

The Extended CAN Message 29-bit Identifier is structured as follows:

Module Address (2-bit)	Module ID (4-bit)	Data Header (3-bit)	Message Type (4-bit)	Data ID (16-bit)
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- **Module Address (2-bit):** These bits represent the specific address of the module within the network. With 2 bits, there are 4 possible addresses (00, 01, 10, 11). So, a maximum of 4 modules of the same type can be connected.
- **Module ID (4-bit):** These bits identify the type of module. With 4 bits, there are 16 possible module IDs (0000 to 1111).
- **Data Header (3-bit):** These bits provide additional information about the data being sent. With 3 bits, there are 8 possible headers (000 to 111).
- **Message Type (4-bit):** These bits specify the type of message being sent. With 4 bits, there are 16 possible message types (0000 to 1111).
- **Data ID (16-bit):** These bits represent the specific data id or payload associated with the message. With 16 bits, there are 65536 possible data IDs (0000000000000000 to 1111111111111111).

Types of Modules	Module Address	Module ID
ETU	0	0
TCP	0	1
TM1	0	2
TM2	1	2
DIO1	0	3
DIO2	1	3
DIO3	2	3
DIO4	3	3
EL	0	4
BLE	0	5

Extended Message ID and DLC Format Understanding with CAN v2.0B.

Data Header (3-bit)		Message Type (4-bit)		Data ID (16-bit)	Frame Type	DLC	Process Description
2	Breaker Data Status	0	Data Read Request	UID	REMOTE	-	Breaker Status Read: The initiator module sends 'Data Read Request' with 'UID' of the first parameter. The data owner Module sends 'Data Read Response' with the data bytes of the queried parameters. Please note that the Data Read Request is sent only once, Data Read Response and Data Read Acknowledgement are the frames needed to be communicated from the initiator and target modules respectively for sending larger payload data. Example for the same is explained below.
		1	Data Read Response	Same as Request	DATA	8	
		9	Data Read Acknowledgement	Same as Request	DATA	8	
7	Heartbeat	14 (E)	Data Transmit	UID	DATA	8	This is a process defined so that a Module can transmit uptime and health data without any request using 'Heartbeat' message.

Example 1: In case of TCP to ETU Communication over CAN - Querying for retrieving Breaker Data Status:

- The **Module Address** of TCP Module is 0x00.
- The initiator module is TCP Module having **Module ID** 0x01.
- The **Data Header** is Breaker Data Status 0x02.
- The **Message Type** is **Data Read Request** i.e. 0x00.
- The UID i.e. the **Data ID** is Breaker Data Status' Start Address i.e. 0x0333.

The final CAN Extended ID is generated as **0x01200333**. (Query from TCP to ETU)

Example 1: In case of ETU to TCP Communication over CAN - Sending response to the above Query for Breaker Data Status:

- The **Module Address**, **Module ID**, **Data Header** and **Data ID** will remain the same as Query.
- The **Message Type** is **Data Read Response** i.e. 0x01.

The final CAN Extended ID is updated to **0x01210333**. (Response from ETU to TCP)

An elaborate example is shown below with Message ID and DLC Data. Please refer to Section (B).

CAN v2.0B Messages for TCP Modules communicating with ETU Module.

A. Heartbeat Message (Initiator Node/Module - Ethernet):

The "Heartbeat" Message refers to a periodic message broadcast by each type of module on the CAN bus. This message serves as a health check, ensuring that the node is still active and functioning correctly.

The CAN Extended Message ID is **0x017E0333** and the CAN Frame Format is **Classic CAN** and DLC is **8 bytes**.

The DLC Payload Structure's first 4 bytes consist of the uint32_t upTimeTCP and remaining three bytes are 0:

```
CAN_HeartBeatMessage.ui8_Data[0] = (uint8_t)(upTimeTCP >> 24);
CAN_HeartBeatMessage.ui8_Data[1] = (uint8_t)(upTimeTCP >> 16);
CAN_HeartBeatMessage.ui8_Data[2] = (uint8_t)(upTimeTCP >> 8);
CAN_HeartBeatMessage.ui8_Data[4] = (uint8_t)upTimeTCP;
CAN_HeartBeatMessage.ui8_Data[4] = 0;
CAN_HeartBeatMessage.ui8_Data[5] = 0;
CAN_HeartBeatMessage.ui8_Data[6] = 0;
CAN_HeartBeatMessage.ui8_Data[7] = 0;
```

CAN Frame as seen on the bus:

```
TCP Heartbeat:    0x017E0333 | 0x00 0x00 0x00 0x01 0x00 0x00 0x00 0x00 | Classic CAN | 8 bytes | RTR Data
TCP Heartbeat:    0x017E0333 | 0x00 0x00 0x00 0x02 0x00 0x00 0x00 0x00 | Classic CAN | 8 bytes | RTR Data
TCP Heartbeat:    0x017E0333 | 0x00 0x00 0x00 0x03 0x00 0x00 0x00 0x00 | Classic CAN | 8 bytes | RTR Data
```

This CAN_HeartBeatMessage is to be transmitted every 500ms on the CAN Bus without expecting any acknowledgement from any other nodes/modules.

B. Data Read Request Message (Initiator Node/Module - Ethernet & Target Node/Module - ETU):

This is a message request from the TCP Module to the ETU Module to receive a struct data.

We have a struct data which is to be transmitted over CAN.

```

typedef struct __attribute__((packed))
{
    uint16_t data1;
    uint16_t data2;
    uint16_t data3;
    uint16_t data4;
    uint16_t data5;
    uint16_t data6;
    uint16_t data7;
    uint16_t data8;
    uint16_t data9;
    uint16_t data10;
    uint16_t data11;
    uint16_t data12;
    uint16_t data13;
    uint16_t data14;
    uint16_t data15;
    uint16_t data16;
    uint16_t data17;
    uint16_t data18;
    uint16_t data19;
    uint16_t data20;
    uint16_t data21;
    uint16_t data22;
    uint16_t data23;
    uint32_t data24;
    uint32_t data25;
    uint16_t data26;
} BR_DATA;

```

Converting the above typedef struct to a uint8_t buffer_BR_DATA []

```

uint8_t buffer_BR_DATA[] =
{
    0x01, 0x00,           // data1
    0x00, 0x00,           // data2
    0x01, 0x00,           // data3
    0x02, 0x00,           // data4
    0x01, 0x00,           // data5
    0x00, 0x00,           // data6
    0x01, 0x00,           // data7
    0x96, 0x00,           // data8
    0x05, 0x00,           // data9
    0x91, 0x00,           // data10

```

```

0x0A, 0x00,          // data11
0x03, 0x00,          // data12
0x01, 0x00,          // data13
0x02, 0x00,          // data14
0x04, 0x00,          // data15
0x01, 0x00,          // data16
0x32, 0x00,          // data17
0x30, 0x00,          // data18
0x0A, 0x00,          // data19
0x05, 0x00,          // data20
0x04, 0x00,          // data21
0x06, 0x00,          // data22
0x03, 0x00,          // data23
0x10, 0x27, 0x00, 0x00, // data24
0xF4, 0x01, 0x00, 0x00, // data25
0x01, 0x01           // data26
};

```

CAN DLC and Extended Message ID Explanation:

1. Calculate the number of CAN Frames:

Number of CAN Frames = (sizeof(buffer_BR_DATA) / 5).

Important: If there is a remainder, round up to the next whole number.

2. Querying and Reception of CAN Frames:

- a. An RTR frame of Remote type is sent by the **TCP Module** using Message ID: **0x01200333** to which the **ETU Module** will send a RTR Data Frame as a response with Message ID: **0x01210333** appending CAN Frame Number (1 byte), then first 5 bytes of the buffer_BR_DATA[] (5 bytes) to the DLC. Lastly calculating the 16-bit CRC of bytes 0 to 5 and appending the same (2 bytes) to the DLC as shown below:

1 byte	-----	5 bytes	-----	2bytes
CAN Frame Number (DLC byte 0)		Payload Data (DLC bytes 1 to 5)		16-bit CRC (DLC bytes 6 and 7)

TCP Request: **0x01200333** | ----- | **Classic CAN** | **0 bytes** | **RTR Remote**

ETU Response 1: **0x01210333** | **0x01 0x01 0x00 0x00 0x00 0x01 0xFF 0xFC** | **Classic CAN** | **8 bytes** | **RTR Data**

- b. The **TCP Module** checks the CRC and the CAN Frame Number, if the CRC check is successful then the **TCP Module** sends an Acknowledgement CAN Frame of Message ID: **0x01490333** clearing the Payload Data (i.e., settings the bytes as 0) but retaining the CAN Frame Number. The CRC of bytes 0 to 5 is then recalculated and appended to the DLC of the new CAN Frame.

TCP Frame Ack 1: **0x01290333** | **0x01 0x00 0x00 0x00 0x00 0x00 0xFF 0xFE** | **Classic CAN** | **8 bytes** | **RTR Data**

- c. **ETU Module** receives the above Acknowledgement CAN Frame.

- The DLC of the new ETU response frame updates here. In the DLC; byte 0 CAN Frame Number increments by 1; followed by this, the next 5 bytes of `buffer_BR_DATA[]` are appended.
- Lastly calculating the 16-bit CRC of bytes 0 to 5 and appending the same (2 bytes) to the DLC.
- The Message ID is updated by adding payload data size (5 bytes) to the previous response sent by ETU i.e., **0x01210333 + 0x05 = 0x01210338**.

ETU Response 2: **0x01210338** | **0x02 0x00 0x02 0x00 0x01 0x00 0xFF 0xFA** | **Classic CAN** | **8 bytes** | **RTR Data**

- The TCP Module then replies with the Acknowledgement upon successful reception of data.

TCP Frame Ack 2: **0x01290338** | **0x02 0x00 0x00 0x00 0x00 0x00 0xFF 0xFD** | **Classic CAN** | **8 bytes** | **RTR Data**

- d. Steps (a) to (d) are repeated for all transmitting all the data frames.

ETU Response 3: **0x0121033D** | **0x03 0x00 0x00 0x01 0x00 0x96 0xFF 0x65** | **Classic CAN** | **8 bytes** | **RTR Data**

Extended Message ID and DLC Format Understanding with CAN v2.0B.

TCP Frame Ack 3:	0x0129033D		0x03	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xFC		Classic CAN		8 bytes		RTR Data
ETU Response 4:	0x01210342		0x04	0x00	0x05	0x00	0x91	0x00	0x00	0xFF	0x65		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 4:	0x01290342		0x04	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xFB		Classic CAN		8 bytes		RTR Data
ETU Response 5:	0x01210347		0x05	0x0A	0x00	0x03	0x00	0x01	0x00	0xFF	0xEC		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 5:	0x01290347		0x05	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xFA		Classic CAN		8 bytes		RTR Data
ETU Response 6:	0x0121034C		0x06	0x00	0x02	0x00	0x04	0x00	0x00	0xFF	0xF3		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 6:	0x0129034C		0x06	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF9		Classic CAN		8 bytes		RTR Data
ETU Response 7:	0x01210351		0x07	0x01	0x00	0x32	0x00	0x30	0x00	0xFF	0x95		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 7:	0x01290351		0x07	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF8		Classic CAN		8 bytes		RTR Data
ETU Response 8:	0x01210356		0x08	0x00	0x0A	0x00	0x05	0x00	0x00	0xFF	0xE8		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 8:	0x01290356		0x08	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF7		Classic CAN		8 bytes		RTR Data
ETU Response 9:	0x0121035B		0x09	0x04	0x00	0x06	0x00	0x03	0x00	0xFF	0xE9		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 9:	0x0129035B		0x09	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF6		Classic CAN		8 bytes		RTR Data
ETU Response 10:	0x01210360		0x0A	0x00	0x10	0x27	0x00	0x00	0x00	0xFF	0xBE		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 10:	0x01290360		0x0A	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF5		Classic CAN		8 bytes		RTR Data
ETU Response 11:	0x01210365		0x0B	0xF4	0x01	0x00	0x00	0x01	0x00	0xFE	0xFE		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 11:	0x01290365		0x0B	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF4		Classic CAN		8 bytes		RTR Data
ETU Response 12:	0x0121036A		0x0C	0x01	0x00	0x00	0x00	0x00	0x00	0xFF	0xF2		Classic CAN		8 bytes		RTR Data
TCP Frame Ack 12:	0x0129036A		0x0C	0x00	0x00	0x00	0x00	0x00	0x00	0xFF	0xF3		Classic CAN		8 bytes		RTR Data