回归分析

特征选择

线性模型特征选择(Linear model variable selection)

$$Y = \beta_0 + \beta_1 X_1 + \dots + \beta_p X_p + \epsilon.$$

子集**选择**(subset selection):

Adjusted R^2

Mellow Cp

AIC、BIC

Validation selection

N-fold validation selection

(k折交叉验证)

特征**缩**减(Shrinkage method):

Lasso regression

Ridge regression

降**维**(dimension deduction):

PCR

PLS 偏最小二乘法

逐步回**归**(Stepwise Regression)

• $\{x_1, x_2, x_3\}$

• 全选择

- 1. $\{x_1\}$, $\{x_2\}$, $\{x_3\}$ 建立回归模型 找出RSS最小。
- 2. $\{x_1, x_2\}$, $\{x_1, x_3\}$, $\{x_2, x_3\}$ 建立回归模型找出最小RSS的。
- 3. $\{x_1, x_2, x_3\}$ 建立回归模型。

向前选择(Forward selection)

• $\{x_1, x_2, x_3\}$

• 向前选择

- 1. $\{x_1\}$, $\{x_2\}$, $\{x_3\}$ 建立回归模型 找出RSS最小。 比如**选**中的是 $\{x_1\}$
- 2. $\{x_1, x_2\}$, $\{x_1, x_3\}$ 建立回归模型找出最小RSS的。
- 3. $\{x_1, x_2, x_3\}$ 建立回归模型。

向后选择(Backward selection)

• $\{x_1, x_2, x_3\}$

• 向前选择

- 1. $\{x_1, x_2, x_3\}$ 建立回归模型。
- 2. $\{x_1, x_2\}$, $\{x_1, x_3\}$, $\{x_2, x_3\}$ 建立回归模型找出最小RSS的。 假如是 $\{x_1, x_3\}$ 最小
- 3. $\{x_1\}$, $\{x_3\}$ 建立回归模型找出最小RSS的。

逐步回**归**(Stepwise Regression)

• 向前向后**选则进**行了 $1 + \frac{p(p+1)}{2}$ 次回归

• 全选择进行了2^p次回归

子集选择

- 1. 逐步回归 $\{x_1, x_2, x_3\}, \{x_2, x_3\}, \{x_3\}$
- 2. 从逐步回归中选出最好的模型
 - Adjusted R^2
 - Mellow Cp
 - AIC、BIC
 - Validation selection
 - N-fold validation selection 交叉验证

特征选择

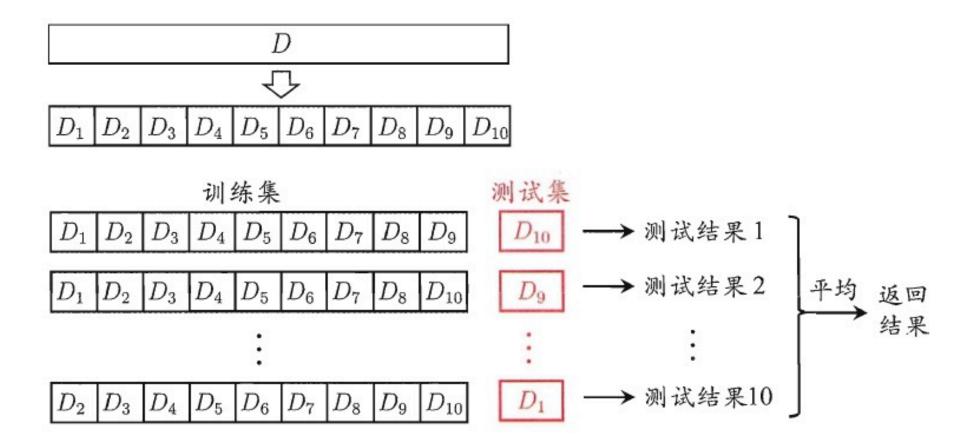
从逐步回**归**中选出最好的模型

Adjusted R^2

```
R^2 adjusted = 1- \frac{(1 - R^2)(N - 1)}{N - p - 1}
where
R^2 = sample R-square
p = Number of predictors
N = Total sample size.
```

- Mellow Cp
- AIC、BIC
- Validation selection
- N-fold validation selection 交叉验证

K折交叉验证



特征缩减(Shrinkage method)

回归模型:
$$Y=\beta_0+\beta_1X_1+\cdots+\beta_pX_p+\epsilon$$

RSS =
$$\sum_{i=1}^{n} \left(y_i - \beta_0 - \sum_{j=1}^{p} \beta_j x_{ij} \right)^2$$
.

Lasso I) : Loss=
$$\sum_{i=1}^n \left(y_i - \beta_0 - \sum_{j=1}^p \beta_j x_{ij} \right)^2 + \lambda \sum_{j=1}^p |\beta_j| = \text{RSS} + \lambda \sum_{j=1}^p |\beta_j|.$$

当
$$\lambda \to$$
无穷, $\hat{\beta} = \begin{pmatrix} y \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \end{pmatrix}$

特征缩减(Shrinkage method)

回归模型:
$$Y=eta_0+eta_1X_1+\cdots+eta_pX_p+\epsilon$$

RSS =
$$\sum_{i=1}^{n} \left(y_i - \beta_0 - \sum_{j=1}^{p} \beta_j x_{ij} \right)^2$$
.

岭回归: Loss=
$$\sum_{i=1}^{n} \left(y_i - \beta_0 - \sum_{j=1}^{p} \beta_j x_{ij} \right)^2 + \lambda \sum_{j=1}^{p} \beta_j^2 = \text{RSS} + \lambda \sum_{j=1}^{p} \beta_j^2,$$

常识性的微性间泪损失函数
$$J(\omega) = \sum_{i=1}^{N} \| \omega^{T} \alpha_{i} - y_{i} \|^{2} + \lambda \omega^{T} \omega$$

$$= (W^{T} x^{T} - Y^{T})(XW - Y) + \lambda \omega^{T} \omega$$

$$= (W^{T} x^{T} - Y^{T})(XW - Y) + \lambda \omega^{T} \omega$$

$$= W^{T} x^{T} x w - 2 w^{T} x^{T} Y + Y^{T} Y + \lambda \omega^{T} \omega$$

$$= W^{T} (x^{T} x + \lambda I) w - 2 w^{T} x^{T} Y + Y^{T} Y$$

$$\hat{W} = \underset{\partial W}{\operatorname{arg min }} J(\omega)$$

$$\frac{\partial J(\omega)}{\partial w} = 2 (x^{T} x + \lambda I) w - 2 x^{T} Y = 0$$

$$\hat{\omega} = (x^{T} x + \lambda I)^{T} x^{T} Y.$$

$$\frac{\partial W}{\partial u} = 1 x^{T} x + \lambda I x^{T} Y$$

$$\frac{\partial W}{\partial u} = 1 x^{T} x + \lambda I x^{T} Y$$

特征降维 (PCR)

PCA:
$$X_1, X_2, \dots, X_p \rightarrow Z_1, Z_2, \dots, Z_m$$

找到p*m维的 Φ ,使得 $X * \Phi = Z$

$$\begin{bmatrix} x_{11} & \cdots & x_{1p} \\ \vdots & \ddots & \vdots \\ x_{n1} & \cdots & x_{np} \end{bmatrix} \begin{bmatrix} \phi_{11} & \cdots & \phi_{1m} \\ \vdots & \ddots & \vdots \\ \phi_{p1} & \cdots & \phi_{pm} \end{bmatrix} = \begin{bmatrix} z_{11} & \cdots & z_{1m} \\ \vdots & \ddots & \vdots \\ z_{n1} & \cdots & z_{nm} \end{bmatrix}$$

如何求Φ?

PCA:
$$X_1, X_2, \dots, X_p \rightarrow Z_1, Z_2, \dots, Z_m$$

找到p*m维的 ϕ ,使得 $X * \Phi = Z$

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如何求 Φ ?

$$\Phi_{1} = \begin{bmatrix} \phi_{11} \\ \vdots \\ \phi_{p1} \end{bmatrix} \qquad \begin{cases} Z_{1} = X * \Phi_{1}, \ \max(Var(Z_{1})) \\ \Phi_{1}^{T} * \Phi_{1} = 1 \end{cases}$$

$$\Phi_{2} = \begin{bmatrix} \vdots \\ \vdots \\ \phi_{p2} \end{bmatrix} \qquad \begin{cases} Z_{2} = X * \Phi_{2}, \ \max(Var(Z_{2})) \\ \Phi_{2}^{T} * \Phi_{2} = 1 \\ \Phi_{1} 和 \Phi_{2} \land \text{相关}, \ \Phi_{2}^{T} * \Phi_{1} = 0 \end{cases}$$

$$\Phi_{m} = \begin{bmatrix} \vdots \\ \vdots \\ \phi_{pm} \end{bmatrix} \begin{cases} Z_{m} = X * \Phi_{m}, \max(Var(Z_{m})) \\ \Phi_{m}^{T} * \Phi_{m} = 1 \\ \Phi_{1}, \Phi_{2}, \Phi_{3} \dots, \Phi_{m}$$
不相关

PCA: $X_1, X_2, ..., X_p \rightarrow Z_1, Z_2, ..., Z_m$ 找到p*m维的 ϕ ,使得 $X * \Phi = Z$

$$\begin{bmatrix} x_{11} & \cdots & x_{1p} \\ \vdots & \ddots & \vdots \\ x_{n1} & \cdots & x_{np} \end{bmatrix} \quad \begin{bmatrix} \phi_{11} & \cdots & \phi_{1m} \\ \vdots & \ddots & \vdots \\ \phi_{p1} & \cdots & \phi_{pm} \end{bmatrix} \quad = \quad \begin{bmatrix} z_{11} & \cdots & z_{1m} \\ \vdots & \ddots & \vdots \\ z_{n1} & \cdots & z_{nm} \end{bmatrix}$$

特征降维 (PLS)

$$\begin{split} \Phi_1 &= [\begin{array}{c} \phi_{11} \\ \vdots \\ \phi_{p1} \\ \end{split} \qquad \begin{cases} Z_1 = X * \Phi_1, & \max(\rho_{Z_1,Y}) \\ \Phi_1^T * \Phi_1 = 1 \\ \end{cases} \\ \Phi_2 &= [\begin{array}{c} \vdots \\ \vdots \\ \phi_{p2} \\ \end{cases} \end{cases} \qquad \begin{cases} Z_2 = X * \Phi_2, & \max(\rho_{Z_2,Y}) \\ \Phi_2^T * \Phi_2 = 1 \\ \Phi_1 和 \Phi_2 \text{ π} \text{ $\#$} \text{ $\#$}, & \Phi_2^T * \Phi_1 = 0 \end{cases} \\ \vdots & \vdots & \vdots \\ \Phi_m &= [\begin{array}{c} \vdots \\ \vdots \\ \phi_{pm} \\ \end{cases} \qquad \begin{cases} Z_m = X * \Phi_m, & \max(\rho_{Z_m,Y}) \\ \Phi_m^T * \Phi_m = 1 \\ \Phi_1, \Phi_2, \Phi_3 \dots, \Phi_m \text{ π} \text{ $\#$} \text{ $\#$} \end{cases} \end{split}$$

PLS: 通过 $\max(\rho_{Z_i,Y})$, where $Z_i = X * \Phi_i$, 建立回归模型。

$$\Phi_{1} = \begin{bmatrix} \phi_{11} \\ \vdots \\ \phi_{p1} \end{bmatrix} \qquad \begin{cases} Z_{1} = X * \Phi_{1}, & \max(\rho_{Z_{1},Y}) \\ \Phi_{1}^{T} * \Phi_{1} = 1 \end{cases}$$

$$\Phi_2 = [\ \vdots\] \\ \phi_{p2} \qquad \begin{cases} Z_2 = X * \Phi_2, \ \max(\rho_{Z_2,Y}) \\ \Phi_2^T * \Phi_2 = 1 \\ \Phi_1 和 \Phi_2 \text{ 不相关, } \Phi_2^T * \Phi_1 = 0 \end{cases}$$

:

$$\begin{split} \Phi_{\mathrm{m}} &= [& \vdots \\ \phi_{pm} &= \begin{bmatrix} \mathcal{Z}_m = X * \Phi_m, & \max(\rho_{Z_m,Y}) \\ \Phi_m^T * \Phi_m &= 1 \\ \Phi_1, \Phi_2, \Phi_3 \dots, \Phi_m \overline{\wedge} & \text{ } \# \not \in \end{split}$$