connection while SOCK_DGRAM is used for udp connection. The protocol parameter specifies the protocol used and is always 0. The header files used are <sys/types.h> and <sys/socket.h>.

Experiment 3

Implementation of Client-Server communication using Socket Programming and TCP as transport layer protocol

Aim: Client sends a string to the server using tcp protocol. The server reverses the string and returns it to the client, which then displays the reversed string.

Description:

Steps for creating a TCP connection by a client are:

1. Creation of client socket

int socket(int domain, int type, int protocol);

This function call creates a socket and returns a socket descriptor. The domain parameter specifies a communication domain; this selects the protocol family which will be used for communication. These families are defined in <sys/socket.h>. In this program, the domain AF_INET is used. The socket has the indicated type, which specifies the communication semantics. SOCK_STREAM type provides sequenced, reliable, two-way, connection based byte streams. The protocol field specifies the protocol used. We always use 0. If the system call is a failure, a -1 is returned. The header files used are sys/types.h and sys/socket.h.

2. Filling the fields of the server address structure.

The socket address structure is of type struct sockaddr_in.

```
struct sockaddr_in {

u_short sin_family;
u_short sin_port;
struct in_addr sin_addr;
char sin_zero[8]; /*unused, always zero*/
};
struct in_addr {

u_long s_addr;

};
```

The fields of the socket address structure are
sin_family which in our case is AF_INET
sin_port which is the port number where socket binds
sin_addr which is the IP address of the server machine

The header file that is to be used is **netinet/in.h**

struct sockaddr_in servaddr;
servaddr.sin_family = AF_INET;
servaddr.sin_port = htons(port_number);

Why htons is used ?. Numbers on different machines may be represented differently (big-endian machines and little-endian machines). In a little-endian machine the low order byte of an integer appears at the lower address; in a big-endian machine instead the low order byte appears at the higher address. Network order, the order in which numbers are sent on the internet is big-endian.

It is necessary to ensure that the right representation is used on each machine. Functions are used to convert from host to network form before transmission- htons for short integers and htonl for long integers.
The value for servaddr.sin_addr is assigned using the following function

inet_pton(AF_INET, "IP_Address", &servaddr.sin_addr);

The binary value of the dotted decimal IP address is stored in the field when the function returns.

3. Binding of the client socket to a local port

This is optional in the case of client and we usually do not use the bind function on the client side.

4. Connection of client to the server

A server is identified by an IP address and a port number. The connection operation is used on the client side to identify and start the connection to the server.

int connect(int sd, struct sockaddr * addr, int addrlen);

sd – file descriptor of local socket
addr – pointer to protocol address of other socket
addrlen – length in bytes of address structure

The header files to be used are sys/types.h and sys/socket.h

It returns 0 on sucess and -1 in case of failure.

5. Reading from socket

In the case of TCP connection reading from a socket can be done using the read system call

int read(int sd, char * buf, int length);

6. writing to a socket

In the case of TCP connection writing to a socket can be done using the write system call

int write(int sd, char * buf, int length);

7. closing the connection

The connection can be closed using the close system call

int close(int sd);

Steps for TCP Connection for server

1. Creating a listening socket

int socket(int domain, int type, int protocol);

This system call creates a socket and returns a socket descriptor. The domain field used is **AF_INET**. The socket type is **SOCK_STREAM**. The protocol field is 0. If the system is a failure, a -1 is returned. Header files used are sys/types.h and sys/socket.h.

2. Binding to a local port

int bind(int sd, struct sockaddr * addr, int addrlen);

This call is used to specify for a socket the protocol port number where it will wait for messages. A call to bind is optional on the client side, but required on the server side. The first field is the socket descriptor of the local socket. Second is a pointer to the protocol address structure of this socket. The third is the length in bytes of the structure referenced by **addr**. This system call returns an integer. It is 0 for success and -1 for failure. The header files are s**ys/types.h** and s**ys/socket.h.**

3. Listening on the port

The listen function is used on the server in connection oriented communication to prepare a **socke** to accept messages from clients.

int listen(int fd, int qlen);

fd – file descriptor of a socket that has already been bound
qlen – specifies the maximum number of messages that can wait to be processed by the server while the server is busy servicing another request. Usually it is taken as 5. The header files used are sys/types.h and sys/socket.h. This function returns 0 on success and -1 on failure.

4. Accepting a connection from the client

The accept function is used on the server in the case of connection oriented communication to accept a connection request from a client.

int accept(int fd, struct sockaddr * addressp, int * addrlen);

The first field is the descriptor of the server socket that is listening. The second parameter **addressp** points to a socket address structure that will be filled by the address of calling client when the function returns. The third parameter **addrlen** is an integer that will contain the actual length of address structure of the client. It returns an integer that is a descriptor of a new socket called the connection socket. Server sockets send data and read data from this socket. The header files used are sys/types.h and s**ys/socket.h.**

Algorithm

Client

1. Create socket
2. Connect the socket to the server
3. Read the string to be reversed from the standard input and send it to the server
Read the matrices from the standard input and send it to server using socket
4. Read the reversed string from the socket and display it on the standard output
Read product matrix from the socket and display it on the standard output
5. Close the socket

Server

1. Create listening socket
2. bind IP address and port number to the socket
3. listen for incoming requests on the listening socket
4. accept the incoming request
5. connection socket is created when accept returns
6. Read the string using the connection socket from the client
7. Reverse the string
8. Send the string to the client using the connection socket
9. close the connection socket
10. close the listening socket

Client Program

```
#include<stdio.h>
```

```
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<string.h>
#include<stdlib.h>
#include<unistd.h>

int main( int argc, char *argv[])
{
struct sockaddr_in server;
int sd ;
char buffer[200];
if((sd = socket(AF_INET, SOCK_STREAM, 0)) < 0)
{
perror("Socket failed:");
exit(1);
}
// server socket address structure initialisation
bzero(&server, sizeof(server) );
server.sin_family = AF_INET;
server.sin_port = htons(atoi(argv[2]));
inet_pton(AF_INET, argv[1], &server.sin_addr);
if(connect(sd, (struct sockaddr *)&server, sizeof(server))< 0)
{
perror("Connection failed:");
exit(1);
}
fgets(buffer, sizeof(buffer), stdin);
buffer[strlen(buffer) - 1] = '\0';
write (sd,buffer, sizeof(buffer));
read(sd,buffer, sizeof(buffer));
printf("%s\n", buffer);
close(fd);
}
```

Server Program

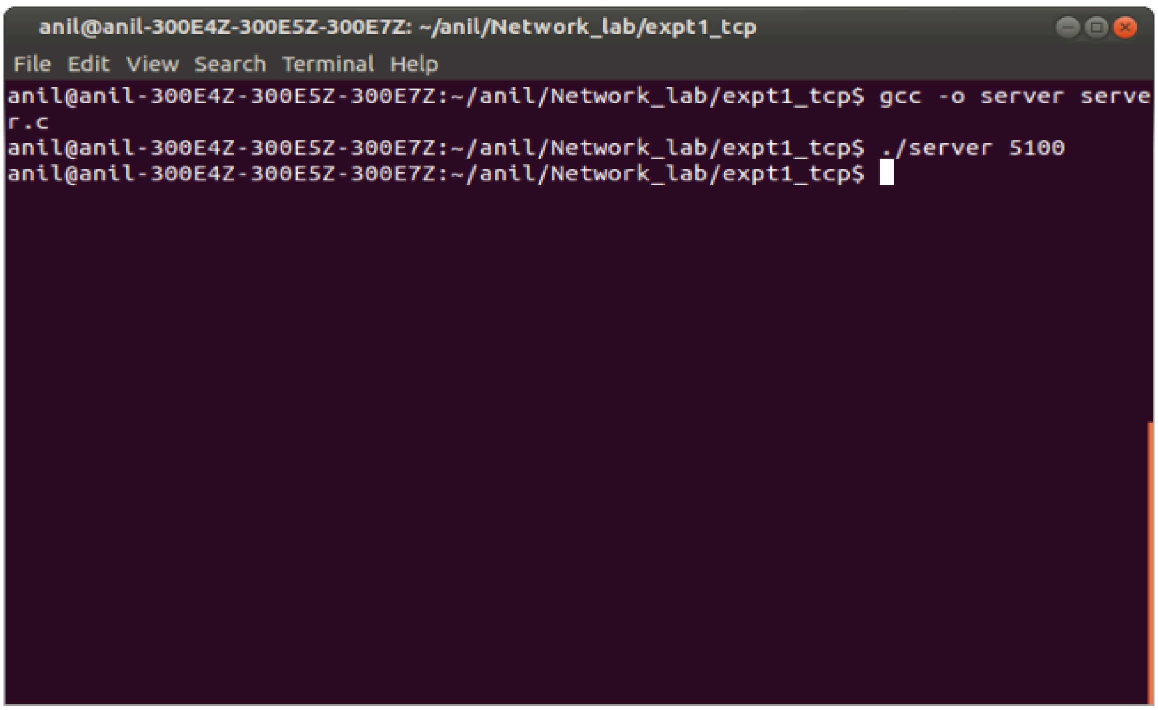
```
#include<stdio.h>
```

```
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<string.h>
#include<stdlib.h>
#include<unistd.h>

int main( int argc, char *argv[])
{
struct sockaddr_in server, cli;
int cli_len;
int sd, n, i, len;
int data, temp;
char buffer[100];
if((sd = socket(AF_INET, SOCK_STREAM, 0)) < 0)
{
perror("Socket failed:");
exit(1);
}

// server socket address structure initialisation
bzero(&server, sizeof(server) );
server.sin_family = AF_INET;
server.sin_port = htons(atoi(argv[1]));
server.sin_addr.s_addr = htonl(INADDR_ANY);
if(bind(sd, (struct sockaddr*)&server, sizeof(server)) < 0)
{
perror("bind failed:");
exit(1);
}
listen(sd,5);
if((data = accept(sd , (struct sockaddr *) &cli, &cli_len)) < 0)
{
perror("accept failed:");
exit(1);
}
read(data,buffer, sizeof(buffer));
len = strlen(buffer);
```

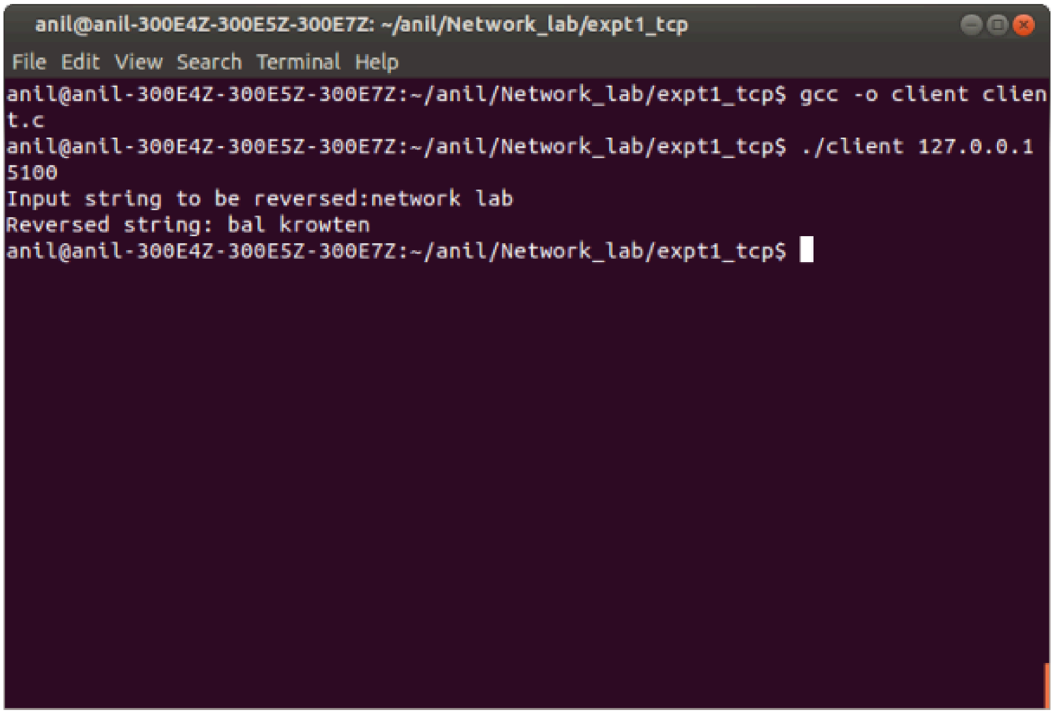
```
for( i =0; i<= len/2; i++)
{
temp = buffer[i];
buffer[i] = buffer[len - 1-i];
buffer[len-1-i] = temp;
}
write (data,buffer, sizeof(buffer));
close(data);
close(sd);
}
```

Output

Server



Client



Experiment 8

Implementation of Client-Server communication using Socket Programming and UDP as transport layer protocol

Aim: Client sends two matrices to the server using udp protocol. The server multiplies the matrices and sends the product to the client, which then displays the product matrix.

Description:

Steps for transfer of data using UDP

1. Creation of UDP socket

The function call for creating a UDP socket is

int socket(int domain, int type, int protocol);

The domain parameter specifies a communication domain; this selects the protocol family which will be used for communication. These families are defined in <sys/socket.h>. In this program, the domain **AF_INET** is used. The next field type has the value **SOCK_DGRAM**. It supports datagrams (connectionless, unreliable messages of a fixed maximum length). The protocol field specifies the protocol used. We always use 0. If the socket function call is successful, a socket descriptor is returned. Otherwise -1 is returned. The header files necessary for this function call are sys/types.h and s**ys/socket.h.**

2. Filling the fields of the server address structure.

The socket address structure is of type struct sockaddr_in.

```
struct sockaddr_in {

u_short sin_family;
u_short sin_port;
struct in_addr sin_addr;
char sin_zero[8]; /*unused, always zero*/
};
struct in_addr {

u_long s_addr;

};
```

The fields of the socket address structure are

sin_family which in our case is **AF_INET**
sin_port which is the port number where socket binds
sin_addr is used to store the IP address of the server machine and is of type struct **in_addr**

The header file that is to be used is **netinet/in.h**

The value for servaddr.sin_addr is assigned using the following function

inet_pton(AF_INET, “IP_Address”, &servaddr.sin_addr);

The binary value of the dotted decimal IP address is stored in the field when the function returns.

3. Binding of a port to the socket in the case of server

This call is used to specify for a socket the protocol port number where it will wait for messages. A call to bind is optional in the case of client and compulsory on the server side.

int bind(int sd, struct sockaddr* addr, int addrlen);

The first field is the socket descriptor. The second is a pointer to the address structure of this socket. The third field is the length in bytes of the size of the structure referenced by **addr**. The header files are **sys/types.h** and s**ys/socket.h.** This function call returns an integer, which is 0 for success and -1 for failure.

4. Receiving data

ssize_t recvfrom(int s, void * buf, size_t len, int flags, struct sockaddr * from, socklen_t * fromlen);

The **recvfrom** calls are used to receive messages from a socket, and may be used to receive data on a socket whether or not it is connection oriented. The first parameter s is the socket descriptor to read from. The second parameter buf is the buffer to read information into. The third parameter len is the maximum length of the buffer. The fourth parameter is flag. It is set to zero. The fifth parameter from is a pointer to **struct sockaddr** variable that will be filled with the IP address and port of the originating machine. The sixth parameter fromlen is a pointer to a **local int** variable that should be initialized to **sizeof(struct sockaddr).** When the function returns, the integer variable that fromlen points to will contain the actual number of bytes that is contained in the socket address structure. The header files required are **sys/types.h** and **sys/socket.h.** When the function returns, the number of bytes received is returned or -1 if there is an error.

5. Sending data

sendto- sends a message from a socket

ssize_t sendto(int s, const void * buf, size_t len, int flags, const struct sockaddr * to, socklen_t tolen);

The first parameter s is the socket descriptor of the sending socket. The second parameter buf is the array which stores data that is to be sent. The third parameter len is the length of that data in bytes. The fourth parameter is the flag parameter. It is set to zero. The fifth parameter to points to a variable that contains the destination IP address and port. The sixth parameter tolen is set to **sizeof(struct sockaddr**). This function returns the number of bytes actually sent or -1 on error. The header files used are **sys/types.h** and **sys/socket.h.**

Algorithm

Client

1. Create socket
2. Read the matrices from the standard input and send it to server using socket
3. Read product matrix from the socket and display it on the standard output
4. Close the socket

Server

1. Create socket
2. bind IP address and port number to the socket
3. Read the matrices socket from the client using socket
4. Find product of matrices
5. Send the product matrix to the client using socket
6. close the socket

Client program

```
#include<stdio.h>
#include<string.h>
#include<sys/socket.h>
#include<sys/types.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<stdlib.h>
main(int argc, char * argv[])
{
int i,j,n;
int sock_fd;
struct sockaddr_in servaddr;
int matrix_1[10][10], matrix_2[10][10], matrix_product[10][10];
int size[2][2];
int num_rows_1, num_cols_1, num_rows_2, num_cols_2;
if(argc != 3)
{
fprintf(stderr, "Usage: ./client IPaddress_of_server port\n");
exit(1);
}
printf("Enter the number of rows of first matrix\n");
```

```
scanf("%d", &num_rows_1);
printf("Enter the number of columns of first matrix\n");
scanf("%d", &num_cols_1);
printf("Enter the values row by row one on each line\n" );
for ( i = 0; i < num_rows_1; i++)
for( j=0; j<num_cols_1; j++)
{
scanf("%d", &matrix_1[i][j]);
}
size[0][0] = num_rows_1;
size[0][1] = num_cols_1;
printf("Enter the number of rows of second matrix\n");
scanf("%d", &num_rows_2);
printf("Enter the number of columns of second matrix\n");
scanf("%d", &num_cols_2);
if( num_cols_1 != num_rows_2)
{
printf("MATRICES CANNOT BE MULTIPLIED\n");
exit(1);
}
printf("Enter the values row by row one on each line\n");
for (i = 0; i < num_rows_2; i++)
for(j=0; j<num_cols_2; j++)
{
scanf("%d", &matrix_2[i][j]);
}
size[1][0] = num_rows_2;
size[1][1] = num_cols_2;
if((sock_fd = socket(AF_INET, SOCK_DGRAM, 0)) < 0)
{
printf("Cannot create socket\n");
exit(1);
}
bzero((char*)&servaddr, sizeof(servaddr));
servaddr.sin_family = AF_INET;
servaddr.sin_port = htons(atoi(argv[2]));
inet_pton(AF_INET, argv[1], &servaddr.sin_addr);

// SENDING MATRIX WITH SIZES OF MATRICES 1 AND 2
n = sendto(sock_fd, size, sizeof(size),0, (struct sockaddr*)&servaddr, sizeof(servaddr));
```

```
if( n < 0)
{
perror("error in matrix 1 sending");
exit(1);
}
// SENDING MATRIX 1
n = sendto(sock_fd, matrix_1, sizeof(matrix_1),0, (struct sockaddr*)&servaddr,
sizeof(servaddr));
if( n < 0)
{
perror("error in matrix 1 sending");
exit(1);
}
// SENDING MATRIX 2
n = sendto(sock_fd, matrix_2, sizeof(matrix_2),0, (struct sockaddr*)&servaddr,
sizeof(servaddr));
if( n < 0)
{
perror("error in matrix 2 sending");
exit(1);
}
if((n=recvfrom(sock_fd, matrix_product, sizeof(matrix_product),0, NULL, NULL)) == -1)
{
perror("read error from server:");
exit(1);
}
printf("\n\nTHE PRODUCT OF MATRICES IS \n\n\n");
for( i=0; i < num_rows_1; i++)
{
for( j=0; j<num_cols_2; j++)
{
printf("%d ",matrix_product[i][j]);
}
printf("\n");
}
close(sock_fd);
}
```

Server Program

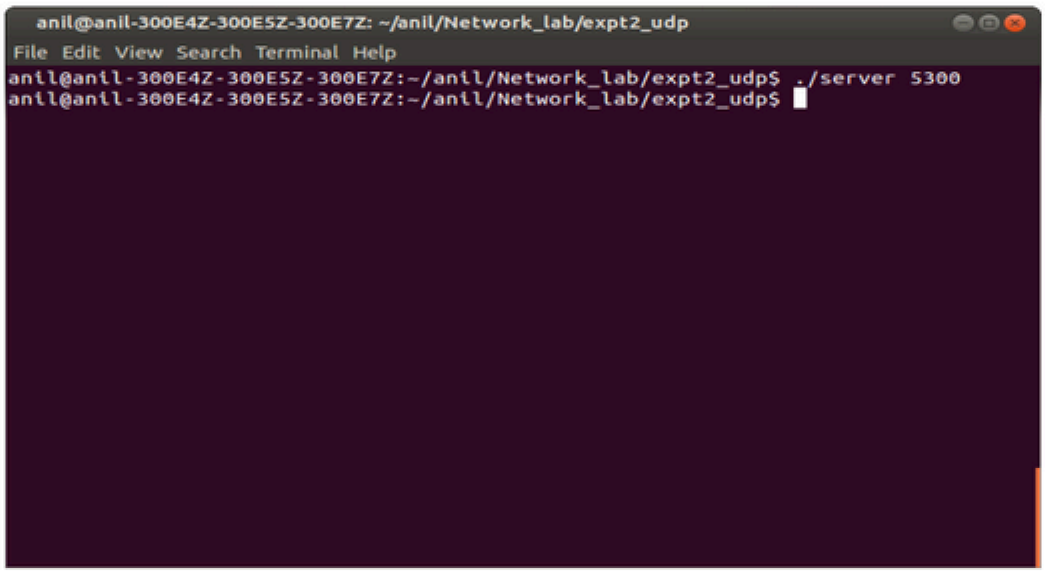
```
#include<stdio.h>
#include<string.h>
#include<sys/socket.h>
#include<sys/types.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<stdlib.h>

main(int argc, char * argv[])
{
int n;
int sock_fd;
int i,j,k;
int row_1, row_2, col_1, col_2;
struct sockaddr_in servaddr, cliaddr;
int len = sizeof(cliaddr);
int matrix_1[10][10], matrix_2[10][10], matrix_product[10][10];
int size[2][2];
if(argc != 2)
{
fprintf(stderr, "Usage: ./server port\n");
exit(1);
}

if((sock_fd = socket(AF_INET, SOCK_DGRAM, 0)) < 0)
{
printf("Cannot create socket\n");
exit(1);
}
bzero((char*)&servaddr, sizeof(servaddr));
servaddr.sin_family = AF_INET;
servaddr.sin_port = htons(atoi(argv[1]));
servaddr.sin_addr.s_addr = htonl(INADDR_ANY);
if(bind(sock_fd, (struct sockaddr*)&servaddr, sizeof(servaddr)) < 0)
{
perror("bind failed:");
exit(1);
}
// MATRICES RECEIVE
```

```
if((n = recvfrom(sock_fd, size, sizeof(size), 0, (struct sockaddr *)&cliaddr, &len)) == -1)
{
perror("size not received:");
exit(1);
}
// RECEIVE MATRIX 1
if((n = recvfrom(sock_fd, matrix_1, sizeof(matrix_1), 0, (struct sockaddr *)&cliaddr, &len)) ==
-1)
{
perror("matrix 1 not received:");
exit(1);
}
// RECEIVE MATRIX 2
if((n = recvfrom(sock_fd, matrix_2, sizeof(matrix_2), 0, (struct sockaddr *)&cliaddr, &len)) ==
-1)
{
perror("matrix 2 not received:");
exit(1);
}
row_1 = size[0][0];
col_1 = size[0][1];
row_2 = size[1][0];
col_2 = size[1][1];
for (i =0; i < row_1 ; i++)
for (j =0; j <col_2; j++)
{
matrix_product[i][j] = 0;
}
for(i =0; i< row_1 ; i++)
for(j=0; j< col_2 ; j++)
for (k=0; k < col_1; k++)
{
matrix_product[i][j] += matrix_1[i][k]*matrix_2[k][j];
}
n = sendto(sock_fd, matrix_product, sizeof(matrix_product),0, (struct sockaddr*)&cliaddr,
sizeof(cliaddr));
if( n < 0)
{
perror("error in matrix product sending");
exit(1);
```

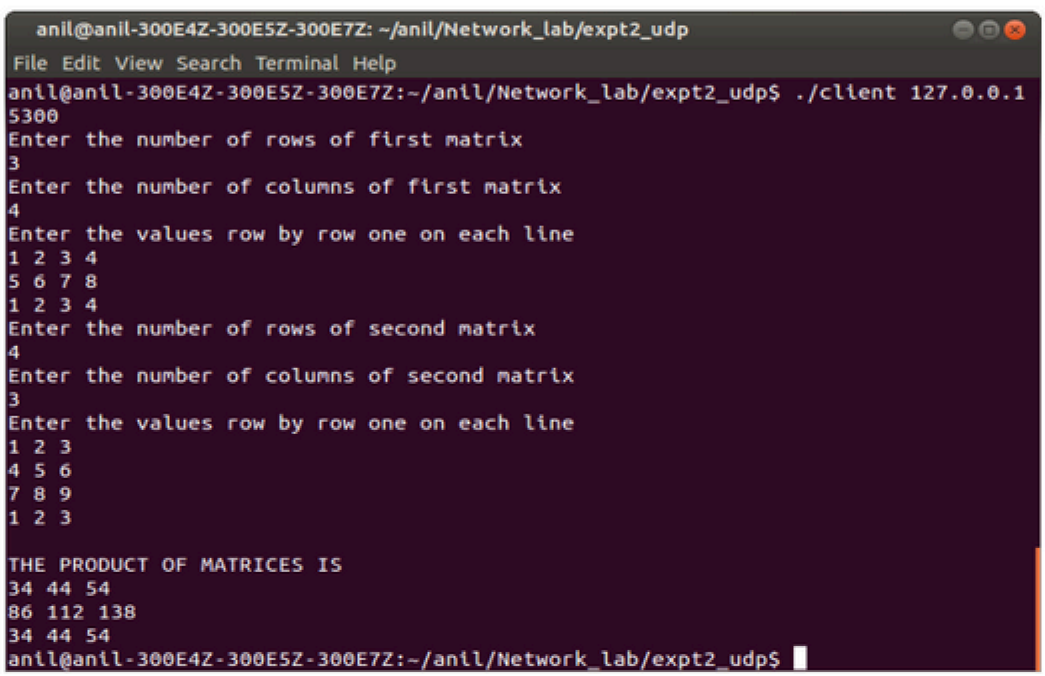
```
}
close(sock_fd);
}
```

Output

Server



Client



Experiment 5

Simulate sliding window flow control protocols. (Stop and Wait, Go back N, Selective Repeat ARQ protocols)

sliding window flow control protocols

Flow control deals with problem that sender transmits frames faster than receiver can accept, and solution is to limit sender into sending no faster than receiver can handle Consider the simplex case: data is transmitted in one direction (Note although data frames are transmitted in one direction, frames are going in both directions, i.e. link is duplex) Stop and wait: sender sends one data frame, waits for acknowledgement (ACK) from receiver before proceeding to transmit next frame This simple flow control will break down if ACK gets lost or errors occur → sender may wait for ACK
that never arrives

Go-back-n ARQ

The basic idea of go-back-n error control is: If frame i is damaged, receiver requests retransmission
of all frames starting from frame i
Notice that all possible cases of damaged frame and ACK / NAK must be taken into account
In selective-reject ARQ error control, the only frames retransmitted are those receive a NAK or which time out

1. Stop and Wait

Server.c

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
```