

1.

MAULANA ABUL KALAM AZAD UNIVERSITY OF TECHNOLOGY, WEST BENGAL

Paper Code : PC-EE 701 Electric Drive UPID : 007598

Time Allotted : 3 Hours Full Marks :70

The Figures in the margin indicate full marks.

Candidate are required to give their answers in their own words as far as practicable

Group-A (Very Short Answer Type Question)

. Ans	wer	any ten of the following:	1 x 10 = 10]
	(1)	Why heating occurs in motor drives?	
	(II)	Which type of drive is used in Electric vehicles?	
	(111)	Which control mechanism is used to get speed higher than the base speed of a DC shunt motor ?	
	(IV)	what is meant by the VSCF drive?	
	(V)	What is the expression for step angle?	
	(VI)	How will you classify electric drives based on the method of speed control?	
	(VII)	A three-phase induction motor having a combination of a diode rectifier & line combination of diode line commutated inverter in the rotor circuit can give speedsynchronous speed or	
	(VIII)	What is meant by "short time rating of motor"?	
	(IX)	For the speed lower than the base speed of a DC shunt motor a) armature voltage control is used b) field control is used c) armature resistance control is used d) torque control is used.	
	(X)	The direction of mmf when a single phase supply is given to the stator of three phase induction motor	r is
	(XI)	The Variable frequency control of induction motor is more efficient than stator voltage control. Why?	•
	(XII)	Why is it necessary to operate a solar panel near the maximum power point?	
		Group-B (Short Answer Type Question)	
		Answer any three of the following:	[5 x 3 = 15]
2.	Wha	at are the advantages and disadvantages of ward Leonard method of speed control?	[5]
3.	Writ	te short notes on load commutated thyrister inverter on synchronous motor Drive.	[5]
		by VVVF method of speed control of a three phase induction motor is preferable to the frequency [5] atrol Method?	
5.	Wha	at do you mean by group, individual and multimotor drives?	[5]
6.	Drav	w a neat circuit diagram of a four quadrant MOSFET chopper drive and explain regenerative control.	[5]
		Group-C (Long Answer Type Question)	
		Answer any three of the following:	15 x 3 = 45]
7.	(a)	Explain the principle of speed control of slip ring induction motors by slip power recovery.	[7]
		A three-phase bridge inverter is used to run a three-phase induction motor rated at 440V, 15A, and 1440 rpm. The maximum to minimum speed ratio required is 10:1. Find the minimum and maximum dc input voltage for the inverter. The inverter is operated in 180 conduction mode. If this voltage is to be obtained from a three-phase full controlled bridge converter from 440V mains, calculate the firing angle as needed.	[8]
8.		With the help of relevant characteristics and circuits explain the principle of braking while lowering a load by a dc motor	[6]
		A 220v,10 kW,1200 rpm dc shunt motor has full load efficiency of 85%. The field resistance and the armature resistance are 110 Ω & 0.25 Ω . Neglect rotational losses and armature reaction. Calculate the value of resistance required to be inserted in series with the armature to reduce the speed to 900 rpm when i) load torque is constant regardless of the speed.	[9]

- ii) the load torque is directly proportional to the speed.
- iii)the load torque varies as the square of the speed
- 9. (a) Deduce the relationships necessary to obtain the heating & cooling curve of an electric motor [7]
 - (b) A motor has a thermal heating time constant of 50 minutes. When the motor runs continuously on full load, its final temperature rise is 80° c.
 - I) what would be the temperature rise after 1 hour? if the motor runs continuously on full load?
 - II) How long will the motor take for its temperature to rise from 50° c to 80° c? if it is working at its 1-hour rating.
- (a) Explain stator voltage control using an AC voltage controller for an induction motor with neat
 circuit diagrams. Draw the necessary wave forms.
 - (b) Explain with neat diagrams. how a phase-controlled Cyclo-converter can be used to control the frequency and applied voltage to a synchronous motor to control its speed. Draw the necessary wave forms.
- 11. (a) Explain the principle of Rheostatic braking of a dc separately excited motor [6]
 - (b) A 230V,960 RPM, 200A separately dc motor has an armature resistance of 0.02Ω . The motor is fed from a chopper. The source voltage of 230V. The motor is now operated in dynamic braking with chopper control with a braking resistance of 2 Ω
 - i) Calculate the duty ratio of the chopper for a motor speed of 600 RPM and braking torque of twice the rated value
 - ii)What will be the motor speed for a duty ratio of 0.6 and motor torque equal to twice its rated torque

*** END OF PAPER ***

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[8]

[9]