

Phalanx: An Flexible and Extensible Assembly/Field Evaluation Kernel For Handling Complexity in Simulation

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- Phalanx Contributors
 - Eric Phipps
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 - Dennis Ridzal
 - Andy Salinger



Motivation

- Assembly for general FE/FV PDE discretizations gets quite complex when supporting arbitrary equation sets.
- Issues to Address:
 - Compact and uniform user interface for extensibility
 - Flexibility to easily swap equation sets, material models and material properties while maintaining efficiency
 - Support for user defined data types
 - Support for embedded technology
 - Good OO-design/Code reuse
- Generalization and unification of:
 - Expression Manager in SIERRA/Aria
 - Variable Manager in Charon



Overview

- Phalanx is a local field evaluation kernel designed for assembly of arbitrary equation sets (i.e. evaluating residuals and Jacobians).
 - Equation sets, material models might change drastically
- Decompose a complex problem into a number of simpler problems with managed dependencies
 - Supports rapid development and extensibility
 - Consistent evaluation of fields as dependencies change
- Phalanx supports arbitrary user defined **data types** and **evaluation types** through template metaprogramming.
 - Flexibility for direct integration with user applications
 - Provides extensive support for embedded technology such as automatic differentiation for sensitivities and uncertainty quantification.
- Efficient evaluation of fields using worksets and memory management for efficient use of cache.

Complex Dependency Chains

Momentum $\frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} + \mathbf{T}) - \rho \mathbf{g} = 0$

Continuity $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$

Energy $\rho C_p \frac{\partial T}{\partial t} + \nabla \cdot (\rho C_p T \mathbf{v} - \mathbf{q}) + s = 0$

Species $\rho \frac{\partial y_i}{\partial t} + \nabla \cdot (\rho \mathbf{v} y_i + \mathbf{j}_k) + W_i \dot{\omega}_i$ $i = 1 \dots N_{sp}$

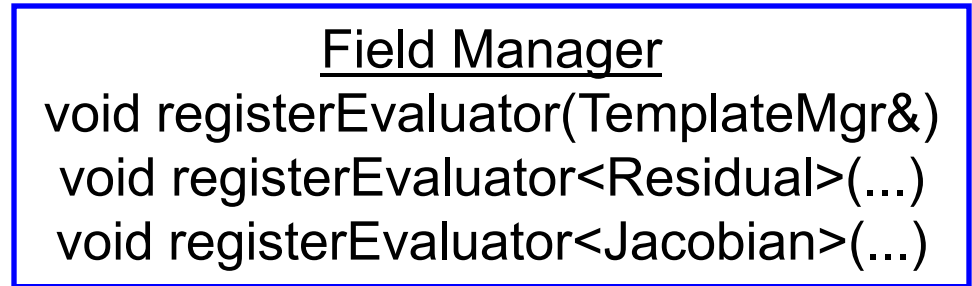
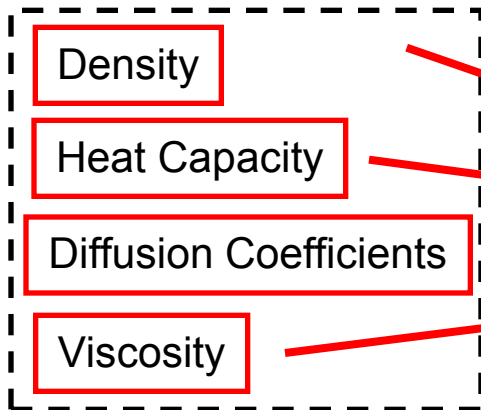
$$\mathbf{T} = P\mathbf{I} + \frac{2}{3}\mu(\nabla \cdot \mathbf{u})\mathbf{I} - \mu(\nabla \mathbf{u} + \nabla \mathbf{u}^T) \quad \mathbf{q} = -k\nabla T$$

$$\mathbf{j}_k = \rho y_k \frac{1}{x_k \bar{W}} \sum_{j=1}^K W_j D_{kj} \nabla x_j$$

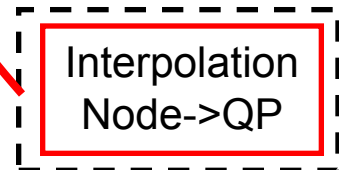
- Complexity spirals when we add new equations, operators, use subsets, etc...
 - Swap eqns/models at runtime (no complex if/switch statements)
- Automatically adjust the dependency tree** $\rho(T, P) \longrightarrow \rho(y_i, P, T)$
- Separate fields so that they are evaluated only once (density)

Idea: Evaluators (Expressions)

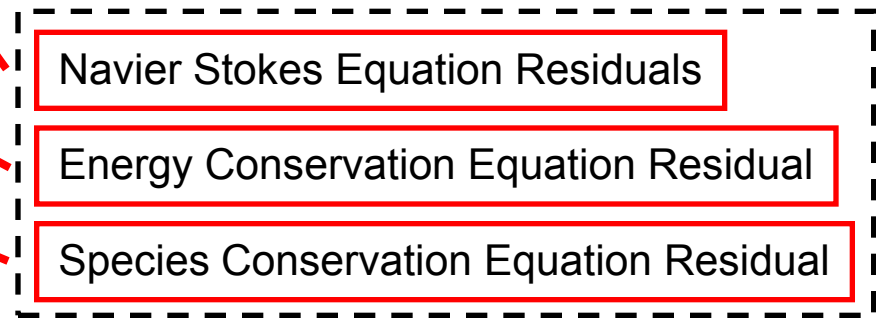
Material Property Library



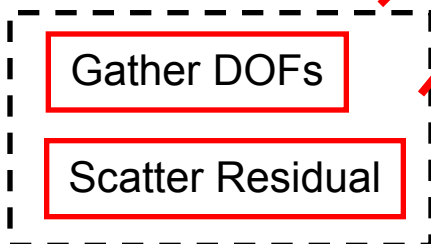
FEM



Physics/Equation Set



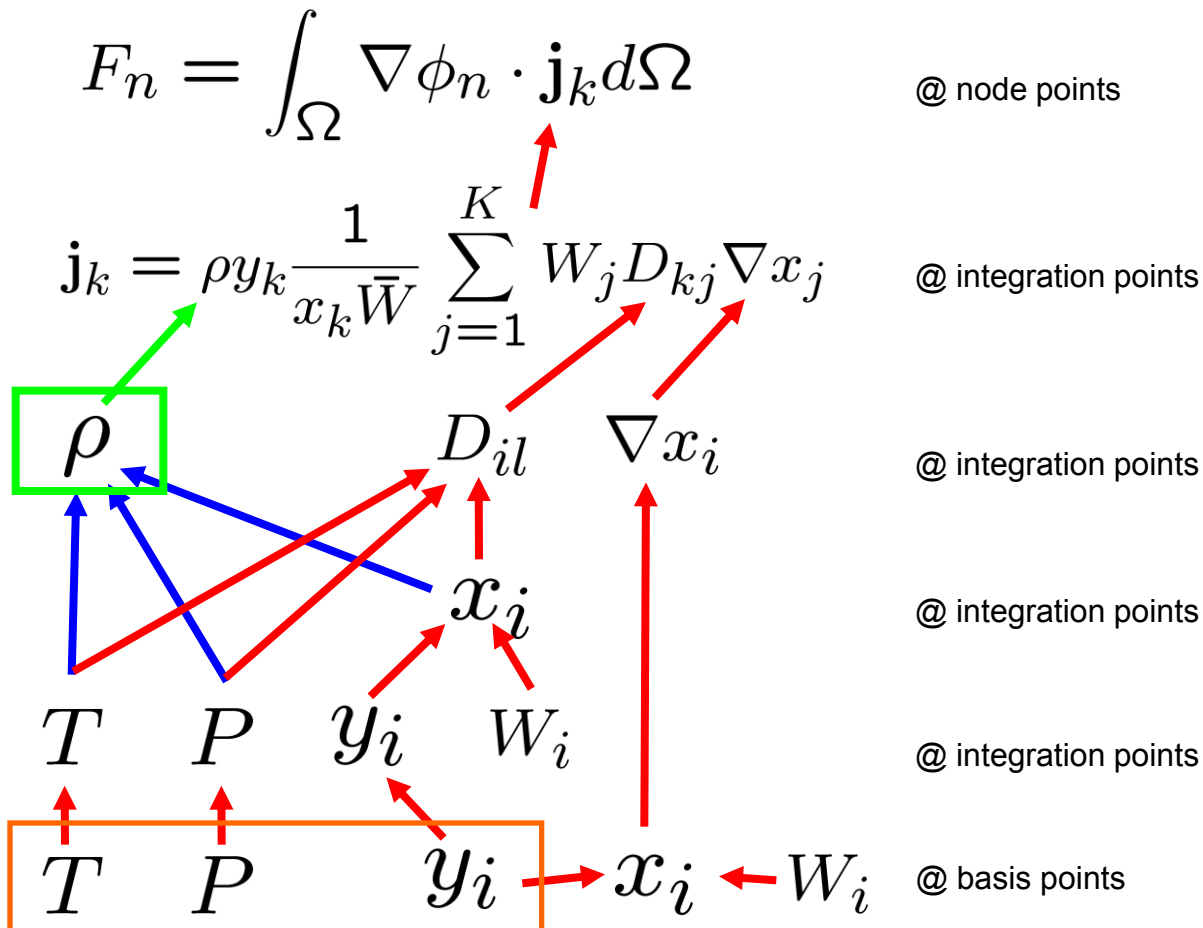
Solver



Evaluators can be registered anytime before `postRegistrationSetup()`

Evaluator Anatomy

$$\rho \frac{\partial y_i}{\partial t} + \nabla \cdot (\rho \mathbf{v} y_i) + \nabla \cdot \mathbf{j}_k + W_i \dot{\omega}_i \Rightarrow F_n = \int_{\Omega} \nabla \phi_n \cdot \mathbf{j}_k d\Omega$$



- Evaluates one or more fields
- Depends on one or more fields
- **CTOR**: Size the fields
- **Setup** Method: Get pointers to memory
- **Evaluate** Method: Evaluate the field(s)
- Intrepid package does the final integration



Idea: Chain of Evaluators

- Phalanx FieldManager will
 - Determine which evaluators to call
 - The order to call the evaluators for consistency
 - Perform the evaluation on a workset

```
field_manager.evaluateFields<Residual>(workset) ;
```

```
field_manager.evaluateFields<Jacobian>(workset) ;
```




Evaluators: Simple for Users

- We must simplify interfaces for analysts to implement
 - Don't expose entire equation set to users
 - Hide advanced c++ (i.e. templating) from analysts looking to add new equations and material models
 - Don't have to know about derivatives/solver techniques

$$\mathbf{q} = -\rho k \nabla T$$

```
PHX_EVALUATOR_CLASS(EnergyFlux)

Field< MyVector<ScalarT> > flux;

Field< ScalarT > density;
Field< ScalarT > k;
Field< MyVector<ScalarT> > grad_temp;

int points_per_cell;

PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
{
    int size = workset.num_cells * points_per_cell;

    for (int i = 0; i < size; ++i)
        flux[i] = -density[i] * k[i] * grad_temp[i];
}
```

Skipped CTOR (field sizing),
Setup (get pointers to memory)



Workset/Memory Management

- Break work up into worksets
 - Chunk of cells in finite element/volume calculation
- Memory allocation of all fields of all scalar types for an evaluation type is done in a single contiguous array!
 - Possibly fit all fields in cache
 - User defined allocators (template parameter in Traits)
- Leverage BLAS in evaluators



What does this buy you?

- Consistent Evaluations: Dependencies are ensured to be up-to-date
- Evaluate each field once per cell
 - No recalculation of temporaries
- **Flexible and Extensible**: each simpler piece becomes an extension point that can be swapped out with different implementations
- Easier to craft code because each piece is simpler, more focused and **easier to test** in isolation
- **Minimal interface**: isolate users from bulk of assembly process
- Efficient: use of worksets
 - Block evaluations → Blas
 - Possibly fits into cache



Embedded Technology!!!

Field Manager is templated on Evaluation Type

Concept: Evaluation Types

- Residual $F(x, p)$

- Jacobian $J = \frac{\partial F}{\partial x}$

- Tangent $\frac{\partial F}{\partial p}$

- Stochastic Galerkin Residual

- Stochastic Galerkin Jacobian

Scalar Types

`double`

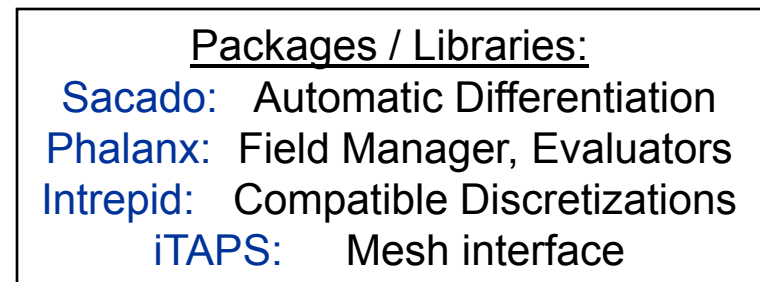
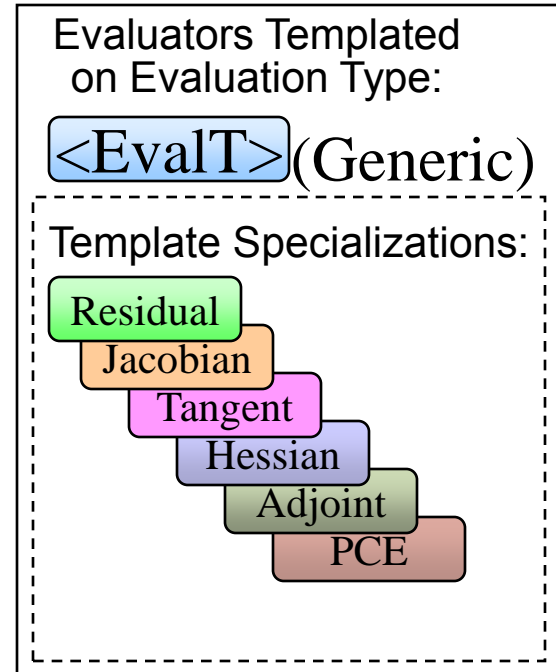
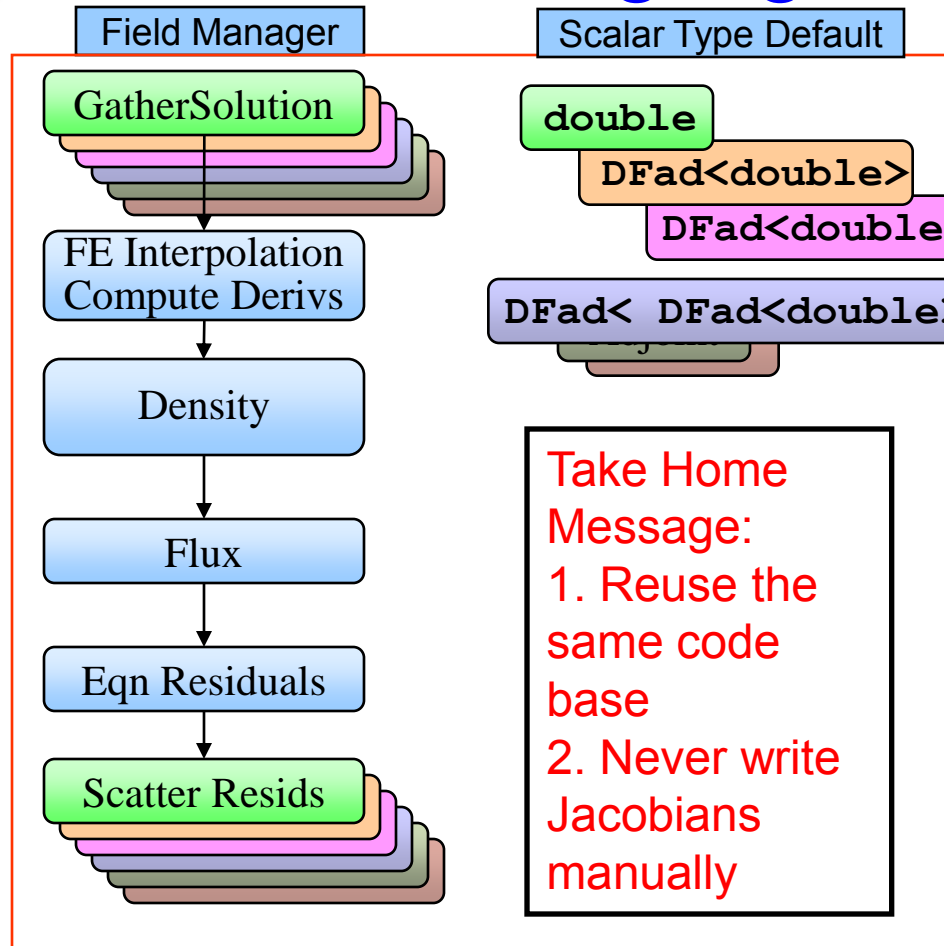
`Sacado::FAD::DFad<double>`

`Sacado::FAD::DFad<double>`

`Sacado::PCE::OrthogPoly<double>`

`Sacado::Fad::DFad< Sacado::PCE::OrthogPoly<double> >`

Transformational PDE Assembly using Agile Components



Rapid, Transformational, Scalable

Example Traits

```
struct MyTraits : public PHX::TraitsBase {
```

```
    typedef double RealType;  
    typedef Sacado::Fad::DFad<double> FadType;
```

← Declare Scalar Types

```
    struct Residual { typedef RealType ScalarT; };  
    struct Jacobian { typedef FadType ScalarT; };
```

← Declare Evaluation Types

```
    typedef boost::mpl::vector<Residual, Jacobian> EvalTypes;
```

← Evaluation Types

```
    // Residual (default scalar type is RealType)  
    typedef boost::mpl::vector< RealType,  
                               MyVector<RealType>,  
                               MyMatrix<RealType>  
    > ResidualDataTypes;
```

← Declare Residual
Data Types

```
    // Jacobian (default scalar type is Fad<double>)  
    typedef boost::mpl::vector< FadType,  
                               MyVector<FadType>,  
                               MyMatrix<FadType>  
    > JacobianDataTypes;
```

← Declare Jacobian
Data Types

```
    // Maps the key EvalType a vector of DataTypes  
    typedef boost::mpl::map<  
        boost::mpl::pair<Residual, ResidualDataTypes>,  
        boost::mpl::pair<Jacobian, JacobianDataTypes>  
    >::type EvalToDataMap;
```

← Maps Evaluation Types
to Data Types

Multidimensional Arrays

(Shards – C. Edwards next)

```
PHX_EVALUATOR_CLASS(EnergyFlux)
```

```
Field< MyVector<ScalarT> > flux;
```

```
Field< ScalarT > density;
```

```
Field< ScalarT > k;
```

```
Field< MyVector<ScalarT> > grad_temp;
```

```
int points_per_cell;
```

```
PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
```

```
{  
    int size = workset.num_cells * points_per_cell;
```

```
    for (int i = 0; i < size; ++i)
```

```
        flux[i] = -density[i] * k[i] * grad_temp[i];
```

```
}
```

```
PHX_EVALUATOR_CLASS(EnergyFlux)
```

```
MDField<ScalarT,Cell,QuadPoint,Dim> flux;
```

```
MDField<ScalarT,Cell,QuadPoint> density;
```

```
MDField<ScalarT,Cell,QuadPoint> dc;
```

```
MDField<ScalarT,Cell,QuadPoint,Dim> grad_temp;
```

```
int num_qp;
```

```
int num_dim;
```

```
PHX_EVALUATOR_CLASS_END
```

```
PHX_EVALUATE_FIELDS(EnergyFlux,workset)
```

```
{  
    int num_cells = workset.num_cells;
```

```
    for (int cell = 0; cell < num_cells; ++cell)
```

```
        for (int qp = 0; qp < num_qp; ++qp)
```

```
            for (int dim = 0; dim < num_dim; ++dim)
```

```
                flux(cell,qp,dim) =
```

```
                    - density(cell,qp) * dc(cell,qp) * grad_temp(cell,qp,dim);
```

```
}
```

Optional compile time checked
access



In closing...

- This package is very advanced
 - C++ templates and template metaprogramming
 - One developer will need to know templates to set up
 - Everyone else only needs to write evaluators (very minimal template code)
- Think hard before using
 - This is a hammer, its not right for every PDE code, especially if your equation set/models doesn't change
- “My understanding keeps changing...” – Andy Salinger
- Don't hesitate to ask for help!
- <http://trilinos.sandia.gov/packages/phalanx>: a very detailed users guide.



Phalanx Summary

- Assembly kernel for cell based discretization of PDEs
- Breaks complex problems into simpler pieces
 - Automatically manage complex dependency chains
 - Easier to unit test
 - Don't expose fully complex system to the user – only expose exactly what they need to write a user defined function
- Supports rapid development and extensibility
 - Easily swap evaluation routines
 - Easily swap dependency trees
- Arbitrary user defined data types and evaluation types: C++
Template metaprogramming
- Embedded technology support