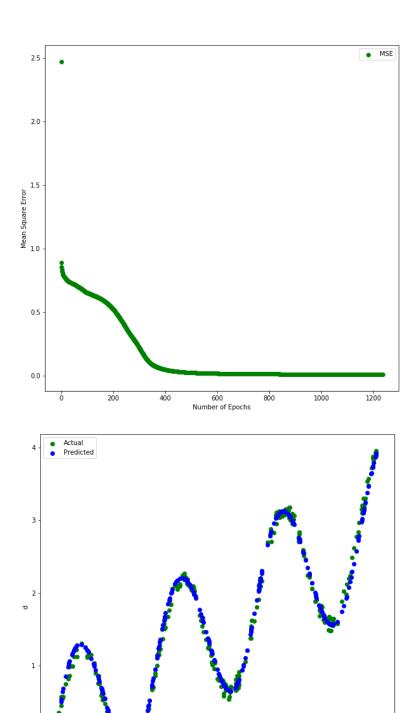
HW4

Q1.



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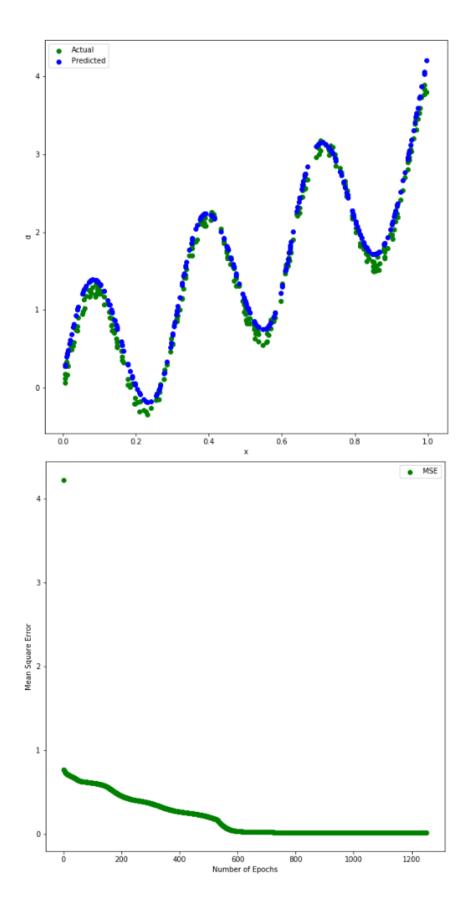
0.2

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	Is uedo code
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0	
	Initialize di = sin (20x;)+3x;+V;
	Initialize feed forward activation functions.
	3) Initialize feed back activation functions.
Land.	3.1) tanh (v) - feed forward
	3.2) 1- tarih(u) - feedback (Derivative)
4	
	4.1) Random uniform distribution for -input &N=24 (5/5)
	4.2) " n a W-bias &N=24(-1,1)
	4-3) " " W-output N=24(-5,5)
	4.4) " " W-final N=1 (-1,1)
5)	Initialize output neuron
,	5.1) V - quaction
	5.2) 1 - denivative.
6)	Fred forward network.
,	6.1) While (True)
	Do → for i < n=300
	aloha = (X[i] * W_input [i]) + W_bias [j]
20	buta = matrix multiplication of alpha & w-output +wfrol
*) backgropagation.
	do e= - ((da) -4 (1) * eta +2)/n
	do e= -((d[]) = eta = 2)/n b) for i= < n= 300.
	for j < N=24
	w_output (weight) = e * alpha.
	W-input (weight) = e * X(i) * w-Dulpud *
	derivative (tanh(1).
	w-output - e + w output [] + derivative (tanh()).
84	Update the weight.
9)	Find mean square error.
-3/	
	for i < n=300.
(0)	plat graph for mean square error & number of epodes.
11)	plot Scatter plat of fud forward whom's output & durind output
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Source Code

```
import numpy as np
import matplotlib.pyplot as plt
# input data
n = 300
x = np.random.uniform(low=0.0, high=1.0, size=n)
v = np.random.uniform(low=-0.1, high=0.1, size=n)
# desired output
d = []
for i in range(n):
    d.append(np.sin(20*x[i]) + (3*x[i]) + v[i])
fig, ax = plt.subplots(figsize=(10,10))
plt.xlabel('x')
plt.ylabel('d')
plt.scatter(x,d, c = 'green', label = 'Actual')
plt.legend(loc = 'best')
plt.show()
# feed-forward activation functions
def act_fun(v):
    return np.tanh(v)
def act_op(v):
    return v
# feedback activation functions
def derv_act_fun(v):
    return (1 - np.tanh(v)**2)
def derv_act_op(v):
    return 1
# weight initialization
w_input = np.random.uniform(low=-5, high=5, size=N)
w_bias = np.random.uniform(low=-1, high=1, size=N)
w_output = np.random.uniform(low=-5, high=5, size=N)
w_final = np.random.uniform(low=-1, high=1, size=1)
eta = 6
```

```
list_mse = []
z = 0
while(True):
    # feed-forward network
    u = []
   y = []
    alphas = []
    betas = []
    for i in range(n):
        v = []
        temp = []
        for j in range(N):
            alpha = (x[i]*w_input[j]) + w_bias[j]
            temp.append(alpha)
            v.append(act_fun(alpha))
        alphas.append(temp)
        u.append(v)
        beta = np.matmul(np.array(u[i]),w output) + w final
        betas.append(beta[0])
        y.append(act_op(beta[0]))
        # backpropagation
        e = -((d[i] - y[i])*eta*2)/n
        w_output_grad = []
        w_input_grad = []
        w bias grad = []
        w final_grad = []
        delta_final = - e
        w_final_grad.append(delta_final)
        for j in range(N):
            delta_u = e * u[i][j]
            w_output_grad.append(delta_u)
            delta_w = e * x[i] * w_output[j] * derv_act_fun(alphas[i][j])
            w_input_grad.append(delta_w)
            delta_bias = e * w_output[j] * derv_act_fun(alphas[i][j])
            w_bias_grad.append(delta_bias)
        # weight update
        w_input = np.subtract(w_input, np.asarray(w_input_grad))
        w_output = np.subtract(w_output, np.asarray(w_output_grad))
        w_bias = np.subtract(w_bias, np.asarray(w_bias_grad))
        w final = np.subtract(w final, np.asarray(w final grad))
    # mean sauare error
   mse = 0
    for i in range(n):
        mse += (d[i] - y[i])**2
    mse = mse/n
    list_mse.append(mse)
    print (mse, eta, z)
    if list_mse[z] > list_mse[z-1]:
        eta = 0.9*eta
    if list_mse[-1]<0.01:
        break
    z += 1
```

```
fig, ax = plt.subplots(figsize=(10,10))
plt.ylabel('Mean Square Error')
plt.xlabel('Number of Epochs')
plt.scatter(range(len(list_mse)), list_mse, c = 'green', label = 'MSE')
plt.legend(loc = 'best')
plt.show()

fig, ax = plt.subplots(figsize=(10,10))
plt.ylabel('d')
plt.xlabel('x')
plt.scatter(x,d, c = 'green', label = 'Actual')
plt.scatter(x,y, c = 'blue', label = 'Predicted')
plt.legend(loc = 'best')
plt.show()
```