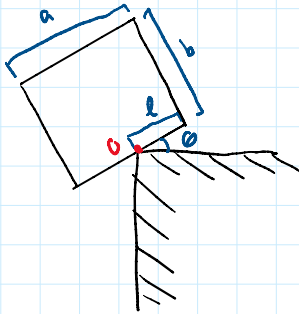


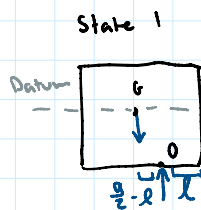
20-R-WE-DK-21 Intermediate Principle of Work and Energy

Inspiration: 10-11.2 Example 2 Mech Notes



A thin plate with dimensions $a = 1 \text{ m}$, $b = 0.8 \text{ m}$, has a mass $m = 2 \text{ kg}$. If the plate is at rest when $\theta = 0$ degrees, determine the angle θ at which it begins to slip. The point of contact O between the plate and the ledge is located a length $l = 0.3 \text{ m}$ from one side of the plate. Take the coefficient of static friction to be $\mu_{s} = 0.3$.

State 1
 $T_1 = 0 \quad v_1 = v_{G1} = 0 \quad \omega_1 = 0$



State 2

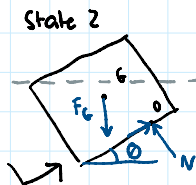
$$T_2 = \frac{1}{2} I_0 \omega^2 \quad \text{as } O \text{ acts as a pin}$$

$$= \frac{1}{2} I_0 \omega^2 + \frac{1}{2} m v_G^2$$

$$I_0 = \frac{1}{2} m (a^2 + b^2) + m \left(\left(\frac{a}{2} \right)^2 + \left(\frac{b}{2} - l \right)^2 \right)$$

$$= \frac{1}{2} (2) (1 + 0.64) + 2 \left((0.4)^2 + (0.5 - 0.3)^2 \right)$$

$$= \frac{101}{150}$$



$$v_2 = v_{G2} = -mg \left(\frac{a}{2} - l \right) \sin \theta$$

$$T_1 + v_1 + \sum U_{1 \rightarrow 2}^{\text{non-cons}} = T_2 + v_2$$

$$\sum U_{1 \rightarrow 2}^{\text{non-cons}} = 0 \quad \text{as friction exists, but if it is not slipping, friction does no work}$$

$$0 = \frac{1}{2} \left(\frac{101}{150} \right) \omega^2 - (2)(9.81)(0.5 - 0.3) \sin \theta$$

$$\omega^2 = \frac{556}{505} \sin \theta$$

State 2

$$\sum F_x: F_f - mg \sin \theta = ma_{Gx}$$

$$\sum F_y: N - mg \cos \theta = ma_{Gy}$$

$$\sum M_O: mg \sin \theta \left(\frac{a}{2} \right) + mg \cos \theta \left(\frac{b}{2} - l \right) = I_0 \alpha$$

$$F_f = \mu_s N$$

$$O \text{ acts like a pin } \vec{a}_O = 0 \quad \vec{a}_G = \vec{a}_O + \vec{\alpha} \times \vec{r}_{G/O} - \omega^2 \vec{r}_{G/O} \quad \vec{r}_{G/O} = \left(-\left(\frac{a}{2} - l \right) \hat{i} + \frac{b}{2} \hat{j} \right)$$

$$\vec{a}_G = \alpha \hat{k} \times (-0.2 \hat{i} + 0.4 \hat{j}) - \omega^2 (-0.2 \hat{i} + 0.4 \hat{j})$$

$$= -0.2 \alpha \hat{j} - 0.4 \alpha \hat{i} + 0.2 \omega^2 \hat{i} - 0.4 \omega^2 \hat{j}$$

$$a_{Gx} = -0.4 \alpha + 0.2 \omega^2 \quad a_{Gy} = -0.2 \alpha - 0.4 \omega^2$$

$$0.3 N - (2)(9.81) \sin \theta = 2(-0.4 \alpha + 0.2 \omega^2)$$

$$N - (2)(9.81) \cos \theta = 2(-0.2 \alpha - 0.4 \omega^2)$$

$$(2)(9.81) \sin \theta (0.4) + (2)(9.81) \cos \theta (0.2) = \frac{101}{150} \alpha$$

$$0.3 N - 19.62 \sin \theta = \frac{11772}{2525} \sin \theta - \frac{23544}{2525} \sin \theta - \frac{11772}{2525} \cos \theta$$

$$N = \frac{25179}{505} \sin \theta - \frac{7844}{505} \cos \theta$$

$$0.3 N - 19.62 \sin \theta = -0.4 \alpha + 0.4 \omega^2$$

$$N - 19.62 \cos \theta = -0.4 \alpha - 0.4 \omega^2$$

$$7.844 \sin \theta + 3.924 \cos \theta = \frac{101}{150} \alpha$$

$$\frac{5846}{505} \sin \theta + \frac{2443}{505} \cos \theta = \alpha$$

$$N - 19.62 \cos \theta = \frac{11772}{2525} \sin \theta - \frac{5846}{2525} \cos \theta - \frac{23544}{2525} \sin \theta \quad N = -\frac{34716}{2525} \sin \theta + \frac{87309}{5050} \cos \theta$$

$$\frac{25179}{505} \sin \theta - \frac{7844}{505} \cos \theta = -\frac{34716}{2525} \sin \theta + \frac{67309}{5050} \cos \theta$$

$$\frac{25179}{505} \sin \theta - \frac{7848}{505} \cos \theta = -\frac{34716}{2525} \sin \theta + \frac{67309}{5050} \cos \theta$$

$$63.66831683 \sin \theta = 32.82950495 \cos \theta$$

$$\tan \theta = 0.514565436$$

$$\theta = 27.4097^\circ$$