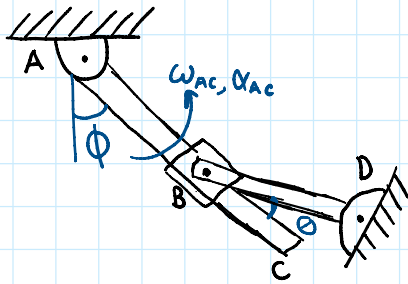


# 20-R-KM-DK-16 Intermediate Rotating Frame Analysis

Inspiration: 16-140 Hibbeler



Bar AC rotates at  $\omega_{AC} = 2 \text{ rad/s}$  with an angular acceleration of  $\alpha_{AC} = 1 \text{ rad/s}^2$ . At that instant, it forms a  $\phi = 55^\circ$  angle with the vertical. If link BD makes a  $\theta = 20^\circ$  angle with bar AC and has a length  $r_{BD} = 0.8 \text{ m}$ , determine the angular velocity and angular acceleration of link BD, as well as the relative acceleration of collar B. The link is connected to a collar which slides along bar AC. The distance to B from A is  $r_{AB} = 1.1 \text{ m}$ .

$$\vec{v}_B = \vec{v}_A + \vec{\Omega} \times \vec{r}_{B/A} + (v_{B/A})_{xyz} \hat{i}$$

$$= 2\hat{k} \times (1.1\hat{i}) + (v_{B/A})_{xyz} \hat{i}$$

$$\vec{v}_B = -\omega_{BD} \hat{k} \times (-0.8 \cos 20^\circ \hat{i} - 0.8 \sin 20^\circ \hat{j})$$

$$= 0.8 \cos 20^\circ \omega_{BD} \hat{j} - 0.8 \sin 20^\circ \omega_{BD} \hat{i}$$

$$\hat{i}: -0.8 \sin 20^\circ \omega_{BD} = (v_{B/A})_{xyz}$$

$$\omega_{BD} = 2.926488 \dots \text{ rad/s}$$

$$\hat{j}: 2.2 = 0.8 \cos 20^\circ \omega_{BD}$$

$$(v_{B/A})_{xyz} = 0.400734515 \text{ m/s}$$

$$\vec{a}_B = \vec{a}_A + \vec{\Omega} \times \vec{r}_{B/A} + \vec{\Omega} \times (\vec{\Omega} \times \vec{r}_{B/A}) + 2\vec{\Omega} \times (v_{B/A})_{xyz} + (\vec{a}_{B/A})_{xyz}$$

$$\vec{a}_B = \alpha_{BD} \hat{k} \times \vec{r}_{B/D} - \omega_{BD}^2 \vec{r}_{B/D}$$

$$= \alpha_{BD} \hat{k} \times (-0.8 \cos 20^\circ \hat{i} - 0.8 \sin 20^\circ \hat{j}) - (2.926488)^2 (-0.8 \cos 20^\circ \hat{i} - 0.8 \sin 20^\circ \hat{j})$$

$$= -0.8 \cos 20^\circ \alpha_{BD} \hat{j} + 0.8 \sin 20^\circ \alpha_{BD} \hat{i} + 6.4362755 \hat{i} + 2.34334 \hat{j}$$

$$\hat{i}: 6.4362755 + 0.8 \sin 20^\circ \alpha_{BD} = 2\hat{k} \times (2\hat{k} \times 1.1\hat{i}) + (a_{B/A})_{xyz}$$

$$\hat{j}: -0.8 \cos 20^\circ \alpha_{BD} + 2.343340651 = 2.2 - 3.20293966$$

$$\alpha_{BD} = 4.451296409 \text{ rad/s}^2$$

$$(a_{B/A})_{xyz} = 12.0562 \text{ m/s}^2$$