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#define trigPin 12
#define echoPin 13
int Buzzer = 8; // Connect buzzer pin to 8
int ledPin= 6; //Connect LEd pin to 6
int duration, distance; //to measure the distance and time taken

void setup() {
    Serial.begin (9600);
    //Define the output and input objects(devices)
    pinMode(trigPin, OUTPUT);
    pinMode(echoPin, INPUT);
    pinMode(Buzzer, OUTPUT);
    pinMode(ledPin, OUTPUT);
}

void loop() {

    digitalWrite(trigPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigPin, LOW);
    duration = pulseIn(echoPin, HIGH);
    distance = (duration/2) / 29.1;
    //when distance is greater than or equal to 200 OR less than or equal to 0,the buzzer and
    LED are off
    if (distance < 100)
    {
        Serial.println("alert");
        digitalWrite(Buzzer,LOW);
        digitalWrite(ledPin,LOW);
    }
    else {
        Serial.println("object detected \n");
        Serial.print("distance= ");
        Serial.print(distance);    //prints the distance if it is between the range 0 to 200
        tone(Buzzer,400);          // play tone of 400Hz for 500 ms
        digitalWrite(ledPin,HIGH);
    }
}
}

```

Output

