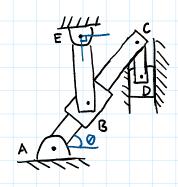
20-R-KM-DK-17

Intermediate Rotating Frame

Inspiration: 5.31 Example



A linkage system consists of several arms, a collar, and a block. Arm AC has a total length r_AC = 1 m and, in the instant shown, is at an angle of theta = 60 degrees with the horizontal. The collar sits on arm AC at a distance r_AB = 0.6 m and is connected to arm BE, which sits vertically and has a length of $r_BE = 0.3 m$. If the collar slides up the arm at a relative velocity of v_B/A_rel = 0.5 m/s, determine the angular velocity and angular acceleration of arm BE.

$$\vec{V}_{B} = \omega_{BE} \hat{k} \times (-0.3 \cos 30 \hat{1} - 0.3 \sin 30 \hat{j}) = -\omega_{BE} 0.3 \cos 30 \hat{j} + 0.3 \omega_{BE} \sin 30 \hat{j}$$

$$\vec{V}_{B} = \Omega_{AC} \hat{k} \times (0.6 \hat{1}) + 0.5 \hat{1} = 0.6 \Omega_{AC} \hat{j} + 0.5 \hat{1}$$

1: 0.5 = 0.5 Was sin 30 =>
$$W_{DE} = \frac{10}{3}$$

1: - $W_{DE} = \frac{10}{3}$
2: - $W_{DE} = \frac{10}{3}$
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$$\vec{Q}_{B} = \vec{Q}_{A} + \vec{\Sigma}_{AC} \times \vec{\Gamma}_{B/A} + 2\vec{\Sigma}_{AC} \times (\vec{V}_{B/A})_{A'1'2'} - \vec{\Omega}_{AC} \cdot \vec{\Gamma}_{B/A} + (\vec{Q}_{B/A})_{A'1'2'} = 0 + \vec{\Sigma}_{AC} \cdot \times (0.6^{\circ}) + 2(-\frac{515}{6} \cdot \hat{k}) \times (0.5^{\circ}) - (-\frac{515}{6})^{\circ}(0.6^{\circ}) + 0$$

$$= 0.6 \cdot \vec{\Omega}_{AC} \cdot \vec{J} - 5\sqrt{5} \cdot \vec{J} - 1.25^{\circ}$$

$$\begin{array}{l}
\overrightarrow{A_{B}} = \overrightarrow{A_{E}} + \overrightarrow{A_{SE}} \times \overrightarrow{A_{S/E}} - \overrightarrow{W_{SE}} \overrightarrow{A_{S/E}} \\
= 0 + 0_{BE} \overrightarrow{E} \times (-0.3 \cos 30 \ \hat{1} - 0.3 \sin 30 \ \hat{1}) - (\frac{10}{3})^{2} (-0.3 \cos 30 \ \hat{1} - 0.3 \sin 30 \ \hat{1}) \\
= -0.3 \ N_{SE} \cos 30 \ \hat{1} + 0.3 \ N_{SE} \sin 30 \ \hat{1} + \frac{10}{3} \cos 30 \ \hat{1} + \frac{10}{3} \sin 30 \ \hat{1}
\end{array}$$