This call is used to specify for a socket the protocol port number where it will wait for messages. A call to bind is optional in the case of client and compulsory on the server side.

int bind(int sd, struct sockaddr* addr, int addrlen);

The first field is the socket descriptor. The second is a pointer to the address structure of this socket. The third field is the length in bytes of the size of the structure referenced by **addr**. The header files are **sys/types.h** and **sys/socket.h**. This function call returns an integer, which is 0 for success and -1 for failure.

4. Receiving data

ssize_t recvfrom(int s, void * buf, size_t len, int flags, struct sockaddr * from, socklen_t *
fromlen);

The **recvfrom** calls are used to receive messages from a socket, and may be used to receive data on a socket whether or not it is connection oriented. The first parameter s is the socket descriptor to read from. The second parameter buf is the buffer to read information into. The third parameter len is the maximum length of the buffer. The fourth parameter is flag. It is set to zero. The fifth parameter from is a pointer to **struct sockaddr** variable that will be filled with the IP address and port of the originating machine. The sixth parameter fromlen is a pointer to a **local int** variable that should be initialized to **sizeof(struct sockaddr)**. When the function returns, the integer variable that fromlen points to will contain the actual number of bytes that is contained in the socket address structure. The header files required are **sys/types.h** and **sys/socket.h**. When the function returns, the number of bytes received is returned or -1 if there is an error.

5. Sending data

sendto- sends a message from a socket

ssize_t sendto(int s, const void * buf, size_t len, int flags, const struct sockaddr * to, socklen t tolen);

The first parameter s is the socket descriptor of the sending socket. The second parameter buf is the array which stores data that is to be sent. The third parameter len is the length of that data in bytes. The fourth parameter is the flag parameter. It is set to zero. The fifth parameter to points to a variable that contains the destination IP address and port. The sixth parameter tolen is set to **sizeof(struct sockaddr)**. This function returns the number of bytes actually sent or -1 on error. The header files used are **sys/types.h** and **sys/socket.h.**

Algorithm

Client

- 1. Create socket
- 2. Read the matrices from the standard input and send it to server using socket
- 3. Read product matrix from the socket and display it on the standard output
- 4. Close the socket

Server

- 1. Create socket
- 2. bind IP address and port number to the socket
- 3. Read the matrices socket from the client using socket
- 4. Find product of matrices
- 5. Send the product matrix to the client using socket
- 6. close the socket

Client program

```
#include<stdio.h>
#include<string.h>
#include<sys/socket.h>
#include<sys/types.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<stdlib.h>
main(int argc, char * argv[])
{
int i,j,n;
int sock fd;
struct sockaddr in servaddr;
int matrix_1[10][10], matrix_2[10][10], matrix_product[10][10];
int size[2][2];
int num rows 1, num cols 1, num rows 2, num cols 2;
if(argc != 3)
fprintf(stderr, "Usage: ./client IPaddress of server port\n");
exit(1);
}
printf("Enter the number of rows of first matrix\n");
```

```
scanf("%d", &num rows 1);
printf("Enter the number of columns of first matrix\n");
scanf("%d", &num cols 1);
printf("Enter the values row by row one on each line\n");
for (i = 0; i < num rows 1; i++)
for(j=0; j<num cols 1; j++)
scanf("%d", &matrix_1[i][j]);
size[0][0] = num rows 1;
size[0][1] = num cols 1;
printf("Enter the number of rows of second matrix\n");
scanf("%d", &num rows 2);
printf("Enter the number of columns of second matrix\n");
scanf("%d", &num_cols_2);
if( num cols 1 != num rows 2)
printf("MATRICES CANNOT BE MULTIPLIED\n");
exit(1);
printf("Enter the values row by row one on each line\n");
for (i = 0; i < num rows 2; i++)
for(j=0; j<num cols 2; j++)
scanf("%d", &matrix_2[i][j]);
size[1][0] = num rows 2;
size[1][1] = num cols 2;
if((sock fd = socket(AF INET, SOCK DGRAM, 0)) < 0)
printf("Cannot create socket\n");
exit(1);
bzero((char*)&servaddr, sizeof(servaddr));
servaddr.sin family = AF INET;
servaddr.sin port = htons(atoi(argv[2]));
inet pton(AF INET, argv[1], &servaddr.sin addr);
// SENDING MATRIX WITH SIZES OF MATRICES 1 AND 2
n = sendto(sock fd, size, sizeof(size),0, (struct sockaddr*)&servaddr, sizeof(servaddr));
```

```
if (n < 0)
perror("error in matrix 1 sending");
exit(1);
}
// SENDING MATRIX 1
         sendto(sock fd,
                            matrix 1,
                                        sizeof(matrix 1),0,
                                                              (struct
                                                                        sockaddr*)&servaddr,
sizeof(servaddr));
if (n < 0)
{
perror("error in matrix 1 sending");
exit(1);
}
// SENDING MATRIX 2
         sendto(sock fd,
                            matrix 2,
                                        sizeof(matrix 2),0,
                                                              (struct
                                                                        sockaddr*)&servaddr,
sizeof(servaddr));
if (n < 0)
perror("error in matrix 2 sending");
exit(1);
if((n=recvfrom(sock fd, matrix product, sizeof(matrix product),0, NULL, NULL)) == -1)
perror("read error from server:");
exit(1);
printf("\n\nTHE PRODUCT OF MATRICES IS \n\n\n");
for (i=0; i < num rows 1; i++)
for(j=0; j<num cols 2; j++)
printf("%d ",matrix_product[i][j]);
printf("\n");
}
close(sock fd);
```

Server Program

```
#include<stdio.h>
#include<string.h>
#include<sys/socket.h>
#include<sys/types.h>
#include<netinet/in.h>
#include<arpa/inet.h>
#include<fcntl.h>
#include<stdlib.h>
main(int argc, char * argv[])
{
int n;
int sock fd;
int i,j,k;
int row_1, row_2, col_1, col_2;
struct sockaddr in servaddr, cliaddr;
int len = sizeof(cliaddr);
int matrix 1[10][10], matrix 2[10][10], matrix product[10][10];
int size[2][2];
if(argc != 2)
fprintf(stderr, "Usage: ./server port\n");
exit(1);
}
if((sock fd = socket(AF INET, SOCK DGRAM, 0)) < 0)
printf("Cannot create socket\n");
exit(1);
bzero((char*)&servaddr, sizeof(servaddr));
servaddr.sin family = AF INET;
servaddr.sin port = htons(atoi(argv[1]));
servaddr.sin addr.s addr = htonl(INADDR ANY);
if(bind(sock fd, (struct sockaddr*)&servaddr, sizeof(servaddr)) < 0)
perror("bind failed:");
exit(1);
}
// MATRICES RECEIVE
```

```
if((n = recvfrom(sock fd, size, sizeof(size), 0, (struct sockaddr *)&cliaddr, &len)) == -1)
perror("size not received:");
exit(1);
// RECEIVE MATRIX 1
if((n = recvfrom(sock fd, matrix 1, sizeof(matrix 1), 0, (struct sockaddr *)&cliaddr, &len)) ==
-1)
perror("matrix 1 not received:");
exit(1);
}
// RECEIVE MATRIX 2
if((n = recvfrom(sock fd, matrix 2, sizeof(matrix 2), 0, (struct sockaddr *)&cliaddr, &len)) ==
-1)
{
perror("matrix 2 not received:");
exit(1);
}
row 1 = size[0][0];
col 1 = size[0][1];
row 2 = size[1][0];
col 2 = size[1][1];
for (i = 0; i < row 1; i++)
for (j = 0; j < col 2; j++)
matrix product[i][j] = 0;
for(i = 0; i < row 1; i++)
for(j=0; j < col 2; j++)
for (k=0; k < col 1; k++)
matrix product[i][j] += matrix 1[i][k]*matrix 2[k][j];
n = sendto(sock fd, matrix product, sizeof(matrix product),0, (struct sockaddr*)&cliaddr,
sizeof(cliaddr));
if (n < 0)
perror("error in matrix product sending");
exit(1);
```

```
}
close(sock_fd);
}
```

Output

Server

```
anil@anil-300E4Z-300E5Z-300E7Z: ~/anil/Network_lab/expt2_udp

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anil@anil-300E4Z-300E5Z-300E7Z: ~/anil/Network_lab/expt2_udp$ ./server 5300

anil@anil-300E4Z-300E5Z-300E7Z: ~/anil/Network_lab/expt2_udp$ 

anil@anil-300E4Z-300E7Z-300E7Z-300E7Z-300E7Z-300E7Z-300E7Z-300E7Z-300E7Z-300E7
```

Client

```
anil@anil-300E4Z-300E5Z-300E7Z: ~/anil/Network_lab/expt2_udp
                                                                            File Edit View Search Terminal Help
anil@anil-300E4Z-300E5Z-300E7Z:~/anil/Network_lab/expt2_udp$ ./client 127.0.0.1
5300
Enter the number of rows of first matrix
Enter the number of columns of first matrix
Enter the values row by row one on each line
1 2 3 4
5 6 7 8
1 2 3 4
Enter the number of rows of second matrix
Enter the number of columns of second matrix
Enter the values row by row one on each line
1 2 3
4 5 6
789
1 2 3
THE PRODUCT OF MATRICES IS
34 44 54
86 112 138
34 44 54
anil@anil-300E4Z-300E5Z-300E7Z:~/anil/Network_lab/expt2_udp$
```

Experiment 5

Simulate sliding window flow control protocols. (Stop and Wait, Go back N, Selective Repeat ARQ protocols)

sliding window flow control protocols

Flow control deals with problem that sender transmits frames faster than receiver can accept, and solution is to limit sender into sending no faster than receiver can handle Consider the simplex case: data is transmitted in one direction (Note although data frames are transmitted in one direction, frames are going in both directions, i.e. link is duplex) Stop and wait: sender sends one data frame, waits for acknowledgement (ACK) from receiver before proceeding to transmit next frame This simple flow control will break down if ACK gets lost or errors occur \rightarrow sender may wait for ACK that never arrives

Go-back-n ARQ

The basic idea of go-back-n error control is: If frame i is damaged, receiver requests retransmission

of all frames starting from frame i

Notice that all possible cases of damaged frame and ACK / NAK must be taken into account

In selective-reject ARQ error control, the only frames retransmitted are those receive a NAK or which time out

1. Stop and Wait

Server.c

#include <stdio.h> #include <stdlib.h> #include <string.h>

```
#include <time.h>
#include <sys/types.h>
#include <svs/stat.h>
#include <sys/socket.h>
#include <unistd.h>
#include <arpa/inet.h>
typedef struct packet{
char data[1024];
}Packet;
typedef struct frame{
int frame kind; //ACK:0, SEQ:1 FIN:2
int sq no;
int ack;
Packet packet;
}Frame;
int main(int argc, char** argv){
if (argc != 2){
printf("Usage: %s <port>", argv[0]);
exit(0);
}
int port = atoi(argv[1]);
int sockfd;
struct sockaddr in serverAddr, newAddr;
char buffer[1024];
socklen taddr size;
int frame id=0;
Frame frame recv;
Frame frame send;
sockfd = socket(AF INET, SOCK DGRAM, 0);
memset(&serverAddr, '\0', sizeof(serverAddr));
serverAddr.sin family = AF INET;
serverAddr.sin port = htons(port);
serverAddr.sin addr.s addr = inet addr("127.0.0.1");
bind(sockfd, (struct sockaddr*)&serverAddr, sizeof(serverAddr));
addr size = sizeof(newAddr);
while(1){
int f recv size = recvfrom(sockfd, &frame recv, sizeof(Frame), 0, (struct
sockaddr*)&newAddr, &addr size);
if (f recv size > 0 && frame recv.frame kind == 1 && frame recv.sq no ==
frame id){
```

```
printf("[+]Frame Received: %s\n", frame recv.packet.data);
frame send.sq no = 0;
frame send.frame kind = 0;
frame send.ack = frame recv.sq no + 1;
sendto(sockfd, &frame_send, sizeof(frame_send), 0, (struct
sockaddr*)&newAddr, addr size);
printf("[+]Ack Send\n");
}else{
printf("[+]Frame Not Received\n");
frame_id++;
}
close(sockfd);
return 0;
}
client.c
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include <arpa/inet.h>
#include <sys/socket.h>
typedef struct packet{
char data[1024];
}Packet;
typedef struct frame{
int frame kind; //ACK:0, SEQ:1 FIN:2
int sq no;
int ack;
Packet packet;
}Frame;
int main(int argc, char **argv[]){
if (argc != 2){
printf("Usage: %s <port>", argv[0]);
exit(0);
}
int port = atoi(argv[1]);
```

```
int sockfd;
struct sockaddr_in serverAddr;
char buffer[1024];
socklen taddr size;
int frame id = 0;
Frame frame send;
Frame frame recv;
int ack recv = 1;
sockfd = socket(AF INET, SOCK DGRAM, 0);
memset(&serverAddr, '\0', sizeof(serverAddr));
serverAddr.sin family = AF INET;
serverAddr.sin port = htons(port);
serverAddr.sin addr.s addr = inet addr("127.0.0.1");
while(1){
if(ack recv == 1){
frame send.sq no = frame id;
frame send.frame kind = 1;
frame send.ack = 0;
printf("Enter Data: ");
scanf("%s", buffer);
strcpy(frame send.packet.data, buffer);
sendto(sockfd, &frame send, sizeof(Frame), 0, (struct
sockaddr*)&serverAddr, sizeof(serverAddr));
printf("[+]Frame Send\n");
int addr size = sizeof(serverAddr);
int f recv size = recvfrom(sockfd, &frame recv, sizeof(frame recv), 0, (struct
sockaddr*)&serverAddr, &addr size);
if( f recv size > 0 && frame recv.sq no == 0 && frame recv.ack ==
frame id+1){
printf("[+]Ack Received\n");
ack recv = 1;
}else{
printf("[-]Ack Not Received\n");
ack_recv = 0;
}
frame id++;
close(sockfd);
return 0;
```

}

OUTPUT

```
Activities Terminal To Pip2ogadministrator-russ: -/unni/CN

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IIIII Nelcome to Linux Server IIIII

Last login: Tue Jun 21 20:04:53 2022 from 392.108.99.215 pl220Badministrator-russ: -/unni/CNS pl220
```

2. Go_Back ARQ

Reciver.c

```
#include<stdio.h>
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<string.h>
#include<time.h>
#include<stdlib.h>
#include<ctype.h>
#include<arpa/inet.h>
#define W 5
#define P1 50
#define P2 10
char a[10];
char b[10];
void alpha9(int);
int main()
struct sockaddr_in ser,cli;
int s,n,sock,i,j,c=1,f;
```

```
unsigned int s1;
s=socket(AF INET,SOCK STREAM,0);
ser.sin_family=AF_INET;
ser.sin port=6500;
ser.sin_addr.s_addr=inet_addr("127.0.0.1");
bind(s,(struct sockaddr *) &ser, sizeof(ser));
listen(s,1);
n=sizeof(cli);
sock=accept(s,(struct sockaddr *)&cli, &n);
printf("\nTCP Connection Established.\n");
s1=(unsigned int) time(NULL);
srand(s1);
strcpy(b,"Time Out ");
recv(sock,a,sizeof(a),0);
f=atoi(a);
while(1)
for(i=0;i< W;i++)
recv(sock,a,sizeof(a),0);
if(strcmp(a,b)==0)
{
break;
}
i=0;
while(i<W)
{
j=rand()%P1;
if(j < P2)
{
send(sock,b,sizeof(b),0);
break;
}
else
{
alpha9(c);
if(c \le f)
{
printf("\nFrame %s Received ",a);
```

```
send(sock,a,sizeof(a),0);
}
else
{
break;
C++;
if(c>f)
break;
}
j++;
close(sock);
close(s);
return 0;
}
void alpha9(int z)
int k,i=0,j,g;
k=z;
while(k>0)
{
j++;
k=k/10;
}
g=i;
i--;
while(z>0)
{
k=z%10;
a[i]=k+48;
i--;
z=z/10;
a[g]='\0';
```

Client.c

```
#include<stdio.h>
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<string.h>
#include<time.h>
#include<stdlib.h>
#include<ctype.h>
#include<arpa/inet.h>
#define W 5
#define P1 50
#define P2 10
char a[10];
char b[10];
void alpha9(int);
int main()
{
struct sockaddr in ser,cli;
int s,n,sock,i,j,c=1,f;
unsigned int s1;
s=socket(AF_INET,SOCK_STREAM,0);
ser.sin_family=AF_INET;
ser.sin port=6500;
ser.sin addr.s addr=inet addr("127.0.0.1");
bind(s,(struct sockaddr *) &ser, sizeof(ser));
listen(s,1);
n=sizeof(cli);
sock=accept(s,(struct sockaddr *)&cli, &n);
printf("\nTCP Connection Established.\n");
s1=(unsigned int) time(NULL);
srand(s1);
strcpy(b,"Time Out ");
recv(sock,a,sizeof(a),0);
f=atoi(a);
while(1)
for(i=0;i<W;i++)
```

```
recv(sock,a,sizeof(a),0);
if(strcmp(a,b)==0)
{
break;
}
i=0;
while(i<W)
j=rand()%P1;
if(j < P2)
send(sock,b,sizeof(b),0);
break;
}
else
alpha9(c);
if(c \le f)
printf("\nFrame %s Received ",a);
send(sock,a,sizeof(a),0);
}
else
break;
}
C++;
if(c>f)
break;
j++;
close(sock);
close(s);
return 0;
}
```

```
void alpha9(int z)
{
  int k,i=0,j,g;
  k=z;
  while(k>0)
{
  i++;
  k=k/10;
}
  g=i;
  i--;
  while(z>0)
{
  k=z%10;
  a[i]=k+48;
  i--;
  z=z/10;
}
  a[g]='\0';
}
```

3. Selective repeat ARQ

Reciver.c

```
#include<stdio.h>
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<string.h>
#include<time.h>
#include<stdlib.h>
#include<ctype.h>
#include<arpa/inet.h>
#define W 5
#define P1 50
#define P2 10
char a[10];
char b[10];
void alpha9(int);
void alp(int);
int main()
{
struct sockaddr in ser,cli;
int s,n,sock,i,j,c=1,f;
unsigned int s1;
s=socket(AF_INET,SOCK_STREAM,0);
ser.sin_family=AF_INET;
ser.sin port=6500;
ser.sin addr.s addr=inet addr("127.0.0.1");
bind(s,(struct sockaddr *) &ser, sizeof(ser));
listen(s,1);
n=sizeof(cli);
sock=accept(s,(struct sockaddr *)&cli, &n);
printf("\nTCP Connection Established.\n");
s1=(unsigned int) time(NULL);
srand(s1);
strcpy(b,"Time Out ");
recv(sock,a,sizeof(a),0);
f=atoi(a);
while(1)
for(i=0;i<W;i++)
```

```
recv(sock,a,sizeof(a),0);
if(strcmp(a,b)==0)
{
break;
}
i=0;
while(i<W)
{
L:
j=rand()%P1;
if(j < P2)
{
alp(c);
send(sock,b,sizeof(b),0);
goto L;
}
else
{
alpha9(c);
if(c \le f)
printf("\nFrame %s Received ",a);
send(sock,a,sizeof(a),0);
}
else
break;
C++;
if(c>f)
break;
j++;
close(sock);
close(s);
```

```
return 0;
}
void alpha9(int z)
int k,i=0,j,g;
k=z;
while(k>0)
{
j++;
k=k/10;
}
g=i;
i--;
while(z>0)
{
k=z%10;
a[i]=k+48;
i--;
z=z/10;
}
a[g]='\0';
void alp(int z)
{
int k,i=1,j,g;
k=z;
b[0]='N';
while(k>0)
{
j++;
k=k/10;
}
g=i;
i--;
while(z>0)
{
k=z%10;
b[i]=k+48;
i--;
z=z/10;
```

```
b[g]='\0';
Client.c
#include<stdio.h>
#include<sys/types.h>
#include<sys/socket.h>
#include<netinet/in.h>
#include<string.h>
#include<time.h>
#include<stdlib.h>
#include<ctype.h>
#define W 5
char a[10];
char b[10];
void alpha9(int);
int con();
int main()
int s,f,wl,c=1,x,i=0,j,n,p=0,e=0;
struct sockaddr_in ser;
s=socket(AF_INET,SOCK_STREAM,0);
ser.sin family=AF INET;
ser.sin port=6500;
ser.sin addr.s addr=inet addr("127.0.0.1");
connect(s,(struct sockaddr *) &ser, sizeof(ser));
printf("\nTCP Connection Established.\n");
printf("\nEnter the number of Frames: ");
scanf("%d",&f);
alpha9(f);
send(s,a,sizeof(a),0);
strcpy(b,"Time Out ");
while(1)
for(i=0;i<W;i++)
alpha9(c);
send(s,a,sizeof(a),0);
```

```
if(c \le f)
printf("\nFrame %d Sent",c);
C++;
}
i=0;
wl=W;
while(i<W)
{
recv(s,a,sizeof(a),0);
p=atoi(a);
if(a[0]=='N')
{
e=con();
if(e<f)
printf("\nNAK %d",e);
printf("\nFrame %d sent",e);
i--;
}
}
else
if(p \le f)
printf("\nFrame %s Acknowledged",a);
wl--;
}
else
{
break;
if(p>f)
break;
j++;
```

```
if(wl==0 \&\& c>f)
send(s,b,sizeof(b),0);
break;
else
{
c=c-wl;
wI=W;
close(s);
return 0;
void alpha9(int z)
int k,i=0,j,g;
k=z;
while(k>0)
{
į++;
k=k/10;
}
g=i;
i--;
while(z>0)
{
k=z%10;
a[i]=k+48;
i--;
z=z/10;
}
a[g]='\0';
int con()
{
char k[9];
int i=1;
while(a[i]!='\0')
{
```

```
k[i-1]=a[i];
i++;
}
k[i-1]='\0';
i=atoi(k);
return i;
}
```

Experiment 6

Implement and simulate algorithm for Distance Vector Routing protocol

Aim: To implement and simulate algorithm for Distance vector routing protocol

Description:

This algorithm is iterative, and distributed. Each node receives information from its directly attached neighbors, performs some calculations and results to its neighboring nodes. This process of updating the information goes on until there is no exchange of information between neighbors.

Algorithm:

(adapted from Computer Networking – A top down approach by Kurose and Rose)

Bellman Ford algoithm is applied.

Let dx(y) be the cost of the least cost path from node x to node y. Then Bellman Ford equation states that

$$dx(y) = min\{ c(x,v) + dv(y) \}$$

٧

where v is a neighbour of node x. dv(y) is the cost of the least cost path from v to y. c(x,v) is the cost

from x to neighbour v. The least cost path has a value equal to minimum of c(x,v) + dv(y) over all its

neighbours v. The solution of Bellman Ford equation provides entries in node x's forwarding table.

Distance vector (DV) algorithm

At each node x

Initialization:

for all destinations y in N:

 $Dx(y) = c(x,y) /* if y is not a neighbour of x, then <math>c(x,y) = \infty */$

for each neighbour w, send distance vector $Dx = \{ Dx(y): y \text{ in } N \}$ to w loop: for each y in N: $Dx(y) = min \{ c(x,v) + Dv(y) \}$