 2,4,7,8,10
   # ORG 0000H
   # N EQU 5
   # X EQU 7
5
                MVI C.N
                             ; Number of elements in the Array
                DCR C
                             ; Now we will be using C as the high pointer of Binary Search
                MVI B,00
                             ;It is the low pointer of Binary Search
                MVI D,X
                             ; Number we are looking for
                CALL SEARCH
                LXI H, ARR
11
                ADD L
                MOV L,A
                JNC NAD
14
                INR H
   NAD:
                MOV A,D
16
                CMP M
17
                JZ ND
18
                JC ND
19
                HLT
20
   ND:
                CMC
21
                             ;Complement the carry flag
                HLT
22
                             ;Halt
23
                MOV A,B
   SEARCH:
24
25
                CMP C
                             ;Checking if low < high
                RNC
                             ;Return if not carry
26
                ADD C
                             ;Now acc has B+C
27
                JNC NOCARRY
                CMC
29
30
   NOCARRY:
                RAR
                             ;Rotate Accumulator right by 1 bit (A = A >> 1) i.e A = (B+C)/2
                MOV E,A
                LXI H, ARR
                             ;H-L now has 2000h
33
                ADD L
                             ;Accumlator now has the offset to the mid point
34
                MOV L,A
                             ;H-L now points to the mid
35
36
                JNC NOPE
                INR H
37
38
   NOPE:
                MOV A,D
                             ;Accumulator now has the number we are looking for
39
                CMP M
                             ;Compare the number we are looking for with the mid point
40
                JC LEFT
41
                             ; If less than mid point, go left
                JZ ND
42
                             ; If equal, return
                MOV B,E
                             ;E had the previous mid point index
43
44
                INR B
                             ;Now looking for [M+1:]
                JMP SEARCH
                             ;Recall search
45
46
   LEFT:
                MOV C,E
                DCR C
48
                JNZ SEARCH
49
50
                JZ ND
51
52
   ; CMP M
   ; If A less than (R/M), the CY flag is set and Zero flag is reset.
53
   ;If A equals to (R/M), the Zero flag is set and CY flag is reset.
   ; If A greater than (R/M), the CY and Zero flag are reset.
```

Listing 11: assembly program for the implementation of Binary Search

Instruction Counter				22					Instruction Counter		106									
Clock Cycle Counter			148	3				Clock Cycle Counter		682										
Program Counter(PC) 001D									Program Counter(PC)			001B								
Program Status Word(PSW) 0755										Program Status Word(PSW)		1A04							
Stack Pointer(5P) FFFE Memory Pointer (HL) 2002										Memory Pointer (HL)					200)4				
1752										Stack Pointer(SP)					000	00				
Type Value									Type \							Value				
Flag Resister	55	0	1	0	1	0	1	0	1	Flag Resister	04	0	0	0	0	0	1	0	0	
Resister	Value	S	Z	*	AC	*	Р	*	CY	Resister	Value	S	Z	*	AC	*	Р	*	C,	
		_					_													
Memory(M)	07	0	0	0	0	0	1	1	1	Memory(M)	10	0	0	0	1	0	0	0	0	
Register L	02	0	0	0	0	0	0	1	0	Register L	04	0	0	0	0	0	1	0	0	
Register H	20	0	0	1	0	0	0	0	0	Register H	20	0	0	1	0	0	0	0	0	
Register E	02	0	0	0	0	0	0	1	0	Register E	03	0	0	0	0	0	0	1	1	
Register D	07	0	0	0	0	0	1	1	1	Register D	1A	0	0	0	1	1	0	1	(
Register C	04	0	0	0	0	0	1	0	0	Register C	04	0	0	0	0	0	1	0	0	
Register B	00	0	0	0	0	0	0	0	0	Register B	04	0	0	0	0	0	1	0	(
Accumulator	07	0	0	0	0	0	1	1	1	Accumulator	1A	0	0	0	1	1	0	1	(
Register	Value	7	6	5	4	3	2	1	0	Register	Value	7	6	5	4	3	2	1	(

- (a) result of the program when X is in array
- (b) result of the program when X is not in array

Figure 10: Result of Program Execution

11.5 Conclusion

We see that when X is in array, Cy flag is set and HL points to the data's address in array; but then X is not present, Cy flag is not set.

12.1 Objective

Suppose that you are reading a bit of an input port (say, PORT 0) to which the output of a function generator, producing a rectangular wave, is connected. Measure the ON of this repetitive rectangular waveform time in terms of millisecond.

12.2 Procedure

- 1. We first wait in an infinite loop, waiting for the signal to turn 0 (in case we started program when signal was already 1).
- 2. Then when the signal turns 0, the actual count procedure starts, we again keep waiting in an infinite loop, waiting for the signal to go 1 again.
- 3. When the signal goes 1 now, we start counting the amount of time the signal is 1 in another infinite loop.
 - The two register pair is too small to count the number of machine cycles it took for the signal to go to 0.
 - so we added a delay (1 ms) after every count, now the count signifies the amount of (1ms) delays it took for signal to go to 0.
- 4. now the signal is back to 0, and we have the amount of delays it took for signal to go to 0, we write that data to SAVELOC.

12.3 Program

```
# ORG 1000H
   ;delay -> 1
   DELAY:
                MVI D,DE
   DELAYLoop:
                DCR D
                JNZ DELAYLoop
                RET
6
   # ORG 0000
   # PORTX EQU 10
8
   INPUT:
                IN PORTX
9
                                  ;input data goes to A
                RAR
                JC INPUT
                                 ; if already high read again
   ;now input port data 0 (actual low->high timing cont begins now)
                IN PORTX
                RAR.
14
                                  ;if LOW read again
15
                JNC L1
   ;now input HIGH -> start counting
16
17
                LXI B,0000
18
   COUNT:
                INX B
                                  ;6T
                CALL DELAY
19
20
                IN PORTX
                                  ;10T
                RAR
21
                                 ;4T
                JC COUNT
                                 ;10T -> jump till input is 1
22
   ;now input is 0 we save counter
23
   ; time taken = BC*(30*1/3 + 1ms) = BC*11ms +- 2 ms
24
   # SAVELOC
                EQU 5000H
25
                LXI H, SAVELOC
                MOV M,B
27
                INX H
28
                MOV M,C
                HLT
30
```

Listing 12: assembly program to calculate time period of rectangular wave

12.4 Conclusion

We created a program which will calculate the time period of a rectangular wave as follows

$$T = BC * (30 * 1/3 + 1ms) = BC * 11ms \pm 2ms$$