Abhishek Kolekar

abhishek_kolekar@outlook.com

Framgången 220, Göteborg, 41280 (in) /k

(2) Transcript

+46-727777635

(in) /kolekar-abhishek

Have IDP, B-type ongoing



₽ Profile

Passionate engineer with a strong interest in the automotive industry, with multifaceted knowledge in areas of powertrain systems and vehicle dynamics. I hold a Master of Science in Mobility Engineering, focusing on vehicle dynamics, safety, and control. Through various roles during my Formula Student tenure and projects, I have developed skills and knowledge geared toward vehicle propulsion and energy storage systems, balancing performance and efficiency. Motivated and detail-oriented, I strive to build sustainable and impactful technologies. I am eager to bring my expertise and enthusiasm to your company, where I can grow professionally while contributing to shaping the future of mobility.

Education

Chalmers University of Technology

Master of Science (MSc.) in Mobility Engineering

• Focus on Vehicle Dynamics, Safety & Control

PCT's A. P. Shah Institute of Technology

Bachelor of Engineering (BE) in Mechanical Engineering

08/2022 - 08/2024 | Göteborg, Sweden

08/2018 - 11/2022 | Thane, India

Projects

Tire Warmup Relation to Rolling Resistance

Master's Thesis with Volvo Car Corporation

01/2024 - 06/2024

- Designed an innovative **MATLAB model** for calculating **transient rolling resistance using tire temperature** as a model input, enhancing the precision of **energy efficiency assessments** and adding insights to the tire selection process.
- Improved upon and **verified and validated** an existing Thermal-Schuring model for rolling resistance through **statistical analysis** of **experimental data**, achieving model accuracy within 5% of measured values.
- Developed **test methodologies** and **conducted rolling resistance tests** on steel drum and dynamometer rigs over a 4-month period; employed **INCA**, **MDA**, and **MATLAB** for comprehensive data analysis.
- Proactively identified opportunities to **improve vehicle efficiency from a rolling resistance perspective**, with modeled rolling energy loss deviating between 3% and 6% from measured values.
- Acquired knowledge of range testing certification in accordance with the SAE J1634 standard.

Method to Improve a Wheel Suspension Design using

08/2023 - 01/2024

VI-CarRealTime and optimization techniques

Automotive Engineering Project with Volvo Car Corporation

- Automated vehicle simulations in VI-CarRealTime by integrating it with a Reinforcement Learning Agent via the MATLAB API.
- Utilized Reinforcement Learning to optimize polynomial curve coefficients of wheel motion splines, consistently achieving specified target ranges.

Drivetrain Anomaly Troubleshooting and HIL Integration of ECU using CAN Protocol for Formula Student Vehicle

06/2023 - 08/2023

Summer Project at Chalmers REVERE

- Conducted Hardware-in-the-Loop (HIL) testing for motor control.
- Assisted in developing a Python script to **establish communication between the motor controller and the ECU** using the **CAN** protocol.

Virtual Vehicle Control Design & SIL Testing using IPG CarMaker

03/2023 - 05/2023

Vehicle Motion & Control - Course Project

- Designed a normal force estimator and implemented a low-normal force warning function.
- Modeled AD/ADAS features such as cruise control and curve speed control; executed function verification and validation (V&V) and performed Software-in-the-Loop (SIL) testing using IPG CarMaker.
- Optimized suspension tuning parameters and compliances, achieving the desired handling characteristics.

Microservice Development with CI/CD Integration

Connected Fleets - Course Project

- Formulated a simple microservice using Docker containers.
- Established a **CI/CD pipeline** using GitLab to automate the build, test, and deployment process for the microservice with **cross-compilation across different architectures** (linux/amd64 and linux/arm64).

Other Notable Relevant Projects

- <u>Development of a Lap-Time Simulation and Energy Consumption Estimation for Electric Vehicles</u> *§*
- Development of Traction Control in Automobiles.
- CFD Analysis, Wind Tunnel Testing, and Shape Optimization of a Bus Model.

A Positions of Responsibility

Modified Auto Club Racing - Formula Student

02/2021 - 11/2021

Team Manager

- Managed and supervised a team of 32 people, devising solutions for cohesive working and problem solving, achieving the 7th overall rank in the Formula Bharat Virtuals 2021 competition.
- **Prepared design critical documents** like FMEA, Design Verification & Validation Plan, Design Spec Sheet, Production Planning Gantt Chart, and Cost Report of the vehicle.

Modified Auto Club Racing - Formula Student

02/2021 - 11/2021

Powertrain Department Lead

- Led a team in designing a high-performance Formula Student vehicle's drivetrain, achieving a **0-100 km/hr** theoretical time under 3.5 seconds and a top speed of 115 km/hr.
- Optimized drivetrain parameters for performance and energy efficiency using MATLAB and OptimumLap, improving efficiency by 12% from baseline spec.
- Designed parts and assemblies of the drivetrain subsystem in **SOLIDWORKS** & **CATIA V5**, and carried out structural FEM analysis using **ANSYS Mechanical**.

☆ Certificates

- Certified SOLIDWORKS Associate Mechanical Design
- Certified SOLIDWORKS Associate Additive Manufacturing *⊗*
- ENGR2000X: A Hands-on Introduction to Engineering Simulations CornellX EdX ∂

Software Skills

MATLAB/Simulink — Expert Python — Expert

Microsoft Office Suite — Expert C++ — Proficient

Git – Proficient MDA & INCA – Proficient

CAN (using Kvaser CanKing) — Competent CI/CD (Gitlab, Docker, Jenkins) — Competent

Languages

English — Native/Bilingual Swedish — Conversational

战 References

References Available Upon Request