

Several arms are linked to form the system shown. Link AB has a length of $I_AB = 0.5 m$, link CD has a length of $I_CD = 0.5 m$, and the distance from B to C is $r_C/B = -1 i + 1 j m$. If the angle between link AB is theta = 45 degrees, determine the angular acceleration of link CD. The angular velocities of the links are given as omega_AB = -3 rad/s and omega_BC = (3sqrt2)/4 rad/s, while the angular acceleration of AB is given as alpha_AB = -5 rad/s^2.

= -3
$$\hat{k} \times (-0.5\cos 45 \hat{i} - 0.5\sin 45 \hat{j}) = 1.5\cos 45 \hat{j} - 1.5\sin 45 \hat{j}$$

$$= -\frac{3\sqrt{2}}{2} \uparrow$$

$$\hat{T}: -\frac{3\sqrt{2}}{2} - \omega_{00}(0.5) = 0$$
 $\omega_{00} = -3\sqrt{2}$

=7510453 + 200545 ?

$$\vec{\Omega}_{c} = \vec{\Omega}_{BC} \times \vec{\Gamma}_{CIB} - \vec{\omega}_{BC}^{2} \vec{\Gamma}_{CIB}$$

$$= \vec{\Omega}_{BC} \hat{k} \times (-1 \hat{r} + 1\hat{j}) - \frac{2}{3} (-1 \hat{r} + 1\hat{j})$$

$$= -\vec{\Omega}_{BC} \hat{j} - \vec{\Omega}_{BC} \hat{i} + \frac{2}{3} \hat{i} - \frac{2}{3} \hat{j}$$

$$\vec{\Omega}_{c} = \vec{\Omega}_{CD} \times \vec{\Gamma}_{CIO} - \vec{\omega}_{CO}^{2} \vec{\Gamma}_{CID}$$

$$= \vec{\Omega}_{CD} \hat{k} \times (-0.5 \hat{j}) - 18 (-0.5 \hat{j})$$

1:
$$0.5 \, \alpha_{cD} = - \, \alpha_{BC} + \frac{9}{8}$$

2: $9 = - \, \alpha_{BC} - \frac{9}{8}$

$$Q_{BC} = -\frac{81}{6}$$
 $Q_{CO} = 22.5$