



### Destination Index (DI 16-Bits)

It is normally used to hold the **offset address** for **Extra segment** but can also be used for other segments using Segment Overriding. It holds **offset address** of **destination** in Extra Seg, during **String Operations**.

### c) **ALU (16-Bits)**

It has a **16-bit ALU**. It performs 8 and 16-bit arithmetic and logic operations.

### d) **Operand Register**

It is a 16-bit register used by the control register to hold the operands temporarily.  
It is **not available** to the Programmer.

### e) **Instruction Register and Instruction Decoder** (Present inside the Control Unit)

The **EU** fetches an **opcode** from the **queue** into the **Instruction Register**. The **Instruction Decoder** decodes it and sends the information to the control circuit for execution.

### f) Flag Register (16-Bits)

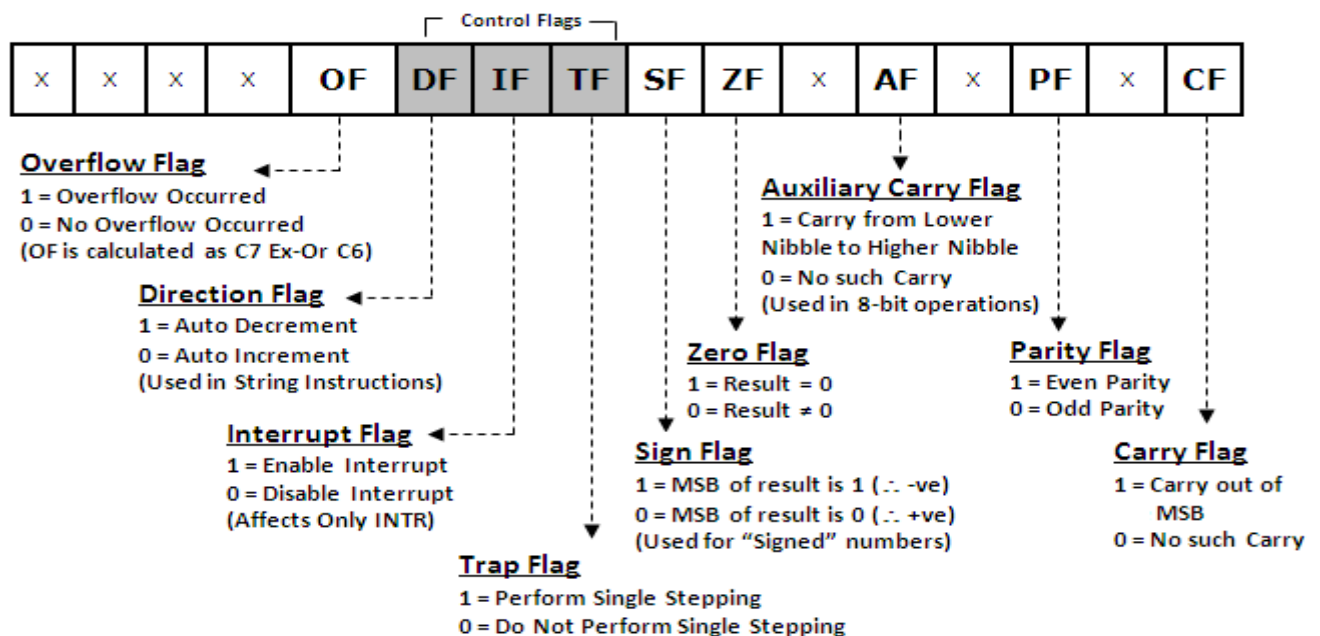
It has **9 Flags**.

These flags are of two types: **6-Status** (Condition) Flags and **3-Control** Flags.

**Status flags** are affected by the ALU, after every arithmetic or logic operation. They give the **status of the current result**.

The **Control flags** are used to control certain operations.

They are changed by the programmer.



## STATUS FLAGS

1) Carry flag (CY)

It is **set** whenever there is a **carry** {or borrow} out of the MSB of a the result  
(D7 bit for an 8-bit operation D15 bit for a 16-bit operation)

2) Parity Flag (PF)

It is **set** if the result has **even parity**.

3) Auxiliary Carry Flag (AC)

It is **set** if a carry is generated out of the **Lower Nibble**.  
It is used only in 8-bit operations like DAA and DAS.

4) Zero Flag (ZF)

It is **set** if the result is **zero**.

5) Sign Flag (SF)

It is **set** if the **MSB** of the result is **1**.  
For **signed** operations, such a number is treated as **-ve**.

6) Overflow Flag (OF)

It will be set if the **result of a signed operation is too large to fit** in the number of bits available to represent it. It can be **checked using the instruction INTO** (Interrupt on Overflow). #Please refer Bharat Sir's Lecture Notes for this ...

## CONTROL FLAGS

1) Trap Flag (TF)

It is used to **set** the Trace Mode i.e. start **Single Stepping Mode**.  
Here the  $\mu P$  is **interrupted after every instruction** so that, the **program** can be **debugged**.

2) Interrupt Enable Flag (IF)

It is used to mask (disable) or unmask (enable) the INTR interrupt.

3) Direction Flag (DF)

If this flag is **set**, **SI** and **DI** are in **auto-decrementing** mode in **String Operations**.