

ISSUES FACED DURING PROJECT 2

1. Response time was long.
2. The bot couldn't detect multiple signs in short distances.
3. Documentation for demo 8 was not helpful.
4. The track was not properly laid out. The white lines were worn out and as a result the lane following was sometimes not accurate.
5. The solution to some of the errors in running demo 8 were not found anywhere.
6. Questions posted on the Duckiebot forum were not answered.
7. Figuring out the parameters which made the bot run satisfactorily took some time.
8. The simulation doesn't translate into the robot.
9. It requires Movidus Neural network stick which is a bit expensive to buy for 1 project.
10. If possible the TA could be given 2 sticks by the instructors so the simulation could be implemented on the bot.
11. Imitation learning doesn't work properly is hard to install on linux.