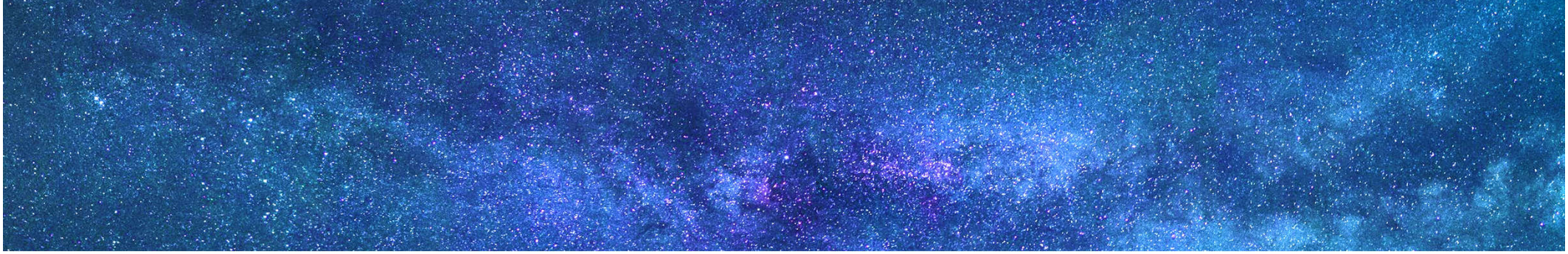
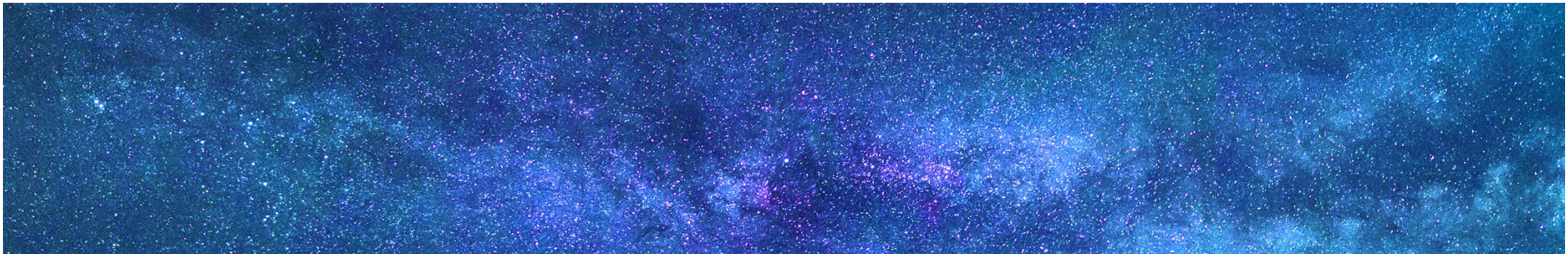


Operating System

Chapter 12: I/O Management



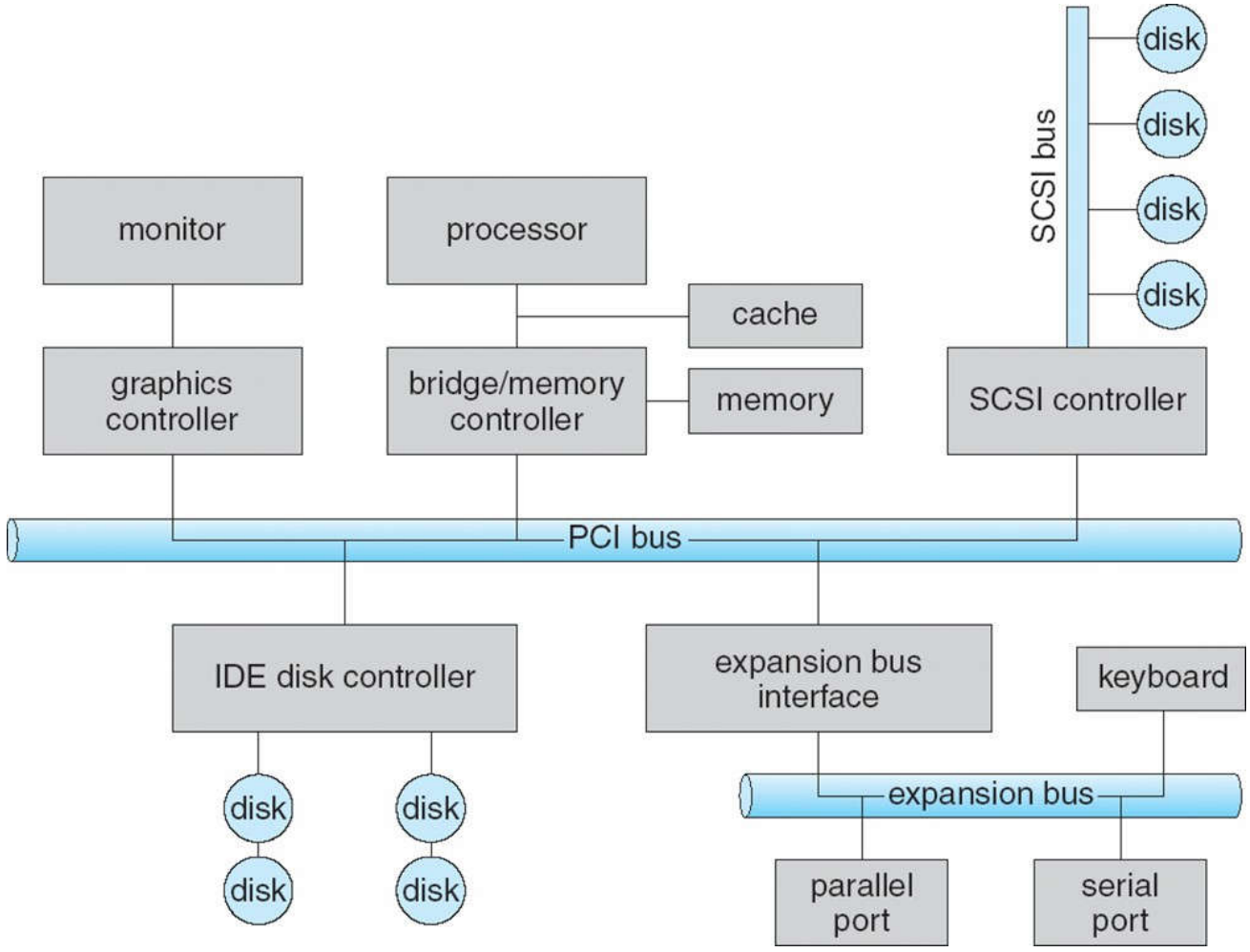
Overview

- I/O management is a major component of OS design and operation
  - important aspect of computer operation
    - I/O devices is the way computer to interact with user and other systems
    - I/O devices vary greatly
    - various methods to control them performance varies
    - device drivers encapsulate device details; presents an uniform interface
    -
  - new types of devices frequently emerges

I/O Hardware

- Incredible variety of I/O devices
  - storage, communication, human-interface
- Common concepts: signals from I/O devices interface with computer
  - bus: an interconnection between components (including CPU)
  - port: connection point for device
  - controller: component that control the device
    - can be integrated to device or separate circuit board
    - usually contains processor, microcode, private memory, bus controller, etc
- I/O access can use polling or interrupt

A Typical PC Bus Structure



I/O Hardware

- Some CPU architecture has **dedicated I/O instructions**
  - e.g., x86: in, out, ins, outs
- Devices usually provide registers for data and control I/O of device
  - device driver places (pointers to) commands and data to register
  - registers include **data-in**/**data-out**, **status**, **control** (or command) register
  - typically 1-4 bytes, or FIFO buffer
- Devices are assigned addresses for registers or on-device memory
  - **direct I/O instructions**
    - to access (mostly) registers
  - **memory-mapped I/O**
    - data and command registers mapped to processor address space
    - to access (large) on-device memory (graphics)

I/O Ports on PCs (Partial)

I/O address range (hexadecimal)	device
000–00F	DMA controller
020–021	interrupt controller
040–043	timer
200–20F	game controller
2F8–2FF	serial port (secondary)
320–32F	hard-disk controller
378–37F	parallel port
3D0–3DF	graphics controller
3F0–3F7	diskette-drive controller
3F8–3FF	serial port (primary)

Polling

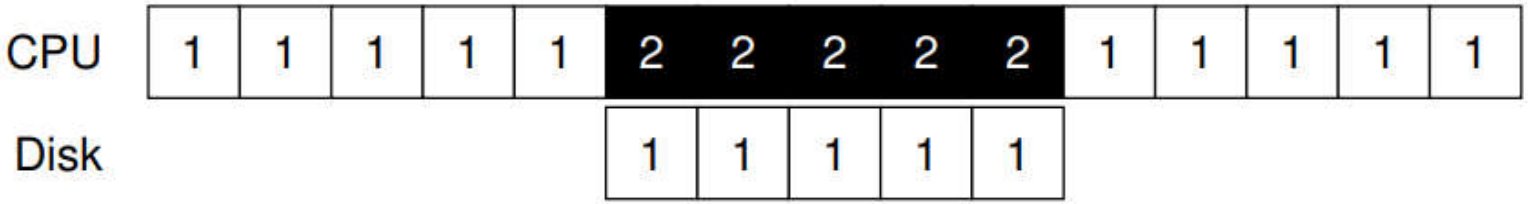
- For each I/O operation:
  - busy-wait if device is busy (status register)
  - send the command to the device controller (command register)
  - read status register until it indicates command has been executed
  - read execution status, and possibly reset device status

```
While (STATUS == BUSY)
    ; // wait until device is not busy
Write data to DATA register
Write command to COMMAND register
    (starts the device and executes the command)
While (STATUS == BUSY)
    ; // wait until device is done with your request
```

- Polling requires busy wait
  - reasonable if device is fast; inefficient if device slow

Interrupts

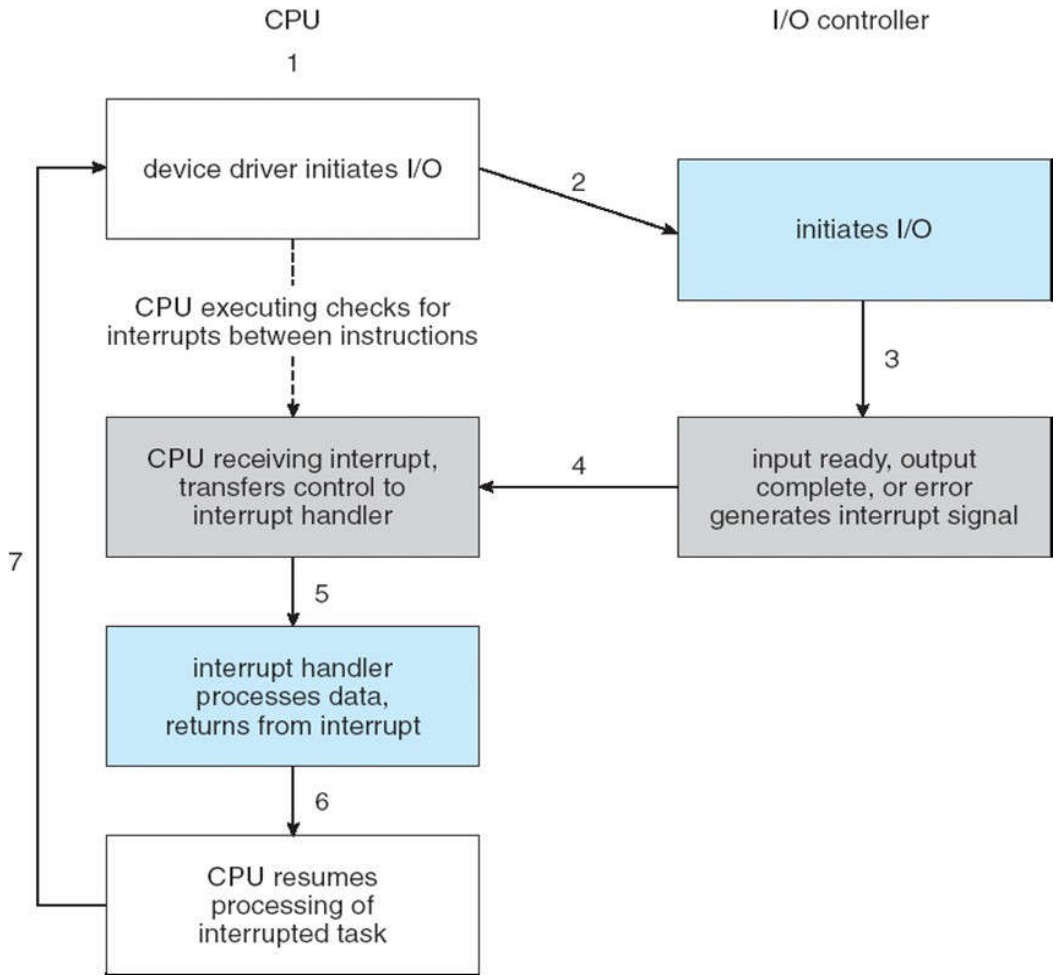
- Polling requires busy-wait, inefficient use of CPU resource
- Interrupts can avoid busy-wait
  - device driver send a command to the controller, and return
  - OS can schedule other activities
  - device will interrupt the processor when command has been executed
  - OS retrieves the result by handling the interrupt



- Interrupt-based I/O requires context switch at start and end
  - if interrupt frequency is extremely high, context switch wastes CPU time
  - solution: use polling instead
  - example: NAPI in Linux enables polling under very high network load

Interrupt-Driven I/O Cycle

- the device controller ***raises*** an interrupt by asserting a signal on the interrupt request line
- the CPU ***catches*** the interrupt and ***dispatches*** it to the interrupt handler
- the handler ***clears*** the interrupt by servicing the device.



Intel Pentium Interrupt Vector Table

vector number	description
0	divide error
1	debug exception
2	null interrupt
3	breakpoint
4	INTO-detected overflow
5	bound range exception
6	invalid opcode
7	device not available
8	double fault
9	coprocessor segment overrun (reserved)
10	invalid task state segment
11	segment not present
12	stack fault
13	general protection
14	page fault
15	(Intel reserved, do not use)
16	floating-point error
17	alignment check
18	machine check
19–31	(Intel reserved, do not use)
32–255	maskable interrupts

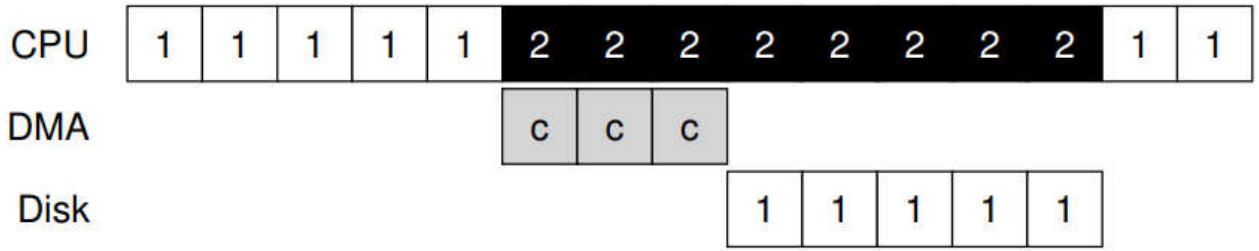
Interrupts

- Interrupt is also used for exceptions
  - protection error for access violation
  - page fault for memory access error
  - software interrupt for system calls

- Multi-CPU systems can process interrupts concurrently
  - sometimes a CPU may be dedicated to handle interrupts
  - interrupts can also have CPU affinity

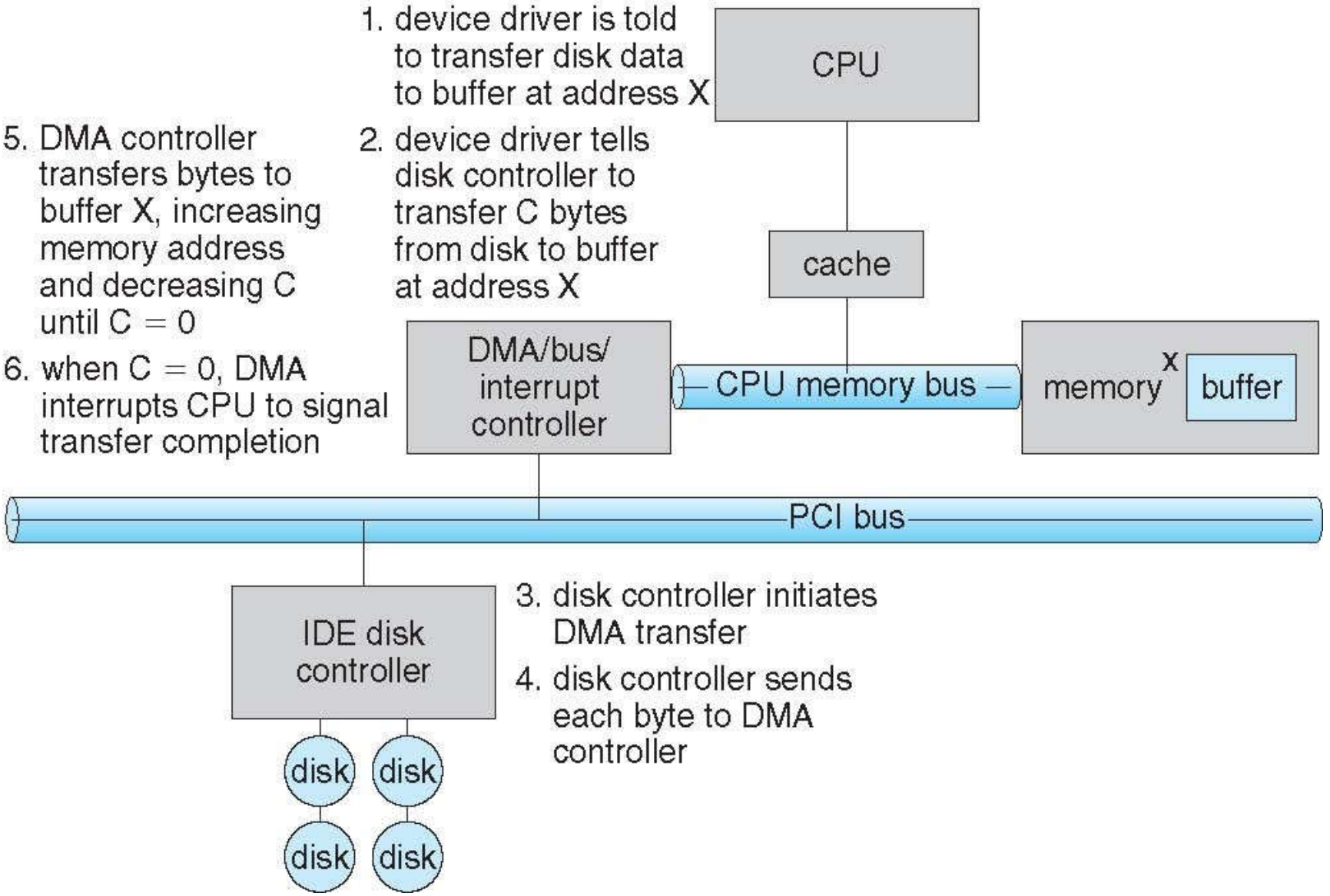
Direct Memory Access

- DMA transfer data directly between I/O device and memory
  - OS only need to issue commands, data transfers bypass the CPU
  - no programmed I/O (one byte at a time), data transferred in large blocks
  - it requires DMA controller in the device or system



- OS issues commands to the DMA controller
  - a command includes: operation, memory address for data, count of bytes…
  - usually it is the pointer of the command written into the command register
  - when done, device interrupts CPU to signal completion

Six Steps of DMA Transfer

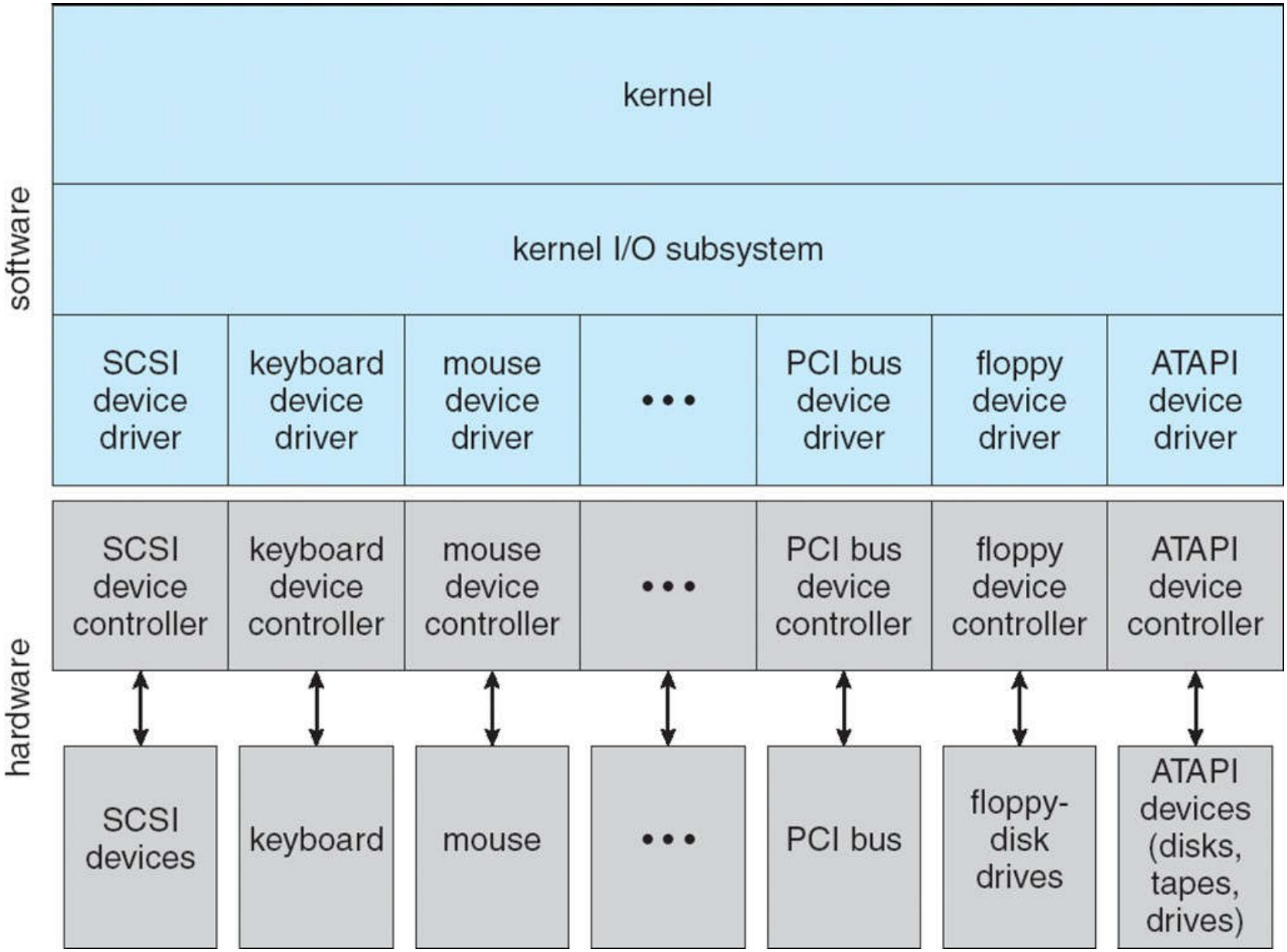


Application I/O Interface

- I/O system calls encapsulate device behaviors in generic classes
  - in Linux, devices can be accessed as files; low-level **access with ioctl**

- Device-driver layer hides differences among I/O controllers from kernel
  - each OS has its own I/O subsystem and device driver frameworks
  - new devices talking already-implemented protocols need no extra work

Kernel I/O Structure



Characteristics of I/O Devices

- Devices vary in many dimensions
  - character-stream or block
  - sequential or random-access
  - synchronous or asynchronous (or both) sharable or dedicated
  - speed of operation
  - read-write, read only, or write only

aspect	variation	example
data-transfer mode	character block	terminal disk
access method	sequential random	modem CD-ROM
transfer schedule	synchronous asynchronous	tape keyboard
sharing	dedicated sharable	tape keyboard
device speed	latency seek time transfer rate delay between operations	
I/O direction	read only write only read–write	CD-ROM graphics controller disk

Characteristics of I/O Devices

- Broadly, I/O devices can be grouped by the OS into
  - block I/O: read, write, seek
  - character I/O (Stream)
  - memory-mapped file access
  - network sockets

Block and Character Devices

- Block devices access data in blocks, such as disk drives…
  - commands include read, write, seek
  - raw I/O, direct I/O, or file-system access
  - memory-mapped file access possible (e.g., memory-mapped files)
  - DMA
- Character devices include keyboards, mice, serial ports…
  - very diverse types of devices

Network Devices

- Varying enough from block and character to have own interface
  - very different from pipe, mailbox…
- Popular interface for network access is the socket interface
  - it separates network protocol from detailed network operation
  - network operations are implemented as sockets
    - e.g., Unix socket

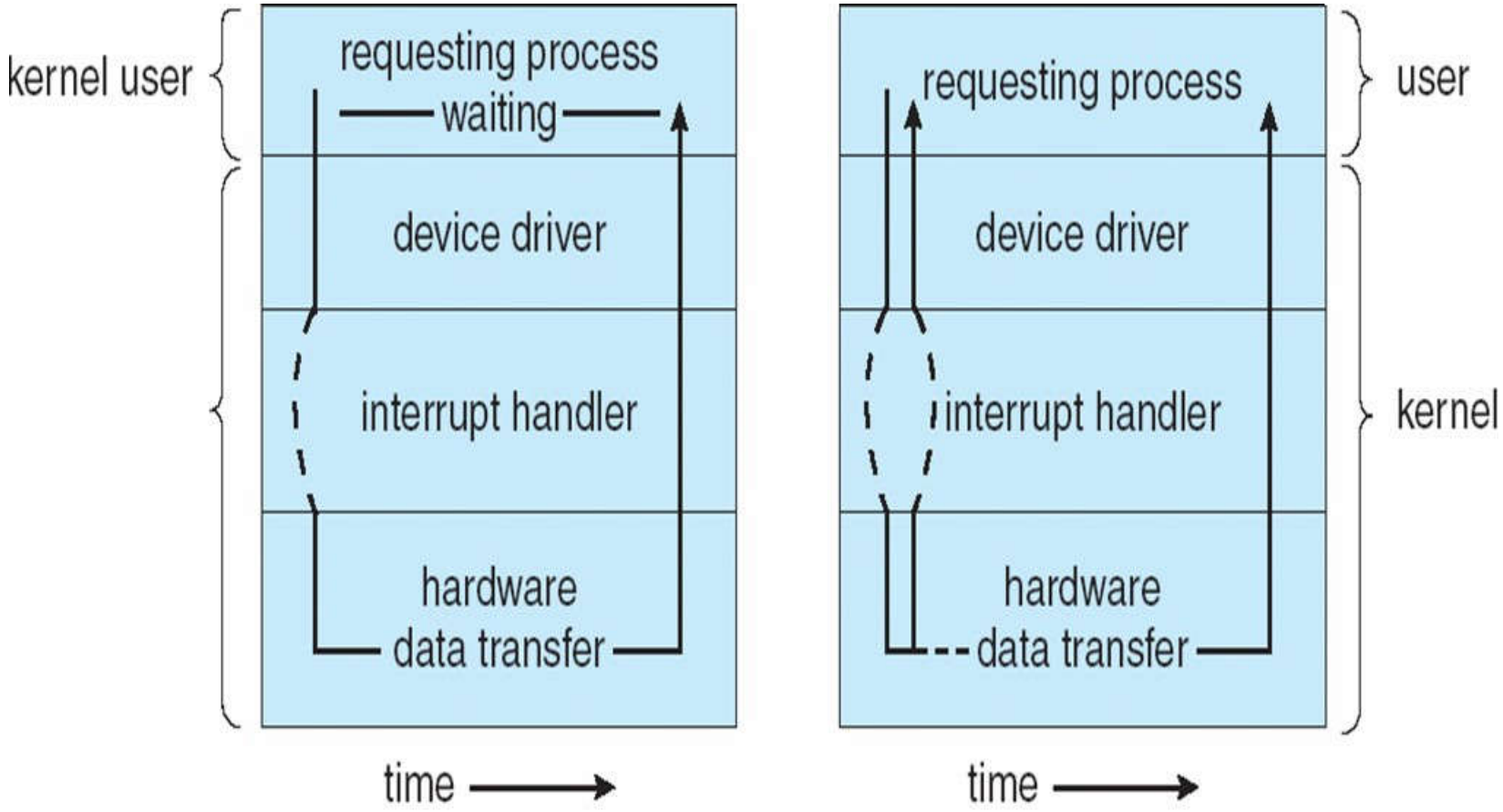
Clocks and Timers

- Clocks and timers can be considered as character devices
  - very important devices as they provide current time, elapsed time, timer
  - Normal resolution about 1/60 second, some OS provides higher-resolution ones

Synchronous/Asynchronous I/O

- Synchronous I/O includes blocking and non-blocking I/O
  - blocking I/O: process suspended until I/O completed
    - ✓ easy to use and understand, but may be less efficient
    - ✓ insufficient for some needs
  - non-blocking I/O: I/O calls return as much data as available
    - ✓ process does not block, returns whatever existing data (read or write)
    - ✓ use select to find if data is ready, then use read or write to transfer data
- Asynchronous I/O: process runs while I/O executes,
  - I/O subsystem signals process when I/O completed via signal or callback
  - difficult to use but very efficient

Two I/O Methods



Kernel I/O Subsystem

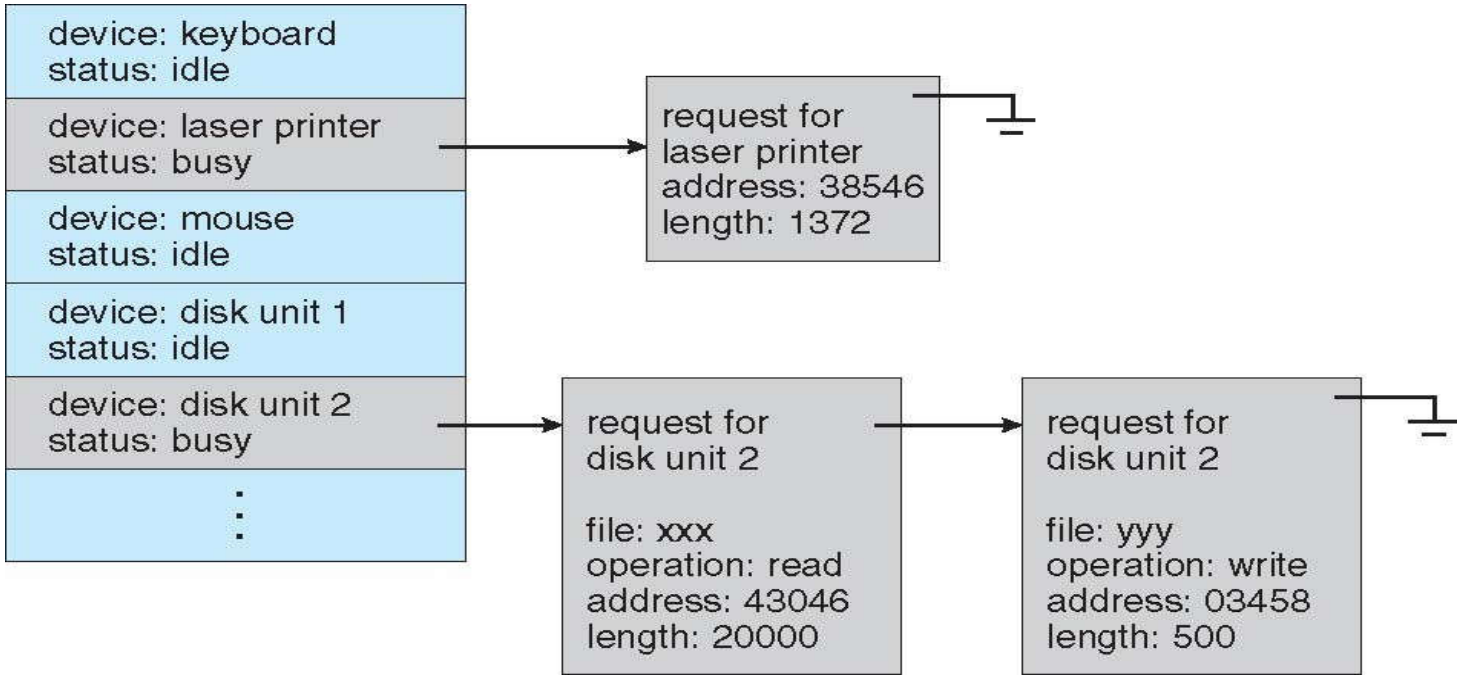
- I/O scheduling
  - to queue I/O requests via per-device queue
  - to schedule I/O for fairness and quality of service

- Buffering - store data in memory while transferring between devices
  - to cope with device speed mismatch: receive from network and write to ssd, double buffering
  - to cope with device transfer size mismatch: network buffer reassembly of message
  - to maintain “copy semantics”: write()

Kernel I/O Subsystem

- **Caching:** hold a copy of data for fast access
  - key to performance
  - sometimes combined with buffering
    - Buffer in memory is also used as caching for file operations
- **Spooling**: hold output if device can serve only one request at a time
  - i.e., printing
- **Device reservation**: provides exclusive access to a device
  - system calls for allocation and de-allocation
  - watch out for deadlock

Device-status Table



- The wait queue is attached to a device-status table. The kernel manages this table that contains an entry for each I/O device
- Each table entry indicates the device's type, address, and state (not functioning, idle, or busy)

Error Handling

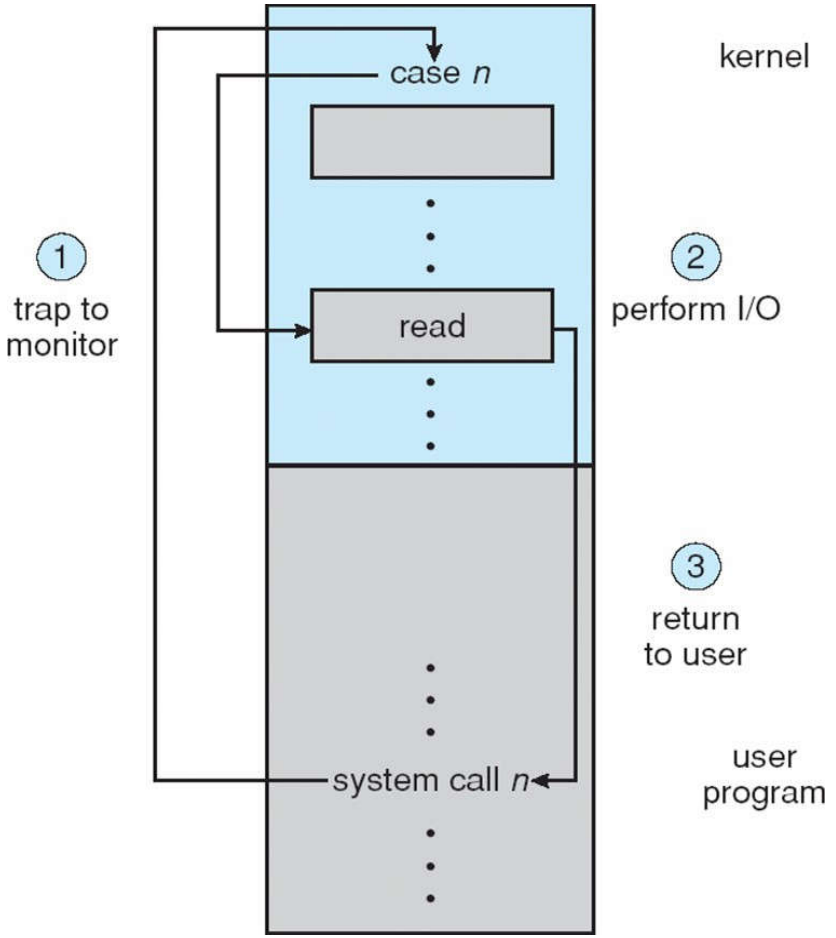
- Some OSes try to recover from errors
  - e.g., device unavailable, transient write failures
  - sometimes via retrying the read or write
  - some systems have more advanced error handling
    - track error frequencies, stop using device with high error frequency
- Some OSes just return an error number or code when I/O request fails
  - system error logs hold problem reports

I/O Protection

- OS need to protect I/O devices
  - e.g., keystrokes can be stolen by a keylogger if keyboard is not protected
  - always assume user may attempt to obtain illegal I/O access
- To protect I/O devices:
  - define all I/O instructions to be privileged
    - I/O must be performed via system calls
  - memory-mapped I/O and I/O ports must be protected too

Use System Call to Perform I/O

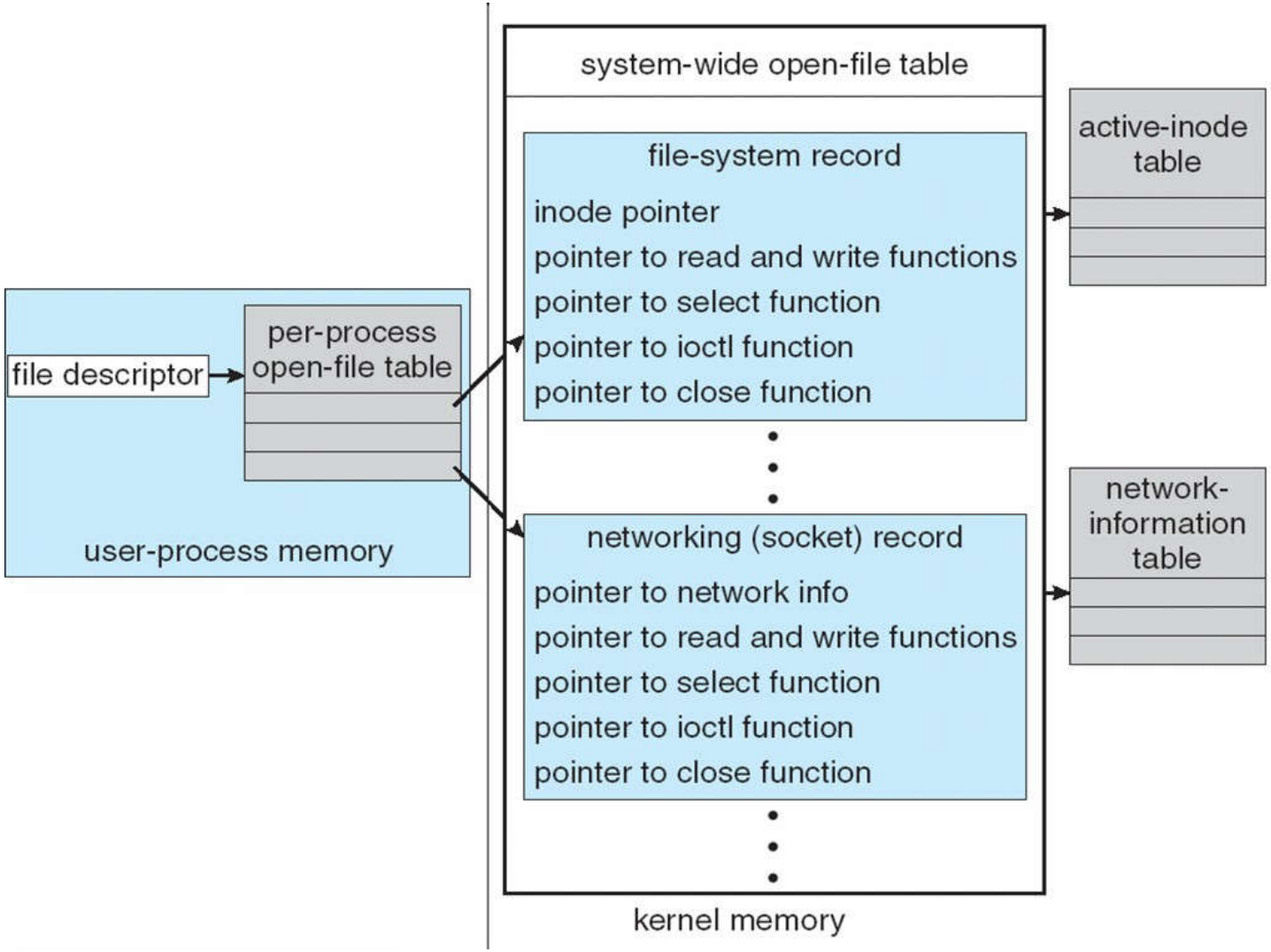
- To prevent users from performing illegal I/O
  - all I/O instructions are privileged instructions
- Users cannot issue I/O instructions directly. they must do it through the operating system.
- To do I/O, a user program executes a system call to request that the operating system perform I/O on its behalf



Kernel Data Structures

- Kernel keeps state info for I/O components
  - e.g., open file tables, network connections, character device state
  - many data structures to track buffers, memory allocation, “dirty” blocks
    - sometimes very complicated
- Some OS uses message passing to implement I/O, e.g., Windows
  - message with I/O information passed from user mode into kernel
  - message modified as it flows through to device driver and back to process

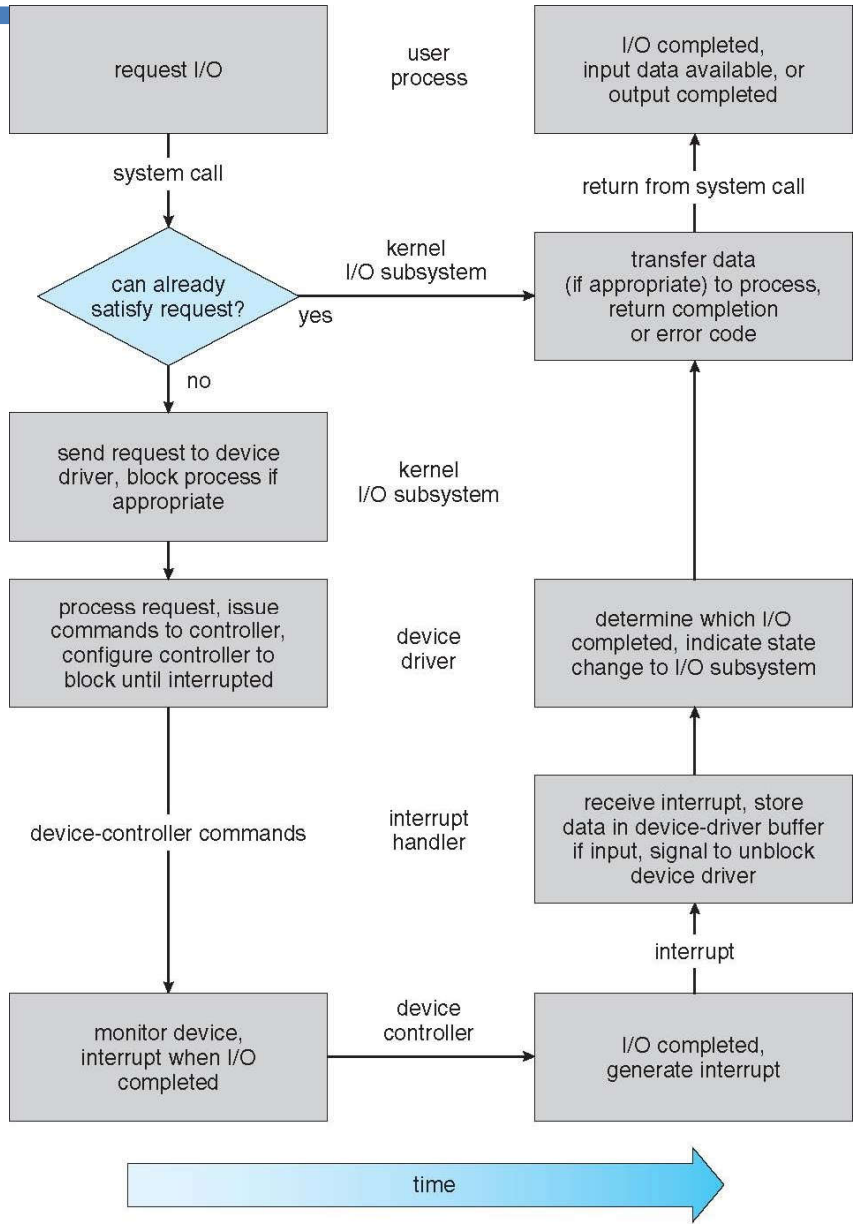
UNIX I/O Kernel Structure



I/O Requests to Hardware

- System resource access needs to be mapped to hardware
- Consider reading a file from disk for a process:
  - determine device holding file
  - translate name to device representation
    - FAT, UNIX: major/minor
  - physically read data from disk into buffer
  - make data available to requesting process
  - return control to process

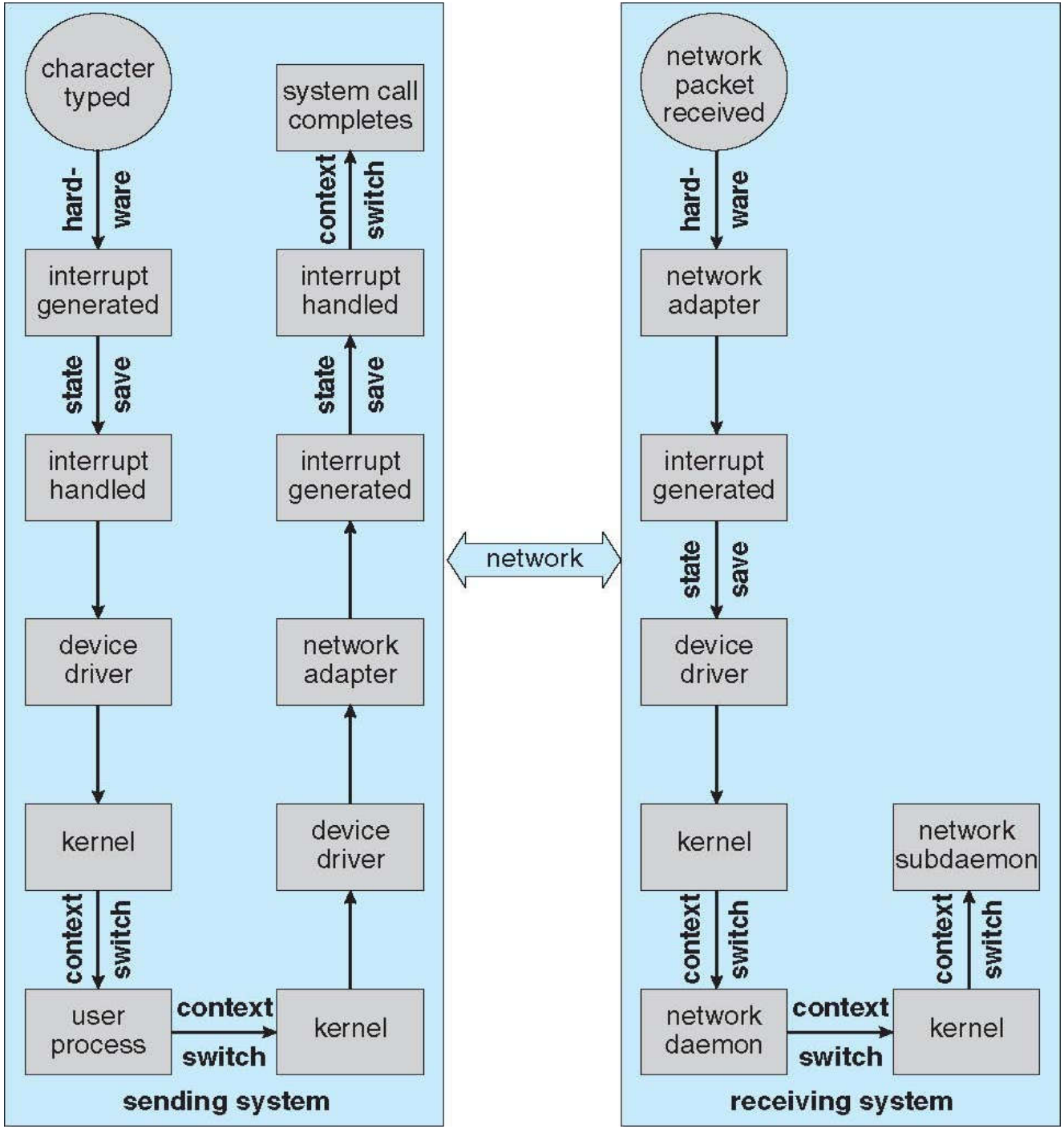
Life Cycle of An I/O Request



Performance

- I/O is a major factor in system performance
  - CPU to execute device driver, kernel I/O code
  - context switches due to interrupts
  - data buffering and copying
    - network traffic especially stressful

Network Communications: high context switch



Improve Performance

- Reduce number of context switches
- Reduce data copying
- Reduce interrupts by using large transfers, smart controllers, polling Use DMA
- Use smarter hardware devices
- Balance CPU, memory, bus, and I/O performance for highest throughput
- Move user-mode processes / daemons to kernel threads

Questions?