AIR MOUSE:CONTROLLING MOUSE USING GESTURES

INTRODUCTION:

The emergence of gesture-based interaction has revolutionized the way humans interact with technology, offering a natural and intuitive approach to control devices and interfaces. Among various gesture recognition systems, hand gesture control stands out as a promising technology that allows users to interact with digital interfaces using hand gestures in the air. By leveraging computer vision and machine learning techniques, hand gesture control systems can accurately detect and interpret hand movements captured by a webcam or other sensors, enabling seamless navigation and interaction without physical touch or input devices.

Installation:

It will be best idea to install these tools on virtual environment.

- pip install mediapipe for installing mediapipe.
- pip install mouse for installing mouse package.

PRELIMINARY TASKS:

Import the libraries:

```
import wediapipe as mp
import cv2
import mouse
import numpy as np
import tkinter as tk
```

Get Screen Size:

The use of tkinter is only to find screen size

```
In (2): root = tk.Tk()
    screen_width = root.winfo_screenwidth()
    screen_height = root.winfo_screenheight()
    ssize = (screen_height, screen_width)
    ssize

Out[2]: (768, 1366)
```

Write Basic Functions

• We need to convert the landmark position from the frame world to our screen world thus the method frame_pos2screen_pos is written.

• We will be working with Euclidean Distance to make some sense about gestures.

```
def frame_pos2scroom_pos(frame_size(#18, 540), scroom_sizes(763, 1366), frame_pos3Nome):
    x,y = scroom_size[1]/frame_size[0], scroom_size[0]/frame_size[1]
    scroom_pos = [frame_pos(0)*x, frame_pos[1)*y]
    return scroom_pos

def exclideam(pt1, pt2):
    d = *po.scrt((pt1[0]-pt2[0])**3*(pt1[1]-pt2[1])**2)
    return d
    exclideam(#4, 3), (0, 0))
Cur[1] 5.0
```

The below code utilizes OpenCV and MediaPipe for hand gesture recognition and control of mouse events. It starts by initializing a webcam capture (cam) and setting up parameters such as frame size, region of interest (ROI), and event detection frequency (check_every). It then creates instances for drawing utilities (mp_drawing) and hand tracking (mp_hands).

Within the main loop, it continuously reads frames from the webcam, processes them to detect hand landmarks using MediaPipe, and maps hand gestures to mouse events. Specifically, it identifies the positions of finger landmarks (e.g., index finger tip, thumb tip) relative to the defined ROI, calculates distances between finger points to determine gestures like single click, double click, right click, and drag, and translates these gestures into corresponding mouse actions using the mouse object. The script also handles event timing and updates the last_event variable accordingly to maintain gesture continuity.

```
cam = rv2.VideoCapture(0)
fsize = (520, T20)
left_top_right_bottom=(300, 100, 500, 300)
mp drawing = mp. solutions.drawing utils
og hands = mp.solutions.hands
theck every a 18
check_cnt = 8
esents = ["sclick", "delick", "relick", "drag"]
with op_hands.Hands(
static image moderirus,
nar num hands = 1,
min_detection_confidence=8.7) as hunds:
    while com.isOpened():
        ret, frame = camuread()
        if not ret
           continue
        frame = cv2.flip(frame, 1)
        frame = cv2.resize(frame, [fslze[1], fsize[0]))
        cv2.rectargle(frame, (left, top), (right, bottom), (8, 0, 255), 1)
        h, H, I frame shape
        rgb = cv2.cvt(sisr(frame, cv2.00100_BGR2RGB)
        rgb.flags.writestle : False
        res = hunds.process(rgb)
        rgb.flags.writesble = True
        if res.multi_hanf_landmarks:
            for hand landmarks in res.multi_hand_landmarks:
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if res.multi_hand_landmarks:
for hand_landmarks in res.multi_hand_landmarks:
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    band_landwark_inp_hands_HensLandwark_INDEX_FINGER_DIF).s,
               hand_landwarks.landwark[ep_hands.HandLandwark.DEEX_EDGEE_DDF].y,
          index tip s mp_drawing.sermalized_to_pixel_coordinates(
    band_landmarks.landmark(mp_hands.Handlandmark.DOEX_FINSER_TIP].s,
               kand\_Landmarks\_Landmark[up\_hands\_HandLandmark\_DRGEN\_FDRGEN\_TDF], g,
          index_pip = rp.arrsy(sp_drawing__normalized_to_pixel_roordinates)
hand_landwarks_landmark(sp_hands_Handbark,DDEX_FINGEX_FIP).s,
               hand_landwarks_landwark_mp_hands_Handsandwark_DREE_FINGER_PIP].y.
               w. h33
          thusb_tip = sp_drawing_normalized_to_pixel_coordinates(
kand_landsurkc.landsurk(sp_bandc.Hand;undsurk.THPE_TIP].x,
               hand_landwarks.landeark[ap_hands.HandLandeark.THUMB_TDF]-y,
          midfle_tip = mp_drawing.pormalized_to_pixel_coordinates(
    hand_landmarks_landmark(mp_hands_Handmark.HIDDLE_FIMSER_TIP).s,
               hand_landmarks.landmark[ep_hands.HandLandmark.HDDLE_FINGEN_TIP].y,
          if index_gip is not None:

if check_cntzzcheck_every:
                    If themb_tip is not None and index_tip is not None and middle_tip is not None:
                          eprint(exclideon(inser_tip, middle_tip))
                          if malldem(index_lip, middle_tip)<58: # 58 whould be relative to the bright of frame
last event = "mile".
                          sels
                               if last_event=="delich":
                                    last_event=None
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         for introducional transition of (x,y) and (x,y) if we also be relative to be ignitive to form
              list evert . "milis"
         sile
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         of exclines them tip, indeption of Ad-
              lest_electr'sress'
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if last_sent = 'green'
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    if there tip is not have not brock tip is not home and mixtle tip is not been
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land, event + "rights"
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             if let every relief
    check_critrit.
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         mas right click)
    die
         man release))
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(Wendatastan e na MideoCapture)
        fsize = (53%, 72%)
         mp_drawing = mp.solutions.drawing_utils
        mo_hands = mp.solutions.hands
         left, top, right, bottom = (200, 100, 500, 400)
        events = ["solick", "bolick", "volick", "drag", "release"]
        theolymeny = 15
         ded_ot = 1
         last_event = None
         aut = n\Omega \lambda (idealriter("vot.wil", n\Omega \lambda (idealriter_force)"Vol"), 30, (fsize[1], fsize[1]) \rangle
         with no hands Hands (static image note-line,
                           nac rum hands = 1,
                            min_detection_confidence=0.5) as herdo:
             while can.is(pened():
                ret, frame = can.rest()
                if we ret
                    ontine
                 frame = cv2.flip(frame, 1)
                 frame = cv2.resize(frame, (fsize[1], fsize[0]))
                 cul.rectargle(frame, (left, top), (right, buttom), (0, 0, 25), []
                 rgb = ciQ.crtCclor(Frame, cv2.CDLCR_SERINGS)
                 res = hands.process(rgb)
                 if resmulti_tend_landmarks;
                     for hand landmarks in resumulti hand landmarks:
                        index_tip = np_drawing, normalizet_to_mixel_coordinates|
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                            hand Jandran's Jandran's op hands Handlandhank DOEX, FINER, TUP), y,
                           u, h)
                        index_dip = no_drawing._normalized_to_dixel_coordinates(
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                            hand_landmarks_landmark()rp_hands_HandLandmark_DIGEX_FDIGEX_DIFF).y,
                            a, h)
                        index_sip = rp.array(np_drawing, normalized_to_sibel_coordinates)
                            hand Jandran's Jandran's (ing hands Handlandhan's DOEX, FDHER, FTF) \alpha_{\rm c}
                            hand_Landmarks_Landmark(mp_hands_HandLandmark_DIGEX_FDIGEX_FDF).//,
                        thust tip = np_drawing, normalized to pixel_coordinates(
                            hand Jandhanks Jandhank op hands HandLandhank (HJME FIP) x_{\rm c}
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When we run the above snap code, we observe various outputs that demonstrate its functionality

The below snaps are the outputs



(a)

Fig(a) Dragging

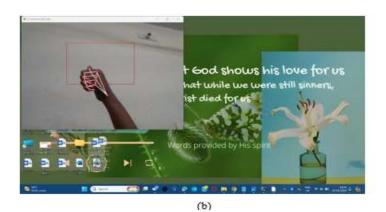
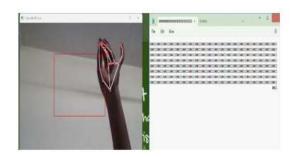


Fig.(b) Single click



Fig.(c) Screen adjust



(d) Fig.(d) press and release





(e) Fig. (e) Right click

(f) Fig. (f) double click

CONCLUSION:

It demonstrates the implementation of a hand gesture recognition system using a webcam for mouse control. By leveraging computer vision techniques and libraries such as Media Pipe and Open CV, the code captures real-time video frames from the webcam, detects hand landmarks, and recognizes specific gestures performed by the user. These gestures are then translated into corresponding mouse movements and actions, allowing for intuitive interaction with digital interfaces without the need for physical touch or input devices.