

## Vellore - 632014, Tamil Nadu, India SCHOOL OF ELECTRICAL ENGINEERING FALL SEMESTER 2023-2024 CAT-I

SLOT: G2 + TG2

Programme Name & Branch : B.Tech (EEE, EIE)

Course Code: BEEE303L

Course Name

: Control Systems

Faculty Members

: Dr. V. Bagyavcereswaran

Class Number(s): 2936, 2938

Dr. E. VinodhKumar

Date of the Examination

: 16 - 09 - 2023

Duration: 90 minutes

Max. Marks : 50

## General instruction(s): Answer all the questions

Q. No

## Question

Marks

A high-precision positioning slide is shown in Figure 1. Determine the transfer function  $X_p(s)/X_m(s)$  when the drive shaft friction is  $b_d = 0.7$ , the drive shaft spring [10] constant is  $k_d = 2$ ,  $m_c = 1$ , and the sliding friction is  $b_s = 0.8$ .

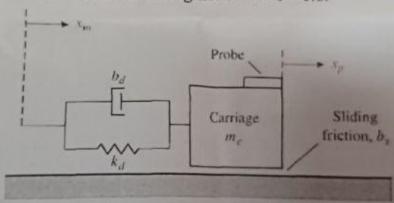


Figure 1

Write the differential equations governing the rotational mechanical system shown 2. in Figure 2. Also draw the torque-voltage and torque-current analogous circuits.

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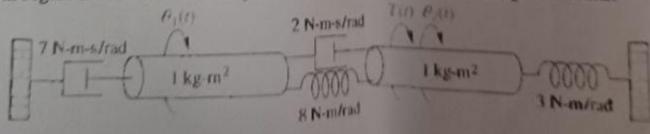


Figure 2

A control engineer, N. Minorsky, designed an innovative ship steering system in A control engineer, N. Minorsky, designed the 1930s for the U.S. Navy. The system is represented by the block diagram shown 3. the 1930s for the U.S. Navy. The system is R(s) is the desired course, and R(s) is in Figure 3, where Y(s) is the ship's course, R(s) is the desired course, and R(s) is the rudder angle. Find the transfer function Y(s)/R(s).

[10]