



or

WHAT HAPPENS WHEN DOGS AND CATS ARE LEFT UNSUPERVISED



Outline

1. Theory

- A. Semi-supervised learning
- B. Generative Adversarial Networks
- C. Semi-supervised learning with GANs

2. Practice

A Tale of Cats and Dogs

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Semi-Supervised Learning: what

- Unsupervised learning (unlabelled training data): e.g. clustering, GAN
- Supervised learning (labelled training data): e.g. regression, classification
- Semi-supervised learning:
 - a subset of the training data is labeled
 - the rest is unlabelled
 - supervised learning tasks

Semi-Supervised Learning: why

- In practice, many tasks of interest come from supervised learning
- Deep learning: models need a lot of training data
- Labelling data is <u>expensive</u>
- Unlabelled data: easier to collect
- <u>Semi-supervised learning</u>: use unlabelled data to boost the performance of supervised ML models

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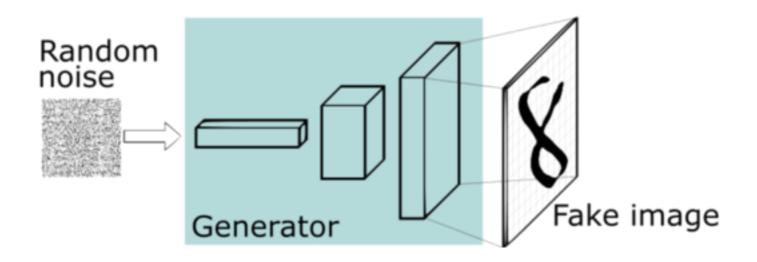
Ref: lan Goodfellow et al., 2014

- Unsupervised learning: unlabelled training data (e.g., MNIST images)
- Goal: generate data from the same distribution (e.g. new images that look like MNIST)



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- Discriminator

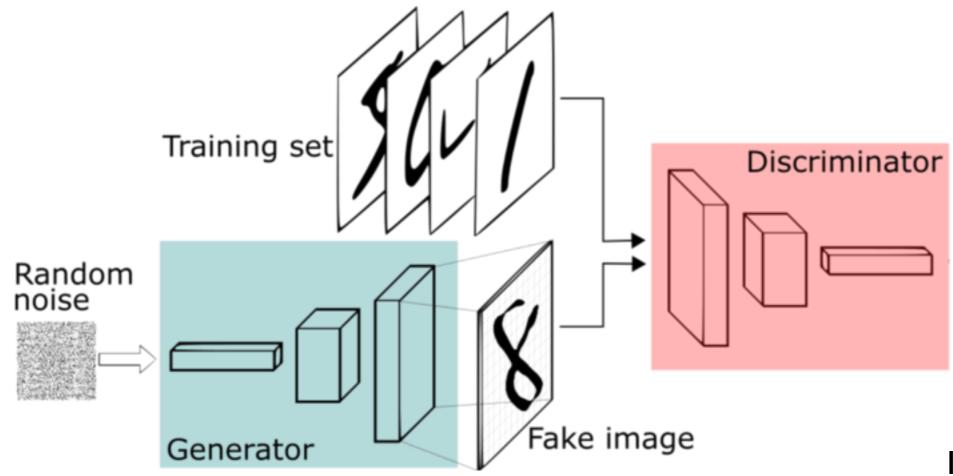
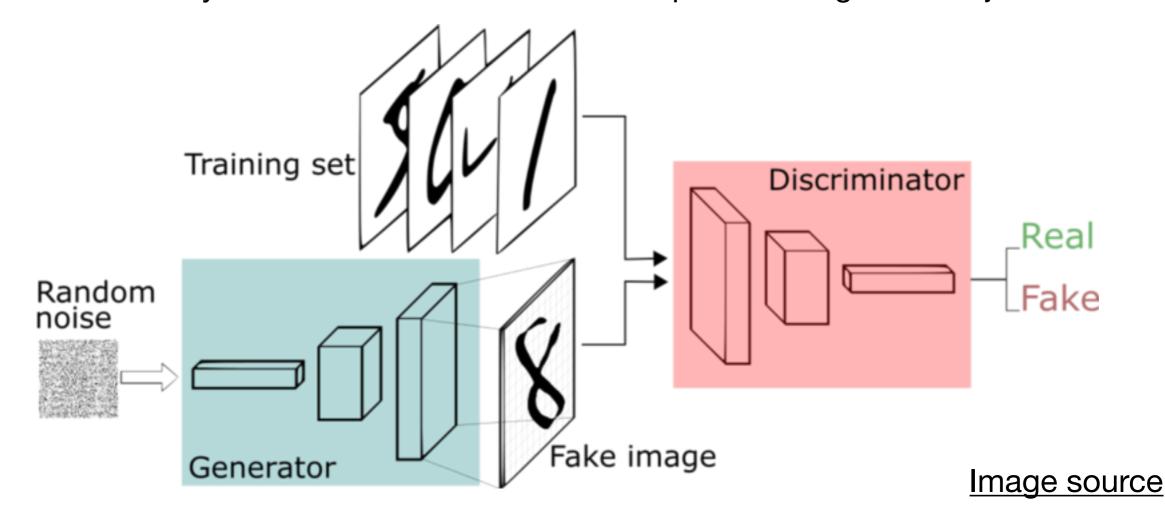


Image source

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- Unsupervised learning: unlabelled training data (e.g., MNIST images)
- Goal: generate data from the same distribution (e.g. new images that look like MNIST)
- Generator: deConv network that generates an image from random input noise
- Discriminator: binary classifier that is trained to accept Real images and reject Fake ones



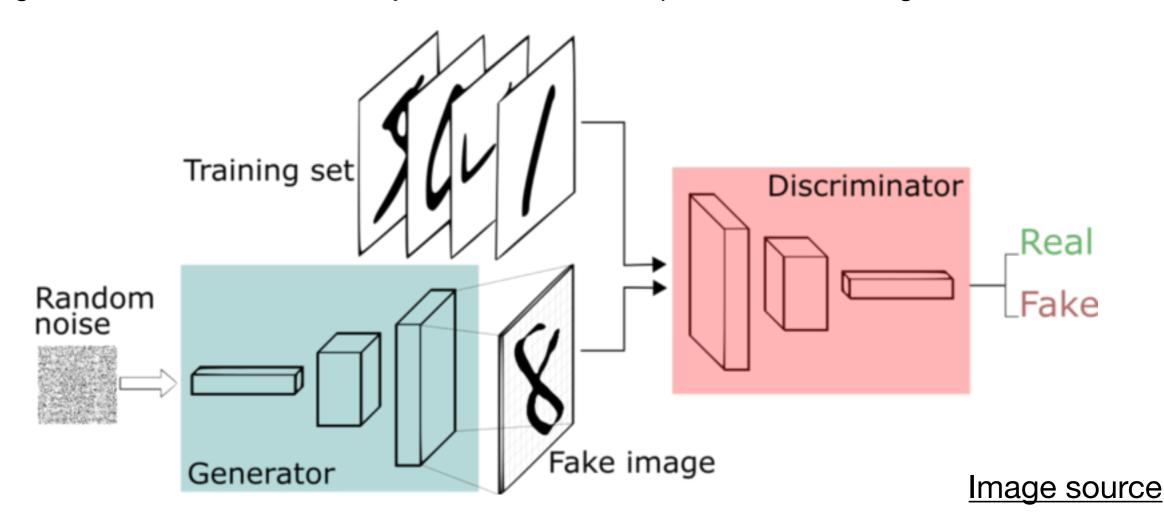
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Training of the Discriminator

• Straightforward binary classification (Real for the training set, Fake for the generated images)

Training of the Generator

- We pass the generated image as input to the Discriminator
- If the image is classified as Fake, we adjust the Generator to produce better images



Ref: lan Goodfellow et al., 2014

In practice: G and D are trained separately, one after another, for each batch:

```
## Train D with all-real batch
            netD.zero grad()
            real = data # a batch of images from the training set
            label = torch.ones(real.size(0))
            output = netD(real).view(-1)
            errD real = criterion(output, label) #criterion = nn.BCELoss()
10
            errD real.backward()
11
12
13
            ## Train D with all-fake batch
14
            noise = torch.randn(real.size(0), nz, 1, 1) # (generate a batch of inputs z for netG)
15
            fake = netG(noise)
16
            label = torch.zeros(real.size(0))
            output = netD(fake.detach()).view(-1) #fake.DETACH() because we are not training netG here
17
18
            errD fake = criterion(output, label)
19
            errD fake.backward()
20
21
            # Update D
22
            optimizerD.step()
23
24
            ## Train G to fool D
25
            netG.zero grad()
26
            label = torch.ones(real.size(0))
            output = netD(fake).view(-1) # Since D was just updated ;-)
27
            errG = criterion(output, label)
28
29
            errG.backward()
30
31
            # Update G
                                                                               Pytorch GAN tutorial
           optimizerG.step()
32
33
```

Ref: lan Goodfellow et al., 2014

- Real data: $x \sim p(x)$
- Generated data: $x \sim p_G(x)$ (Actually, $x \sim p_G(x|z)$)
- Goal: $p_G(x) \approx p(x)$
- Discriminator D is trained to assign the correct label (Real vs Fake)
- Generator G is trained to produce images that will fool the Discriminator D

$$\min_{G} \max_{D} V(D,G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})}[\log (1 - D(G(\boldsymbol{z})))]$$

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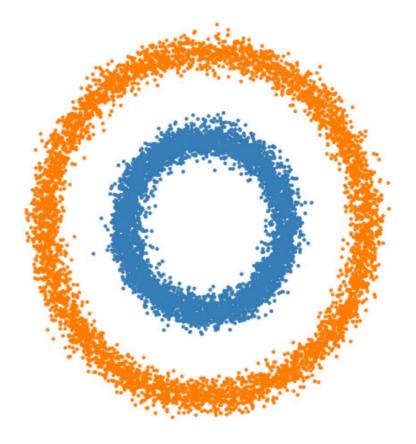
Ref: Improved Techniques for Training GANs, 2016

Basic idea:

- Our training data has a certain distribution
- The GAN will attempt to learn that distribution
- • "clustering" + using the labeled samples to assign labels to classes

Example:

 2D data: two circles = two classes, but only a few of the points are labeled



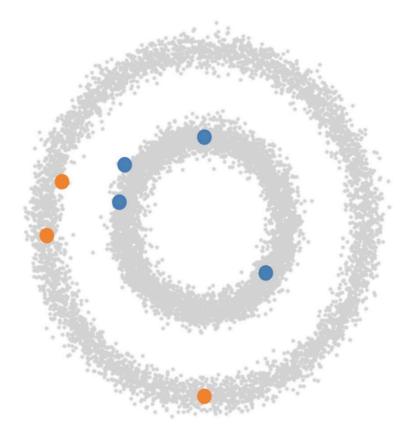
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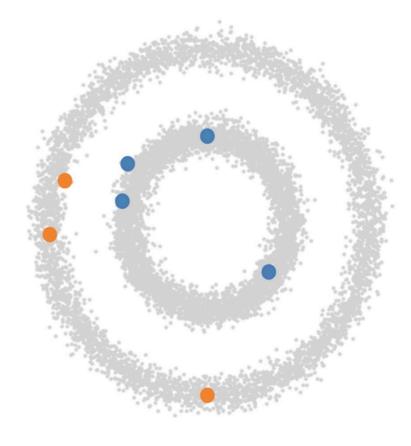
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- GAN will learn that there are two circles



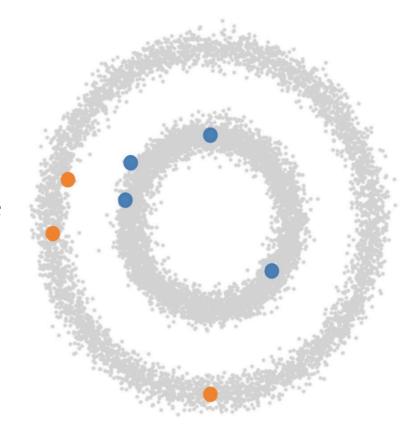
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Example:

- 2D data: two circles = two classes, but only a few of the points are labeled
- GAN will learn that there are two circles and the labeled points will help classify them as two classes



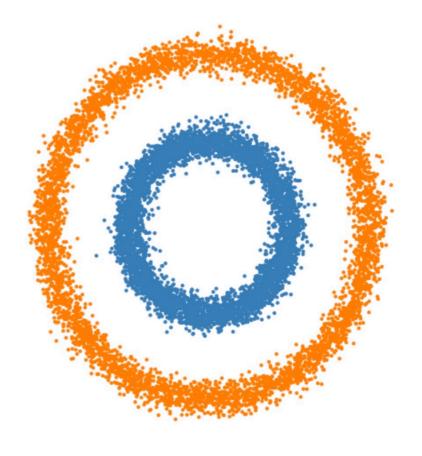
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SSL with GANs: how?

Ref: Unsupervised and Semi-supervised Learning with Categorical Generative Adversarial Networks, 2016

- <u>Unsupervised GAN</u>: **Generator** + **Discriminator** (*Real* vs. *Fake*)
- Supervised classifier: K classes
- <u>Semi-supervised</u>: Discriminator = Classifier into *K*+1 *classes*
- The first *K* classes are *Real*; the added (*K*+1) class is *Fake*
- Semi-supervised GAN: Generator + the new Discriminator/Classifier

Training

- **Discriminator** is trained to assign:
- labeled data to correct classes
- unlabelled data to one of K classes
- generated data to (K+1) class

- Generator is trained to:
- produce images that the Discriminator would assign to one of K classes

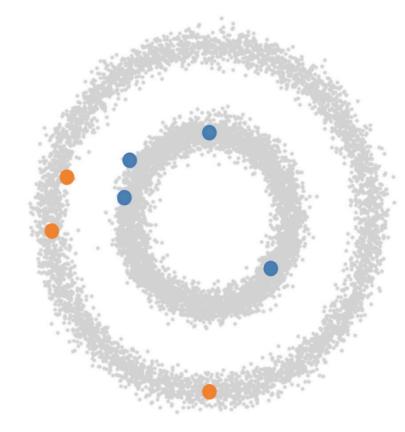


Ref: Good Semi-supervised Learning that Requires a Bad GAN, 2017

- State-of-the-art GANs achieve very impressive results (e.g., www.thispersondoesnotexist.com)
- However, the GANs used for semi-supervised learning do not
- To get a good classifier, the Generator should be "bad" = complement

(generates complement samples in feature space)

- Generating more points for the two circles would not help us
- Generating Fake points between circles
 - → better decision boundary between classes





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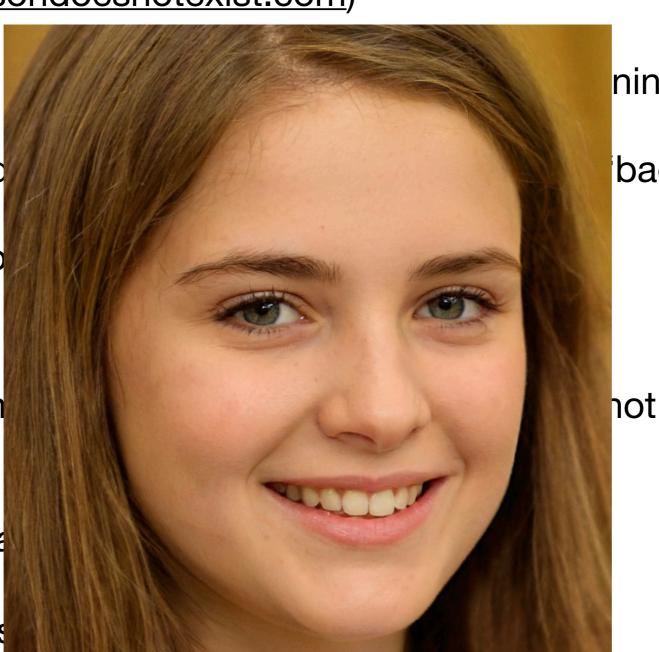
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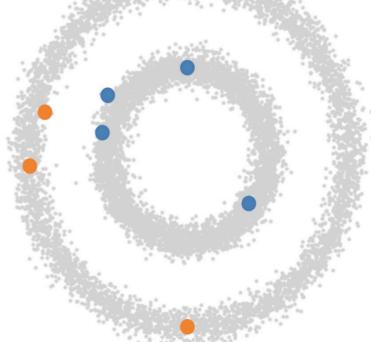
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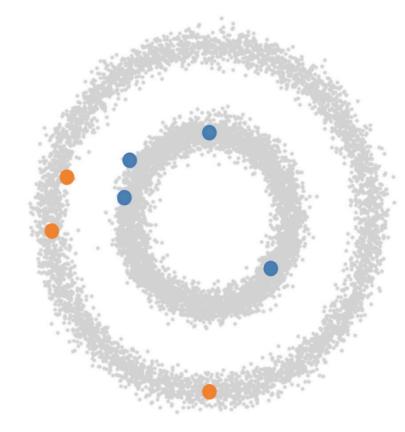


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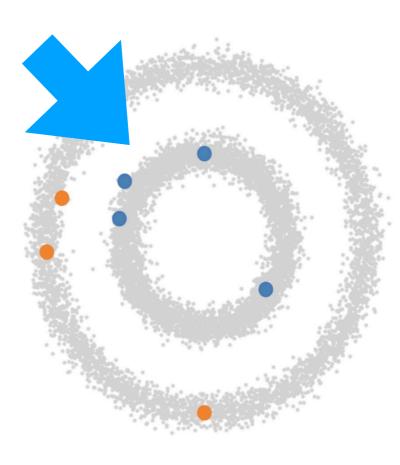


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What is next?

• Simple Generator + Classifier GAN has a problem:

Classifier has two conflicting goals, classifying Real and rejecting Fake

Solution: Triple GAN = Generator + Discriminator + Classifier

Ref: *Triple Generative Adversarial Nets, 2017*

• The Good, the Bad, and the GAN:

get both a good Classifier and a good Generator (UGAN)

Ref: <u>Semi-supervised Learning using Adversarial Training with Good and Bad Samples, 2019</u>

Results

Table 2: Test accuracy on semi-supervised MNIST. Results are averaged over 10 runs. * denotes hand selection of labeled data. † denotes our implementation of the model.

Model	Test accuracy for a given number of labeled samples			
	20	50	100	200
FM-GAN [32]	$83.23 \pm 4.52\%$	$97.79 \pm 1.36\%$	$99.07 \pm 0.07\%$	$99.10 \pm 0.04\%$
Bad GAN [5]	-	-	$99.21 \pm 0.10\%$	-
Triple-GAN [4]	$95.19 \pm 4.95\%$	$98.44 \pm 0.72\%$	$99.09 \pm 0.58\%$	$99.33 \pm 0.16\%$
Bad GAN [†]	$88.38 \pm 3.08\%$ *	$96.24 \pm 0.16\%$	$99.17 \pm 0.03\%$	$99.20 \pm 0.03\%$
Triple-GAN [†]	$95.93 \pm 4.45\%^*$	$98.68 \pm 1.12\%$	$99.07 \pm 0.46\%$	$99.17 \pm 0.08\%$
UGAN	$97.34 \pm 6.86\%^*$	${\bf 98.92 \pm 0.13\%}$	$99.21 \pm 0.08\%$	$99.35 \pm 0.05\%$

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- Option I:
- add a third (Fake) class; increase dim_out of Classifier by one
- Unlabelled data: D wants to minimize probability of 3rd class
- Generated data: D wants to minimize probability of 1 and 2 classes, G wants to minimize probability of 3rd class

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- Option II:
- do not increase dim_out of Classifier
- output a strong class prediction for Real examples, and small class predictions for Fake examples

$$D(\boldsymbol{x}) = \frac{Z(\boldsymbol{x})}{Z(\boldsymbol{x})+1}$$
, where $Z(\boldsymbol{x}) = \sum_{k=1}^{K} \exp[l_k(\boldsymbol{x})]$

Ref: <u>Improved Techniques for Training GANs, 2016</u>, <u>Unsupervised and Semi-supervised Learning with</u> <u>Categorical Generative Adversarial Networks, 2016</u>

