Langkah-Langkah Pengerjaan ROS Tutorial 2 (ROS1)

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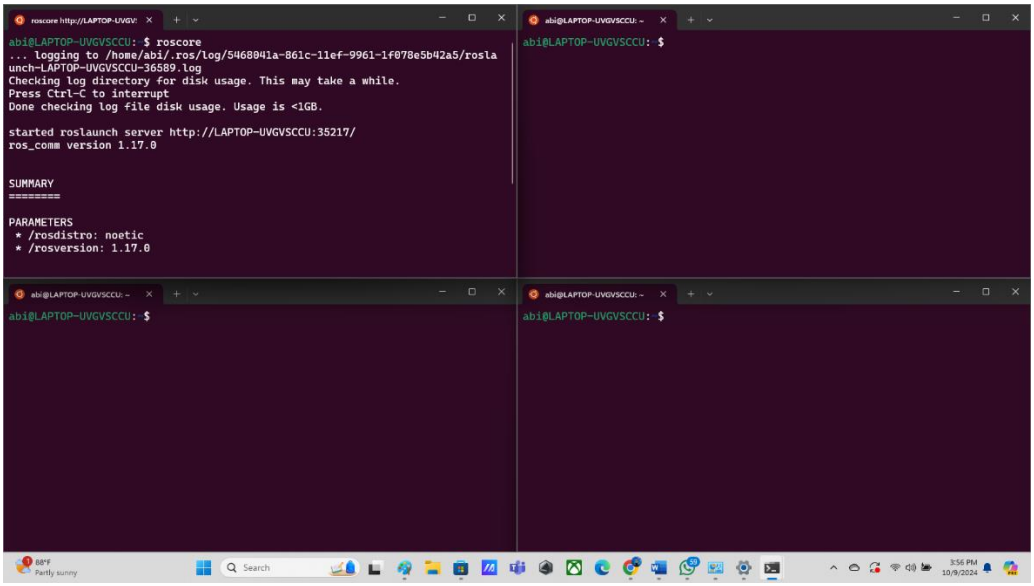
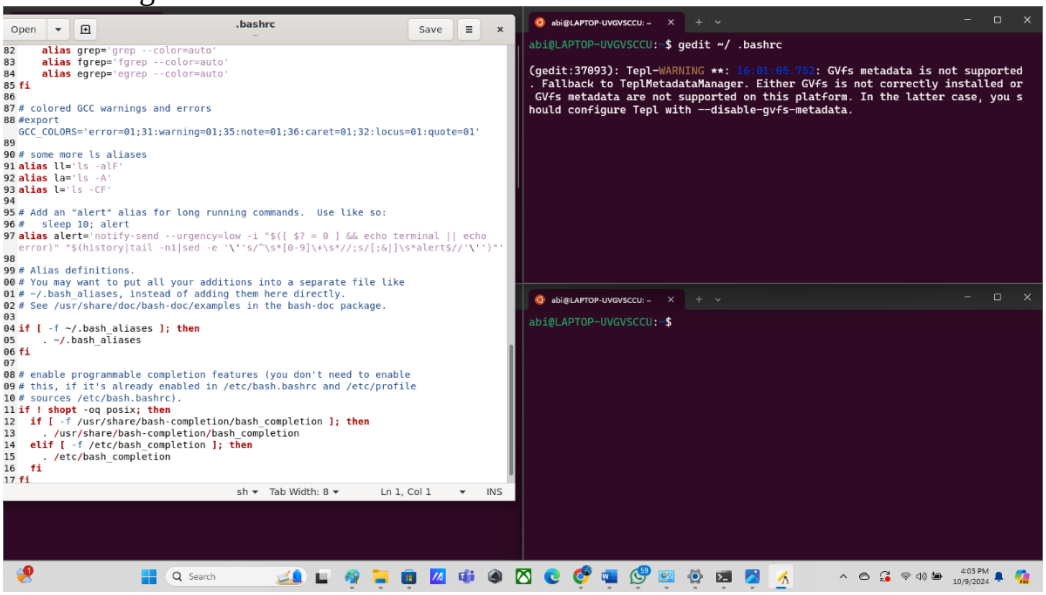
Kelas : TK-45-G09

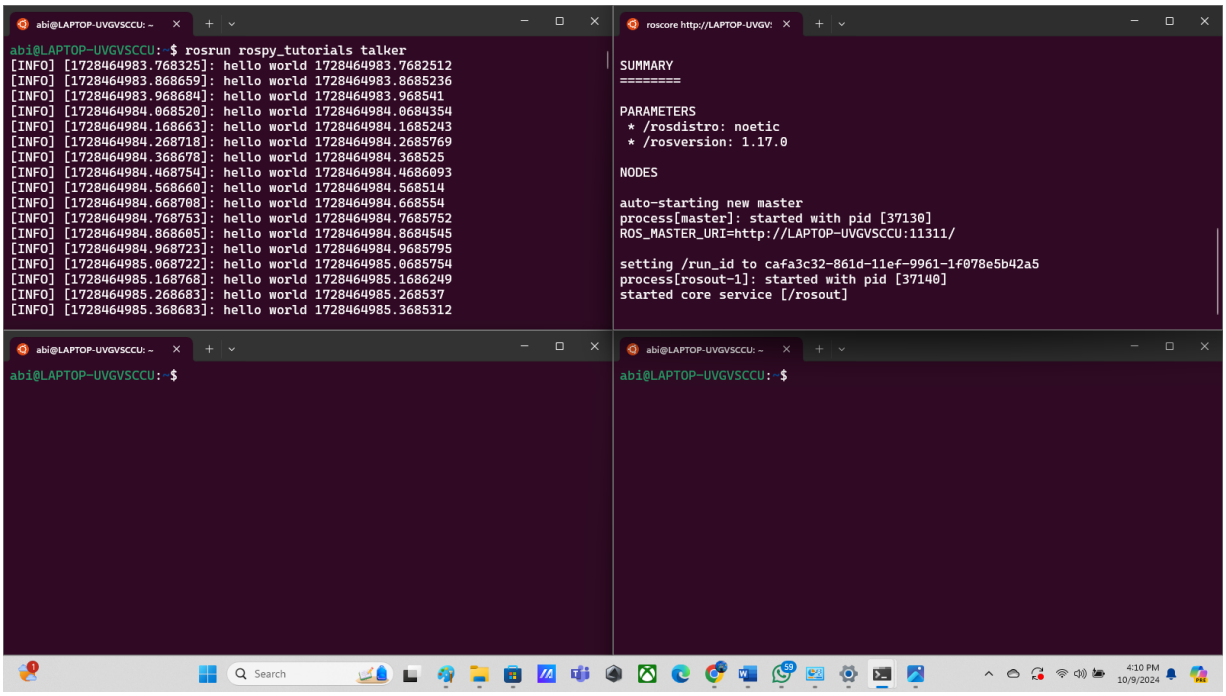
1. Masukkan syntax **roscore** untuk menjalankan komunikasi antar node ROS



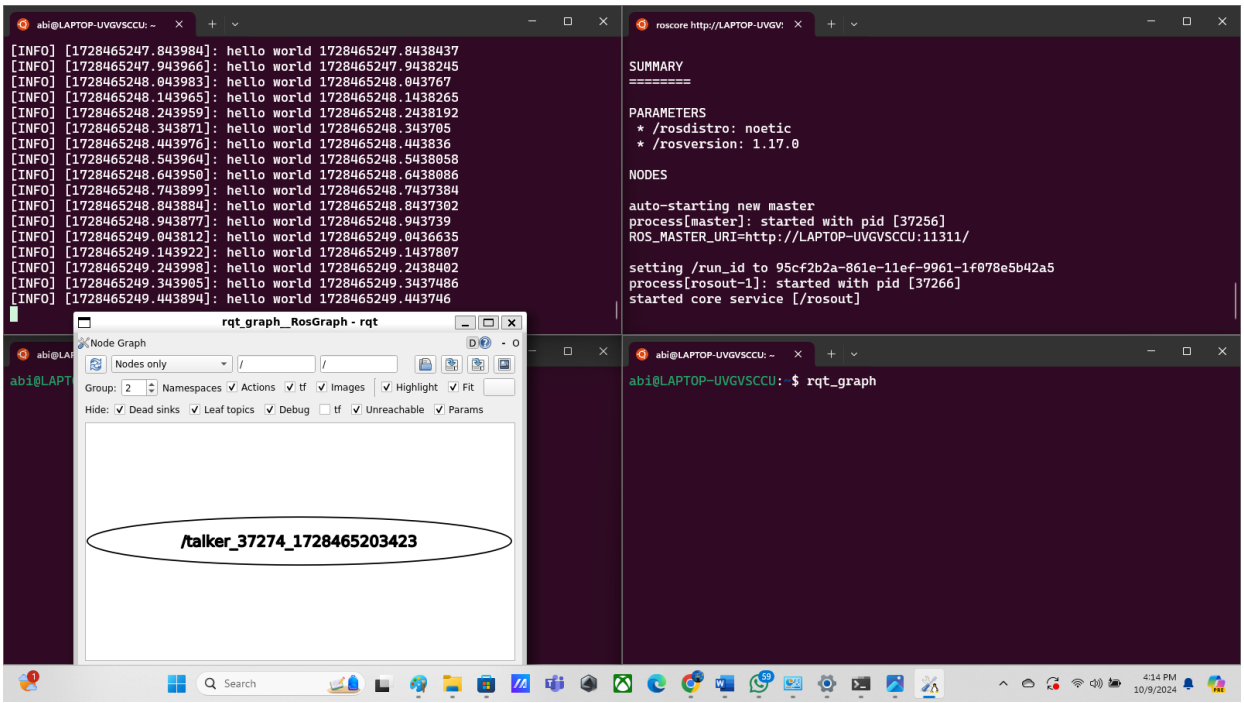
2. Masukkan Syntax **gedit ~/.bashrc** dan tambahkan **source/opt/res/noetic/setup.bash** untuk menginisialisasi environment ROS



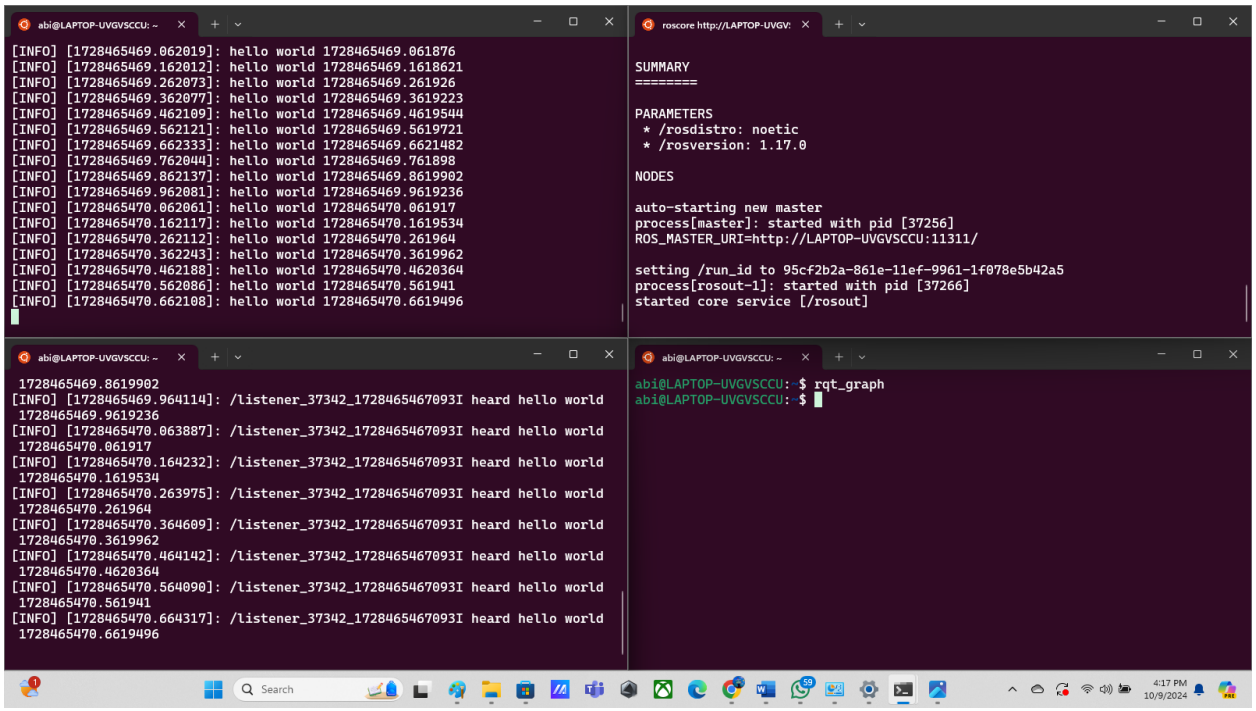
3. Masukkan Syntax **rosrun rospy_tutorials talker** untuk menjalankan node talker.



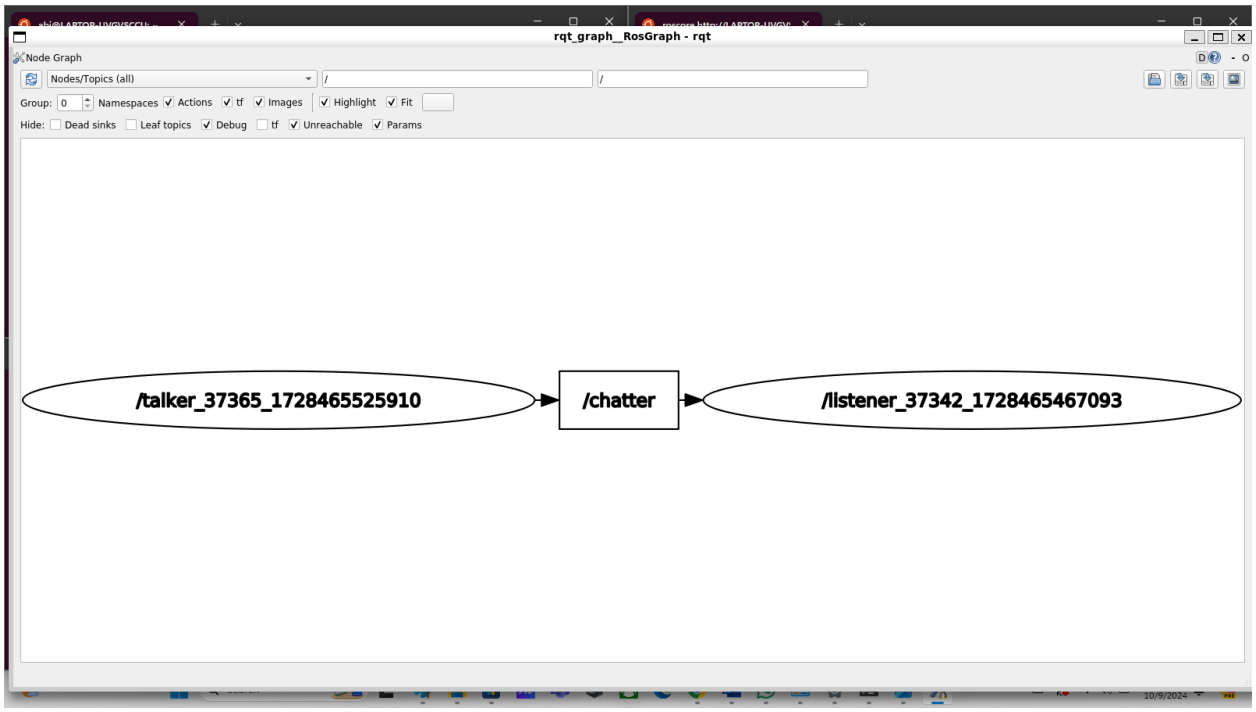
4. Masukkan Syntax **rqt_graph** untuk menampilkan diagram hubungan antar node.



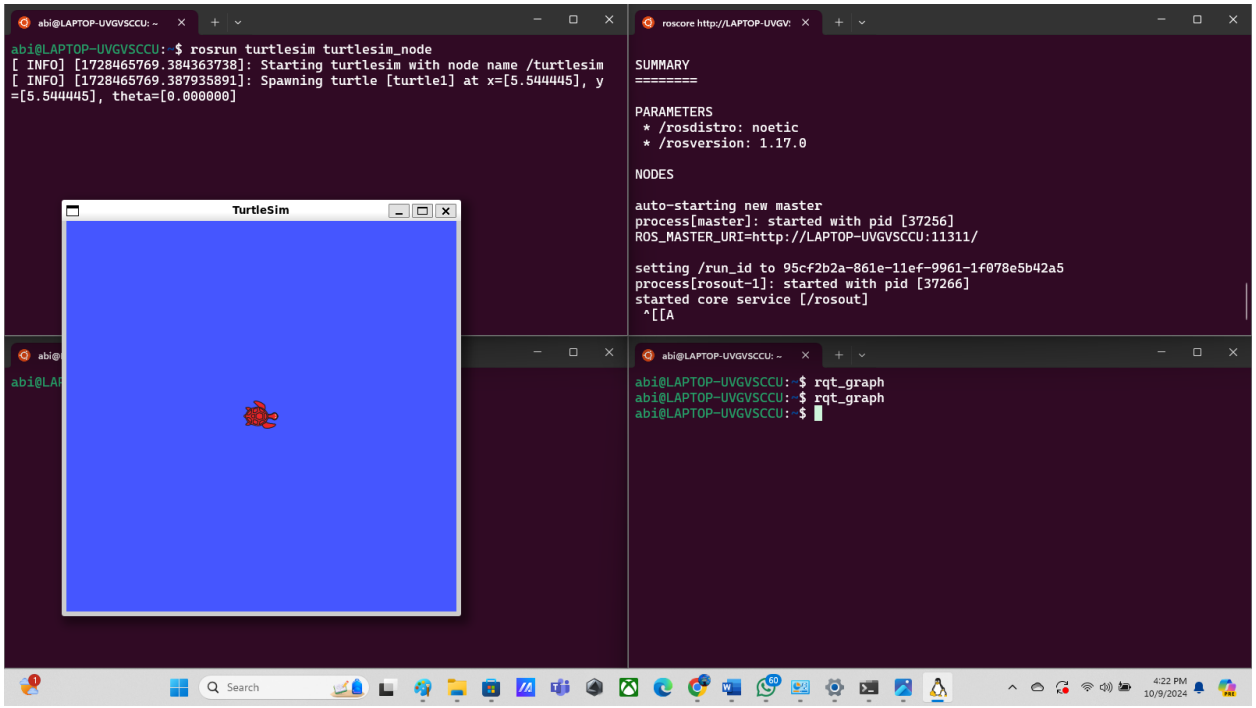
5. Masukkan Syntax **rospy_tutorials listener** untuk menjalankan node listener



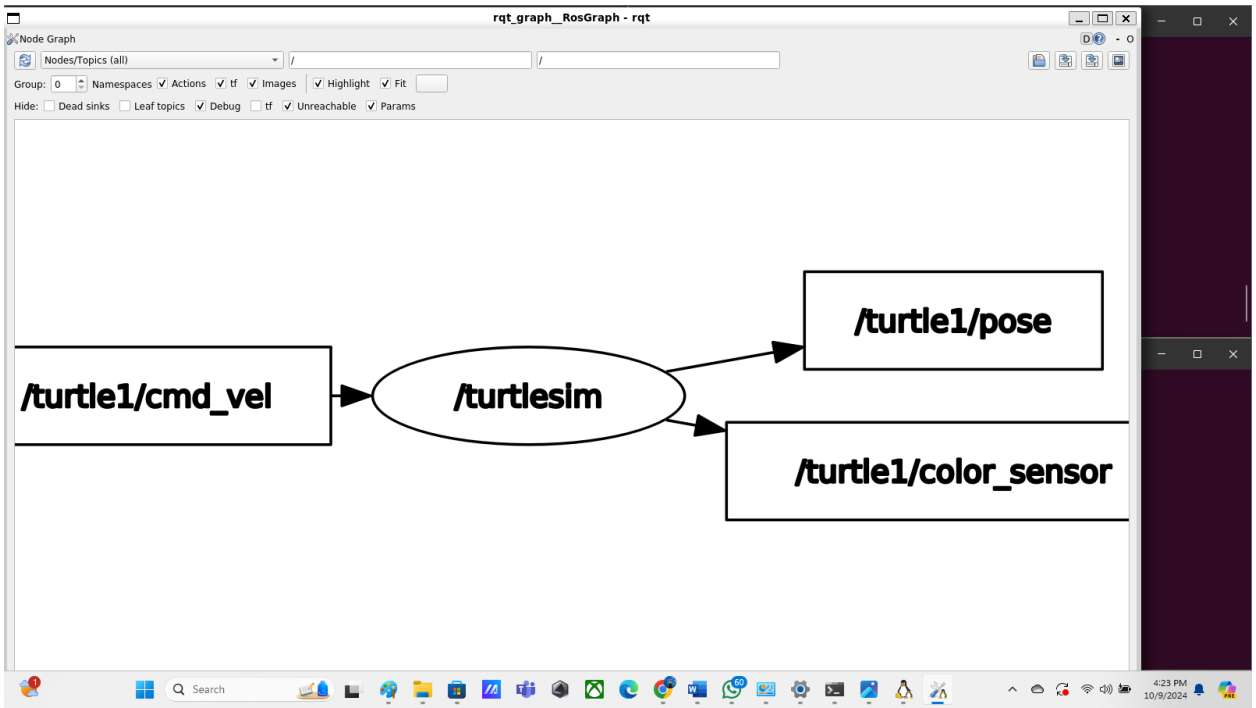
6. Masukkan syntax **rqt_graph** untuk melihat bagaimana node listener dapat terhubung dengan node talker.



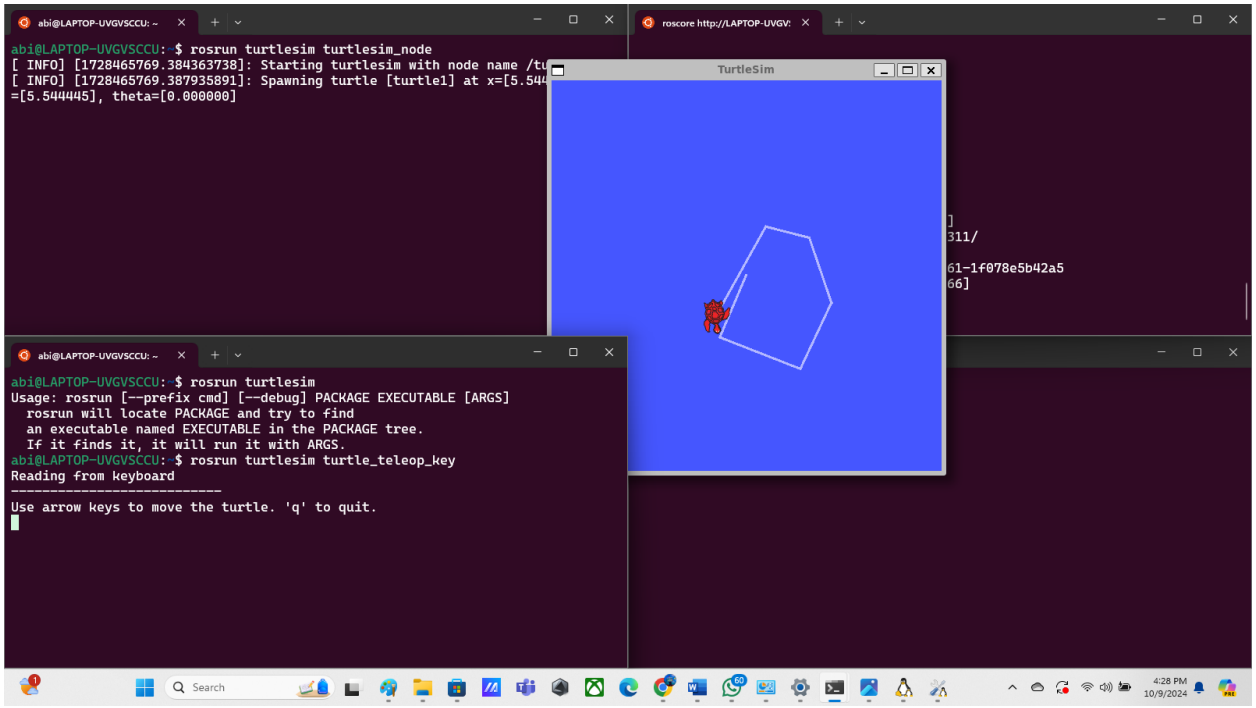
7. Masukkan syntax **rosrun turtlesim turtlesim_node** untuk menjalankan simulasi turtlesim



8. Masukkan syntax **rqt_graph** untuk melihat node turtlesim_node



9. Masukkan syntax **rosrun turtlesim turtle_teleop_key** untuk mengendalikan kura-kura menggunakan keyboard



10. Masukkan syntax **rqt_graph** untuk melihat bagaimana node turtle_teleop_key terhubung dengan turtlesim_node