#Bluetooth control car

Char m = 0;

Void setup() {

pinMode(9, OUTPUT);

pinMode(10, OUTPUT);

pinMode(11, OUTPUT);

pinMode(12, OUTPUT);

Serial.begin(9600);

}

Void loop() {

If (Serial.available() > 0)

{

M = Serial.read();

Serial.println(m);

}

If (m == ‘R’) {

digitalWrite(9, HIGH);

digitalWrite(10, LOW);

digitalWrite(11, HIGH);

digitalWrite(12, LOW);

}

Else if (m == ‘L’) {

digitalWrite(9, LOW);

digitalWrite(10, HIGH);

digitalWrite(11, LOW);

digitalWrite(12, HIGH);

}

Else if (m == ‘F’) {

digitalWrite(9, HIGH);

digitalWrite(10, LOW);

digitalWrite(11, LOW);

digitalWrite(12, HIGH);

}

Else if (m == ‘B’) {

digitalWrite(9, LOW);

digitalWrite(10, HIGH);

digitalWrite(11, HIGH);

digitalWrite(12, LOW);

}

Else if (m == ‘S’) {

digitalWrite(9, LOW);

digitalWrite(10, LOW);

digitalWrite(11, LOW);

digitalWrite(12, LOW);

}

}