Module: Computer Vision - Session 1



Dr. Sunita Dhavale, DIAT



Online Training & Certification Course on Artificial Intelligence & Machine Learning
Defence Institute of Advanced Technology (DU), Pune.



Computer Vision



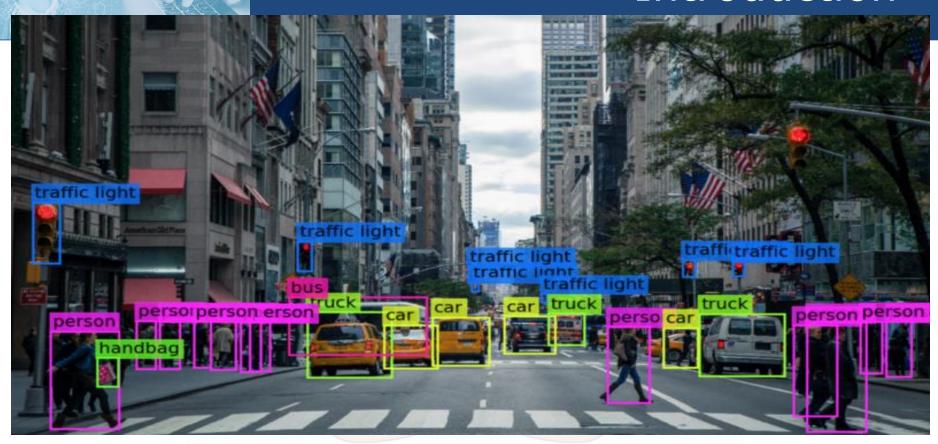
Introduction to Image Processing Techniques



Online Training & Certification Course on AI & ML Defence Institute of Advanced Technology (DU), Pune.



Introduction





Syllabus

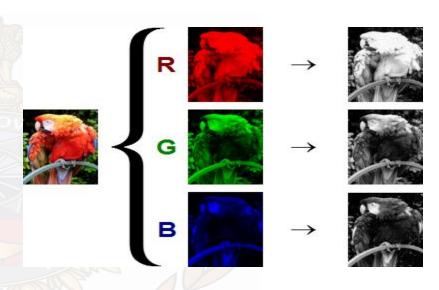
Part I (10 Hrs)	Part II (10 Hrs)
Introduction to Image processing techniques Images, Noise, Convolution, Filtering Thresholding techniques, Image segmentation Edge Detection techniques Interest Point Detection, Harris Corner Detector SIFT, Histograms of Oriented Gradients Binary shape analysis, connectedness, object labeling and counting Boundary tracking procedures, active contours Boundary descriptors, chain codes, Fourier descriptors, region descriptors, moments Hough Transform	Optical Flow, Motion Models, Global Motion KLT Tracking, Mean-Shift Tracking Deep Sort Camera Model and Calibration Fundamental Matrix, Stereo Images 3 D Image processing Deep learning for Chest X-ray Image analysis Face Recognition based on video Human activity detection based on video Audio/speech, based personality detection/prediction

Outline of Presentation

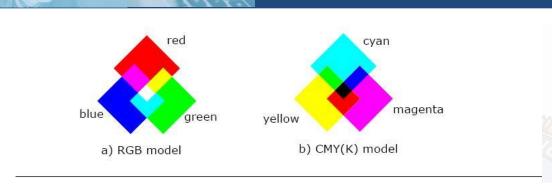
- Introduction
- Images
- Color Spaces
- Color Models
- Python and OpenCV

Images

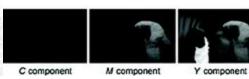
- Pixels
- Grayscale
- RGB
- Black and White
- Resolution
- Size

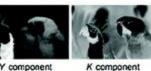


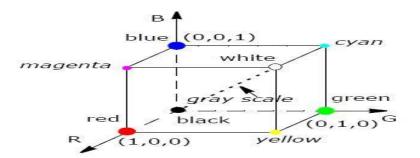
Color Spaces



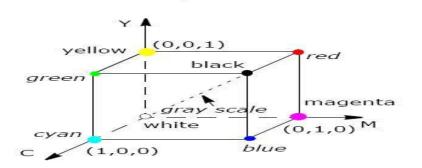








a) RGB



b) CMY

Color Models

colour cone

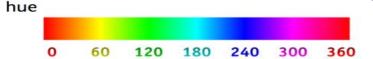
- H = hue / colour in degrees ∈ [0,360]
- S = saturation ∈ [0,1]
- V = value ∈ [0,1]

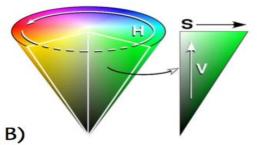
conversion RGB → HSV

- V = max = max (R, G, B), min = min (R, G, B)
- S = (max min) / max (or S = 0, if V = 0)

$$\begin{tabular}{ll} \blacksquare & H = 60 \times \\ \begin{tabular}{ll} $0 + (G - B)/(max - min)$, & if $max = R$ \\ $2 + (B - R)/(max - min)$, & if $max = G$ \\ $4 + (R - G)/(max - min)$, & if $max = B$ \\ \end{tabular}$$

$$H = H + 360$$
, if $H < 0$





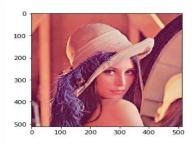
Python and OpenCV

- On Windows-> Install Anaconda, Spyder, Python framework, OpenCV, skimage, matplotlib, numpy
- Anaconda powershell -> conda info --envs
- Use pip install on python prompt or conda create newenv, conda activate newenv, conda install package on anaconda command prompt
- OpenCV -> open source computer vision, Version 3.4.3 of OpenCV, in conjunction with version 3.7 of Python
- Start anaconda navigator
- Start spyder -> Scientific Python Development Environment
- To verify the installation is error-free->
 - >>import cv2
 - >>print(cv2.__version___)

Try Following Code:

- from PIL import Image
- Img=Image.open('E:/computervision/Lena.png') #read Image
- import matplotlib.pyplot as plt
- plt.imshow(Img) #display image
- import numpy as np
- print(np.shape(Img)) #see the size (512, 512, 3)
- #convert into numpy array
- img1=np.asarray(Img)
- #read only one channel
- plt.imshow(img1[:,:,1],cmap='gray')
- #see pixel values
- img1[1:10,1:10,1]
- #see each channel of RGB color image
- r,g,b=Img.split()
- img1=np.asarray(g)
- plt.imshow(Img)

```
array([[137, 137, 136, 138, 129, 138, 134, 140, 136],
        [137, 137, 136, 138, 129, 138, 134, 140, 136],
        [137, 137, 136, 138, 129, 138, 134, 140, 136],
        [137, 137, 136, 138, 129, 138, 134, 140, 136],
        [140, 131, 130, 136, 133, 132, 133, 136, 134],
        [134, 141, 133, 134, 137, 132, 128, 134, 137],
        [133, 129, 132, 131, 133, 129, 131, 131, 137],
        [129, 133, 133, 134, 134, 130, 132, 139, 131],
        [130, 133, 134, 128, 127, 129, 130, 135, 128]],
        dtype=uint8)
```



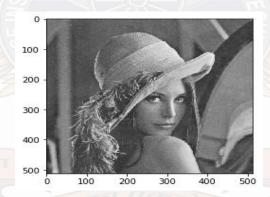


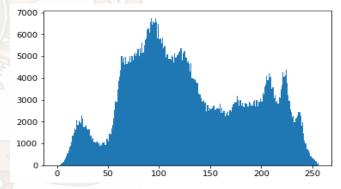
Try:

- from skimage.color import rgb2hsv
- hsvimg=rgb2hsv(Img)
- print(img1[1:10,1:10,0])
- print(hsvimg[1:10,1:10,0])
- print(hsvimg[1:10,1:10,1])
- print(hsvimg[1:10,1:10,2])
- #if RGB=255 then H=S=0 and V=1

Histogram

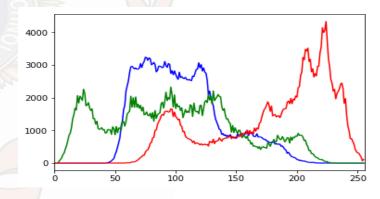
- another representation for images, is the frequency of intensity value in the image, captures the distribution of gray levels in the image
- def histogram(im):
 - h = np.zeros(255)
 - for row in im.shape[0]:
 - for col in im.shape[1]:
 - val = im[row, col]
 - h[val] += 1





Try:

- import numpy as np
- import cv2
- from matplotlib import pyplot as plt
- img = cv2.imread("E:/computervision/Lena.png")
- #plot a histogram
- histogram_image = cv2.calcHist([img],[0],None,[256],[0,256])
- hist,bins = np.histogram(img.ravel(),256,[0,256])
- np.shape(hist) ## (256,)
- hist[1:10] ## array([0, 0, 11, 65, 111, 164, 261, 315, 431], dtype=int64)
- #flaten the histogram
- plt.hist(img.ravel(),256,[0,256])
- plt.show()
- #view color channels
- color = ['b','g','r']
- #seperate the colors and plot the histogram
- for i, col in enumerate(color):
- hist = cv2.calcHist([img], [i], None, [256], [0,256])
- plt.plot(hist, color = col)
- plt.xlim([0,256])
- plt.show ()
- Homework: find mean, median, mode, std, var, count, min, max on histogram (use numpy)



Reference Material

- 1. E. R. Davies, "Computer & Machine Vision", Fourth Edition, Academic Press, 2012.
- 2. R. Szeliski, "Computer Vision: Algorithms and Applications", Springer 2011.
- 3. Simon J. D. Prince, "Computer Vision: Models, Learning, and Inference", Cambridge University Press, 2012.
- 4. Mark Nixon and Alberto S. Aquado, "Feature Extraction & Image Processing for Computer Vision", Third Edition, Academic Press, 2012.
- 5. Sunita Dhavale, "Advanced Image-Based Spam Detection and Filtering Techniques", Book Published by CyberTech: An Imprint of MKP Technologies, Hershey, PA, USA IGI Global, March 2017, ISBN13: 9781683180135|ISBN10: 1683180135|EISBN13: 9781683180142|DOI: 10.4018/978-1-68318-013-5.
- 6. Gonzalez and R. Woods Digital Image Processing, Addison-Wesley Publishing Company, 1992, p 442.

<<Epilogue>>

- We will meet in next scheduled lecture.
- Start using python to check various image properties.
- Feel free to ask your questions.
- Email: sunitadhavale@diat.ac.in



