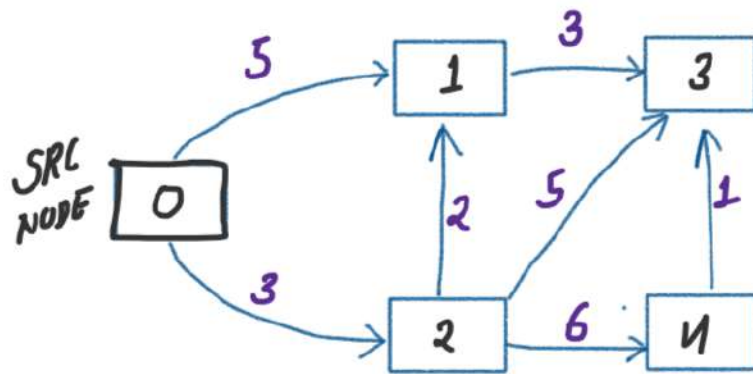


२५/०२/२०२५

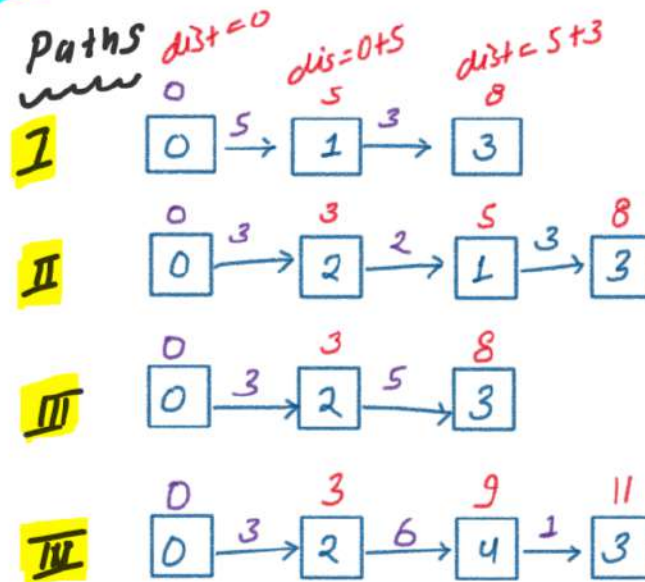
## GRAPHS CLASS - 4

# 1. Shortest path in a weighted directed graph using DFS

SSSPA: SINGLE SOURCE SHORTEST PATH ALGORITHMS



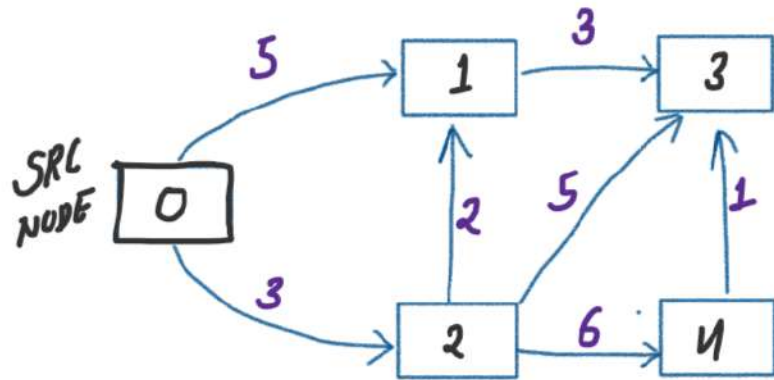
Explanation



Node	Shortest Distance
0	0
1	5
2	3
3	8
4	9

Output 0 5 3 8 9

Find shortest distance from SRC [0] to each nodes [1], [2], [3], [4]



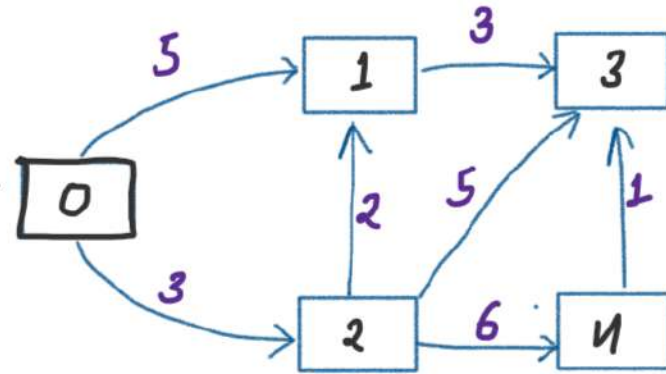
**SSSP AYO**  
 Single source shortest  
 path Algorithm

Why Topological Sort Algorithm used?  
 ↳ Because Yaha par Nodes ki Bich me **Dependency** create ho Rahi Hai.

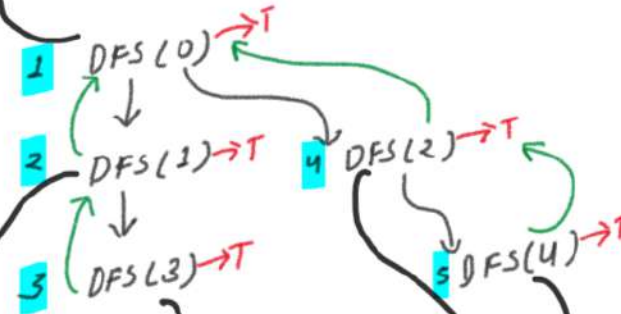
- STEP 1 Create Topological Ordernum using DFS.
- STEP 2 STORE All shortest distances using Topological Ordernum.
- STEP 3 Print All shortest distances

# STEP 1

SRC NODE



① have two child ① and ②  
 visited already  
 not visited now  
 go to call DFS(2)



Key	Value
0	{1, 2}
1	{3}
2	{1, 3, 4}
3	X
4	{3}

AdjList

Key	Value
0	<del>F</del> T
1	<del>F</del> T
2	<del>F</del> T
3	<del>F</del> T
4	<del>F</del> T

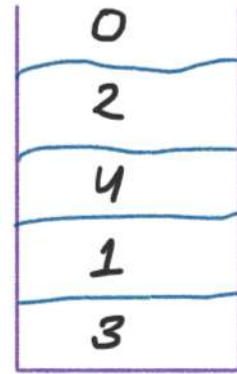
visited

nobody depends on ③  
 so push it into stack first -

① have only one child ③ so already visited Hai so push ① into stack

② have 3 child ① ③ ④  
 push 2 when all child of it are visited  
 visited already  
 not visited now go to call DFS(4)  
 already visited so push ④ into stack

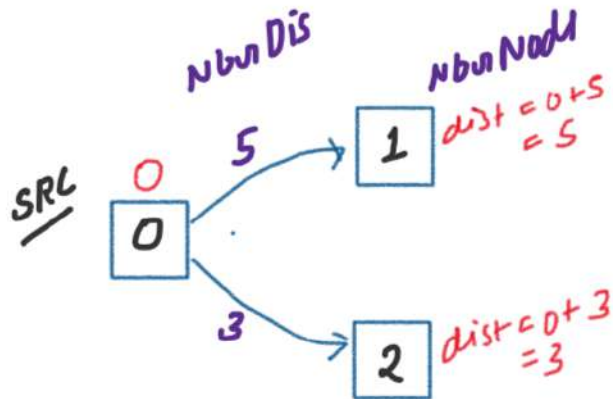
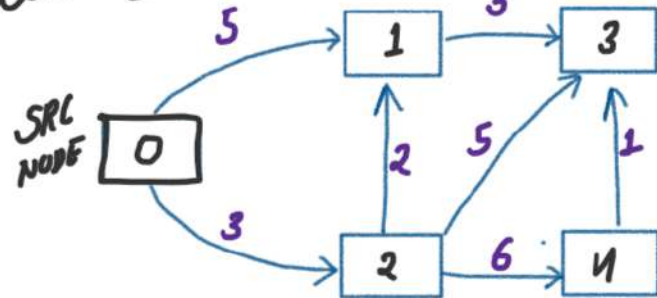
④ have only 1 child ③  
 already visited



STACK

TOPO ORDER

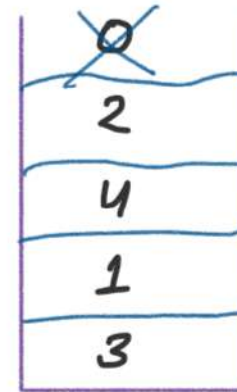
STEP 2 Iteration 1



(A) go to stack top  
Element which is  
SRC

(B) go to AdjList to get  
All child of SRC

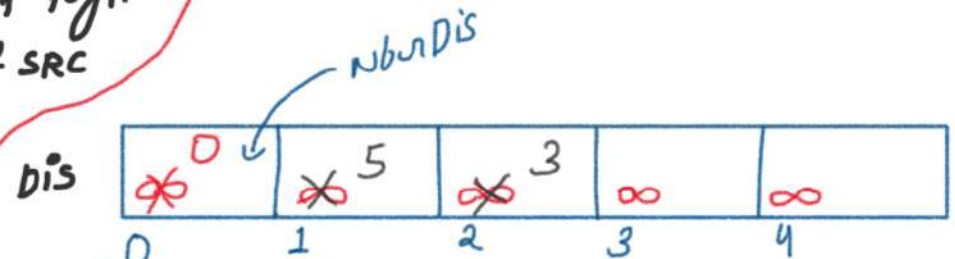
(C) store distanc of  
NbrNode when  
 $\text{dist}[\text{NbrNode}] >$   
 $\text{NbrDis} + \text{dist}[\text{SRC}]$



Stack (TopoOrder)

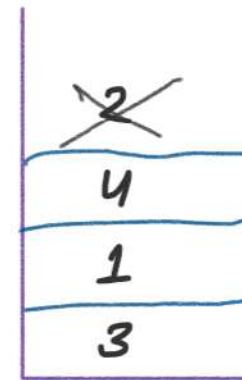
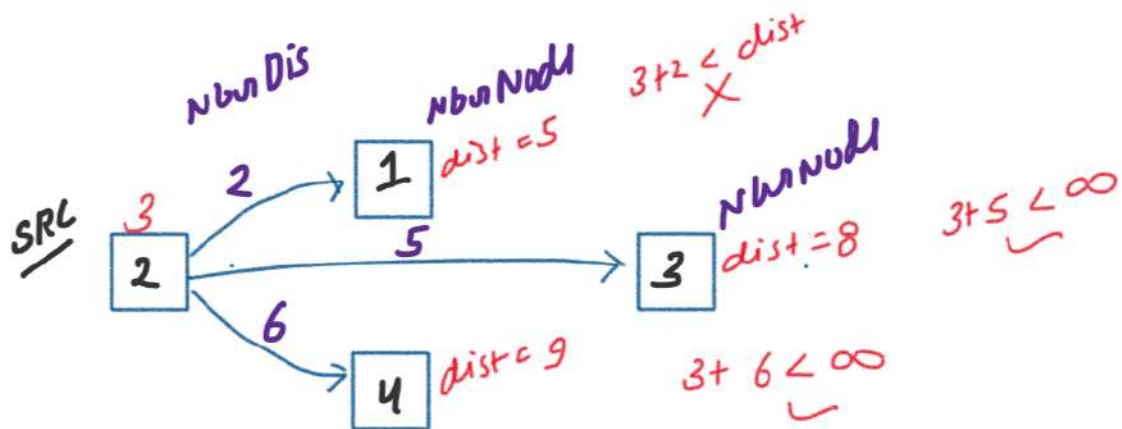
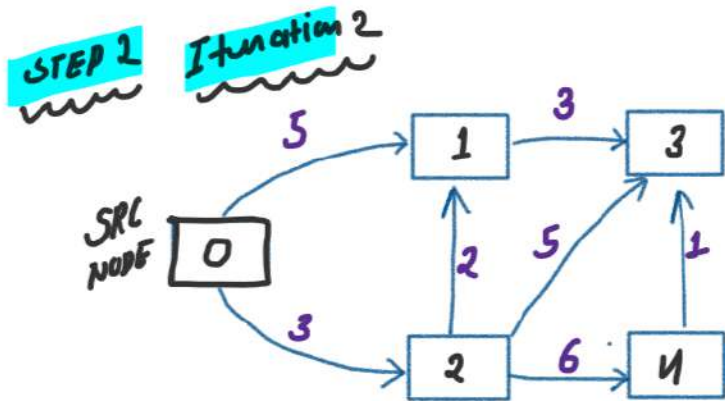
Key	Value
0	{ {1,5}, {2,3} }
1	{ {3,3} }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList



NbrNode Distance Array to store minimum distanc of  
Each node from SRC Node

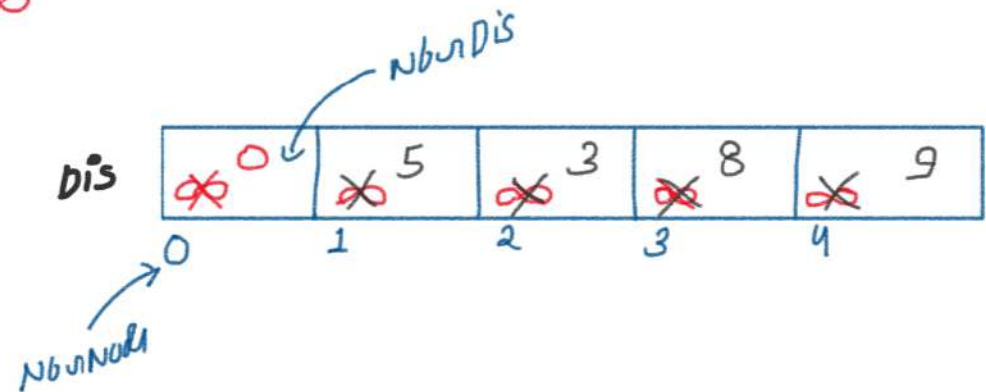


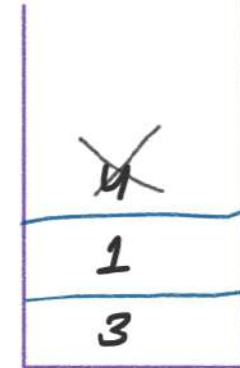
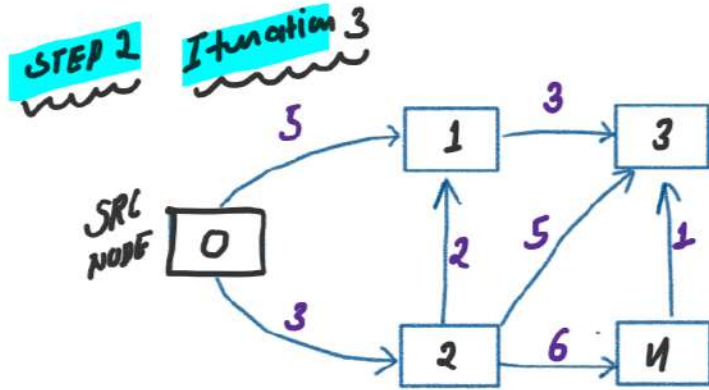


Stack (TopoOrder)

Key	value
0	{ {1,5}, {2,3} }
1	{ {3,3} }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList

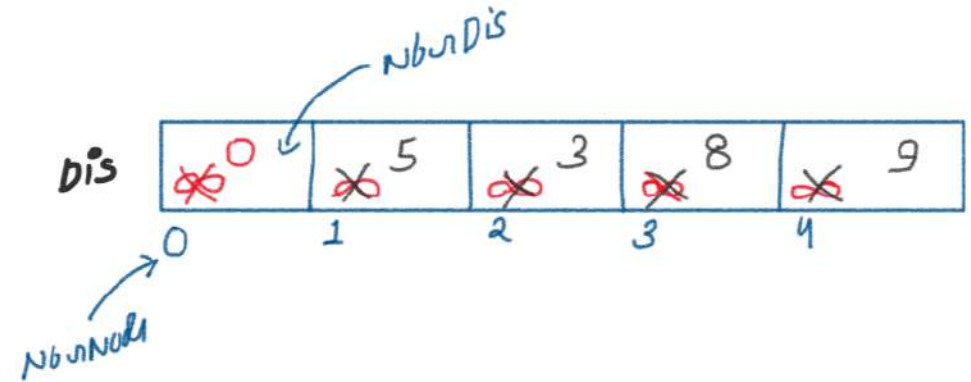
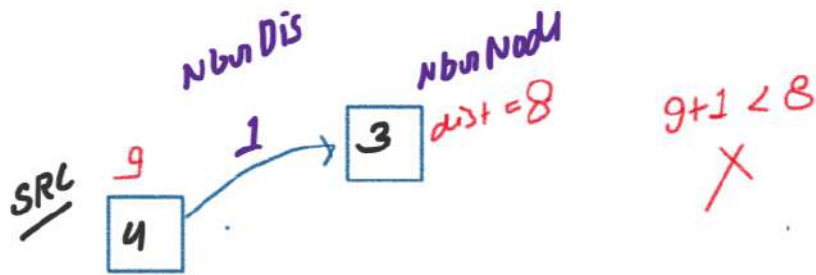




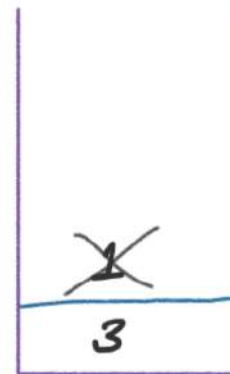
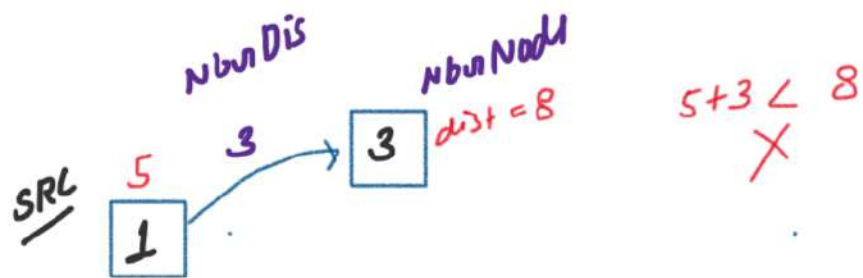
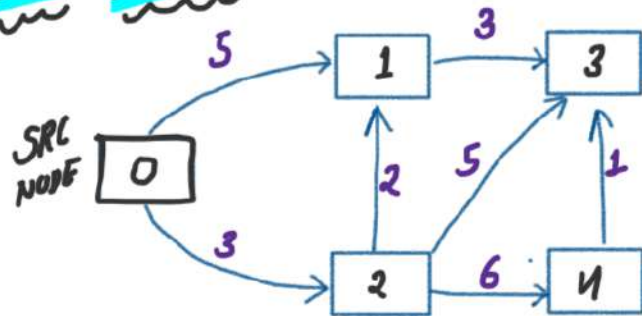
Stack (TopoOrder)

Key	Value
0	{ {1,5}, {2,3} }
1	{ {3,3} }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList



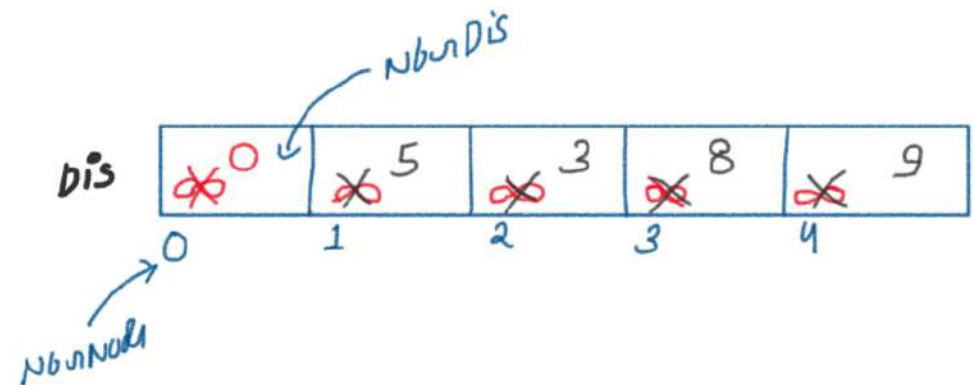
**STEP 2** **Iteration 4**



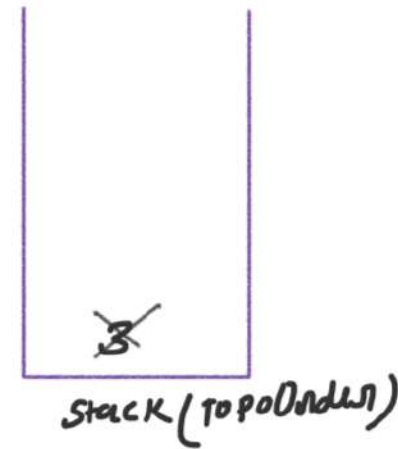
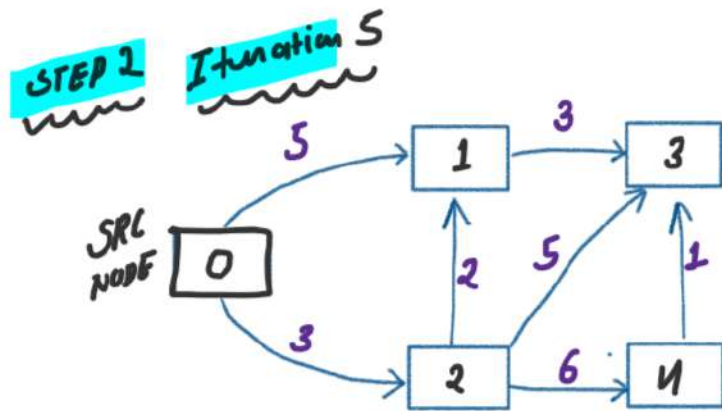
Stack (TopoOrder)

key	value
0	{ {1,5}, {2,3} }
1	{ {3,3} }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList





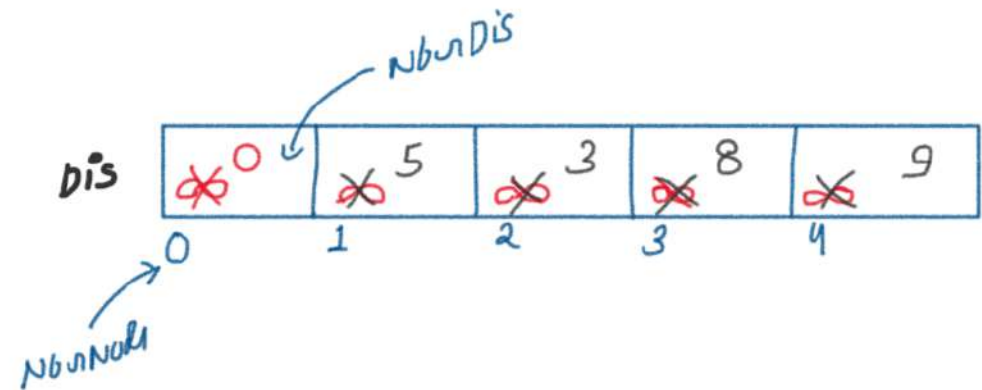


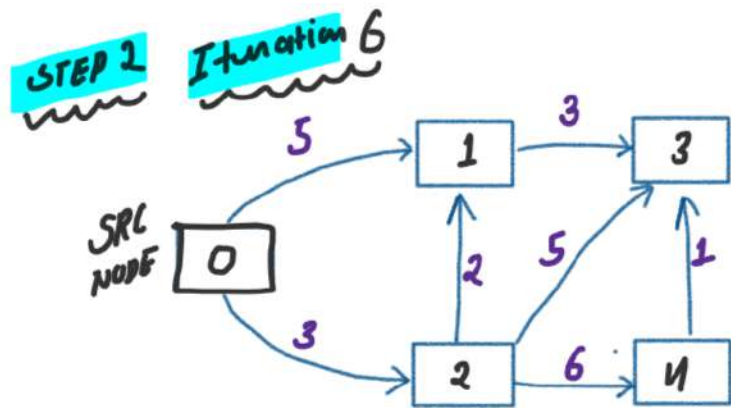
Key	Value
0	{ {1,5}, {2,3} }
1	{ {3,3} } { }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList

SRC 8  
3

[3] does not have any child / nbr node





Empty

Stack (TopoOrder)

Key	Value
0	{ {1,5}, {2,3} }
1	{ {3,3} }
2	{ {1,2}, {3,5}, {4,6} }
3	{ }
4	{ {3,1} }

AdjList

**STEP 3**  
Print This  
ARRAY

Output

dis

0	5	3	8	9
0	1	2	3	4

```

// 1. Shortest path in a weighted directed graph using DFS (SSSP Algorithm)

#include<iostream>
#include<stack>
#include<vector>
#include<unordered_map>
#include<limits.h>
#include<list>

using namespace std;

class Graph
{
public:
    unordered_map<int, list<pair<int, int>>> adjList;

    void addEdges(int u, int v, int wt, int direction){
        if(direction == 1){
            // Directed Graph
            adjList[u].push_back({v,wt});
        }
        else{
            // Undirected Graph
            adjList[u].push_back({v,wt});
            adjList[v].push_back({u,wt});
        }
    }

    // Step 1: Create topological order using DFS
    void topologicalSortUsingDFS(int src, unordered_map<int, bool> &visited, stack<int> &topoOrder){
        ....
    }

    // Step 2: Store all shortest distances from src node using topoOrder
    void shortestPath(stack<int> &topoOrder, int n){
        ....
    }
};

int main(){
    Graph g;
    g.addEdges(0,1,5,1);
    g.addEdges(0,2,3,1);
    g.addEdges(2,1,2,1);
    g.addEdges(1,3,3,1);
    g.addEdges(2,3,5,1);
    g.addEdges(2,4,6,1);
    g.addEdges(4,3,1,1);

    int src = 0;
    unordered_map<int, bool> visited;
    stack<int> topoOrder;
    g.topologicalSortUsingDFS(src, visited, topoOrder);

    int n = 5;
    g.shortestPath(topoOrder, n);

    return 0;
}

```

Time and space complexity

?

0

—

```
// Step 1: Create topological order using DFS
void topologicalSortUsingDFS(int src, unordered_map<int, bool> &visited, stack<int> &topoOrder){
    // Initial state
    visited[src] = true;

    for(auto nbrPair: adjList[src]){
        int nbrNode = nbrPair.first;
        // int nbrDist = nbrPair.second;
        if(!visited[nbrNode]){
            topologicalSortUsingDFS(nbrNode, visited, topoOrder);
        }
    }
    // Push into stack to create the topoOrder
    topoOrder.push(src);
}
```

```
// Step 2: Store all shortest distances from src node using topoOrder
void shortestPath(stack<int> &topoOrder, int n){
    // Create an vector to store the shortest distance of each nodes from src node
    vector<int> dist(n, INT_MAX);

    // A: Initial state
    int src = topoOrder.top();
    topoOrder.pop();
    dist[src] = 0;

    // B: Goto adjList to get the all childs of src node
    for(auto nbrPair: adjList[src]){
        int nbrNode = nbrPair.first;
        int nbrDist = nbrPair.second;
        // C: Update the distance when
        if(dist[src] + nbrDist < dist[nbrNode]){
            dist[nbrNode] = dist[src] + nbrDist;
        }
    }

    // Apply the same Step A, B, & C to all remaining node
    while (!topoOrder.empty()){
        // A: Initial state
        int src = topoOrder.top();
        topoOrder.pop();

        // B: Goto adjList to get the all childs of src node
        for(auto nbrPair: adjList[src]){
            int nbrNode = nbrPair.first;
            int nbrDist = nbrPair.second;
            // C: Update the distance when
            if(dist[src] + nbrDist < dist[nbrNode]){
                dist[nbrNode] = dist[src] + nbrDist;
            }
        }
    }

    // Step 3: Print all shortest distance from created
    cout << "Print all shortest distance: " << endl;
    for(auto i: dist){
        cout << i << " ";
    }
}
```

## 2. Shortest path/distance in a weighted undirected graph

🚀 Dijkstra Algorithm: Source, Destination, Minimum

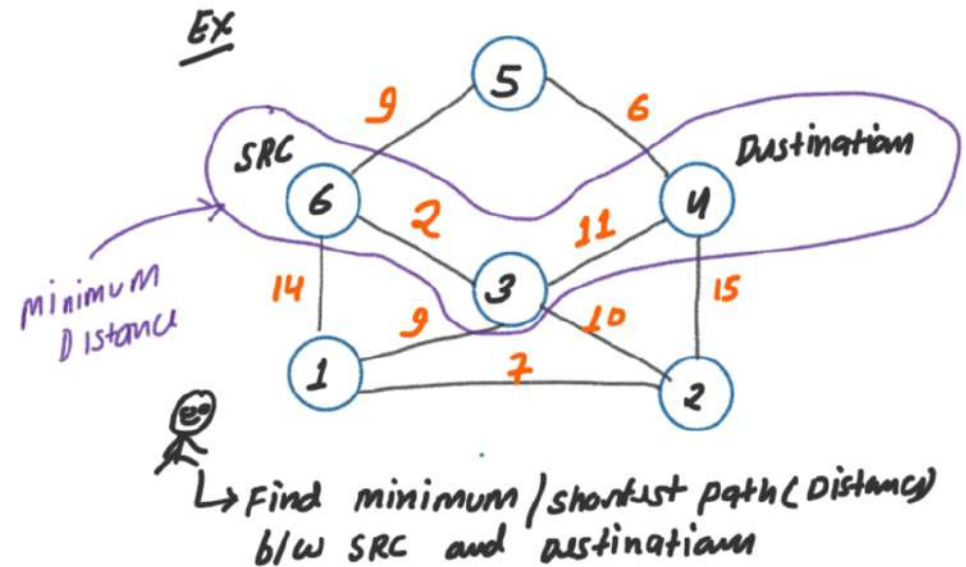
What is Dijkstra Algorithm and where to use it?

Dijkstra's Algorithm is a popular graph search algorithm used to find the **shortest** path between a **source** node and all other nodes in a **weighted, directed or undirected** graph.



**Dijkstra's Algorithm Applications in real Life:**

1. To find the shortest path from source to destination
2. In social networking applications
3. In a telephone network
4. To find the Locations in the map



**Dijkstra's Algorithm Complexity:**

Time Complexity:  $O(E \log V)$

Space Complexity:  $O(V)$

where,  $E$  is the number of edges and  $V$  is the number of vertices



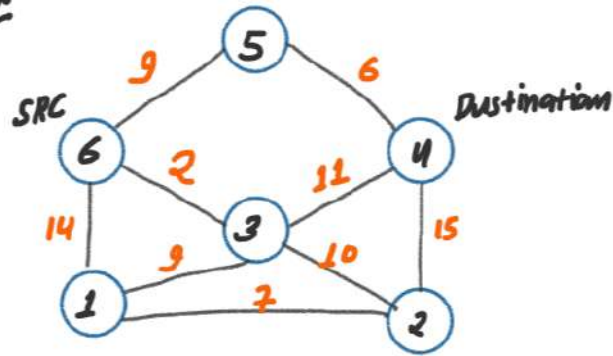
```

graph LR
    SRC((6)) ---|9| 5((5))
    5 ---|6| 4((4))
    SRC ---|2| 3((3))
    3 ---|11| 4
    SRC ---|14| 1((1))
    1 ---|9| 3
    3 ---|10| 2((2))
    1 ---|7| 2
    4 ---|15| 2
    style SRC fill:#fff,stroke:#000,stroke-width:2px
    style 4 fill:#fff,stroke:#000,stroke-width:2px
    style 1 fill:#fff,stroke:#000,stroke-width:2px
    style 2 fill:#fff,stroke:#000,stroke-width:2px
    style 3 fill:#fff,stroke:#000,stroke-width:2px
    style 5 fill:#fff,stroke:#000,stroke-width:2px
    
```

Output = 13      Input  $\Rightarrow$  SRC = 6  
Dist = 4

# Dijkstra Algo with SET DATA STRUCTURE

Ex



Dist

ARRAY

→ This Array is used to store the total shortest distance from src to All nodes including src and Destination node.

SET

Why use set?

→ Kyunki Hum shortest distance pahle chahiye from SRC to DST.

Why distance is first in the set's pair?

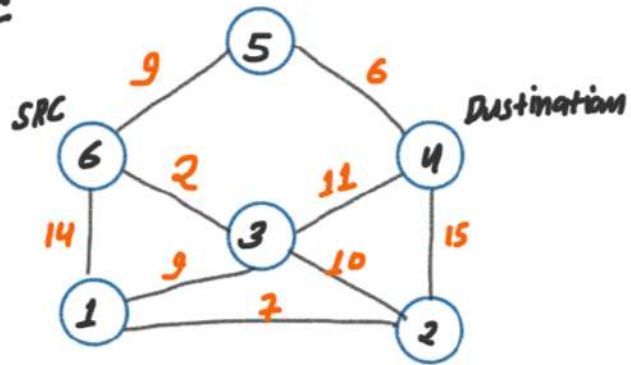
→ Kyunki Hum set ko distance ke sorted order me chahate hai

jiske dwara hume shortest distance pahle mil jayega from src to dst.

Set < pair < int, int > > st;

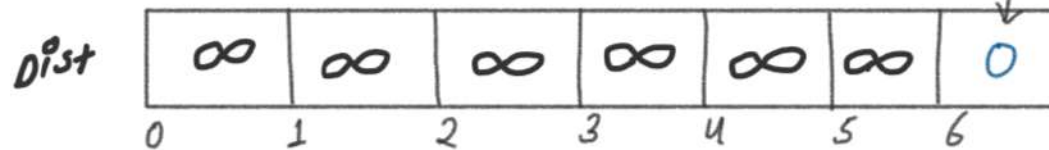
Distance SRC

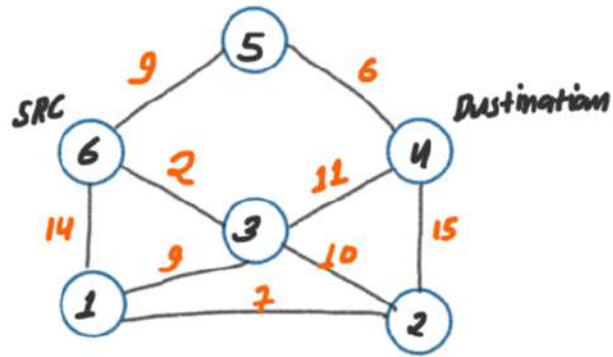
Ex



initial state

```
st.push( { dist, src } );  
dist[src] = 0;
```





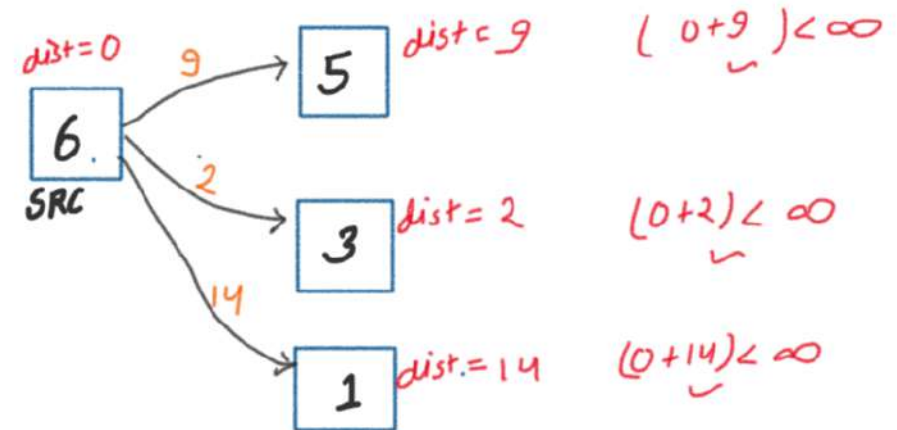
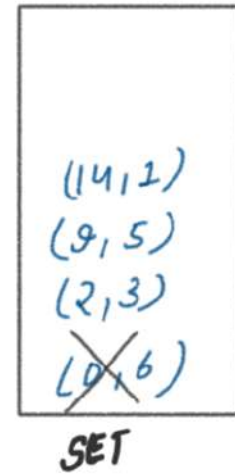
Iteration 1

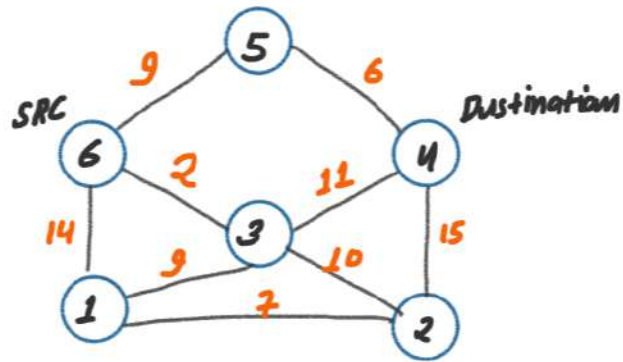
Dist							
	0	1	2	3	4	5	6
	$\infty$	14	$\infty$	2	$\infty$	9	0

(A) Select shortest distance Node from the set.  
(0,6)

(B) Delete selected node from set

(C) Update new distance for non node and create new entry for new distance in set.





Iteration 2

(A) Select shortest distance node from the set.

(2, 3)

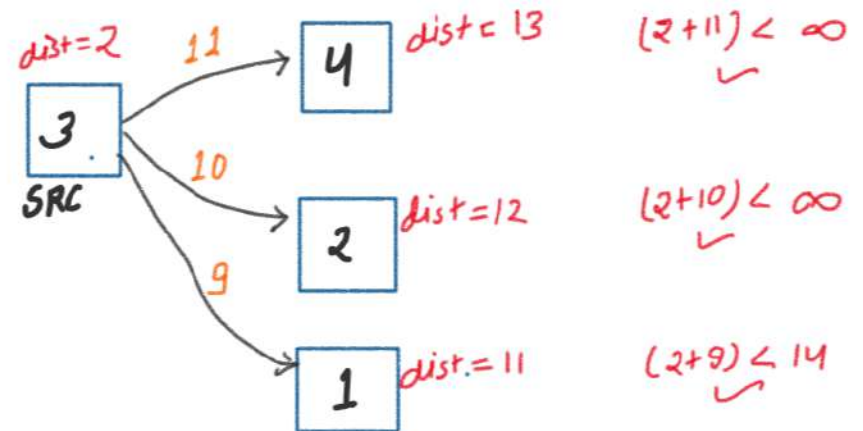
(B) Delete selected node from set

(C) Update new distances for non node and create new entry for new distance in set.

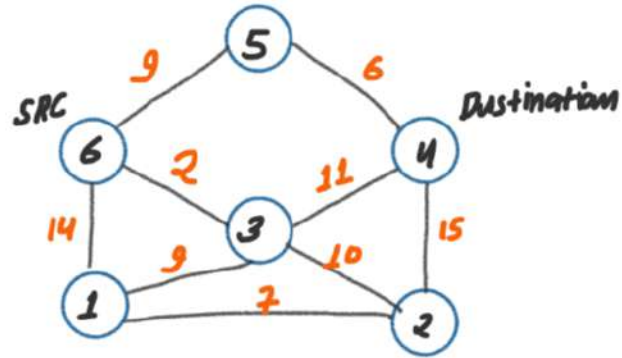
(13, 4)  
 (12, 2)  
~~(14, 1)~~ (11, 1)  
 (9, 5)  
~~(2, 3)~~

SET

Dist							
	$\infty$	11	12	2	13	9	0
	0	1	2	3	4	5	6







Iteration 3

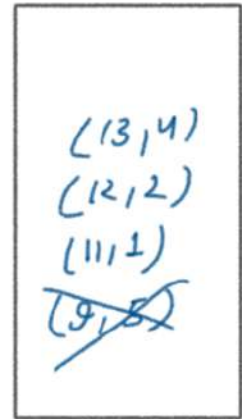
Dist	$\infty$	11	12	2	13	9	0
	0	1	2	3	4	5	6

(A) Select shortest distance Node from the set.

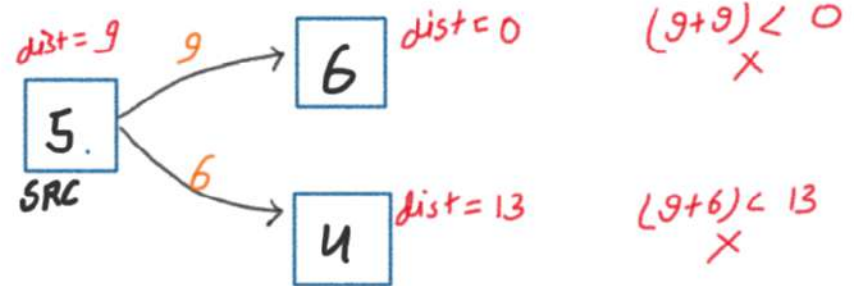
(9, 5)

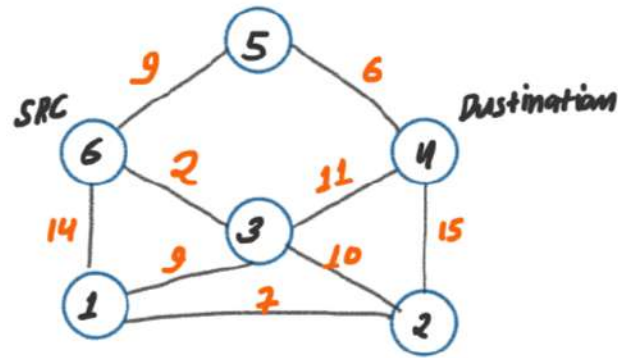
(B) Delete selected node from set

(C) Update new distance for non Node and create new entry for new distance in set.



SET





Iteration 4

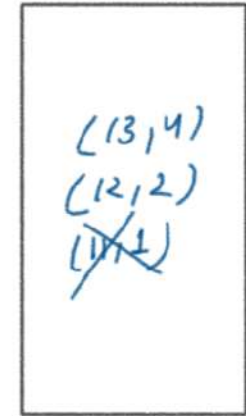
Dist	$\infty$	11	12	2	13	9	0
	0	1	2	3	4	5	6

(A) Select shortest distance node from the set.

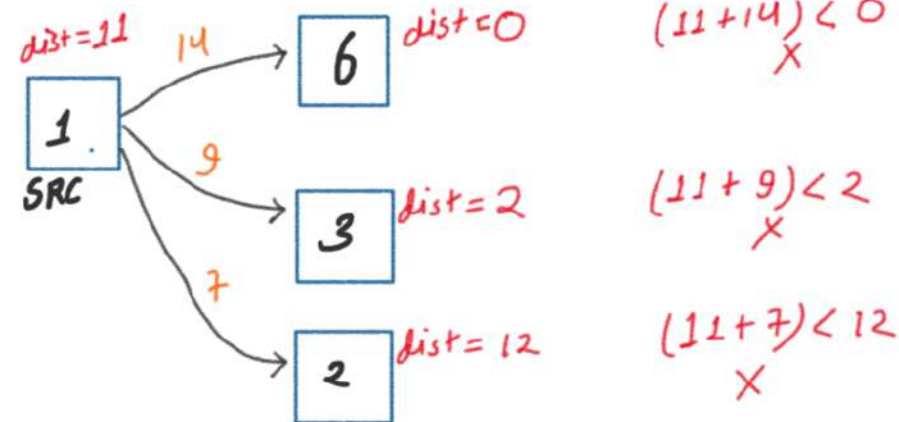
(11, 1)

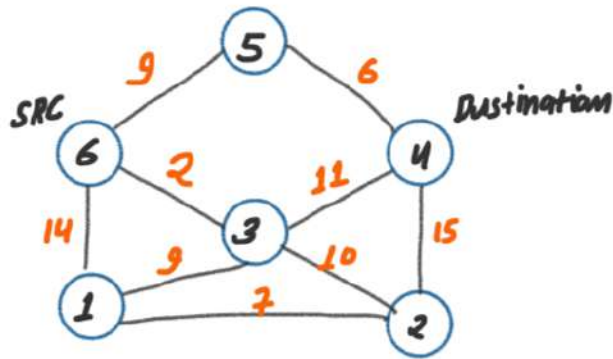
(B) Delete selected node from set

(C) update new distance for non node and create new entry for new distance in set.



SET





Iterations

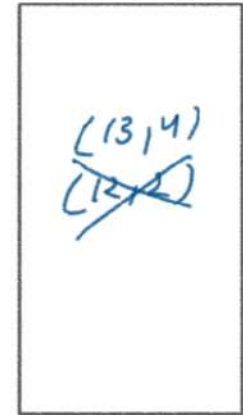
Dist	$\infty$	11	12	2	13	9	0
	0	1	2	3	4	5	6

(A) select shortest distance Node from the set.

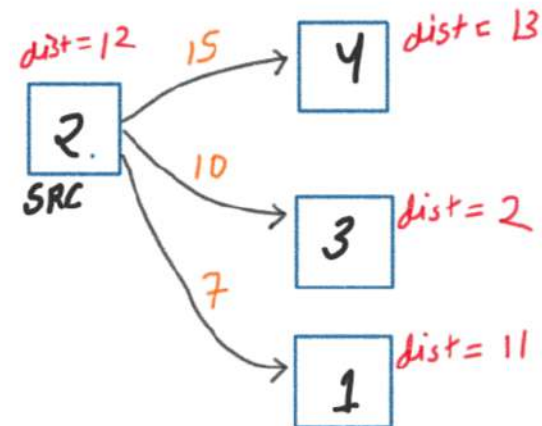
(12, 2)

(B) Delete selected node from set

(C) update new distance for non Node and create new entry for new distance in set.



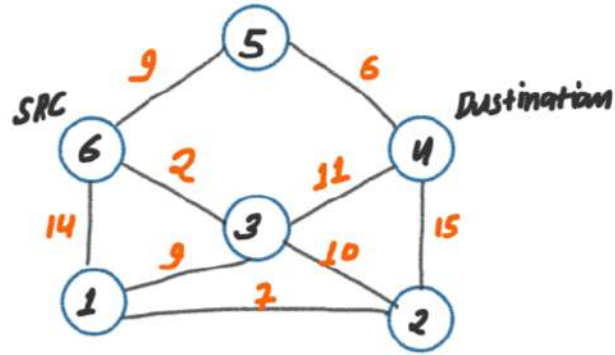
SET



$$(12 + 15) < 13 \quad \times$$

$$(12 + 10) < 2 \quad \times$$

$$(12 + 7) < 11 \quad \times$$



Iteration 6

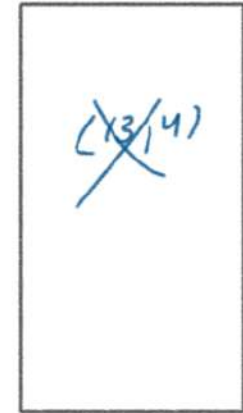
Dist	0	1	2	3	4	5	6
	$\infty$	11	12	2	13	9	0

(A) Select shortest distance Node from the set.

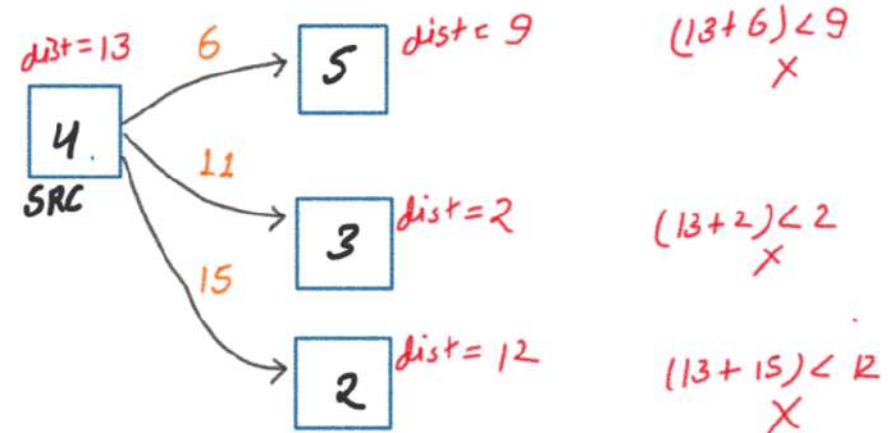
(13, 4)

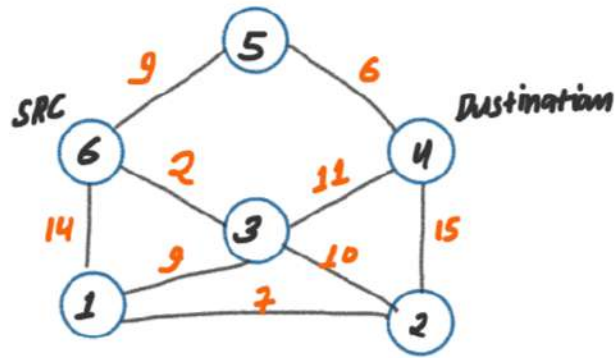
(B) Delete selected node from set

(C) Update new distance for non Node and create new entry for new distance in set.



SET





Iteration 7

Now Set is Empty

ISKA matlab Humne All Shortest Distance find kar li hai from SRC to All nodes Including SRC and destination node SET

Empty  
now

Dist	$\infty$	11	12	2	13	9	0
	0	1	2	3	4	5	6



Dist[4] = 13

This is the shortest path from [6] to [4]

Output



```
// 2. Shortest path in a weighted undirected graph using Dijkstra Algorithm
```

```
#include<iostream>
#include<stack>
#include<vector>
#include<unordered_map>
#include<limits.h>
#include<list>
#include<set>
```

```
using namespace std;
```

```
class Graph
```

```
{
public:
    unordered_map<int, list<pair<int, int>>> adjList;

    void addEdges(int u, int v, int wt, int direction){
        if(direction == 1){
            // Directed Graph
            adjList[u].push_back({v,wt});
        }
        else{
            // Undirected Graph
            adjList[u].push_back({v,wt});
            adjList[v].push_back({u,wt});
        }
    }
}
```

```
void dijkstraShortestDistance(int n, int src, int dest) {.....}
```

```
int main(){
    Graph g;
    g.addEdges(1,6,14,0);
    g.addEdges(1,3,9,0);
    g.addEdges(1,2,7,0);
    g.addEdges(2,3,10,0);
    g.addEdges(2,4,15,0);
    g.addEdges(3,4,11,0);
    g.addEdges(6,3,2,0);
    g.addEdges(6,5,9,0);
    g.addEdges(5,4,6,0);

    g.printAdjList();

    int n = 6;
    int src = 6;
    int dest = 4;
    g.dijkstraShortestDistance(n, src, dest);

    return 0;
}
```

```
void dijkstraShortestDistance(int n, int src, int dest) {
    vector<int> dist(n+1, INT_MAX);
    set<pair<int, int>> st;

    // Initial state
    st.insert({0,src});
    dist[src] = 0;

    // Distance updation logic
    while (!st.empty()){
        // A. select shortest distance node from the set
        auto topElement = st.begin();
        pair<int, int> topPair = *topElement;
        int topDist = topPair.first;
        int topNode = topPair.second;
        // B. Delete the selected node from the set
        st.erase(st.begin());

        // C. update new distance for nbr node and
        // create the new entry for the new distance in set
        for(auto nbrPair: adjList[topNode]) {
            int nbrNode = nbrPair.first;
            int nbrDist = nbrPair.second;

            // Now check the distance: Ki mujhe new distance update krna hai ya nahi
            if(topDist + nbrDist < dist[nbrNode]) {
                // Found the new distance

                // Update the new entry to the set
                // Find previousEntry and delete it
                auto previousEntry = st.find({dist[nbrNode], nbrNode});
                if(previousEntry != st.end()) {
                    // previousEntry present in set then delete it
                    st.erase(previousEntry);
                }

                // Update dist array for new distance
                dist[nbrNode] = topDist + nbrDist;
                // Create a new entry in the set for new distance
                st.insert({dist[nbrNode], nbrNode});
            }
        }
    }

    cout << "Shortest Distance from " << src << " Node to " << dest << " Node: " <<
    dist[dest] << endl;
}
```

OUTPUT FOR OUR GIVEN EXAMPLE  
Shortest Distance  
from 6 Node to 4  
Node: 13

## DIJKSTRA

### Limitation

---

REMBER  
these  
points

---

- ① not used for negative weight
- ② not used for unreachable node
- ③ not used for negative cycle of graph

## SET DATA STRUCTURE

- What is set data structure?
- How set data structure work?
- What is the time complexity of set data structure operation?
  - insert:  $O(1)$
  - find:  $O(1)$
  - erase:  $O(1)$

A set is a container that stores **unique** elements in **sorted** order. It is implemented using a self-balancing binary search tree. The set's elements can be **added** or **deleted**, but once they are added, they **cannot be changed**.

```
// Here is an example of how to use a set in C++:  
  
#include<iostream>  
#include<set>  
using namespace std;  
  
int main() {  
    // Create a set of integers.  
    set<int> mySet;  
  
    // Add some elements to the set.  
    mySet.insert(1);  
    mySet.insert(2);  
    mySet.insert(3);  
  
    // Check if an element is in the set.  
    if (mySet.find(2) != mySet.end()) {  
        cout << "The element 2 is in the set." << std::endl;  
    } else {  
        cout << "The element 2 is not in the set." << std::endl;  
    }  
  
    // Delete an element from the set.  
    mySet.erase(2);  
  
    // Iterate over the elements of the set.  
    for (set<int>::iterator it = mySet.begin(); it != mySet.end(); ++it) {  
        cout << *it << endl;  
    }  
  
    return 0;  
}  
  
/*  
Expected output:  
The element 2 is in the set.  
1  
3  
*/
```

### **INSERTION**

1. To add an element to a set, you use the **insert()** function.

The **insert()** function takes the element as a parameter and returns an iterator to the element.

If the element is already in the set, the **insert()** function does nothing and returns an iterator to the existing element.

### **DELETION**

2. To delete an element from a set, you use the **erase()** function.

The **erase()** function takes the element as a parameter and returns an iterator to the next element in the set.

If the element is not in the set, the **erase()** function does nothing and returns an iterator to the end of the set.

### **SEARCHING**

3. To check if an element is in a set, you use the **find()** function.

The **find()** function takes the element as a parameter and returns an iterator to the element if it is in the set.

If the element is not in the set, the **find()** function returns an iterator to the end of the set.

### **ITERATION**

4. To iterate over the elements of a set, you use a for loop.

The for loop **starts** at the beginning of the set and ends at the end of the set.

The for loop **iterates** over the elements of the set in sorted order.